# 420-J13-AS Advanced Data Structure Lecture 02 - Analysis

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#### **Analysis Terms**

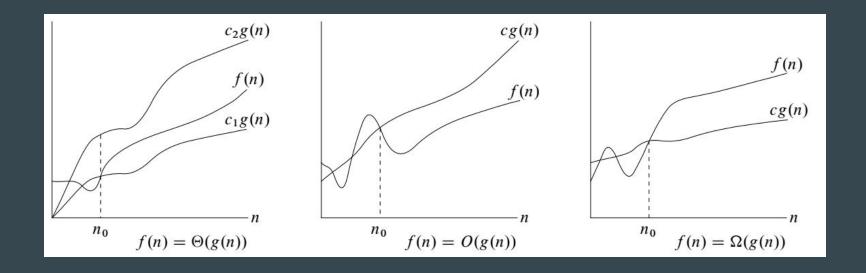
- Input size is number of items in the input
  - Number of bits
  - Number of integers
  - Number of points
- Running time is number of steps executed
  - Add, substract, multiply, divide
  - Load, store, copy
  - Branching

#### Worst-case

- We mostly focus on the worst-case running time for algorithms
- Three reasons
  - It is a guarantee that the algorithm will not take longer
  - Worst case can occur often
  - Average case is often almost as bad as worst case

#### **Asymptotic Notation**

- O-notation (Big Oh) is an asymptotic upper bound
- $\Omega$ -notation is an asymptotic lower bound
- $\Theta$ -notation is both an upper and lower bound



#### **Insertion Sort Analysis**

- Worst-case running time is O(n²)
- Best-case running time is O(n)
- Algorithm follows an incremental approach

# Divide-And-Conquer Approach

- Recursive in structure
- Three steps for every recursion:
  - Divide the problem into subproblems
  - Conquer the problems by solving them recursively
  - Combine the solutions to the subproblems
- Merge sort:
  - Divide n-element sequence into two halves (n/2)
  - Sort the two subsequences recursively
  - Merge the two sorted subsequences

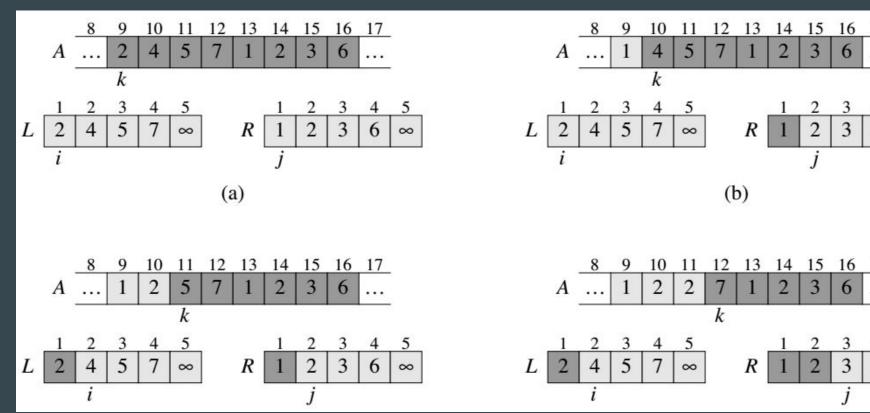
#### Merge Procedure

- Given two piles of cards that are sorted, we want to combine them
- Look at the top card of each pile and put the smallest one on another pile
- Repeat until all cards end up in that pile
- MERGE(A, p, q, r)
  - A is the array
  - $p \le q < r$  are the indices of the array
  - Subarrays A[p .. q] and A[q + 1 .. r] are sorted
  - Output is A [p .. r] is sorted
- We use a sentinel value (∞) to simplify the code. Imagine that the last card of every pile is infinity, so we don't need conditions to check whether a pile is empty or not.

# MERGE(A, p, q, r)

```
n_1 = q - p + 1
      n_2 = r - q
      let L[1 .. n_1 + 1] and R[1 .. n_2 + 1] be new arrays
      for i = 1 to n_1
        L[i] = A[p + i - 1]
      for j = 1 to n_2
      R[j] = A[q + j]
     L[n_1 + 1] = \infty
      R[n_2 + 1] = \infty
     i = 1
     j = 1
      for k = p to r
12.
         if L[i] < R[j]
13.
14.
         A[k] = L[i]
15.
      i = i + 1
     else A[k] = R[j]
17.
```

# MERGE(A, p, q, r) Example



# MERGE-SORT(A, p, r)

- 1. if p < r
- 2. q = (p + r)/2
- 3. MERGE-SORT(A, p, q)
- 4. MERGE-SORT(A, q + 1, r)
- 5.  $\overline{MERGE}(A, p, q, r)$

#### Merge Sort Analysis

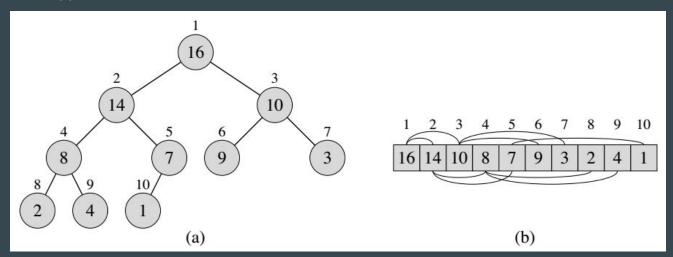
- Worst-case running time is O(n log n)
- Best-case running time is O(n log n)
- Algorithm follows a divide-and-conquer approach

#### Heapsort

- Running time is O(n lg n)
  - Like merge sort
  - Unlike insertion sort
- Can sort in place
  - Like insertion sort
  - Unlike merge sort
- Uses the heap data structure

# Heap

- Binary tree
- Given the index i
  - PARENT(i) => return i/2
  - LEFT(i) => return 2i
  - o RIGHT(i) => return 2i + 1



### Heap Property

- Max-heap property is every node i other than the root:
   A[PARENT(i)] ≥ A[i]
- Min-heap property is every node i other than the root:
   A[PARENT(i)] ≤ A[i]
- Height of a tree with n elements is lg(n)

# Exercises 6.1 (CLRS)

- 1. What are the minimum and maximum numbers of elements in a heap of height *h*?
- 2. Show than an n-element heap has height lg(n)
- 3. Show that in any subtree of a max-heap, the root of the subtree contains the largest value occurring anywhere in that subtree

#### Maintaining The Heap Property

- MAX-HEAPIFY(A, i) maintains the heap property
  - A is the array
  - o i is an index into the array
- When called, we assume that LEFT(i) and RIGHT(i) are max-heaps
- The procedure lets the value at A[i] float down

### MAX-HEAPIFY(A, i)

```
L = LEFT(i)
2. R = RIGHT(i)
    if (L \le A.heap-size and A[L] > A[i])
4.
       largest = L
     else largest = i
    if (R \le A.heap\text{-size} \text{ and } A[R] > A[largest]
       largest = R
     if largest ≠ i
8.
9.
       exchange A[i] with A[largest]
       MAX-HEAPIFY(A, largest)
10.
```

# Exercises 6.2 (CLRS)

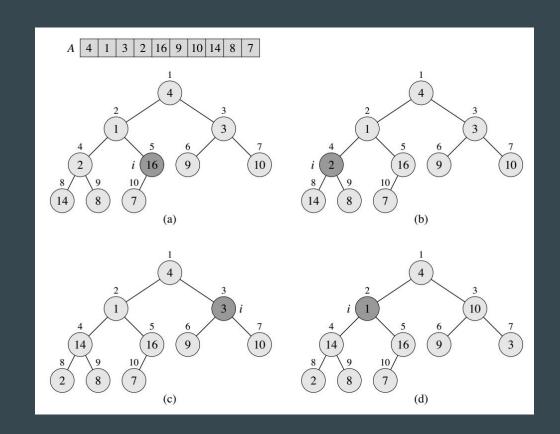
- 1. Illustrate the operation MAX-HEAPIFY(A, 3) on the array A = <27, 17, 3, 16, 13, 10, 1, 5, 7, 12, 4, 8, 9, 0>
- 2. Starting with the procedure MAX-HEAPIFY, write pseudocode for the procedure MIN-HEAPIFY(A, i), which performs the corresponding manipulation on a min-heap
- 3. What is the effect of calling MAX-HEAPIFY(A, i) when A[i] is larger than its children?

#### Building a heap

- Use procedure MAX-HEAPIFY in a bottom-up manner to convert A[1 .. n] into a max-heap
- The elements in the subarray A[(n/2 + 1) ... n)] are all leaves of the tree
- The procedure BUILD-MAX-HEAP goes through the remaining nodes

# BUILD-MAX-HEAP(A)

- 1. A.heap-size = A.length
- 2. for i = A.length/2 downto 1
- 3. MAX-HEAPIFY(A, i)



# Exercises 6.3 (CLRS)

- 1. Illustrate the operation of BUILD-MAX-HEAP on the array A = <5, 3, 17, 10, 84, 19, 6, 22, 0>
- 2. Why do we want the loop index i in line 2 of BUILD-MAX-HEAP to decrease from A.length/2 to 1 rather than increase from 1 to A.length/2?

#### Heapsort Algorithm

- First build a max-heap with BUILD-MAX-HEAP
- Because the maximum element is at A[1] we can swap it with A[n]
- Discard node n from the heap by decrementing A.heap-size
- Restore the max-heap property with MAX-HEAPIFY(A, 1)

# HEAPSORT(A)

- 1. BUILD-MAX-HEAP(A)
- 2. for i = A.length downto 2
- 3. exchange A[1] with A[i]
- 4. A.heap-size = A.heap-size 1
- 5. MAX-HEAPIFY(A, 1)

# Heapsort Analysis

- HEAPSORT takes time O(n lg n)
- BUILD-MAX-HEAP takes O(n)
- Each (n 1) calls to MAX-HEAPIFY takes time O(lg n)

# Exercises 6.4 (CLRS)

1. Illustrate the operation of HEAPSORT on the array  $A = \langle 5, 13, 2, 25, 7, 17, 20, 8, 4 \rangle$ 

#### References

- Cormen, T. (2009). Introduction to algorithms. Cambridge, Mass.: MIT Press.
- <a href="https://en.wikipedia.org/wiki/Merge\_sort">https://en.wikipedia.org/wiki/Merge\_sort</a>
- https://en.wikipedia.org/wiki/Heapsort