

# assignment07

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## 1 Polynomial Fit

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Samilar with last time we did the *Straight-line fit*. We use *least squares data fitting* to find the approximate value of given data set.

### 1.1 Least Squares Problem

Suppose we have a tall matrix  $A$ , so  $Ax = b$  is *over-determined*. For most  $b$ , there is no  $x$  that satisfies  $Ax = b$ .

The *least squares problem* is: choosing  $x$  to minimize  $\|Ax - b\|^2$ .  
We call the solution *least squares approxmimata solution* of  $Ax = b$ , and notate it as  $\hat{x}$ .

### 1.2 Least squares data fitting

If we have a scalar  $y$  and an  $n$ -vector  $x$  that are related by model

$$y \approx f(x)$$

$x$  is the *independent variable*,  
 $y$  is the *outcome*,  
 $f : R^n \rightarrow R$  gives the relation between  $x$  and  $y$ .

Often  $x$  is a feature vector, and  $y$  is something we want to predict.  
We do not know the true relationship  $f$  between  $x$  and  $y$ . So what we want to do is to find a *approximation* of  $f$ .

We define a *linear in the parameters* model:

$$\hat{f}(x) = \theta_1 f_1(x) + \dots + \theta_p f_p(x)$$

$f_i : R^n \rightarrow R$ : are *basis fuctions* that we choose.  
 $\theta_i$ : are *model parameters* that we choose.  
 $\hat{y}^{(i)} = \hat{f}(x^{(i)})$  is prediction of  $y^{(i)}$ .

Thus, our goal becomes to choose model parameters  $\theta_i$  to minimize *residuals*  $r^i = y^{(i)} - \hat{y}^{(i)}$ .  
This can be formulated and solved as a **least squares problem**.

If we define  
 $y^d = (y^{(1)}, \dots, y^{(N)})$  is vector of outcomes,  
 $\hat{y}^d = (\hat{y}^{(1)}, \dots, \hat{y}^{(N)})$  is vector of predictions,  
 $r^d = (r^{(1)}, \dots, r^{(N)})$  is vector of residuals.  
 have  $N \times p$  matrix  $A$  with elements  $A_{ij} = f_j(x^{(i)})$ , so  $\hat{y}^d = A\theta$ .  
 $\|r^d\|^2 = \|y^d - \hat{y}^d\|^2 = \|y^d - A\theta\|^2$

### 1.3 Polynomial Fit

*Polynomial fit* means we set out parameter model to a polynomial equation, So we have:

$$\hat{f}(x) = \theta_0 + \theta_1 x + \dots + \theta_p x^p$$

Our matrix  $A$  becomes to:

$$\begin{bmatrix} 1 & x^{(1)} & \dots & (x^{(1)})^p \\ 1 & x^{(2)} & \dots & (x^{(2)})^p \\ \vdots & \vdots & & \vdots \\ 1 & x^{(N)} & \dots & (x^{(N)})^p \end{bmatrix}$$

#### 1.3.1 First, generate data set.

```
In [1]: import numpy as np
import matplotlib.pyplot as plt

num      = 1001
std      = 5

# x : x-coordinate data
# y1 : (clean) y-coordinate data
# y2 : (noisy) y-coordinate data

def fun(x):

    f = np.sin(x) * (1 / (1 + np.exp(-x)))
    f = np.abs(x) * np.sin(x)

    return f

n        = np.random.rand(num)
nn       = n - np.mean(n)
x        = np.linspace(-10,10,num)
y1       = fun(x)
y2       = y1 + nn * std

plt.plot(x, y1, 'b.', x, y2, 'k.')
plt.show()
```

<Figure size 640x480 with 1 Axes>

### 1.3.2 Second, get $\theta$

Since we have  $A\theta = \hat{y}$ , the best way to get  $\theta$  is to time  $A^{-1}$  at both side.

By *pseudo inverse*:  $(A^T A)^{-1} A$ , we can compute the inverse easily.

Before compute inverse of A, let's define A first. The row of A is  $[1, x, x^2, \dots, x^p]$

```
In [2]: def build_matrix(x, p):
        '''Build basic function matrix
        x: input data set
        p: degree of polynomial
        '''

        matrix = []

        for xi in x:
            poly = [xi**dg for dg in range(p+1)]
            matrix.append(poly)

        return np.array(matrix)
```

Now, let's compute the inverse of A.

Here, we use numpy's function `linalg.pinv()` to compute the pseudo inverse.

```
In [3]: def theta(A, y):
        A_inv = np.linalg.pinv(A)
        theta = np.inner(A_inv, y)

        return theta
```

### 1.3.3 Third, get the $\hat{y}$ function

We have already got  $\theta$  from above, so we can compute our approximate value now.

```
In [4]: def y_hat(x, y, p):

        A = build_matrix(x, p)
        theta_arr = theta(A, y)

        y_i = np.inner(np.array([x**dg for dg in range(p+1)]).T, theta_arr)

        return y_i
```

### 1.3.4 Fourth, define residual function

For comparing fit result, we have  $\sum_{j=1}^n r_j^2$  where  $r_j = y_j - \hat{f}(x_j)$

```
In [5]: def residual(y, y_hat):
        y_diff = y - y_hat
        return sum([e**2 for e in y_diff])
```

## 1.4 Show Result

Let's try some different, and check the error.

### 1.4.1 When $p = 0$

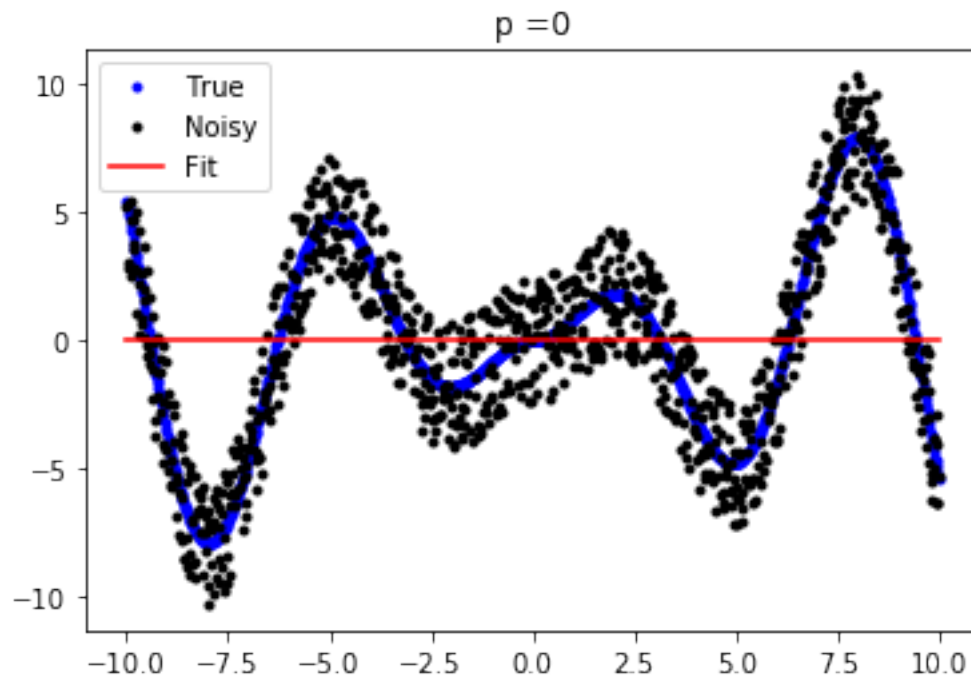
```
In [6]: # list for storing residual of each p
        error = []

        # When p = 0
        def plot_graph(x, y_clean, y_noisy, p):

            y = y_hat(x, y_noisy, p)

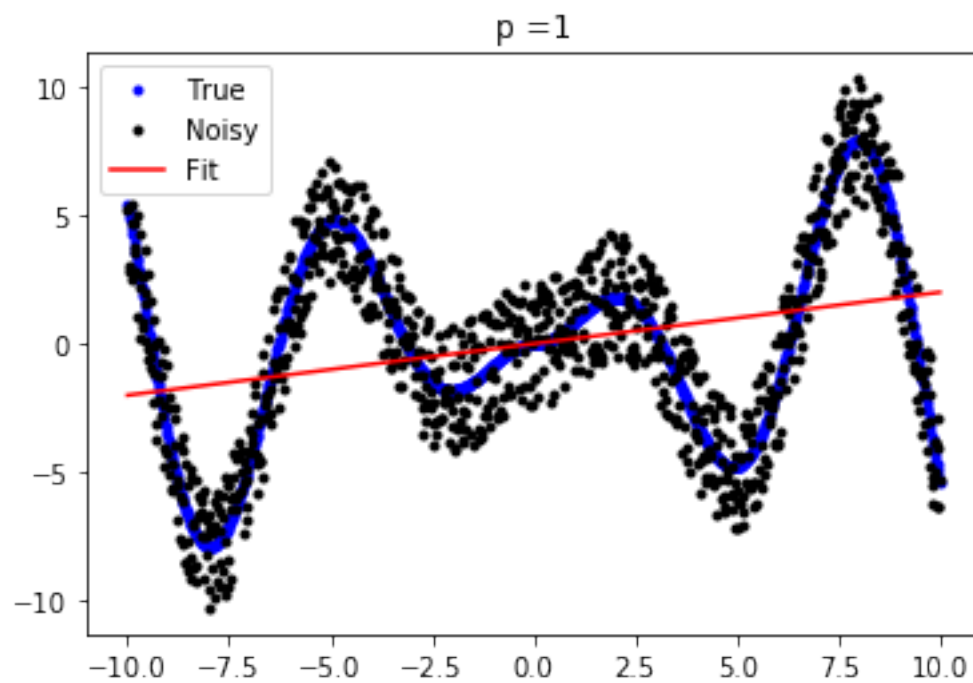
            error.append(residual(y_clean, y))
            # Plot part
            plt.title("p = {}".format(p))
            plt.plot(x, y_clean, 'b.', x, y_noisy, 'k.', x, y, 'r')
            plt.legend(['True', 'Noisy', 'Fit'], loc='upper left')
            plt.show()

        err = plot_graph(x, y1, y2, 0)
```



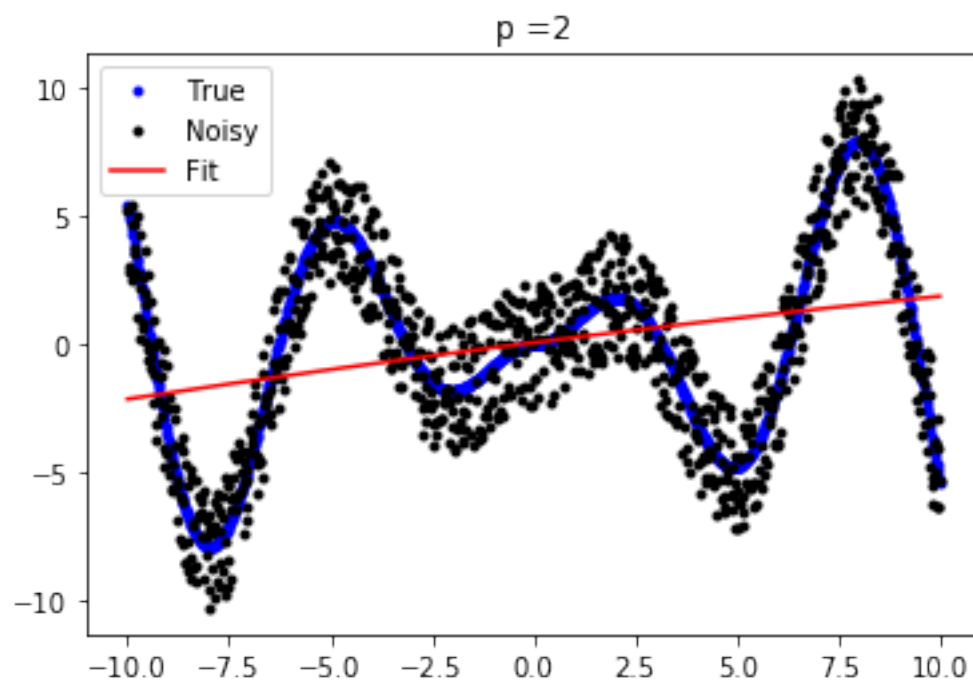
### 1.4.2 When $p = 1$

```
In [7]: plot_graph(x, y1, y2, 1)
```



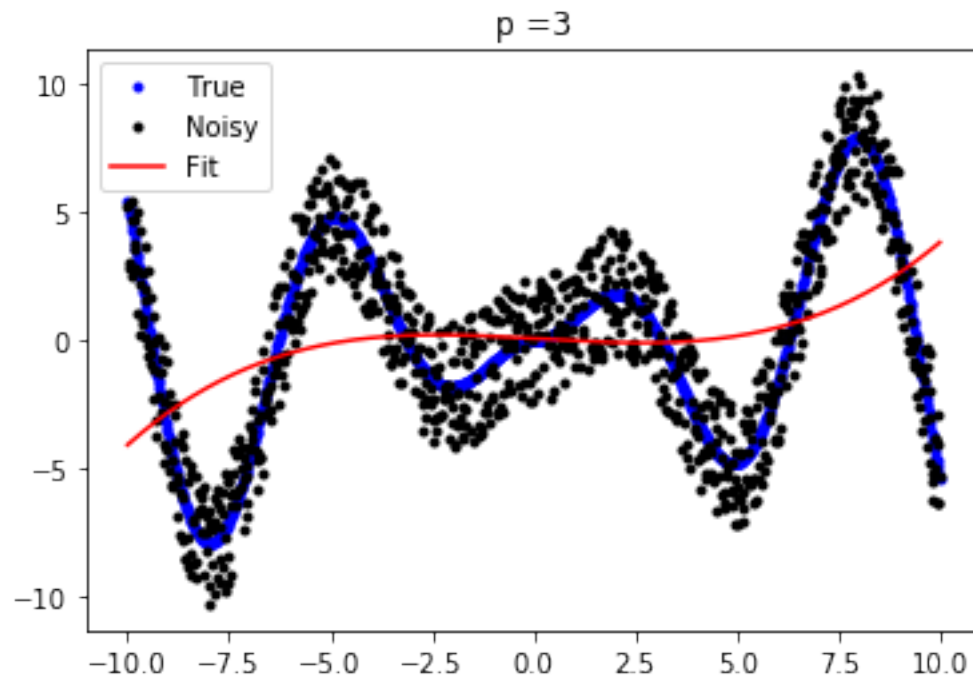
### 1.4.3 When $p = 2$

In [8]: `plot_graph(x, y1, y2, 2)`



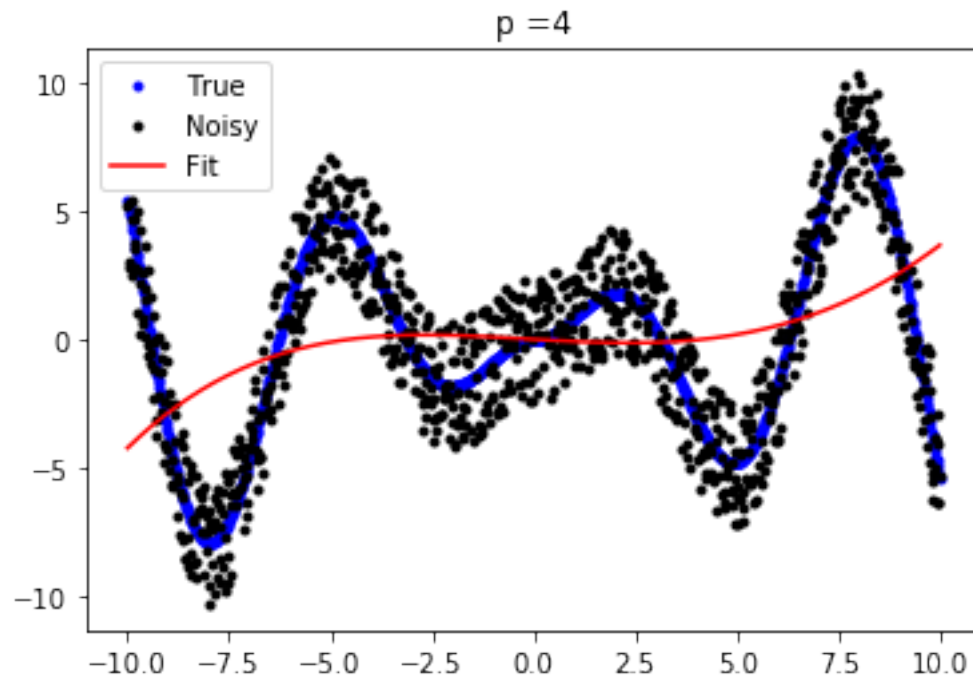
#### 1.4.4 When $p = 3$

In [9]: `plot_graph(x, y1, y2, 3)`



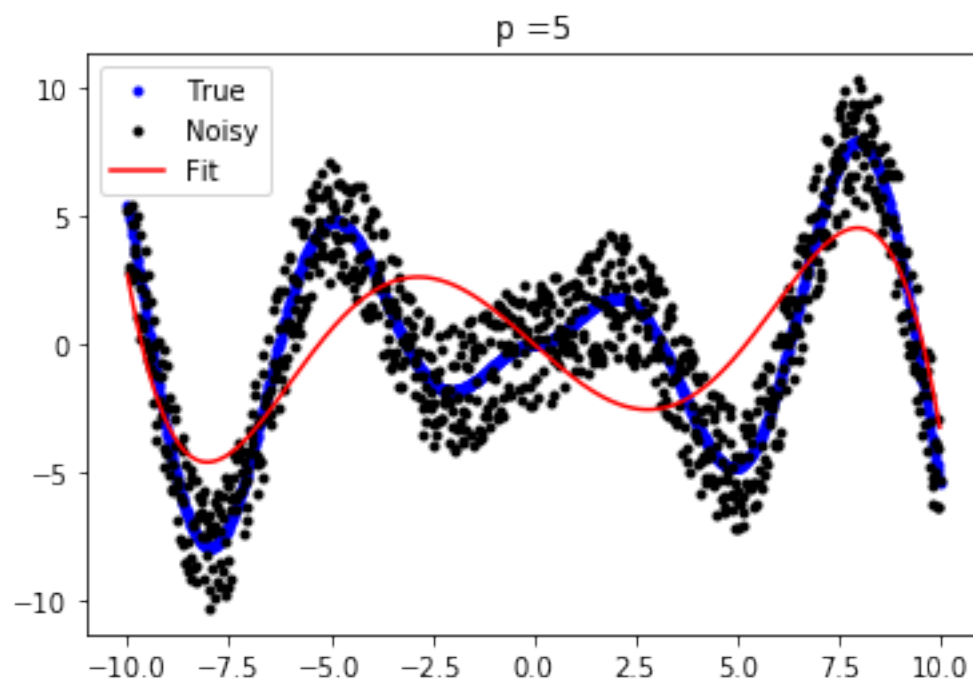
#### 1.4.5 When $p = 4$

In [10]: `plot_graph(x, y1, y2, 4)`



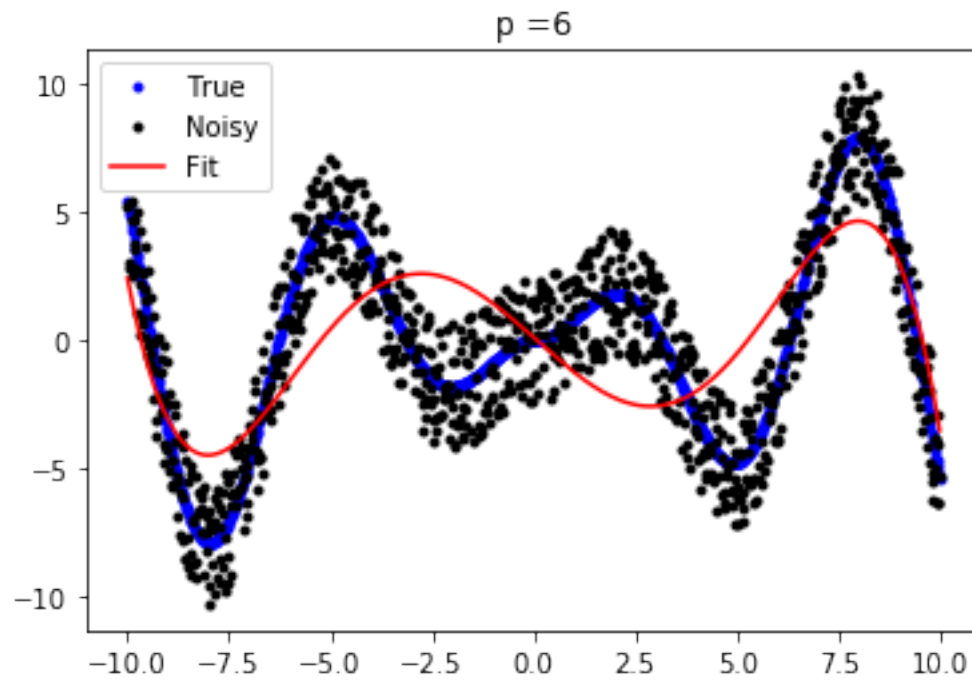
#### 1.4.6 When $p = 5$

In [11]: `plot_graph(x, y1, y2, 5)`



#### 1.4.7 When $p = 6$

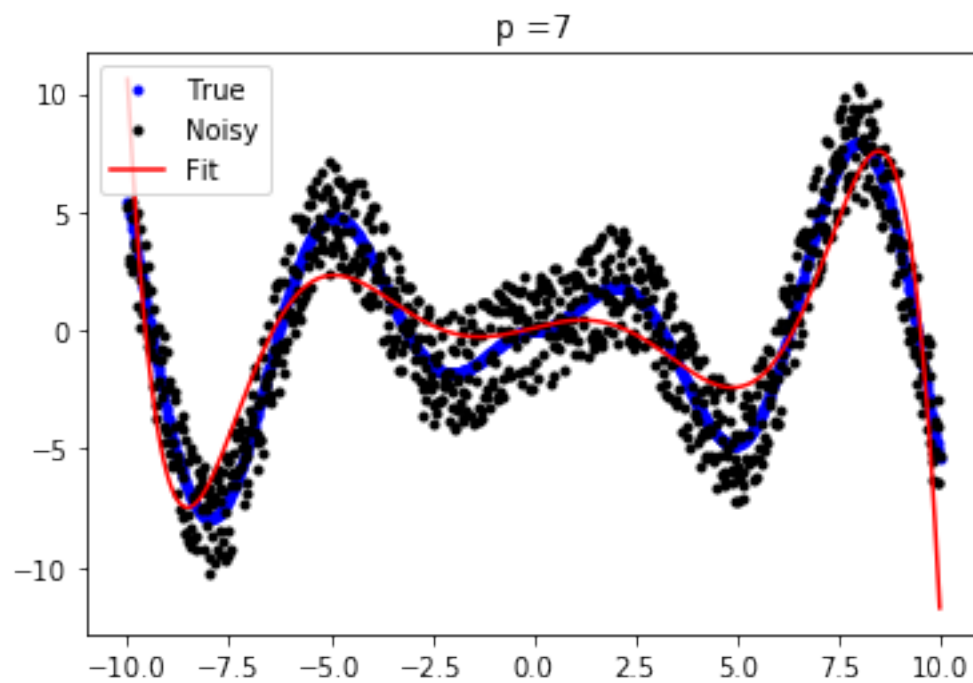
In [12]: `plot_graph(x, y1, y2, 6)`



#### 1.4.8 When $p = 7$

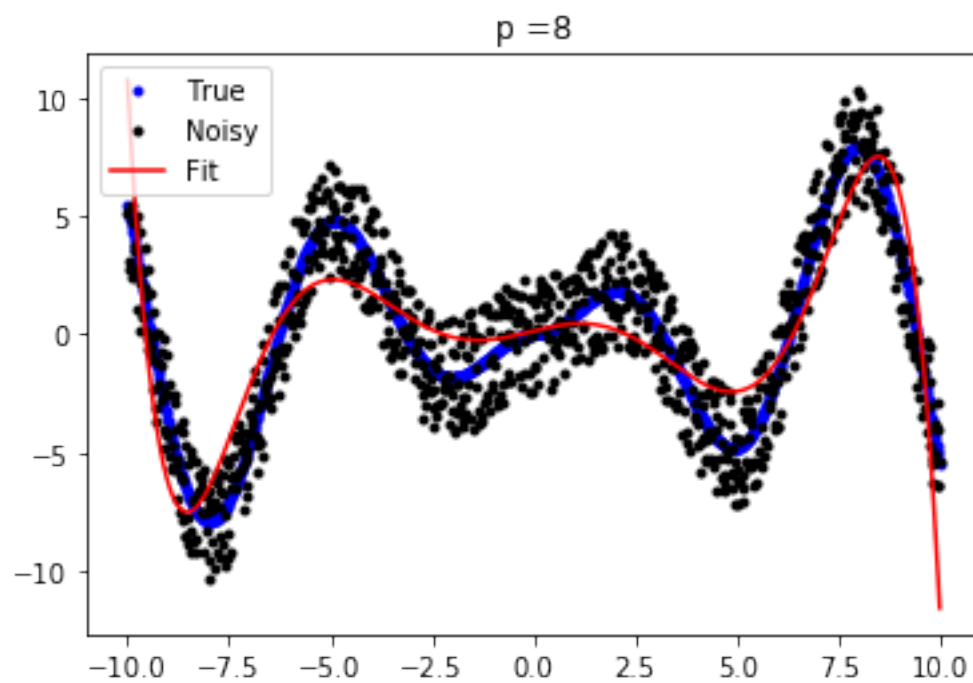
In [13]: `plot_graph(x, y1, y2, 7)`





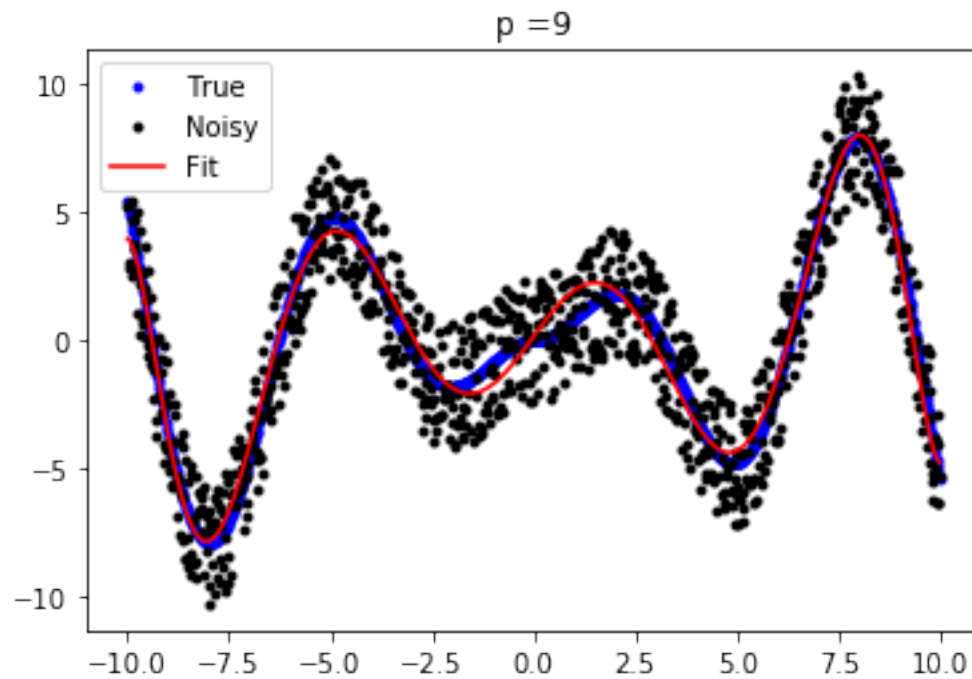
#### 1.4.9 When $p = 8$

In [14]: `plot_graph(x, y1, y2, 8)`



#### 1.4.10 When $p = 9$

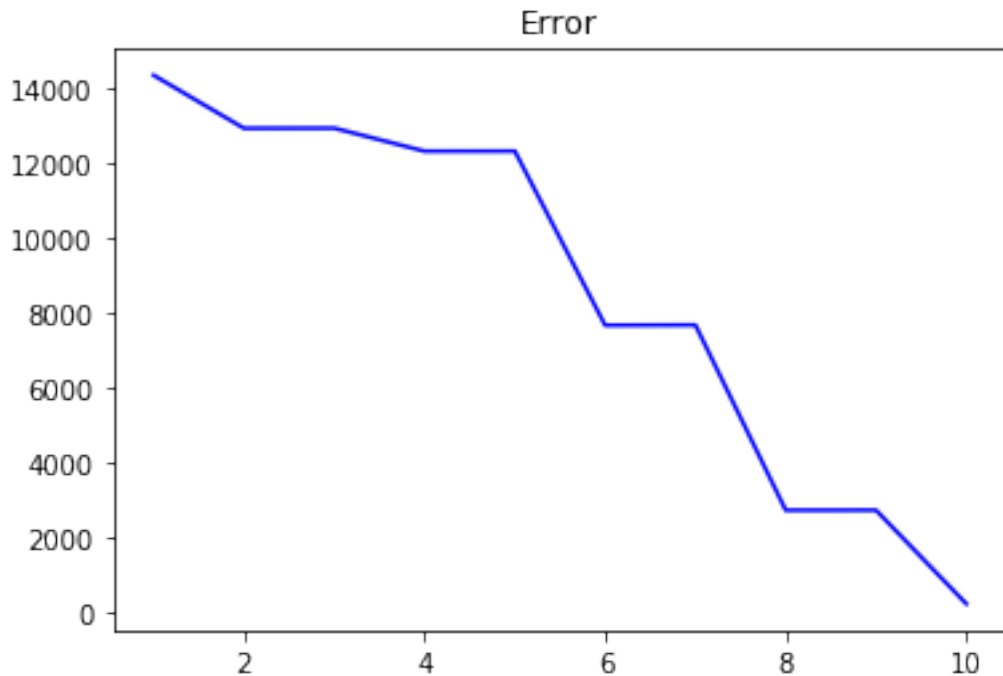
```
In [15]: plot_graph(x, y1, y2, 9)
```



#### 1.4.11 Error

```
In [16]: x_axis = [x for x in range(1, 11)]
```

```
plt.title("Error")  
plt.plot(x_axis, error, 'b-')  
plt.show()
```



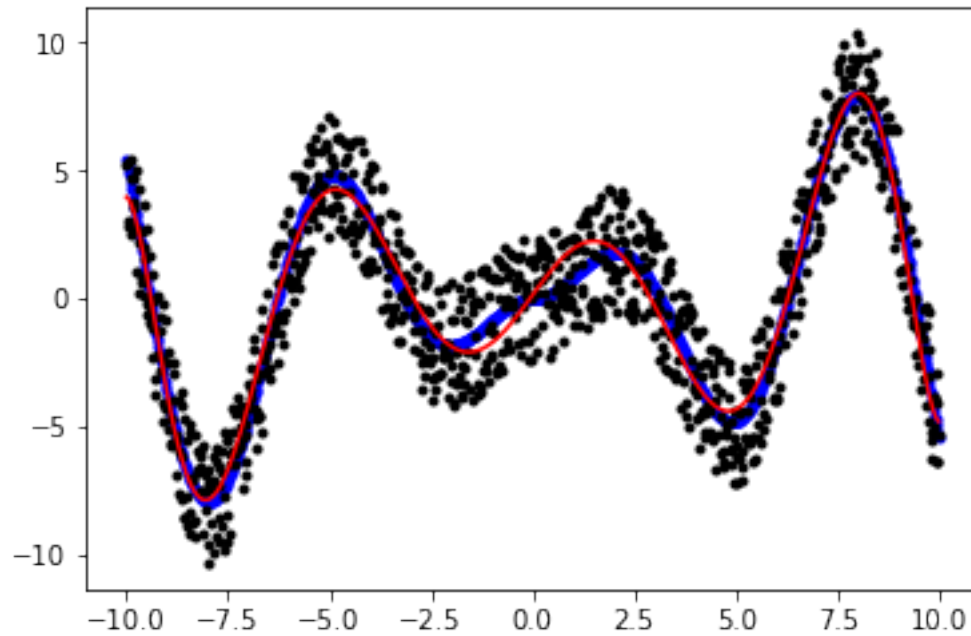
### 1.5 \*Use numpy function

numpy also has functions for polynomial fit:

- `polyfit`: compute  $\theta$
- `polyval`: use given input and  $\theta$  to compute the approximate value

```
In [17]: z = np.polyfit(x, y2, 9)

y_val = np.polyval(z, x)
plt.plot(x, y1, 'b.', x, y2, 'k.', x, y_val, 'r')
plt.show()
```



We can see from the graphs, the result of `numpy.polyfit` and our function are same.

## 1.6 Find optimum $p$

Because we have *residule*, we can use it to find the best  $p$ .

In [20]: `import math`

```
err_prv = math.inf
p = 0
err = residual(y1, y_hat(x, y2, p))
p_op = 0
ite = 3

while(ite):
    if (err >= err_prv):
        if (ite == 3):
            p_op = p - 1
            ite -= 1
        else:
            ite = 3

    err_prv = err
    p += 1
    err = residual(y1, y_hat(x, y2, p))

print("The optimal value of p is {}".format(p_op))
```

The optimal value of  $p$  is 15.

```
In [21]: plot_graph(x, y1, y2, 15)
```

