# ISyE/CS/Math 728: Integer Optimization Software/Implementation

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### Outline

- ► Introduction to IP software in general
- ▶ Use of Gurobi with Python interface as an example

### Integer Optimization Solvers

#### Commmercial solvers:

- ► Gurobi: Perhaps current leader
- ► CPLEX (Ilog, now owned by IBM): Long-time leader
- ► XpressMP (FICO): Close competitor
- ► Mosek: Better for continuous optimization

#### Non-commercial:

- Solving Constraint Integer Programs (SCIP): scip.zib.de very good
- ► COIN Branch-and-cut (CBC): www.coin-or.org

- Software for solving MIP problems
  - Why Modeling Languages—MPS Format

### Communicating instances to a solver

Before a solver can solve an integer optimization instance, you must tell it what it is!

How can we do this?

- ▶ Put the data into a text file in a "standard format"
  - ► You don't want to do this by hand!
- ► Formulate the model using an Algebraic Modeling Language
  - Examples: GAMS, AMPL, AIMMS, Pyomo, JuMP
  - ► This is what you should usually do
- ▶ Build the model using the interface of the solver you will use
  - Closest interaction with the solver
  - ► Easy to integrate solver with other code (C++, Python, ...)

CPLEX, Gurobi, Mosel, OPL

### Using the solver API directly

### API: Application Programming Interface

Build the model using interface functions supplied by the solver.

### Advantages

- Access to all features of the solver
  - Parameters, Callbacks to change solver behavior
- Can use all power and generality of programming language (e.g. C,C++,Java,Python)
- Can be integrated into other applications

#### Disadvantages:

- ► Can take longer to write a model
- Married to the solver
- ► You can "break" a solver

Algebraic Modeling Langues (e.g., GAMS, AIMMS, JuMP) are adding more and more of the API functionality

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### In this course

You can use any solver you have access to. Possibilities:

- ► I'll introduce Gurobi, using a Python interface
  - ➤ You can also download a version for academic use: http://www.gurobi.com
- ► CPLEX: You may also be able to get an academic version
  - Can use callable library (C), Concert Technology (C++), or Python interface
- ▶ JuUMP, GAMS or AMPL I won't be able to help much
- Pyomo, Coin CBC, or SCIP (if you are ambitious)
  - ▶ But you're really on your own there

### Gurobi and python

- Gurobi: A MIP Solver.
- Python: Powerful general-purpose scripting language.

#### How does it work?

- Write a python script that builds and runs a model, using a Gurobi module
  - Can write script in any editor or an Integrated Development Environment (IDE)
- Run the script from a terminal: using gurobi.sh (in mac/linux) or gurobi.bat (in windows), or using your native python installation

### Getting started

- 1. Register for a Gurobi account (use your wisc.edu e-mail)
- 2. Gurobi's quick start guide: https:
   //www.gurobi.com/documentation/quickstart.html
- 3. Download and install Gurobi (painless)
- 4. Request then get a license Gurobi quickstart documentation explains this well

# Optional (maybe): Using your own python installation

Gurobi provides good online instructions for installing within Anaconda, and using e.g., Jupyter notebook or Spyder IDE for editing

► I will use the Spyder IDE

### First example: mip1.py

Let's model a very simple integer program:

$$\begin{aligned} \max & \ x+y+2z\\ \text{s.t.} & \ x+2y+z \leq 4\\ & \ x+y \geq 1\\ & \ x,y,z \in \{0,1\} \end{aligned}$$

Source: Gurobi quick start guide

### Example mip1.py

```
import gurobipy as gp
from gurobipy import GRB
try:
    # Create a new model
    m = gp.Model("mip1")
    # Create variables
    x = m.addVar(vtype=GRB.BINARY, name="x")
    y = m.addVar(vtype=GRB.BINARY, name="y")
    z = m.addVar(vtype=GRB.BINARY, name="z")
```

# Example mip1.py (cont'd)

```
# Set objective
   m.setObjective(x + y + 2 * z, GRB.MAXIMIZE)
   # Add constraint: x + 2 y + 3 z \le 4
   m.addConstr(x + 2 * y + 3 * z \le 4, "c0")
   # Add constraint: x + y >= 1
   m.addConstr(x + y >= 1, "c1")
   # Optimize model
   m.optimize()
for v in m.getVars():
       print('%s %g' % (v.varName, v.x))
   print('Obj: %g' % m.objVal)
```

### Gurobi attributes

Much of the interaction with Gurobi is done through attributes of Gurobi objects

- Gurobi Model attributes: numconstrs, numvars, modelname, runtime, itercount, nodecount, objval, . . .
- ► Gurobi Var (variable) attributes: lb, ub, obj, vtype, varname, x (current solution value), rc (reduced cost), ...
- Gurobi Constr (constraint) attributes: sense, rhs, pi (dual variable value), slack, constrname, . . .

Some attributes can only be queried, others can be queried or set

### A little about python

Key python data structure: List

- A collection of arbitrary objects
- ► Can add to list, remove elements, change elements, etc.

```
l = [1, 'a', 3.5]
print l[1] # prints 'a'
l += 'b'
# Now l = [1, 'a', 3.5, 'b']
```

A similar data structure: Tuple

- Main difference: Tuples cannot be changed once created
- ▶ Importance: Tuples can be used as *keys* to a dictionary

```
t = (1, 'a', 3.5)
print t[1] # prints 'a'
t += 'b' # Produces an error
```

# A little about python (2)

Another data structure: Dictionary

- ► A collection of (key, object) pairs
- Like a list, except access via key rather than by index
- ▶ Useful for storing model elements, like decision variables

```
d = \{\} # creates an empty dictionary d[(5,2,3)] = \text{'object 1'} # Tuple (5,2,3) is the key
```

```
# parentheses on the tuple are optional
d[2,3,4] = 'object 2' # Tuples (2,3,4) is the key
```

### Python dictionary initialization

Python dictionaries can also be initialized like this:

```
values = { 'zero': 0, 'one': 1, 'two': 2 }
print values['zero'] # prints 0
```

Gurobi provides a function, 'multidict', for simultaneously initializing multiple dictionaries having the same key set

▶ Returns a list of the keys, followed by the dictionaries

### Python list comprehension and the tuplelist class

Example of list comprehension for creating a list of tuples:

```
print [(x,y) for x in range(3) for y in range(3) if x != y] # prints: [(0, 1), (0, 2), (1, 0), (1, 2), (2, 0), (2, 1)] # the range(i) command produces list [0,...,i-1]
```

Gurobi provides the 'tuplelist' class for efficiently selecting sublists of tuples

```
l = tuplelist([(1, 2), (1, 3), (2, 3), (2, 4)])
print l.select(1,'*')
# prints: [(1,2), (1,3)]
print l.select('*',3)
# prints: [(1,3), (2,3)]
```

### Gurobi's tupledict class

Similar to 'tuplelist', Gurobi provides a subclass of the general python dictionary called 'tupledict'

- Works like python dictionary, except that the keys are a tuplelist
- ► Enables efficient construction of linear expressions when variables are stored in a 'tupledict' object

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d.sum(1,'\*') # shortcut equivalent to the above statement

# Example model: Multicommodity flow (netflow.py)

#### Mathematical formulation:

- Graph with nodes V and directed arcs A
- ► Set of commodities *H*
- ▶ Arc capacities  $b_{ij}$  for  $(i, j) \in A$
- ▶ Unit shipment costs:  $c_{ijh}$  for  $h \in H$ ,  $(i, j) \in A$
- ▶ Supply/demand of each commodity at each node:  $s_{ih}$  for  $i \in V$ ,  $h \in H$

#### Decision variables:

▶  $x_{ijh}$ : flow of commodity  $h \in H$  on arc  $(i, j) \in A$ 

### Objective:

$$\min \sum_{(i,j)\in A} \sum_{h\in H} c_{ijh} x_{ijh}$$

# Example model: Multicommodity flow (netflow.py)

Arc capacity constraints:

$$\sum_{h \in H} x_{ijh} \le b_{ij}, \quad \forall (i,j) \in A$$

Flow balance constraints:

$$\sum_{(i,j)\in A} x_{ijh} + s_{jh} = \sum_{(j,i)\in A} x_{jih}, \quad \forall j \in V, h \in H$$

```
import gurobipy as gp
from gurobipy import GRB
# Base data
commodities = ['Pencils', 'Pens']
nodes = ['Detroit', 'Denver', 'Boston', 'New York', 'Seattle']
arcs, capacity = gp.multidict({
    ('Detroit', 'Boston'): 100,
    ('Detroit', 'New York'): 80.
    ('Detroit', 'Seattle'): 120,
    ('Denver', 'Boston'): 120,
    ('Denver', 'New York'): 120,
    ('Denver', 'Seattle'): 120})
```

### Initializing the cost data dictionary

```
# Cost for triplets commodity-source-destination
cost = {
   ('Pencils', 'Detroit', 'Boston'): 10,
   ('Pencils', 'Detroit', 'New York'): 20,
   ('Pencils', 'Detroit', 'Seattle'): 60,
   ('Pencils', 'Denver', 'Boston'): 40,
   ('Pencils', 'Denver', 'New York'): 40,
   ('Pencils', 'Denver', 'Seattle'): 30,
   ('Pens', 'Detroit', 'Boston'): 20,
   ('Pens', 'Detroit', 'New York'): 20,
   ('Pens', 'Detroit', 'Seattle'): 80,
   ('Pens', 'Denver', 'Boston'): 60,
   ('Pens', 'Denver', 'New York'): 70,
   ('Pens', 'Denver', 'Seattle'): 30}
```

### Initializing the flow data dictionary

```
# Demand for pairs of commodity-city
inflow = {
    ('Pencils', 'Detroit'): 50,
    ('Pencils', 'Denver'): 60,
    ('Pencils', 'Boston'): -50,
    ('Pencils', 'New York'): -50,
    ('Pencils', 'Seattle'): -10,
    ('Pens', 'Detroit'): 60,
    ('Pens', 'Denver'): 40,
    ('Pens', 'Boston'): -40,
    ('Pens', 'New York'): -30,
    ('Pens', 'Seattle'): -30}
```

Creates the Gurobi model object and the flow variables

```
# Create optimization model
m = gp.Model('netflow')
# Create variables
flow = m.addVars(commodities, arcs, obj=cost, name="flow")
# Arc-capacity constraints
m.addConstrs(
    (flow.sum('*', i, j) <= capacity[i, j] for i, j in arcs), "cap")
# Equivalent version using Python looping
# for i, j in arcs:
   m.addConstr(sum(flow[h, i, j] for h in commodities) <= capacity[i,</pre>
#
                "cap[%s, %s]" % (i, j))
#
```

Creates the flow balance constraints

```
# Flow-conservation constraints
m.addConstrs(
    (flow.sum(h, '*', j) + inflow[h, j] == flow.sum(h, j, '*')
        for h in commodities for j in nodes), "node")

# Alternate version:
# m.addConstrs(
# (gp.quicksum(flow[h, i, j] for i, j in arcs.select('*', j)) + inflow[h, j]
# gp.quicksum(flow[h, j, k] for j, k in arcs.select(j, '*'))
# for h in commodities for j in nodes), "node")
```

- ► the 'select' function is used for the tuplelist arcs to efficiently choose the right arcs to sum over
- 'quicksum' is a Gurobi function that creates the expression representing the sum of the decision variables

Solve the model, check the status, and display the solution

- Solution value is stored in the attribute 'x' of the flow variable object
- ▶ NB: Obtaining all variable values with one call is *much* more efficient than looping and obtaining one at a time

### Solver parameters

MIP solvers have many parameters that you can change to possible change the performance

E.g., many of the choices in branch-and-bound we saw

In Gurobi's python interface, change a parameter associated with a model 'm' with the commands:

- m.setParam("paramname", paramvalue)
- ► m.Params.paramname = paramvalue

where 'paramname' and 'paramvalue' are placeholders

### Examples of paramaters

Nearly all solvers have similar sets of parameters

- ▶ MIPFocus: Feasible solutions (1), optimality (2), or bound (3)
- ► ImproveStartTime: After this amount of time, focus entirely on finding better solutions
- ► TimeLimit: Stop after this amount of time has elapsed
- MIPGap: Stap when gap between lower and upper bound reaches this value
- ► NodeLimit: Stop after processing this many nodes
- Method: Chooses method for solving the initial LP relaxation
- Cuts: Aggressive (2), Conservative (1), Automatic (-1), or None (0)
- ► FlowCoverCuts, etc.: Aggressive (2), Conservative (1),...
- VarBranch: Change the branching variable selection strategy

▶ Presolve: Aggressive (2), Conservative (1),...

### More Gurobi examples

Check out additional examples on your own

- dietmodel.py and diet2.py: Python function, separate data from model
- ▶ fixanddive.py: Implements a simple MIP-based heuristic

### Two types of cuts

User cuts: These never cut off an integer solution that is feasible to the formulation loaded to the solver

- ► These are valid inequalities in the traditional sense
- Only purpose of these cuts is to improve relaxation bound

Lazy cuts: These inequalities help to define the feasible region

- ► They might cut off an integer solution feasible to the formulation originally loaded to the solver
- ► Example: Subtour elimination constraints in TSP
- ► Solvers will let you attempt to generate lazy cuts at every integer solution

You must tell Gurobi which type of cut you are adding.

### Using lazy cuts

- Using lazy cuts to solve a problem with exponentially constraints is sometimes referred to delayed constraint generation
- If you plan to do this, you must turn off some presolve reductions
  - ► These reductions are based on feasibility considerations of the problem, so are not valid if you will change the feasible region
- ▶ In Gurobi: m.Params.lazyConstraints = 1

### Gurobi callbacks

First, declare and implement callback function like this:

def mycallback(model, where):

# Implement the callback routine here

Instruct Gurobi to use the callback when you optimize the model:

```
m.optimize(mycallback)
```

If you need to access data or objects from within the callback, you may add them as private members of the model object, e.g.,

```
m._vars = vars
```

- vars is a list created earlier in the code
- ▶ m.\_vars then stores a pointer to that list for use in the callback

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▶ Names of user data must begin with an underscore

Works but "bad practice": declare global variables above callback function ISyE/CS/Math 728

### Within the callback function

Gurobi provides special functions that can be called within the callback function

model.cbGetSolution, model.cbGetNodeRel, model.cbLazy, model.cbCut, model.cbGet, model.cbSetSolution

The where parameter of the callback routine tells you what step of the solution process Gurobi is in, and limits which functions you can call

```
def mycallback(model, where):
    if where == GRB.callback.SIMPLEX:
        # maybe query something
    if where == GRB.callback.MIP:
        # maybe query something
    if where == GRB.callback.MIPNODE:
        # maybe add user cuts, or set a heuristic solution
    if where == GRB.callback.MIPSOL:
        # maybe add lazy cuts
```

### Getting information in the callback function

Most information on current status can be queried with the function:

- mode.cbGet(what)
- 'what' is the code for the information desired
- Allowed values for 'what' depend on the value of 'where'

```
def mycallback(model, where):
    if where == GRB.callback.SIMPLEX:
        print model.cbGet(GRB.callback.SPX_ITRCNT)
if where == GRB.callback.MIPSOL:
print model.cbGet(GRB.callback.MIPSOL_OBJ)
```

### Gurobi Example: tsp.py

This example finds and adds subtour elimination constraints *only* at integer solutions

```
def subtourelim(model, where):
    if where == GRB.Callback.MTPSOL:
        # make a list of edges selected in the solution
        vals = model.cbGetSolution(model._vars)
        selected = gp.tuplelist((i, j) for i, j in model._vars.keys()
                                if vals[i, j] > 0.5)
        # find the shortest cycle in the selected edge list
        tour = subtour(selected)
        if len(tour) < n:
            # add subtour elimination constr. for every pair of cities
            model.cbLazy(gp.quicksum(model._vars[i, j]
                                     for i, j in combinations(tour, 2))
                         \leq len(tour)-1)
```

Possible variation: Also search for SEC's at fractional solutions