16-311 HW0, p4
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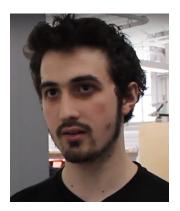
Figure 1: My face

1 Academic Interests

Robotics I enjoy studying the kinematics of robots.

Mechanical Engineering I enjoy building robots.

2 Extracurricular Interests

Robots I enjoy designing robot controllers and communication protocols.

3 Denouement

This concludes the information portion of this report. If you are interested in further related material, you will be able to locate my face in Figure 1. Additionally, you can find more information about robots at the Section 4 website: http://www.andrew.cmu.edu/user/cwcolomb/

$$\frac{\delta L}{\delta \vec{q}_k} - \frac{d}{dt} \frac{\delta L}{\delta \dot{\vec{q}}_k} = 0$$