	Advantage	Disadvantage
Design 1	<ul> <li>Efficiency is great</li> <li>Code is simple but large as it must incorporate both the modules of systems</li> </ul>	Memory consumption     of this is very large
Design 2	<ul> <li>Polar coordinates are useful when studying the motions of the human body. This is because the human body utilizes pivotal joint movements.</li> <li>When discussing orbits, where radial symmetry is involved, or there is a point source, such as the generation of ripples in water, polar coordinates simplify matters.</li> <li>It is used in the positioning of the object This can be used to make an object orbit around another object.</li> <li>Implementation is simple</li> </ul>	<ul> <li>Limited collision avoidance</li> <li>Not very efficient</li> <li>Positional error is large in these systems</li> </ul>
Design 3	<ul> <li>Calculations of distances between points are trivial.</li> <li>Calculations of areas are relatively easy.</li> <li>Graphic representations are realistic, provided the area covered is not too large.</li> <li>Implementation is easy</li> <li>Eficiency is good as compared to design 2</li> </ul>	<ul> <li>These systems are not suitable in solving complex problems</li> <li>Memory consumption increases as compared to design 2</li> </ul>
Design 4	Efficiency is very high     Almost all the easy as well as complex are solved by this type of design.	<ul> <li>Complexity of the code increases</li> <li>Memory consumption is greatest compared to design 1,2,3,5 because</li> </ul>

	Implementation is easy	of incorporating other variables • Simplicity of the code decreases
Design 5	<ul> <li>It is simple to code as both the modules are incorporated in the program.</li> <li>Efficiency of the code depends on the problem type</li> <li>Error detection is easy</li> </ul>	Memory consumption is more as compared to design 1,2,3 but less than 4