

# Assignment 3

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## 1

Data points  $(-1, 1), (0, 0), (1, 1)$ .

### a

Since there are 3 data points,  $\phi_1(t) = 1, \phi_2(t) = t, \phi_3(t) = t^2, \theta = [a, b, c]^\top$ .

$$\Phi_{i,j} = \phi_j(i) \quad (1)$$

$$\Phi = \begin{bmatrix} 1 & -1 & 1 \\ 1 & 0 & 0 \\ 1 & 1 & 1 \end{bmatrix} \quad (2)$$

$$\Phi\theta = y \Leftrightarrow \begin{bmatrix} 1 & -1 & 1 \\ 1 & 0 & 0 \\ 1 & 1 & 1 \end{bmatrix} \begin{bmatrix} a \\ b \\ c \end{bmatrix} = \begin{bmatrix} 1 \\ 0 \\ 1 \end{bmatrix} \Leftrightarrow \begin{bmatrix} a \\ b \\ c \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ 1 \end{bmatrix} \quad (3)$$

Thus,  $p(t) = \phi(t)^\top \theta = t^2$ .

### b

As for Lagrange basis,

$$\phi_i(t) = \prod_{0 \leq j \leq n \wedge i \neq j} \frac{t - t_j}{t_i - t_j} \quad (4)$$

$$\phi_1(t) = \frac{t - 0}{-1 - 0} \frac{t - 1}{-1 - 1} = \frac{t(t - 1)}{2} \quad (5)$$

$$\phi_2(t) = \frac{t + 1}{0 + 1} \frac{t - 1}{0 - 1} = -t^2 + 1 \quad (6)$$

$$\phi_3(t) = \frac{t + 1}{1 + 1} \frac{t - 0}{1 - 0} = \frac{t(t + 1)}{2} \quad (7)$$

$$p(t) = \phi(t)^\top y = t^2 \quad (8)$$

### c

As for Newton basis,  $\theta = [a, b, c]^\top$ ,

$$\phi_i(t) = \prod_{0 \leq j \leq n \wedge i \neq j} (t - t_j) \quad (9)$$

$$\phi_1(t) = 1 \quad (10)$$

$$\phi_2(t) = t + 1 \quad (11)$$

$$\phi_3(t) = t(t + 1) \quad (12)$$

$$\theta_1 = y_1 = 1 \quad (13)$$

$$\theta_{i+1} = \frac{y_{i+1} - p_i(t_{i+1})}{\phi_{i+1}(t_{i+1})} \quad (14)$$

Thus,  $\theta = [1, -1, 1]^\top$ ,  $p(t) = \phi(t)^\top \theta = t^2$ .

**d**

$p(t) = t^2$  is always obtained.

**e**

As for linear interpolating,

$$p(t) = \begin{cases} -t, & -1 \leq t < 0 \\ t, & 0 \leq t \leq 1 \end{cases} \quad (15)$$

**f**

As for cubic natural spline interpolation,

$$p(t) = \begin{cases} p_1(t) = \alpha_1 + \alpha_2 t + \alpha_3 t^2 + \alpha_4 t^3, & -1 \leq t < 0 \\ p_2(t) = \beta_1 + \beta_2 t + \beta_3 t^2 + \beta_4 t^3, & 0 \leq t \leq 1 \end{cases} \quad (16)$$

Interpolate the data at the endpoints,

$$p_1(-1) = \alpha_1 - \alpha_2 + \alpha_3 - \alpha_4 = 1 \quad (17)$$

$$p_1(0) = \alpha_1 = 0 \quad (18)$$

$$p_2(0) = \beta_1 = 0 \quad (19)$$

$$p_2(1) = \beta_1 + \beta_2 + \beta_3 + \beta_4 = 1 \quad (20)$$

The first derivative of the interpolating function is continuous at  $t = 0$ ,

$$\frac{\partial p_1(t)}{\partial t} \Big|_{t=0} = \alpha_2 = \beta_2 = \frac{\partial p_2(t)}{\partial t} \Big|_{t=0} \quad (21)$$

The second derivative of the interpolating function is continuous at  $t = 0$ ,

$$\frac{\partial^2 p_1(t)}{\partial t^2} \Big|_{t=0} = 2\alpha_3 = 2\beta_3 = \frac{\partial^2 p_2(t)}{\partial t^2} \Big|_{t=0} \quad (22)$$

A natural spline has second derivative equal to zero at the endpoints,

$$\frac{\partial^2 p_1(t)}{\partial t^2} \Big|_{t=-1} = 2\alpha_3 - 6\alpha_4 = 0 \quad (23)$$

$$\frac{\partial^2 p_2(t)}{\partial t^2} \Big|_{t=1} = 2\beta_3 + 6\beta_4 = 0 \quad (24)$$

From (17) to (24),

$$[\alpha_1, \alpha_2, \alpha_3, \alpha_4, \beta_1, \beta_2, \beta_3, \beta_4]^\top = \left[ 0, 0, \frac{3}{2}, \frac{1}{2}, 0, 0, \frac{3}{2}, -\frac{1}{2} \right]^\top \quad (25)$$

Thus,

$$p(t) = \begin{cases} p_1(t) = \frac{1}{2}t^3 + \frac{3}{2}t^2, & -1 \leq t < 0 \\ p_2(t) = -\frac{1}{2}t^3 + \frac{3}{2}t^2, & 0 \leq t \leq 1 \end{cases} \quad (26)$$

## 2

Notice that  $[-1, 1]$  is a symmetric interval.

$$P_1(x)P_2(x)w(x) = (3x^3 - x)w(x) \quad (27)$$

is odd function when  $w(x)$  is even.

That is, when  $w(x)$  is even,

$$\int_{-1}^1 P_1(x)P_2(x)w(x)dx = 0 \quad (28)$$

## 3

$$T_k(x) = \cos(k \arccos(t)), t \in [-1, 1] \quad (29)$$

**a**

$$\int_{-1}^1 \frac{T_i(t)T_j(t)}{\sqrt{1-t^2}}dt = \int_{-\pi}^0 \frac{T_i(\cos x)T_j(\cos x)}{\sqrt{1-\cos^2 x}}d \cos x \quad (30)$$

$$= \int_{-\pi}^0 \frac{\cos ix \cos jx}{-\sin x}(-\sin x dx) \quad (31)$$

$$= \int_{-\pi}^0 \cos ix \cos jx dx \quad (32)$$

When  $i \neq j$ ,

$$\int_{-\pi}^0 \cos ix \cos jx dx = \int_{-\pi}^0 \frac{1}{2}[\cos(i+j)t + \cos(i-j)t]dx = 0 \quad (33)$$

When  $i = j$ ,

$$\int_{-\pi}^0 \cos ix \cos jx dx = \int_{-\pi}^0 \cos^2 ix dx \quad (34)$$

$$= \int_{-\pi}^0 \frac{1 + \cos 2ix}{2} dx \quad (35)$$

$$= \frac{\pi}{2} \quad (36)$$

Thus,

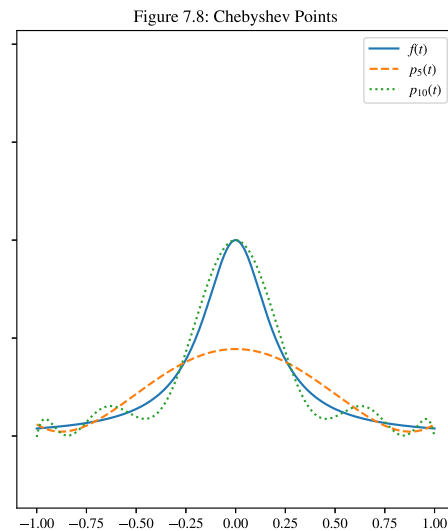
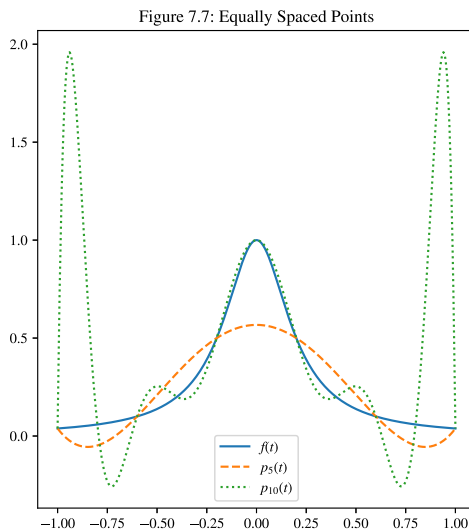
$$\int_{-1}^1 \frac{T_i(t)T_j(t)}{\sqrt{1-t^2}}dt = \frac{\pi}{2}\delta_{i,j} \quad (37)$$

## 4

## Core Code

```
def chebyshev_nodes(n, a, b):  
    return 0.5 * (a + b) + 0.5 * (b - a) * np.cos(np.pi * (2 *  
np.arange(1, n + 1) - 1) / (2 * n))  
  
# Lagrange polynomial interpolation  
def polynomial_interpolation(points, x_values):  
    x_points, y_points = points  
    polynomial = np.zeros_like(x_values)  
    n = len(x_points)  
    for i in range(n):  
        term = y_points[i]  
        for j in range(n):  
            if i != j:  
                term *= (x_values - x_points[j]) / (x_points[i] -  
x_points[j])  
        polynomial += term  
    return polynomial
```

## Result



5

a

$$M(f) = (b - a)f\left(\frac{a + b}{2}\right) = 1 \cdot \left(\frac{1}{2}\right)^3 = \frac{1}{8} \quad (38)$$

$$T(f) = \frac{b - a}{2}(f(a) + f(b)) = \frac{1}{2}(0 + 1) = \frac{1}{2} \quad (39)$$

**b**

$$E(f) = \frac{T(f) - M(f)}{3} = \frac{1}{8} \quad (40)$$

$$-2E(f) = -\frac{1}{4} \quad (41)$$

**c**

$$S(f) = \frac{2M(f) + T(f)}{3} = \frac{1}{4} \quad (42)$$

**d**

Yes, since when  $I(f) = S(f)$ ,  $\frac{\partial^3 R(f)}{\partial x^3} = 0$ , which means the Simpson rule is of degree 3.

**e**

$$\int_0^1 x^3 dx = A_0 f(x_0) + A_1 f(x_1) \quad (43)$$

There are 4 parameters.

$$\int_0^1 1 = 1 = A_0 + A_1 \quad (44)$$

$$\int_0^1 x = \frac{1}{2} = A_0 x_0 + A_1 x_1 \quad (45)$$

$$\int_0^1 x^2 = \frac{1}{3} = A_0 x_0^2 + A_1 x_1^2 \quad (46)$$

$$\int_0^1 x^3 = \frac{1}{4} = A_0 x_0^3 + A_1 x_1^3 \quad (47)$$

The solution is  $[A_0, A_1, x_0, x_1]^\top = [\frac{1}{2}, \frac{1}{2}, \frac{3-\sqrt{3}}{6}, \frac{3+\sqrt{3}}{6}]^\top$

$$G(f) = A_0 f(x_0) + A_1 f(x_1) = \frac{1}{4} \quad (48)$$

The result is exact since  $G(f)$  is of degree  $4 - 1 = 3$ .

**f**

$$M_2(f) = (0.5 - 0)f(0.25) + (1 - 0.5)f(0.75) = 0.21875 \quad (49)$$

$$f(x) = L_n(x) = \sum_{0 \leq k \leq n} f(x_k) l_k(x) \quad (50)$$

$$I(f) = \int_a^b L_n(x) dx = \int_a^b \sum_{0 \leq k \leq n} f(x_k) l_k(x) dx \quad (51)$$

$$= \sum_{0 \leq k \leq n} f(x_k) \int_a^b l_k(x) dx \quad (52)$$

$$= \sum_{0 \leq k \leq n} w_k f(x_k) \quad (53)$$

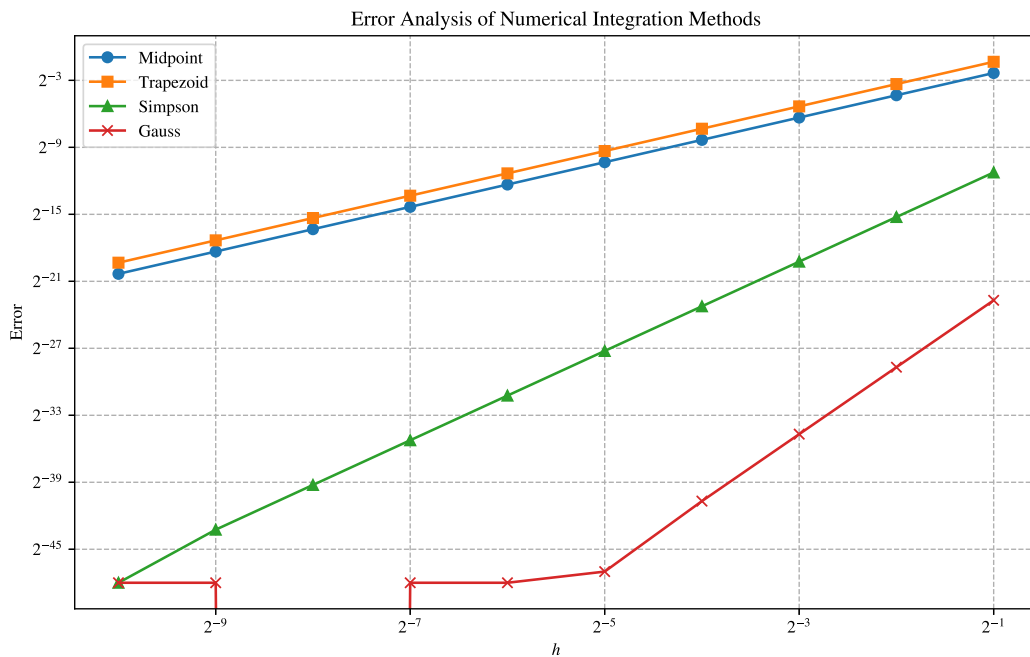
$$e = C \cdot h^n \Leftrightarrow \log e = \log C + n \log h \quad (54)$$

## Output

```
# (C, order)
0.7923224542232744 1.9992933732410973
1.587137649897742 1.9995965300241643
0.007343895022866783 4.041227723532598
9.372066198851523e-06 5.99563201077984
```

That is, the dominant term in error of composite midpoint or Trapezoid rules is  $O(h^2)$ , the dominant term in error of the composite Simpson rule is  $O(h^4)$  and the dominant term in error of the composite 3-points Gauss rules is  $O(h^6)$ .

## Result



## 8

### 8.12

Average them,

$$\frac{\frac{f(x+h)-f(x)}{h} + \frac{f(x)-f(x-h)}{h}}{2} = \frac{f(x+h) - f(x-h)}{2h} \quad (55)$$

By Taylor series,

$$f(x+h) = f(x) + f'(x)h + \frac{1}{2}f''(x)h^2 + O(h^3) \quad (56)$$

$$f(x-h) = f(x) - f'(x)h + \frac{1}{2}f''(x)h^2 + O(h^3) \quad (57)$$

Thus,

$$\frac{f(x+h) - f(x-h)}{2h} = f'(x) + O(h^2) \quad (58)$$

, which is second-order accurate.

### 8.13

$$f(x+h) = f(x) + f'(x)h + \frac{1}{2}f''(x)h^2 + O(h^3) \quad (59)$$

$$f(x+2h) = f(x) + 2f'(x)h + 2f''(x)h^2 + O(h^3) \quad (60)$$

Consider the linear composition  $af(x) + bf(x+h) + cf(x+2h)$ ,

$$\frac{b}{2} + 2c = 0 \quad (61)$$

Suppose  $b = 4, c = -1$ , then  $a = -b - c = -3$  and  $b + 2c = 2$ .

That is,

$$f'(x) = \frac{-3f(x) + 4f(x+h) - f(x+2h)}{2h} + O(h^2) \quad (62)$$

, which is second-order accurate.