# assignment12

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# 1 Polynomial Fit with Regularizations

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Github Repo: assignment12

Samilar with assignment11, this is also a *multi-objective least squares* problem.

This time we want to find a optimal set of model parameters that provide the least square approximate slolution:

$$E(\theta; \lambda) = ||A\theta - y||_2^2 + \lambda ||\theta||_2^2$$

By stacking we can change our weighted sum least squares to a standard least squares form

$$\left\| \begin{bmatrix} \sqrt{\lambda_1} A_1 \\ \vdots \\ \sqrt{\lambda_k} A_k \end{bmatrix} x - \begin{bmatrix} \sqrt{\lambda_1} b_1 \\ \vdots \\ \sqrt{\lambda_k} b_k \end{bmatrix} \right\|^2 = \left\| \tilde{A} x - \tilde{b} \right\|^2$$

So, our cost function can be expressed as

$$\left\| \begin{bmatrix} A \\ \sqrt{\lambda}I \end{bmatrix} \theta - \begin{bmatrix} y \\ 0 \end{bmatrix} \right\|^2 = \left\| \tilde{A}x - \tilde{b} \right\|^2$$

We define our feature function as

$$\hat{f}(x) = \theta_0 + \theta_1 x + \dots + \theta_p x^p$$

Our matrix *A* becomes to:

$$\begin{bmatrix} 1 & x^{(1)} & \cdots & (x^1)^p \\ 1 & x^{(2)} & \cdots & (x^2)^p \\ \vdots & \vdots & & \vdots \\ 1 & x^{(N)} & \cdots & (x^N)^p \end{bmatrix}$$

Have all this infromations, we can compute the parameters  $\theta$ .

### 1.1 Implementation

#### 1.1.1 Generate data set

```
In [1]: import numpy as np
        import math
        import matplotlib.pyplot as plt
                = 1001
        num
                = 5
        std
        \# x : x-coordinate data
        # y1 : (clean) y-coordinate data
        # y2 : (noisy) y-coordinate data
        def fun(x):
            # f = np.sin(x) * (1 / (1 + np.exp(-x)))
            f = np.abs(x) * np.sin(x)
            return f
                = np.random.rand(num)
        n
                = n - np.mean(n)
        nn
                = np.linspace(-10,10,num)
                = fun(x)
                                                  # clean points
        y1
                = y1 + nn * std
                                                # noisy points
        y2
        plt.plot(x, y1, 'b.', x, y2, 'k.')
        plt.show()
```

<Figure size 640x480 with 1 Axes>

#### 1.2 Build cost function

Assume our input data set x is a n-vector, our parameter is a p-vector, then A is a  $n \times p$  matrix and I is a p-identity matrix. We combine them into a  $\tilde{A}$  matrix.

```
In [2]: def create_tilde_matrix(n, p, weight, data):
    """Build tilde matrix A in cost function

Arguments:
    n: number of input data
    p: degree of polynomial
    weight: weight of secondary objective
    data: input data
"""
```

```
I = np.identity(p+1)
             I = math.sqrt(weight) * I
            feature_matrix = build_feature_matix(data, p)
            A = np.vstack((feature_matrix, I))
            return A
        def build_feature_matix(data, p):
             """Build basic function matrix
             data: input data set
             p: degree of polynomial
             n n n
            matrix = []
            for xi in data:
                 poly = [xi**dg for dg in range(p+1)]
                 matrix.append(poly)
            return np.array(matrix)
1.2.1 Generate \tilde{b}
\tilde{b} has same length with \tilde{A}: n+p
In [3]: def create_tilde_b(n, p, data_noisy):
             """Create b vector in cost functions
             Arguments:
                 n: number of input data
                 p: degree of polynomial
                 data_noisy: noisy data
            Return:
                 macthing b vector
             n n n
            length = n + p + 1 # add 1 for degree 0
            b = np.zeros(length)
            for i in range(len(data_noisy)):
                 b[i] = data_noisy[i]
            return b
```

#### **1.2.2** Compute $\theta$

#### 1.2.3 Fitting function

Let's combine all the part together to generate our approximate values.

```
In [5]: def fitting(data_input, output_noisy, p, weight):
            """Compute approximate values with given poly degree
            Arguments:
                data_input: input data
                output_noisy: noisy measurements
                p: degree of polynomial
                weight: weight of secondary objective
            Return:
            11 11 11
            n = len(data_input)
            A = create_tilde_matrix(n, p, weight, data_input)
            b = create_tilde_b(n, p, output_noisy)
            # compute approximation
            params = compute_params(A, b)
            approx = np.inner(np.array([data_input**dg for dg in range(p+1)]).T, params)
            # compute error with approximation and clear data
            basic_A = build_feature_matix(data_input, p)
            error = error_function(A, params, b)
            return approx, error
        def error_function(A, theta, b):
            cost_func = np.inner(A, theta) - b
            return np.linalg.norm(cost_func)**2
```

## 1.3 Check fitting function

Now let's try our fitting function to see how p and  $\lambda$  affect the result.

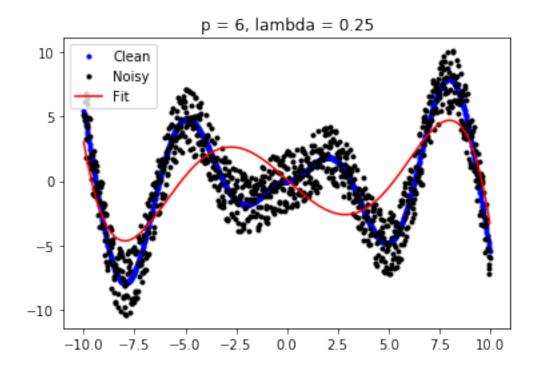
### **1.3.1** Fix $\lambda$ while change p

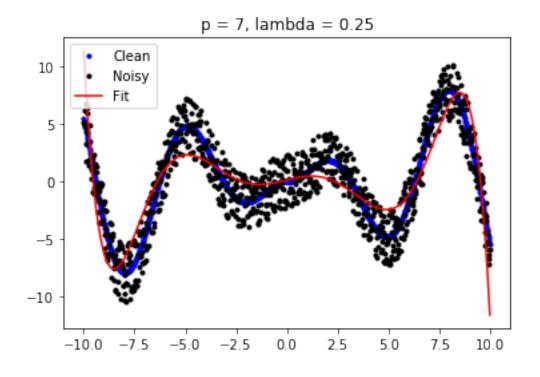
First use a fixed  $\lambda$  and chose p from 6-15 to see the result. To convenient plotting, we define a plot function here

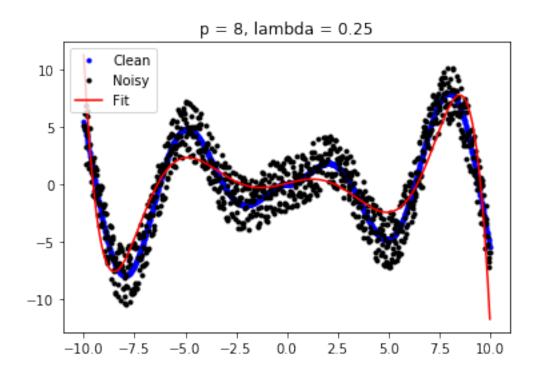
Here use define our  $\lambda$  to 0.25.

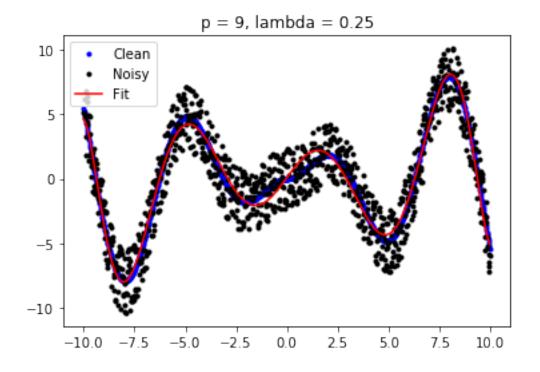
```
In [7]: error_histo_p = []

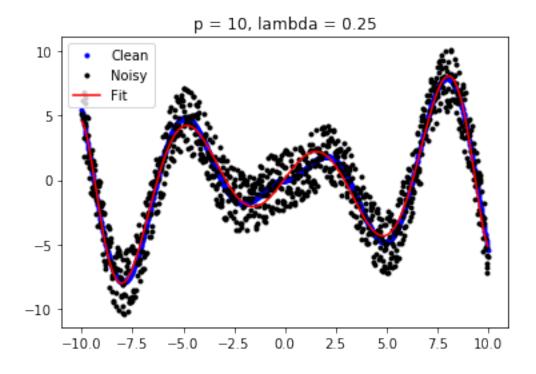
for p in range(6, 16):
    error_histo_p.append(plot_vary_p(x, y1, y2, p, 0.25))
```

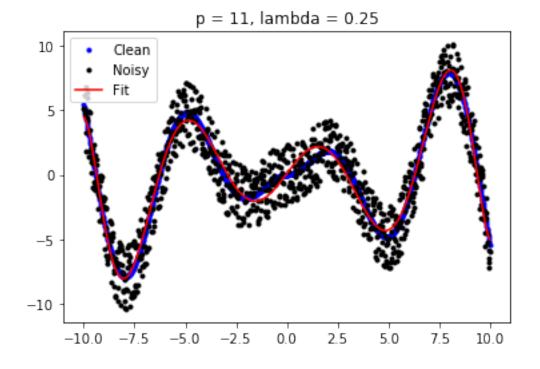


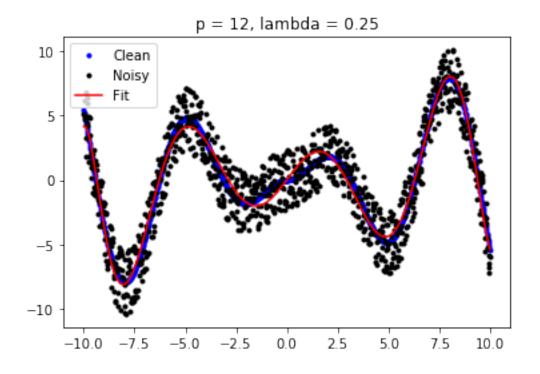


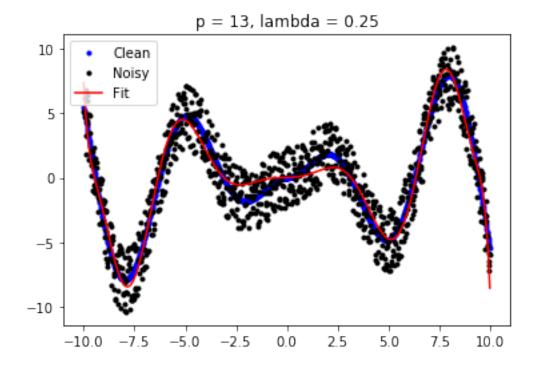


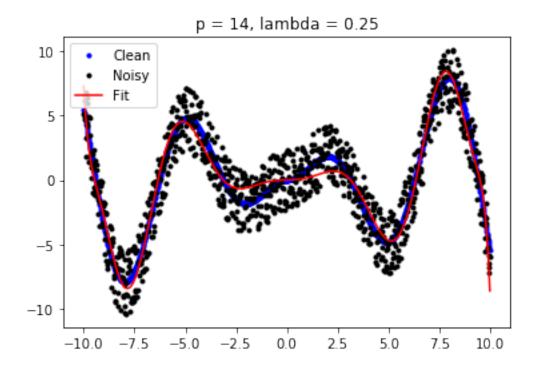


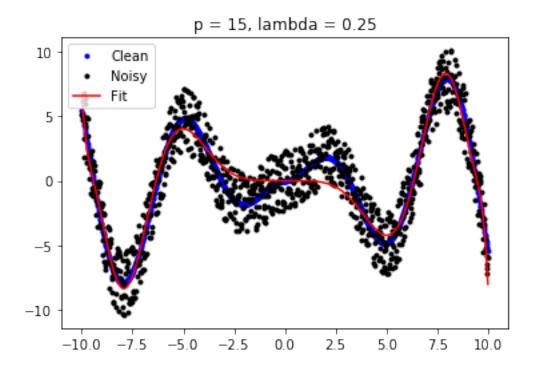












```
In [8]: p_axis = [p for p in range(6, 16)]

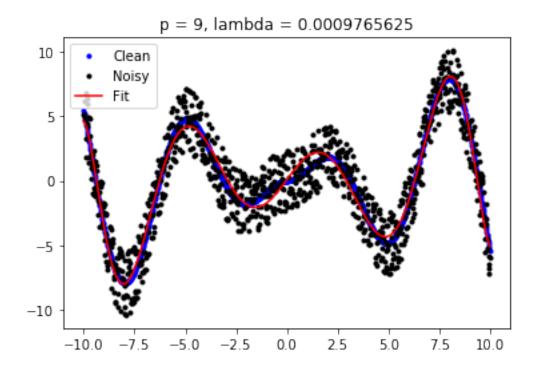
    plt.title("Error with diff p")
    plt.plot(p_axis, error_histo_p, 'b-')
    plt.xlabel('p')
    plt.ylabel('Error')
    plt.show()
```

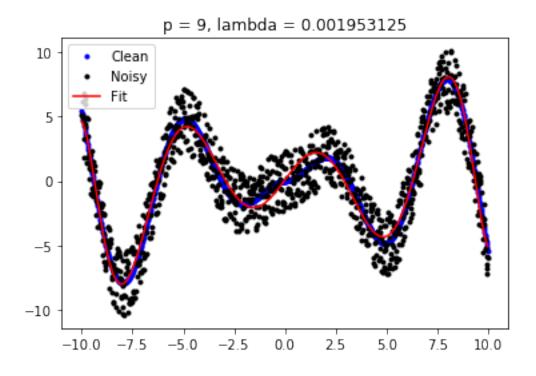


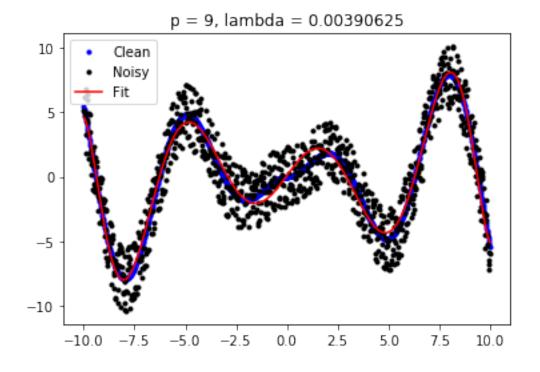
First along *p* increase error is dreacing, but after 12 error changes to increasing again.

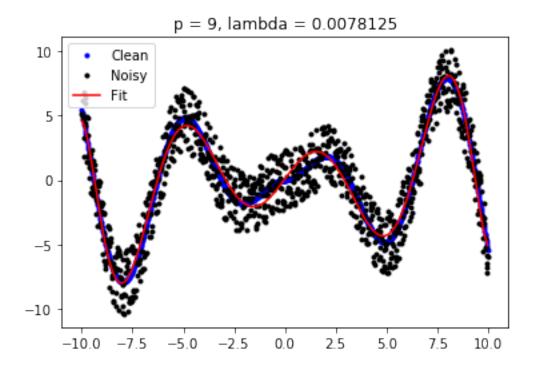
## **1.3.2** Fix p while vary $\lambda$

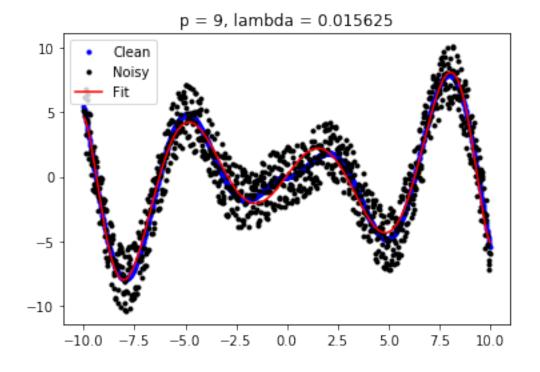
Now, let'us fix p and change  $\lambda$  to see how result changes. Since when p = 9 the error first time near the smallest value, we choose 9 be our p's value.

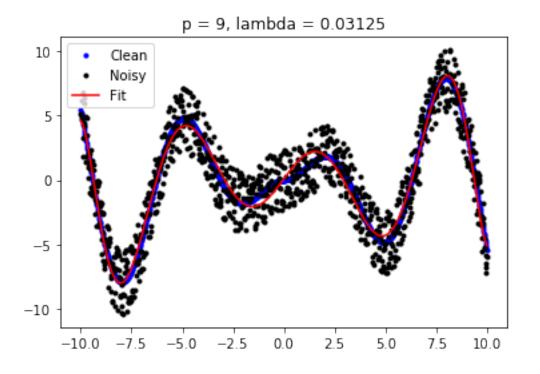


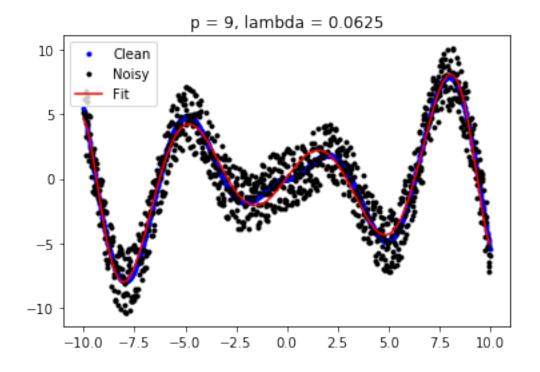


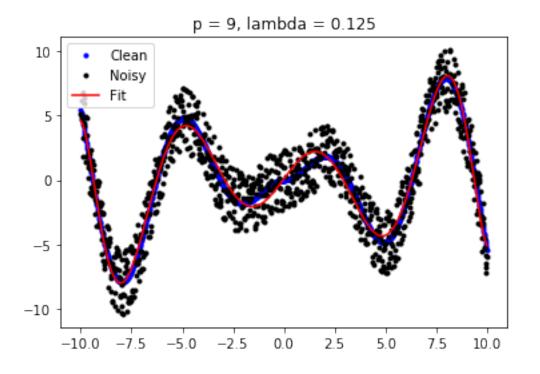


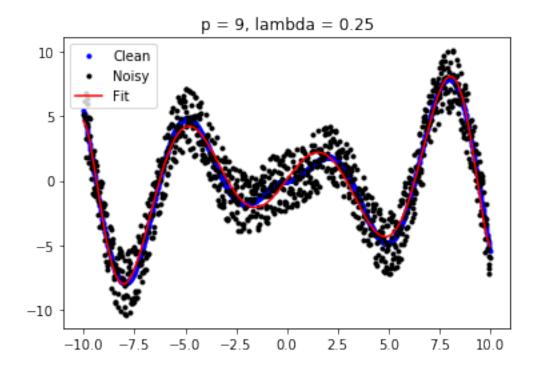


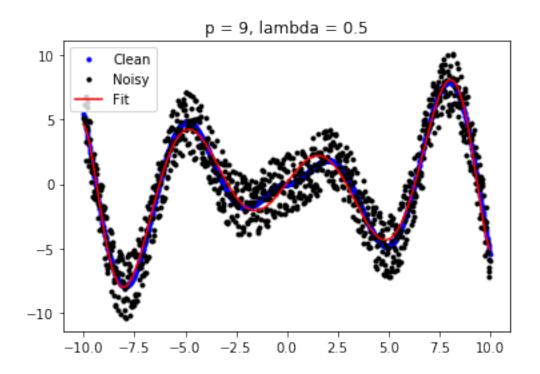


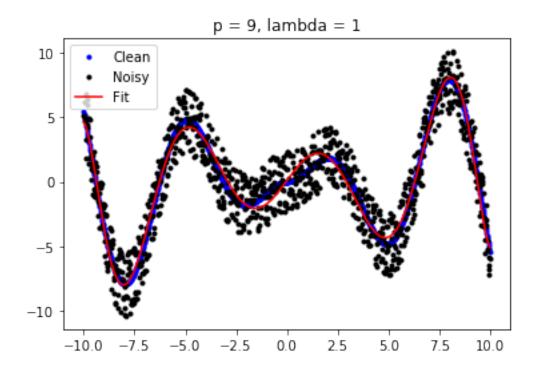


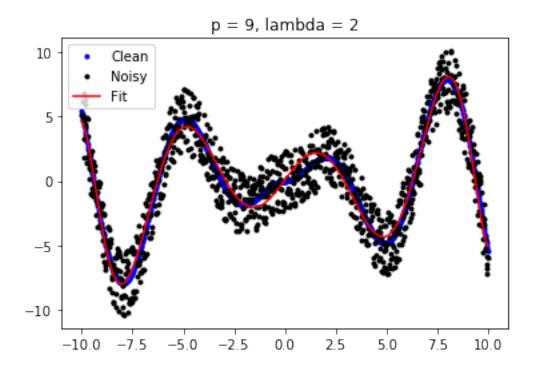


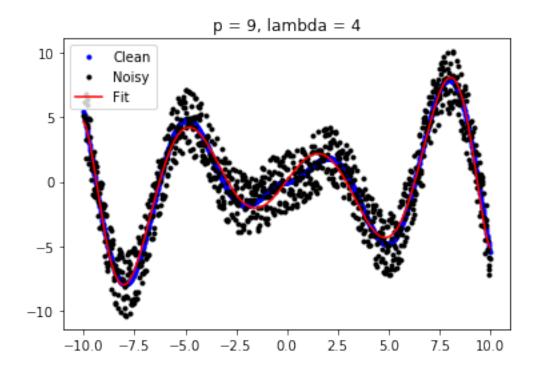


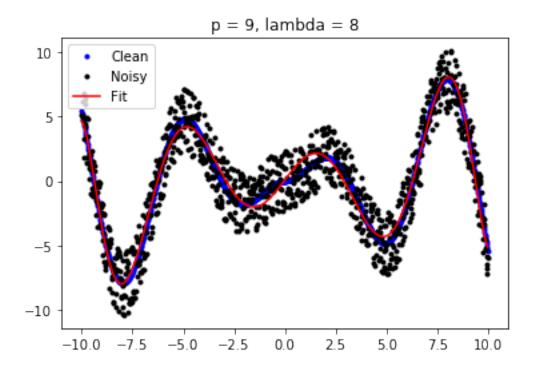


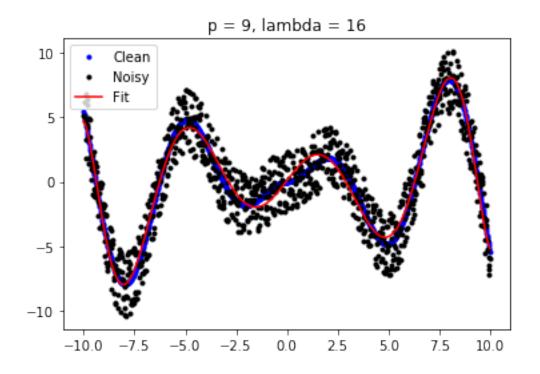


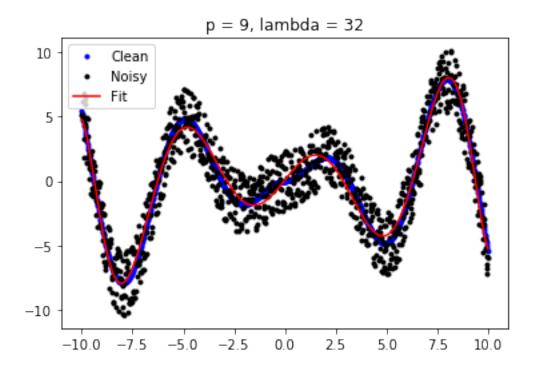


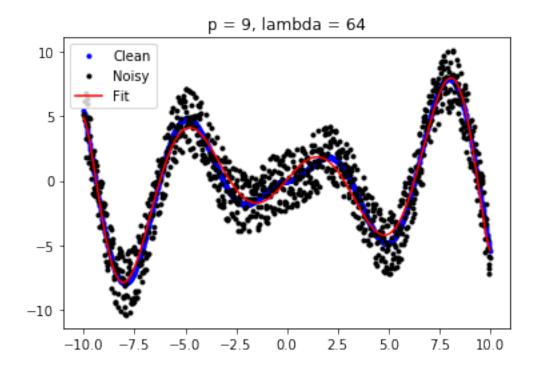


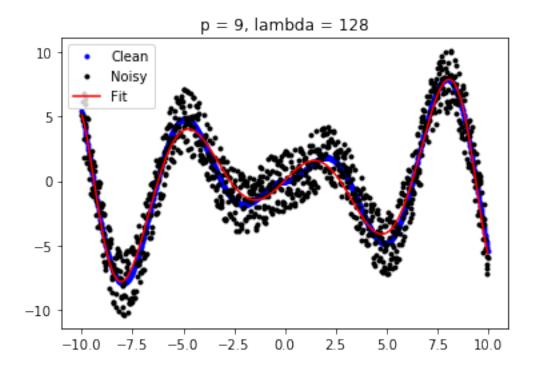


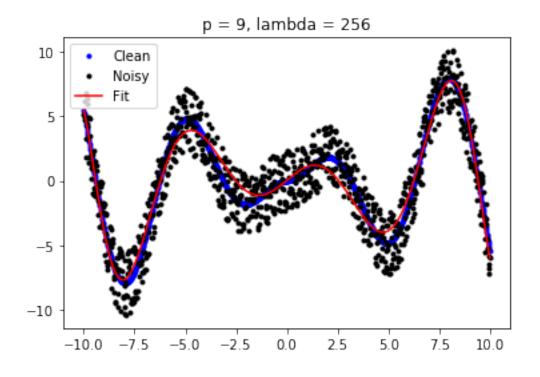


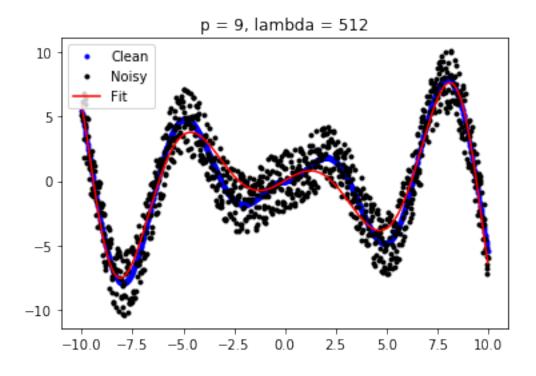


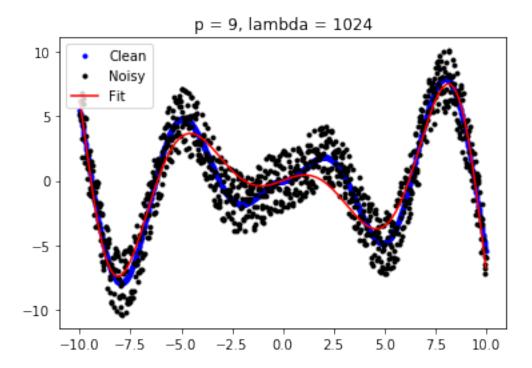


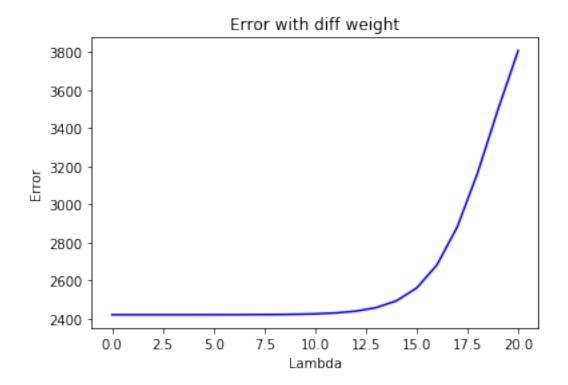




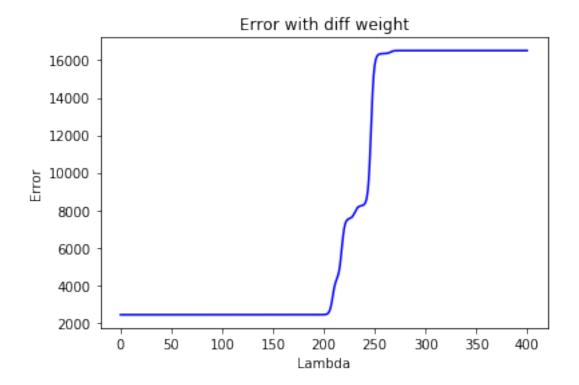








## Extend the range of $\lambda$



When  $\lambda$  is small, the approximate result is close to input data. When  $\lambda$  becomes big, it focus on keep  $\theta$  small, so error value start to grow again.