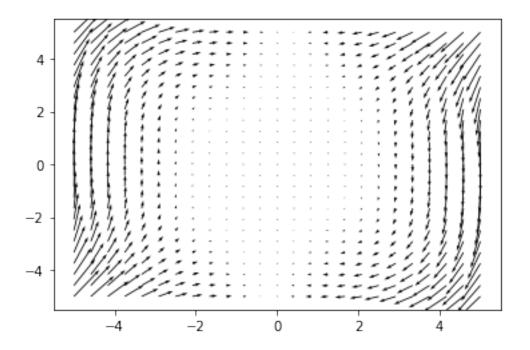
#### October 15, 2020

```
[63]: import numpy as np
      import matplotlib.pyplot as plt
      from mpl_toolkits.mplot3d import Axes3D
      from matplotlib import cm
[50]: def sys(X):
          x1, x2 = X
          return [x2 - x1*np.power(x2,2), -np.power(x1,3)]
      def linsys(X):
          x1, x2 = X
          return [-x2, 0]
[51]: def phase_portrait2D(f, xmin=-5, xmax=5, ymin=-5, ymax=5, num=25):
          x1 = np.linspace(xmin,xmax, num=num)
          x2 = np.linspace(ymin,ymax, num=num)
          x1, x2 = np.meshgrid(x1,x2)
          u, v = np.zeros(x1.shape), np.zeros(x2.shape)
          Nr, Nc = x1.shape
          for r in range(Nr):
              for c in range(Nc):
                  x = x1[r,c]
                  y = x2[r,c]
                  xd = f([x,y])
                  u[r,c] = xd[0]
                  v[r,c] = xd[1]
          Q = plt.quiver(x1,x2, u,v)
```

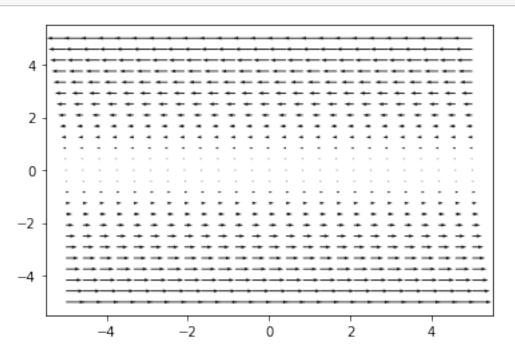
#### 0.1 c.i. Original System Phase Portrait Plot

```
[52]: phase_portrait2D(sys)
```

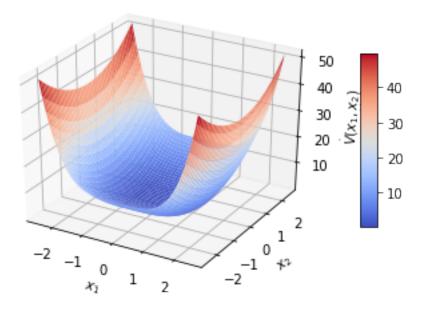


# $0.2\,\,$ c.ii. Linearized System Phase Portrait Plot

# [111]: phase\_portrait2D(linsys)



### 0.3 d. 3D Plot of Lyapunov Function Temporal Derivative



[]: