

# Derivatives

## Why This Matters

**Derivatives measure rate of change.** They answer:

*"How fast is this changing right now?"*

Derivatives are everywhere:

- **Physics:** Velocity, acceleration, forces
- **Economics:** Marginal cost, profit optimization
- **Machine learning:** Gradient descent, backpropagation
- **Engineering:** Control systems, signal processing
- **Data science:** Optimization, curve analysis

Understanding derivatives means understanding **change itself**.

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## The Big Picture: Instantaneous Rate of Change

### Average vs Instantaneous

**Average rate of change** (slope between two points):

$$m_{\text{avg}} = \frac{f(b) - f(a)}{b - a}$$

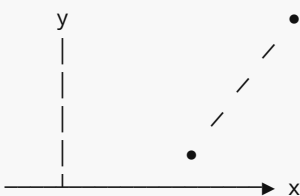
**Instantaneous rate of change** (slope at one point):

$$f'(x) = \lim_{h \rightarrow 0} \frac{f(x + h) - f(x)}{h}$$

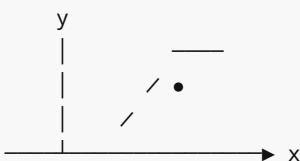
**This is the derivative.**

### Visual: Secant to Tangent

Secant line (average):



Tangent line (instantaneous):



As the two points get closer ( $h \rightarrow 0$ ), the secant becomes the tangent.

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## 1. Definition of the Derivative

### The Limit Definition

$$f'(x) = \lim_{h \rightarrow 0} \frac{f(x+h) - f(x)}{h}$$

**Read as:** "f prime of x" (the derivative of f at x)

**What it means:**

- Change in f divided by change in x
- As the change in x shrinks to zero
- Gives instantaneous rate of change

### Alternative Notation

$f'(x)$	(Lagrange notation)
$df/dx$	(Leibniz notation)
$dy/dx$	(if $y = f(x)$ )
$Df(x)$	(Operator notation)

All mean the same thing.

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## 2. Computing Derivatives from the Definition

### Example 1: $f(x) = x^2$

$$\begin{aligned} f'(x) &= \lim_{h \rightarrow 0} \frac{(x+h)^2 - x^2}{h} \\ &= \lim_{h \rightarrow 0} \frac{x^2 + 2xh + h^2 - x^2}{h} \\ &= \lim_{h \rightarrow 0} \frac{2xh + h^2}{h} \\ &= \lim_{h \rightarrow 0} (2x + h) \\ &= 2x \end{aligned}$$

**Result:** If  $f(x) = x^2$ , then  $f'(x) = 2x$

### Example 2: $f(x) = 3x + 1$

$$\begin{aligned} f'(x) &= \lim_{h \rightarrow 0} \frac{(3(x+h) + 1) - (3x + 1)}{h} \\ &= \lim_{h \rightarrow 0} \frac{3x + 3h + 1 - 3x - 1}{h} \\ &= \lim_{h \rightarrow 0} \frac{3h}{h} \\ &= 3 \end{aligned}$$

**Result:** If  $f(x) = 3x + 1$ , then  $f'(x) = 3$

**General:** Linear functions have constant derivatives (their slopes).

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## 3. Common Derivative Formulas

Instead of using the limit definition every time, we have formulas:

### Power Rule

$$d/dx(x^n) = nx^{n-1}$$

**Examples:**

$$\begin{aligned} d/dx(x^3) &= 3x^2 \\ d/dx(x^5) &= 5x^4 \\ d/dx(x) &= 1x^0 = 1 \\ d/dx(1) &= 0 \quad (\text{constant}) \end{aligned}$$

### Constant Rule

$$d/dx(c) = 0$$

The derivative of a constant is zero (no change)

### Constant Multiple Rule

$$d/dx(cf(x)) = c \cdot f'(x)$$

Constants pull out

**Example:**

$$d/dx(5x^3) = 5 \cdot 3x^2 = 15x^2$$

## Sum/Difference Rule

$$d/dx(f(x) + g(x)) = f'(x) + g'(x)$$

Derivatives distribute over addition

**Example:**

$$\begin{aligned} d/dx(x^3 + 2x^2 - 5x + 7) \\ &= 3x^2 + 4x - 5 + 0 \\ &= 3x^2 + 4x - 5 \end{aligned}$$

## 4. Product and Quotient Rules

### Product Rule

$$d/dx(f \cdot g) = f' \cdot g + f \cdot g'$$

**NOT  $f' \cdot g'$ !**

**Example:**

$$\begin{aligned} d/dx(x^2 \cdot \sin(x)) \\ f = x^2, \quad f' = 2x \\ g = \sin(x), \quad g' = \cos(x) \\ = 2x \cdot \sin(x) + x^2 \cdot \cos(x) \end{aligned}$$

### Quotient Rule

$$d/dx\left(\frac{f}{g}\right) = \frac{f' \cdot g - f \cdot g'}{g^2}$$

**"Low d-high minus high d-low, all over low squared"**

**Example:**

$$\begin{aligned} d/dx\left(\frac{x^2}{x+1}\right) \\ f = x^2, \quad f' = 2x \\ g = x+1, \quad g' = 1 \\ \frac{2x(x+1) - x^2(1)}{(x+1)^2} = \frac{2x^2 + 2x - x^2}{x^2 + 2x + 1} = \frac{x^2 + 2x}{x^2 + 2x + 1} \end{aligned}$$

$$= \frac{\quad}{(x+1)^2} = \frac{\quad}{(x+1)^2} = \frac{\quad}{(x+1)^2}$$

## 5. Chain Rule (The Most Important)

### The Rule

For composite functions:

$$d/dx(f(g(x))) = f'(g(x)) \cdot g'(x)$$

In words: "Derivative of outer  $\times$  derivative of inner"

### Example 1: $(x^2 + 1)^3$

Outer function:  $u^3$

Inner function:  $u = x^2 + 1$

$$\begin{aligned} d/dx((x^2+1)^3) &= 3(x^2+1)^2 \cdot (2x) \\ &= 6x(x^2+1)^2 \end{aligned}$$

### Example 2: $\sin(x^2)$

Outer:  $\sin(u)$

Inner:  $u = x^2$

$$\begin{aligned} d/dx(\sin(x^2)) &= \cos(x^2) \cdot (2x) \\ &= 2x \cdot \cos(x^2) \end{aligned}$$

### Example 3: $e^{x^2}$

$$\begin{aligned} d/dx(e^{x^2}) &= e^{x^2} \cdot (2x) \\ &= 2x \cdot e^{x^2} \end{aligned}$$

## Why It Matters

Most complex derivatives need the chain rule.

```
// In neural networks, backpropagation is repeated chain rule
function backprop(layers) {
  let gradient = 1;
  for (let i = layers.length - 1; i >= 0; i--) {
    gradient *= layers[i].derivative(); // Chain rule!
  }
  return gradient;
}
```

## 6. Derivatives of Standard Functions

## Polynomials

$$d/dx(x^n) = nx^{n-1}$$

## Exponential

$$d/dx(e^x) = e^x \quad (\text{special property!})$$

$$d/dx(a^x) = a^x \cdot \ln(a)$$

## Logarithmic

$$d/dx(\ln(x)) = 1/x$$

$$d/dx(\log_a(x)) = 1/(x \cdot \ln(a))$$

## Trigonometric

$$d/dx(\sin(x)) = \cos(x)$$

$$d/dx(\cos(x)) = -\sin(x)$$

$$d/dx(\tan(x)) = \sec^2(x) = 1/\cos^2(x)$$

## Inverse Trig

$$d/dx(\sin^{-1}(x)) = 1/\sqrt{1-x^2}$$

$$d/dx(\cos^{-1}(x)) = -1/\sqrt{1-x^2}$$

$$d/dx(\tan^{-1}(x)) = 1/(1+x^2)$$

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## 7. What Derivatives Tell Us

### Slope of the Tangent Line

At any point,  $f'(x)$  is the slope of the tangent line.



**Tangent line equation at  $x = a$ :**

$$y - f(a) = f'(a)(x - a)$$

$$\text{or: } y = f'(a)(x - a) + f(a)$$

## Increasing/Decreasing

$f'(x) > 0 \rightarrow f$  is increasing  
 $f'(x) < 0 \rightarrow f$  is decreasing  
 $f'(x) = 0 \rightarrow f$  has a horizontal tangent (critical point)

	∧	$f' > 0$ : rising
	/ \	$f' = 0$ : peak
	/ \	$f' < 0$ : falling

## Critical Points

Where  $f'(x) = 0$  or  $f'(x)$  doesn't exist.

These are **candidates** for max/min values.

**Example:**  $f(x) = x^2 - 4x + 3$

$f'(x) = 2x - 4 = 0$   
 $x = 2$  (critical point)  
  
 $f(2) = 4 - 8 + 3 = -1$  (minimum)

## Concavity (Second Derivative)

**Second derivative**  $f''(x)$  = derivative of  $f'(x)$

$f''(x) > 0 \rightarrow$  concave up (∪)  
 $f''(x) < 0 \rightarrow$  concave down (∩)  
 $f''(x) = 0 \rightarrow$  possible inflection point

# 8. Applications

## Velocity and Acceleration

**Position function:**  $s(t)$  **Velocity:**  $v(t) = s'(t)$  **Acceleration:**  $a(t) = v'(t) = s''(t)$

**Example:**  $s(t) = -16t^2 + 64t + 5$

Velocity:  $v(t) = -32t + 64$   
Acceleration:  $a(t) = -32 \text{ ft/s}^2$  (gravity)  
  
At  $t = 2$ :  
 $v(2) = -32(2) + 64 = 0$  (peak height)

## Optimization

Find maximum or minimum values.

**Method:**

1. Find  $f'(x)$
2. Solve  $f'(x) = 0$  for critical points
3. Test which is max/min (using second derivative or endpoints)

**Example:** Maximize area of rectangle with perimeter 100

Let width =  $x$ , then height =  $(100-2x)/2 = 50-x$

Area:  $A(x) = x(50-x) = 50x - x^2$

$A'(x) = 50 - 2x = 0$

$x = 25$

Max area =  $25(25) = 625$  sq units (square shape)

## Marginal Analysis (Economics)

**Marginal cost** = derivative of cost function **Marginal revenue** = derivative of revenue function **Marginal profit** = derivative of profit function

$C(x) = 1000 + 5x + 0.01x^2$

$C'(x) = 5 + 0.02x$  (marginal cost)

At  $x = 100$ :  $C'(100) = 5 + 2 = \$7$  per unit

## Machine Learning: Gradient Descent

**Update rule:**

$$\theta_{\text{new}} = \theta_{\text{old}} - \alpha \cdot \nabla J(\theta)$$

$\uparrow$              $\uparrow$      $\uparrow$   
 param    learn   gradient (derivative!)  
           rate

**In code:**

```
function gradientDescent(f, df, x0, learningRate, iterations) {
  let x = x0;
  for (let i = 0; i < iterations; i++) {
    x = x - learningRate * df(x); // Move opposite to gradient
  }
  return x;
}

// Minimize f(x) = x^2
const f = x => x**2;
const df = x => 2*x;
gradientDescent(f, df, 10, 0.1, 100); // Converges to 0
```

## Related Rates

When two quantities change over time, relate their derivatives.



**Example:** Balloon radius increasing at 2 cm/s. How fast is volume increasing?

$$V = (4/3)\pi r^3$$

$$dV/dt = 4\pi r^2 \cdot dr/dt \quad (\text{chain rule})$$

If  $dr/dt = 2$  cm/s and  $r = 5$  cm:

$$dV/dt = 4\pi(25)(2) = 200\pi \text{ cm}^3/\text{s}$$

## 9. Programming Derivatives

### Numerical Approximation

```
function derivative(f, x, h = 1e-5) {  
  return (f(x + h) - f(x - h)) / (2*h);  
}  
  
// Example: f(x) = x^3  
const f = x => x**3;  
derivative(f, 2); // ≈ 12 (exact: 3(2^2) = 12)
```

### Automatic Differentiation (Modern ML)

```
// Simplified dual number (stores value and derivative)  
class Dual {  
  constructor(value, derivative = 0) {  
    this.value = value;  
    this.derivative = derivative;  
  }  
  
  add(other) {  
    return new Dual(  
      this.value + other.value,  
      this.derivative + other.derivative  
    );  
  }  
  
  multiply(other) {  
    return new Dual(  
      this.value * other.value,  
      this.derivative * other.value + this.value * other.derivative  
    );  
  }  
}  
  
// Compute f(x) = x^2 at x=3  
const x = new Dual(3, 1); // x=3, dx/dx=1  
const result = x.multiply(x);
```

```
console.log(result.value);      // 9
console.log(result.derivative); // 6 (exact: 2x = 6)
```

## 10. Higher-Order Derivatives

### Notation

$f'(x)$  = first derivative  
 $f''(x)$  = second derivative (derivative of  $f'$ )  
 $f'''(x)$  = third derivative  
 $f^{(n)}(x)$  = nth derivative

### Leibniz notation:

$dy/dx$ ,  $d^2y/dx^2$ ,  $d^3y/dx^3$ , ...

### Example

$f(x) = x^4$   
 $f'(x) = 4x^3$   
 $f''(x) = 12x^2$   
 $f'''(x) = 24x$   
 $f^{(4)}(x) = 24$   
 $f^{(5)}(x) = 0$  (all higher derivatives are zero)

### Physical Meaning

Position:  $s(t)$   
Velocity:  $v(t) = s'(t)$   
Acceleration:  $a(t) = s''(t)$   
Jerk:  $j(t) = s'''(t)$  (rate of change of acceleration)

## Common Mistakes & Misconceptions

### ✗ "Derivative of $f \cdot g$ is $f' \cdot g$ "

**No!** Use product rule:  $f' \cdot g + f \cdot g'$

### ✗ " $d/dx(f/g) = f'/g$ "

**No!** Use quotient rule:  $(f' \cdot g - f \cdot g')/g^2$

### ✗ "Forgetting the chain rule"

$d/dx(\sin(x^2)) \neq \cos(x^2)$

Correct:  $\cos(x^2) \cdot 2x$

## ✗ "f'(x) = 0 means maximum"

Could be minimum, or neither (inflection point). Must test.

## ✗ "Derivative doesn't exist = function doesn't exist"

Function can exist but not be differentiable (sharp corner, vertical tangent).

## Tiny Practice

Find derivatives:

1.  $f(x) = x^3 - 2x + 5$
2.  $f(x) = 3x^4 + 2x^2 - 7$
3.  $f(x) = (x^2 + 1)(x - 2)$
4.  $f(x) = x^2/x + 1$
5.  $f(x) = (x^2 + 1)^3$

**Applications:** 6. If  $s(t) = -16t^2 + 32t$ , find velocity at  $t = 1$  7. Find critical points of  $f(x) = x^3 - 3x$  8. At what  $x$  does  $f(x) = x^2 - 4x + 3$  have minimum?

► Answers

## Summary Cheat Sheet

### Definition

$$f'(x) = \lim_{h \rightarrow 0} \frac{f(x+h) - f(x)}{h}$$

### Key Rules

Function	Derivative
$x^n$	$nx^{n-1}$
$e^x$	$e^x$
$\ln(x)$	$1/x$
$\sin(x)$	$\cos(x)$
$\cos(x)$	$-\sin(x)$
$cf(x)$	$cf'(x)$
$f + g$	$f' + g'$
$fg$	$f'g + fg'$
$f/g$	$(f'g - fg')/g^2$
$f(g(x))$	$f'(g(x)) \cdot g'(x)$

## Interpretation

```
f'(x) > 0 → increasing
f'(x) < 0 → decreasing
f'(x) = 0 → critical point

f''(x) > 0 → concave up
f''(x) < 0 → concave down
```

## Applications

```
Velocity: v = ds/dt
Acceleration: a = dv/dt
Optimization: Set f'(x) = 0, solve
Tangent line: y = f'(a)(x-a) + f(a)
```

## Programming

```
// Numerical
const df = (f, x, h=1e-5) => (f(x+h) - f(x-h))/(2*h);

// Chain rule example
const d_sin_x2 = x => Math.cos(x*x) * 2*x;
```

## Next Steps

Derivatives measure instantaneous rate of change. You now understand:

- The limit definition
- Common derivative rules
- Applications to optimization and motion

Next and finally, we'll explore **Integrals**—the reverse of derivatives, measuring accumulation.

Continue to: [12-integrals.md](#)