SP21 COMPSCI 513 - Homework 5

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$\mathbf{Q}\mathbf{1}$

All the necessary calculation details are in the next four pages.

```
[CODE]
clear
% Declare Matrix Z
Z = [1]
             2
                    3;
             5
     4
                    6;
      7
             8
                    7;
                    3;
      4
             2
                    2]
     4
e = eye(3);
E = eye(5);
% First Step
A0 = Z;
 x = A0 * e(:, 1)
y = norm(x,2) * E(:, 1)
w = (x-y) / norm(x-y, 2)
H1 = E - 2 * w * w'
A1 = H1 * A0
% Second Step
x = A1 * e(:, 2)
y = x(1) * E(:, 1) + norm(x(2:5),2) * E(:, 2)
w = (x-y) / norm(x-y, 2)
H2 = E - 2 * w * w'
A2 = H2 * A1
% Third Step
x = A2 * e(:, 3);
y = x(1) * E(:, 1) + x(2) * E(:, 2) + norm(x(3:5),2) * E(:, 3)
W = (x-y) / norm(x-y, 2)
H3 = E - 2 * w * w'
A3 = H3 * A2
% Calc q and r
q = H1 * H2 * H3
r = H3 * H2 * H1 * Z
% Use qr routine
[Q R] = qr(Z)
[OUTPUT]
>> Q1
Z =
                    3
      1
             5
      4
                    6
      7
             8
                    7
             2
                    3
      4
x =
      1
      4
      7
y =
```

```
9.8995
        0
        0
        0
        0
w =
  -0.6704
   0.3013
   0.5273
   0.3013
   0.3013
H1 =
                    0.7071
-0.3178
0.4438
                               0.4041
                                         0.4041
   0.1010
            0.4041
   0.4041
            0.8184
                               -0.1816
                                         -0.1816
   0.7071
            -0.3178
                               -0.3178
                                         -0.3178
   0.4041
            -0.1816 -0.3178
                               0.8184
                                         -0.1816
   0.4041
           -0.1816 -0.3178
                               -0.1816
                                         0.8184
A1 =
   9.8995
            9.4954
                      9.6975
           1.6311
                      2.9897
      0
   0.0000
           2.1044
                     1.7320
                     -0.0103
            -1.3689
           -1.3689 -1.0103
x =
   9.4954
   1.6311
   2.1044
  -1.3689
  -1.3689
y =
   9.4954
   3.2919
        0
        0
        0
w =
        0
  -0.5023
   0.6364
  -0.4140
  -0.4140
H2 =
   1.0000
                0
                                    0
                          0
             0.4955 0.6393
0.6393 0.1900
                              -0.4158
0.5269
           0.4955
                                         -0.4158
        0
                                         0.5269
```

```
-0.4158
                       0.5269
                                 0.6572
                                          -0.3428
        0
            -0.4158
                       0.5269
                                -0.3428
                                           0.6572
A2 =
   9.8995
             9.4954
                       9.6975
   0.0000
            3.2919
                       3.0129
   0.0000
             0.0000
                     1.7026
   0.0000
            0.0000
                      0.0089
   0.0000
            -0.0000
                      -0.9911
y =
   9.6975
   3.0129
   1.9701
        0
        0
w =
        0
        0
   -0.2606
   0.0086
  -0.9654
H3 =
    1.0000
                                     0
                                               0
                 0
                           0
             1.0000
        0
                           0
                                     0
                                               0
        0
                       0.8642
                                 0.0045
                                          -0.5031
                 0
                       0.0045
        0
                  0
                                 0.9999
                                          0.0167
                      -0.5031
                                 0.0167
                                          -0.8641
A3 =
   9.8995
             9.4954
                       9.6975
             3.2919
                       3.0129
   0.0000
  -0.0000
             0.0000
                      1.9701
             0.0000
                      -0.0000
   0.0000
             0.0000
  -0.0000
                      0.0000
q =
   0.1010
             0.3162
                       0.5420
                                0.3408
                                         -0.6928
   0.4041
             0.3534
                      0.5162
                                -0.5730
                                         0.3422
            0.3906
                                          0.0028
   0.7071
                      -0.5248
                                0.2684
   0.4041
            -0.5580
                      0.3871
                                0.5006
                                          0.3534
   0.4041
            -0.5580
                      -0.1204
                                -0.4825
                                          -0.5273
r =
   9.8995
             9.4954
                       9.6975
            3.2919
                       3.0129
       0
                       1.9701
   -0.0000
            -0.0000
   0.0000
                 0
                      0.0000
```

-0.0000

-0.0000

-0.0000

Q =

-0.1010	-0.3162	0.5420	-0.6842	-0.3577
-0.4041	-0.3534	0.5162	0.3280	0.5812
-0.7071	-0.3906	-0.5248	0.0094	-0.2683
-0.4041	0.5580	0.3871	0.3656	-0.4918
-0.4041	0.5580	-0.1204	-0.5390	0.4695

R =

-9.8995	-9.4954	-9.6975
0	-3.2919	-3.0129
0	0	1.9701
0	0	0
0	0	0

(a) Take a look at the structure of the H matrix.

$$H = I - 2ww'$$

When compute Hv, we have

$$Hv = (I - 2ww')v = v - 2ww'v$$

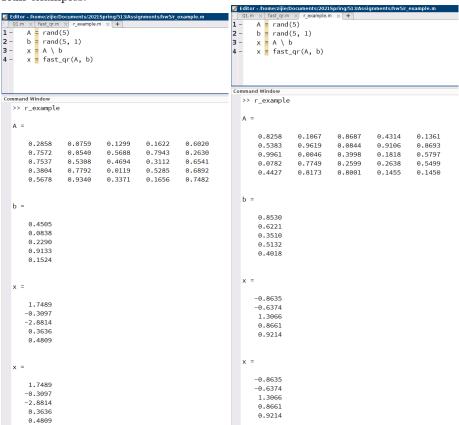
Here, the computational complexity of w'v is O(m), the computational complexity of v-2w(w'v) is O(m). So the final computational complexity is still O(m).

In conclusion, this algorithm is more efficient.

(b) [CODE] fast_qr.m

```
1 function [x] = fast_qr(A,b)
       [n m] = size(A);
 3
      e = eye(m);
      E = eye(n);
 4
 5
      for i=1:m
 6
           x = A * e(:, i);
 7
           y = zeros(n,1);
           for j=1:i-1
 8
               y = y + x(j) * E(:, j);
 9
10
           end
           y = y + norm(x(i:n),2) * E(:, i);
11
           w = (x-y) / norm(x-y, 2);
12
           A = A - 2*w*(w**A);
13
           b = b - 2*w*(w'*b);
14
15
      end
16
      x = zeros(m,1);
      for i=m:-1:1
17
           t = b(i);
18
           for j=i+1:m
19
               t = t - x(j) *A(i,j);
20
21
           end
22
           x(i) = t / A(i,i);
23
      end
24 end
```

(c) Run examples:



(d) Take a look at the code above.

Suppose A is $n \times m$.

Calculate $x, y, w \cos O(n)$

Calculate new $A \cos O(mn)$

Calculate new $b \cos O(m)$

With m times iteration, the total calculation complexity is $O(m^2n)$.