

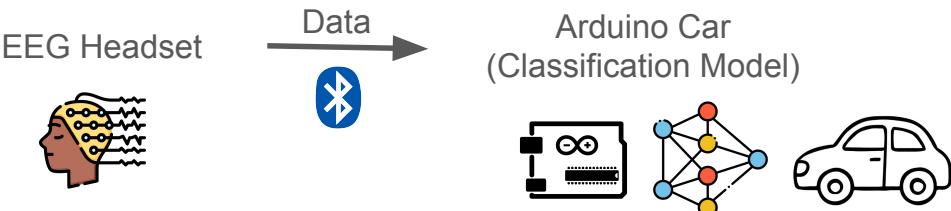


Mind Drive: EEG-Controlled Arduino Car

Members:

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Yicheng Rong

Mind Drive



Motivation & Objective

- **Electroencephalogram (EEG)**, also known as “brain wave”, is a promising brain computer interface technology that is **low-cost** and **non-invasive**.
- **Goal: Build a prototype device that can read EEG, decode the user intent, and use that to control an Arduino Car.**

Target users

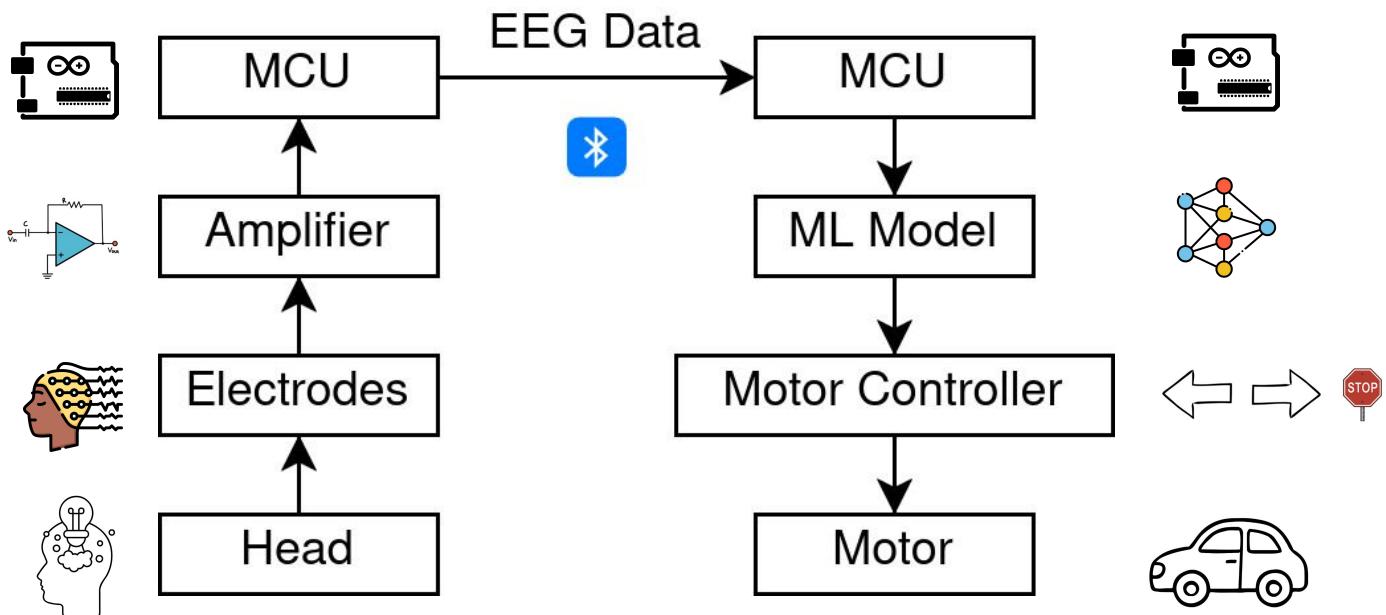
- Disabled people who need a different way to control things
- Hobbists wanting to try out BCI technologies
- Researchers working on EEG related projects

Embedded ML solution

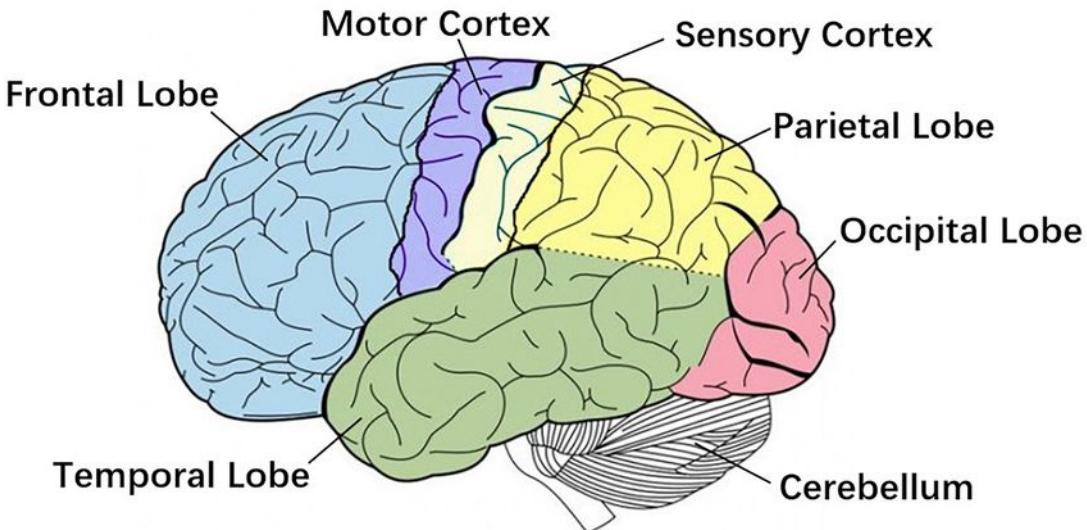
- Latency: real time control
- Economics: no data transmission and cloud processing costs
- Reliability: no need for internet connection
- Privacy: users' EEG signals are sensitive data

Components

System Design



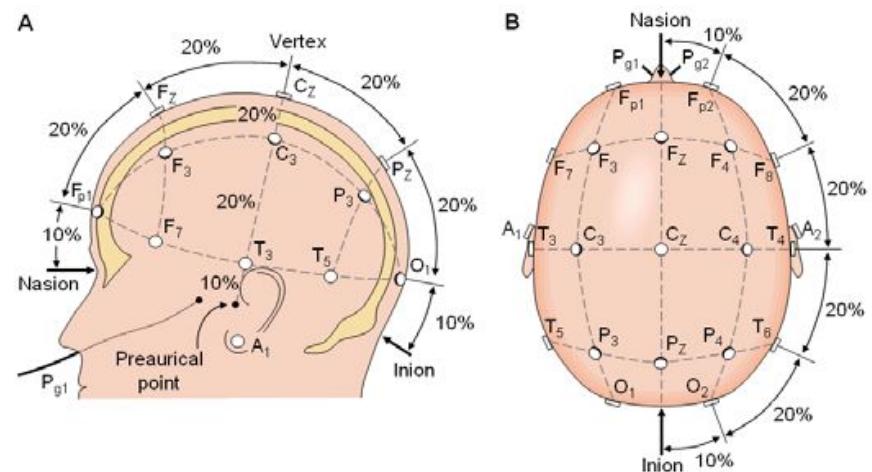
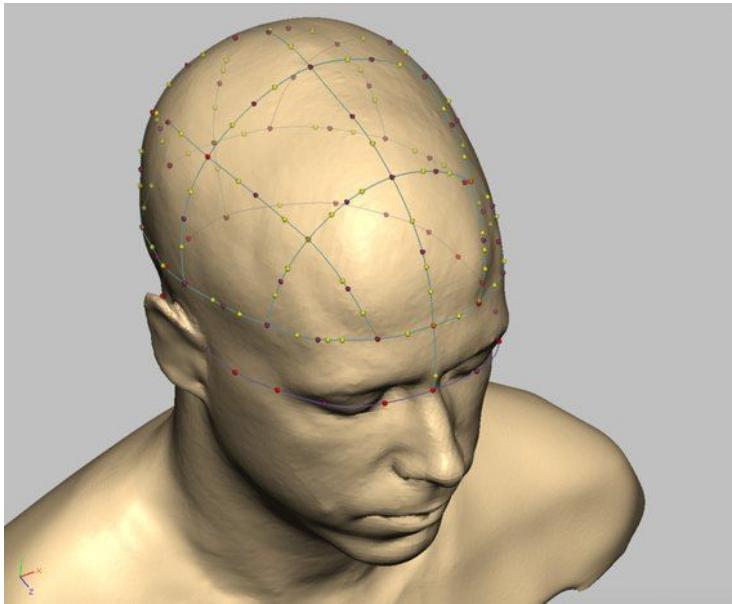
The Motor Cortex



Images:

https://www.researchgate.net/publication/331905251_Corticomuscular_Coherence_and_Its_Applications_A_Review

The EEG 10-20 System



Images:

<https://threeformfashion.com/?p=299>

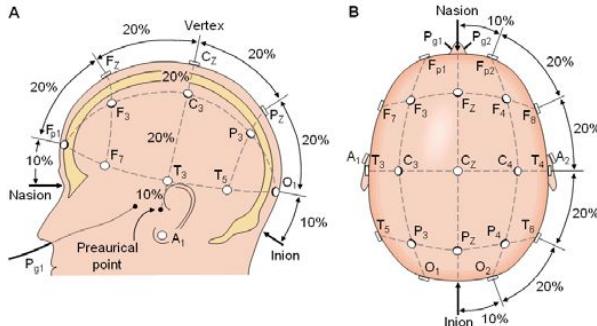
https://www.researchgate.net/publication/303836379_SoundPacman_Audio_Augmented_Reality_in_Location-based_Games

Hardware

EEG Headset



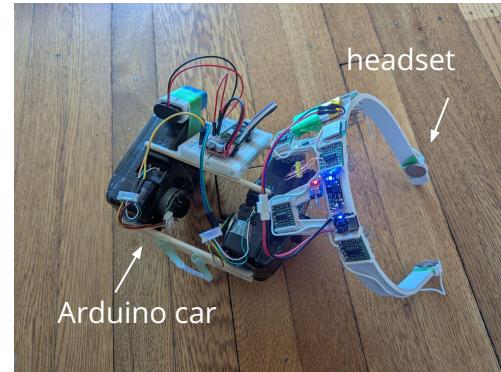
- 5 channels over the motor cortex:
C3, Cz, C4, FC1, FC2



- Instrumentation Amplifier
(3000 times, 1-60Hz bandpass filter)

Arduino Car

- ESP32
- Motor driver IC



Hardware

EEG Headset



5 channels over the motor cortex
(C3 Cz C4 FC1 FC2)

Instrumentation Amplifier
(3000 times, 1-60Hz bandpass filter)

Arduino Car

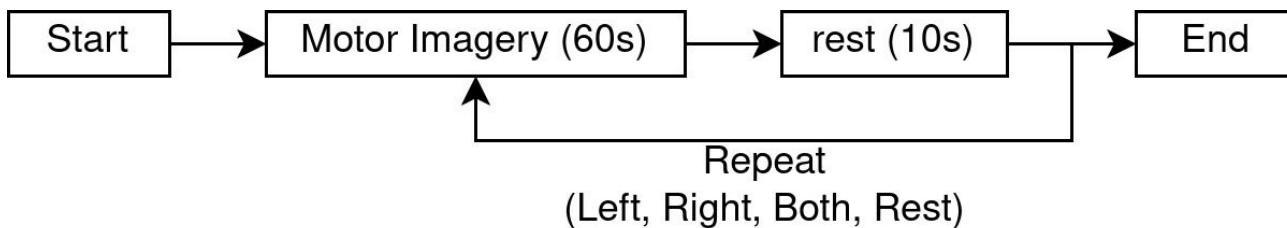
ESP32

Motor driver IC

Dataset Collection

- Collected 10 Sessions (~40 mins) on one person
- 4 classes: Left, Right, Both, Rest
- For each class, make visual imagination
- 5 EEG Channels, 180Hz using the custom made EEG headset

Scheme:



Embedded Machine Learning Model

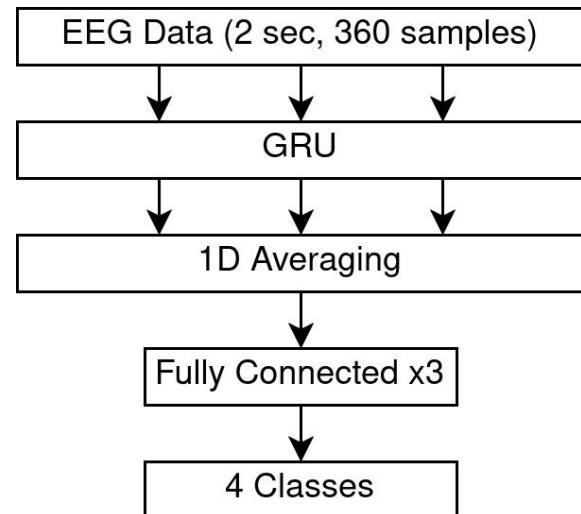
Data preprocessing

- 1-60Hz bandpass filter (remove noisy, uninformative information from the input data)

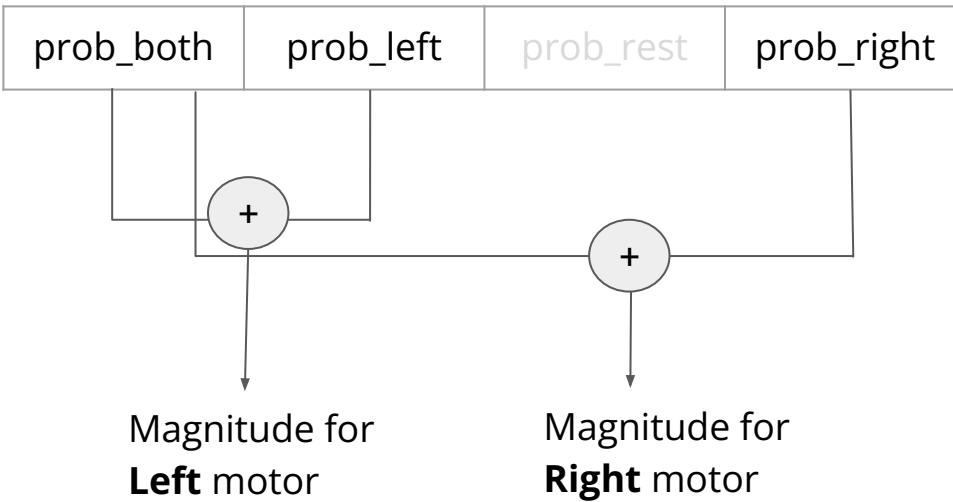
Model selection

- Experimented with various model architectures including CNN, RNN, LSTM, GRU based models
- Sequence models have much better performance than CNN even with less number of parameters
- However, RNN and LSTM are much slower and more difficult to deploy on the microcontroller

Model Architecture

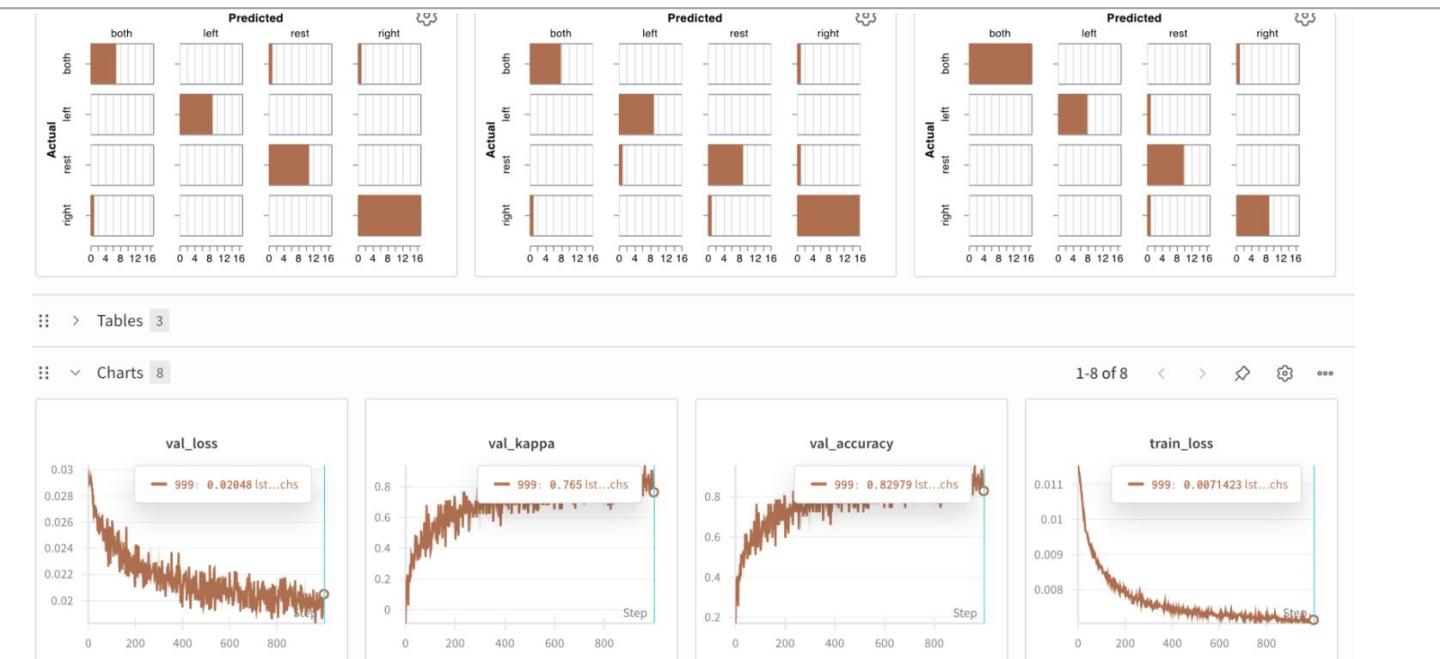


Model Classification to Car Control

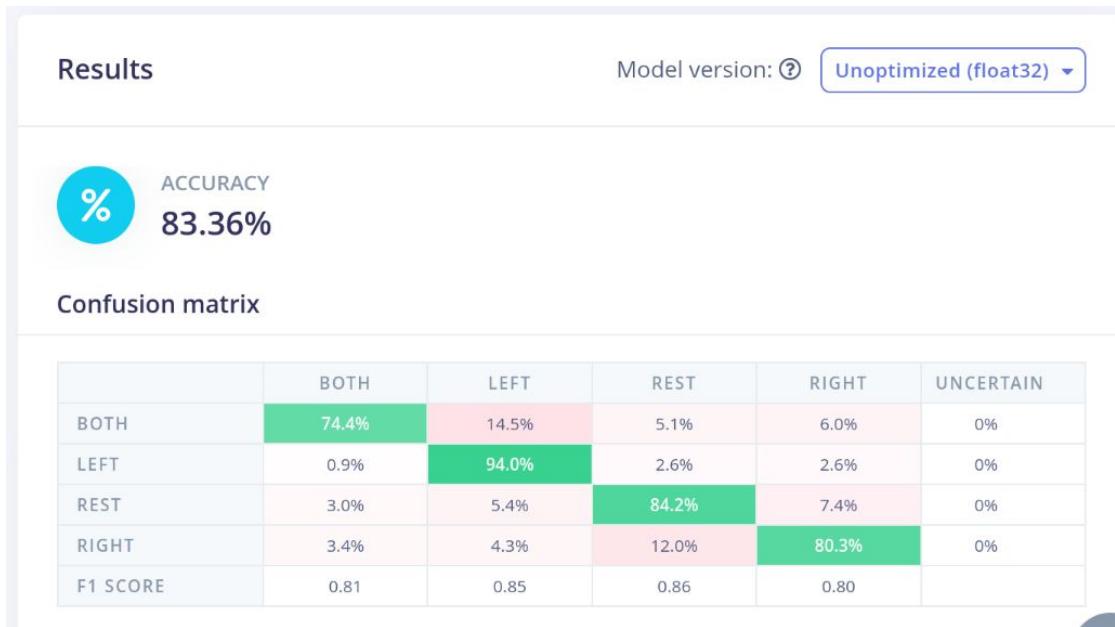


Results

Validation Accuracy



Test Accuracy



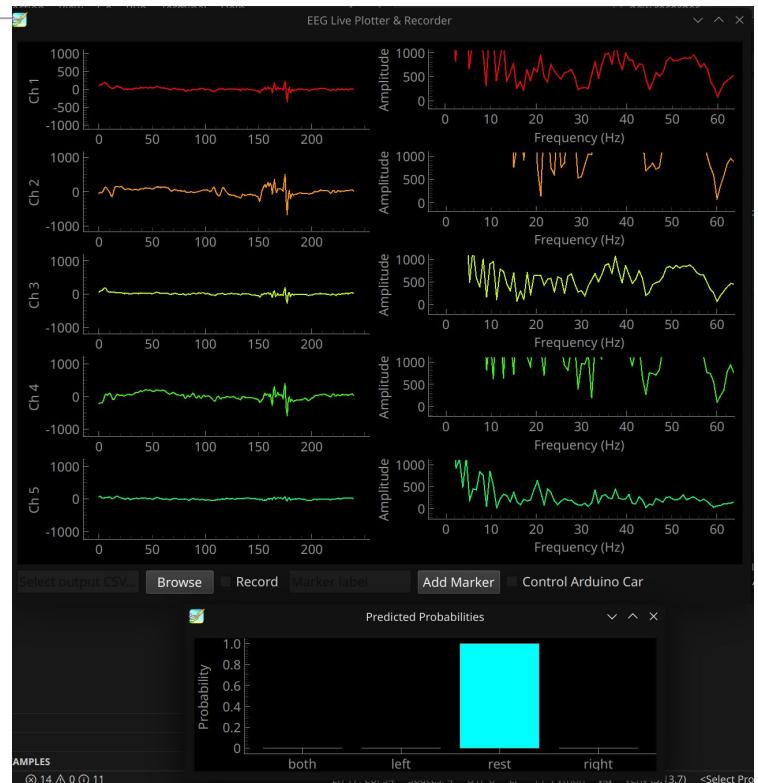
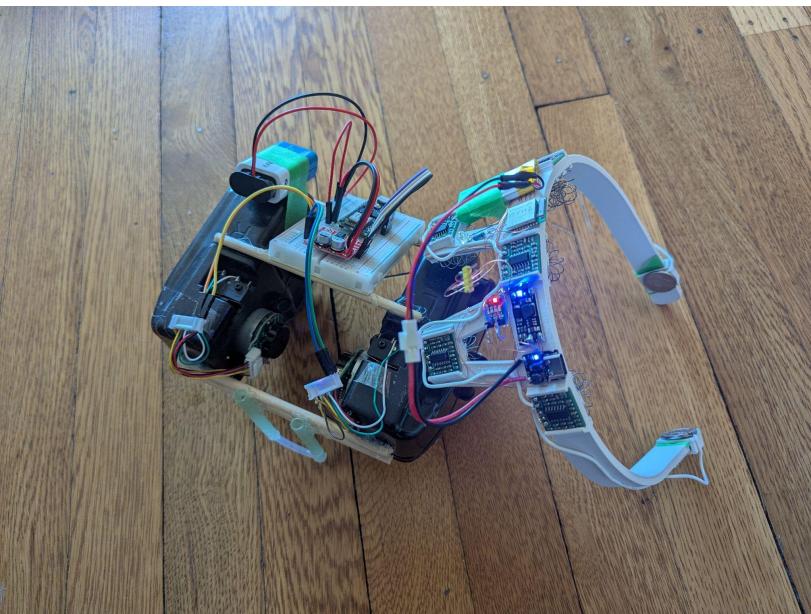
Embedded Performance

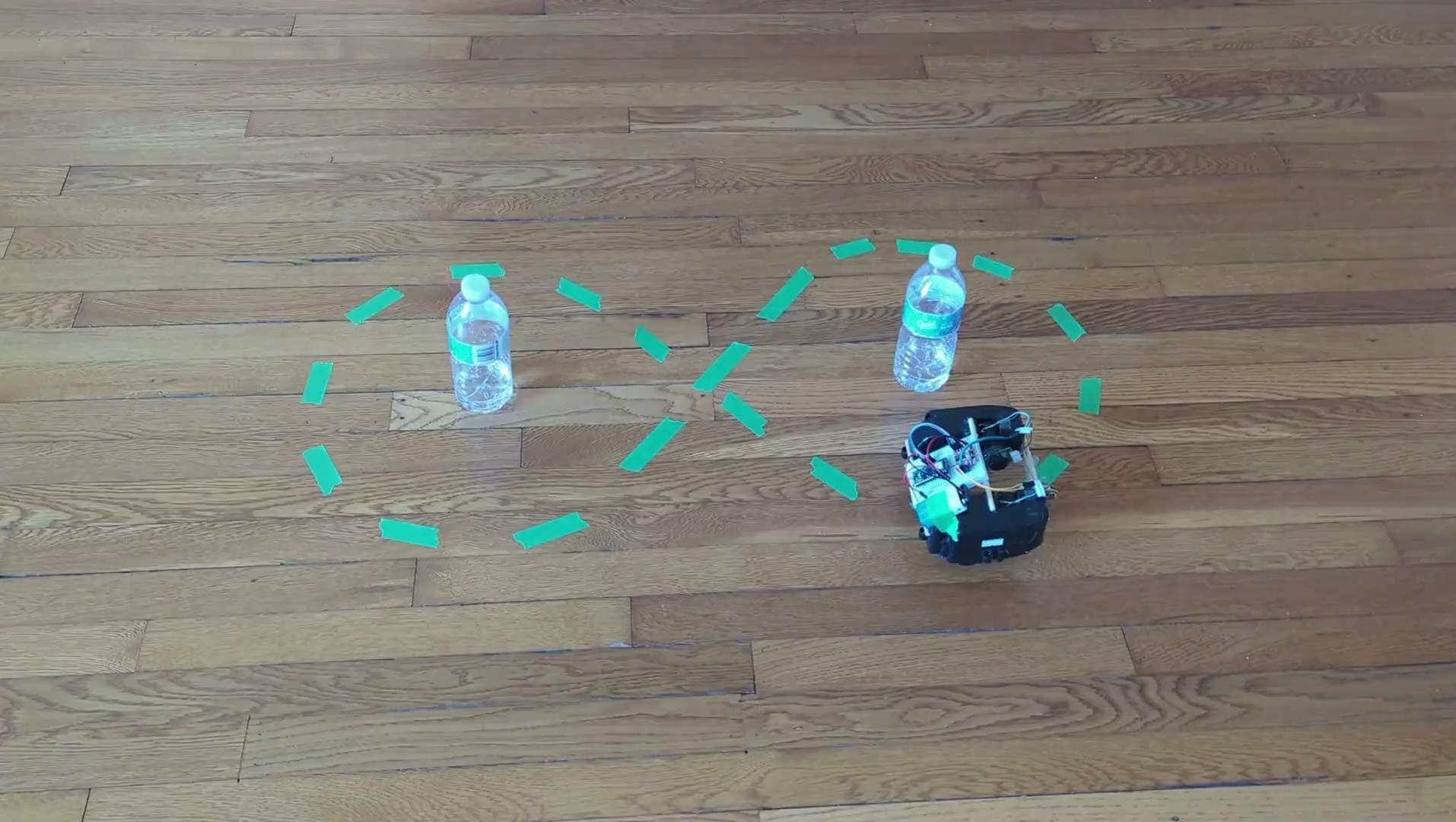
	GRU	Fully Connected
Flash Size	16.4KiB	9.7KiB
RAM Usage	4096 Bytes	1024 Bytes
Inference Time	1ms	1ms

180 samples per second + 10 full inference per second:

180ms + 10ms = 190ms = 19% CPU load

Hardware & Software





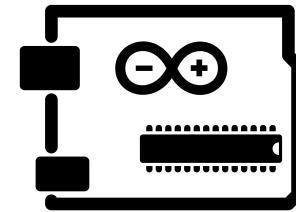
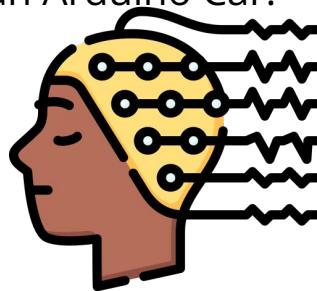
Challenges

- Data Collection
 - Data is noisy, hard to do data cleaning manually
 - Domain shifting issue across session
 - Hard to reuse public datasets
- Model Training
 - Small dataset -> prone to overfitting
 - Model accuracy ≠ user experience (different class have different implication on car controlling)
- Deployment
 - Bad framework support for recursive neural networks
 - Limited computation & memory on MCU
 - Bluetooth debugging

Q&A

Overview

- **Electroencephalogram (EEG)**, also known as “brain wave”, is a promising brain computer interface technology that is **low-cost** and **non-invasive**.
- EEG has potential for various applications, such as health monitoring, accessibility tools, or simply input device for entertainment.
- Goal: Build a prototype device that can read EEG, decode the user intent, and use that to control an Arduino Car.



Carnegie Mellon University

Target Users

This project can be beneficial for:

- Disabled people who need a different way to control things
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Why using Embedded Machine Learning

Latency

- Low latency is required for most applications

Economics

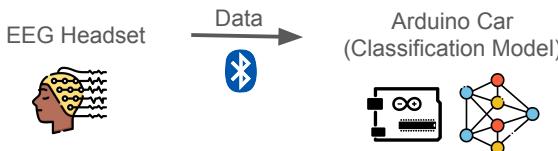
- No data transmission and cloud processing costs

Reliability

- No need for internet connection

Privacy

- The users EEG signals are sensitive data



System Design

