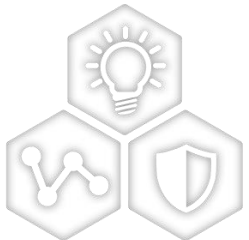


OLED1 Integration



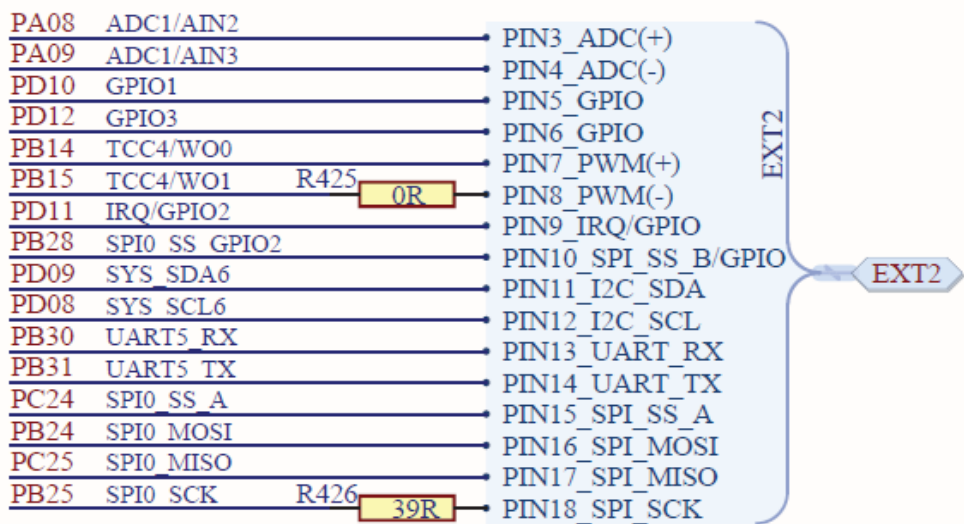
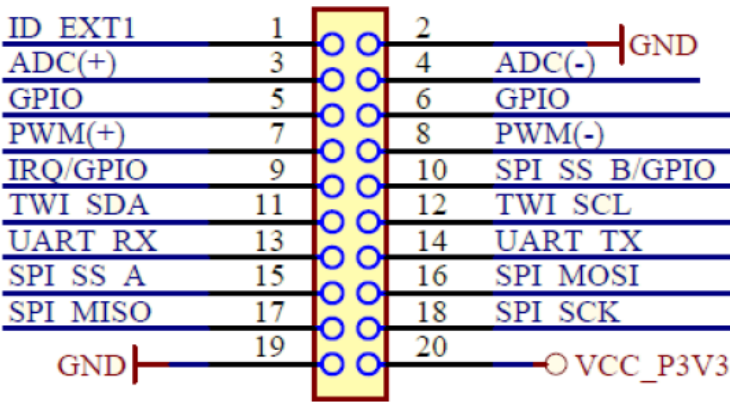
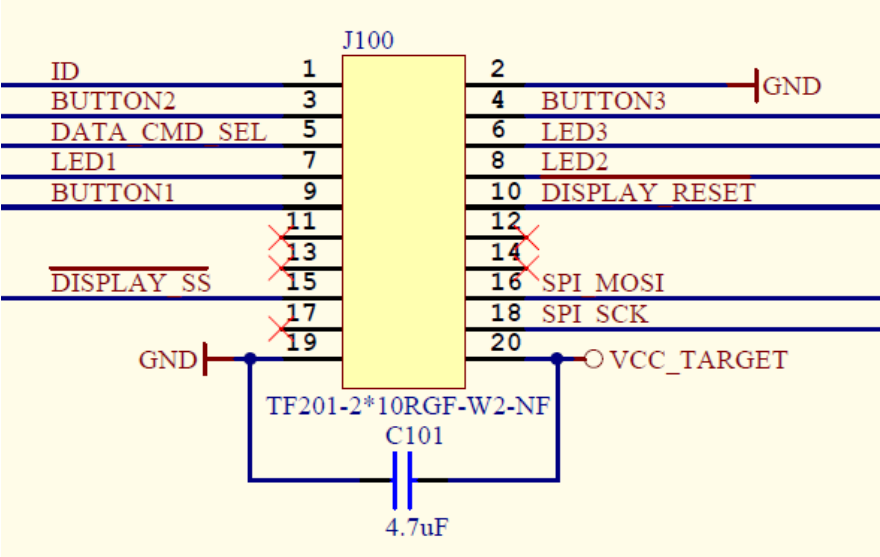
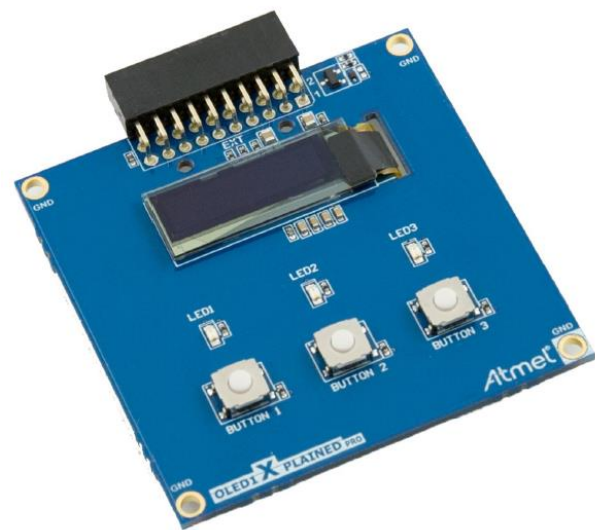
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SMART | CONNECTED | SECURE

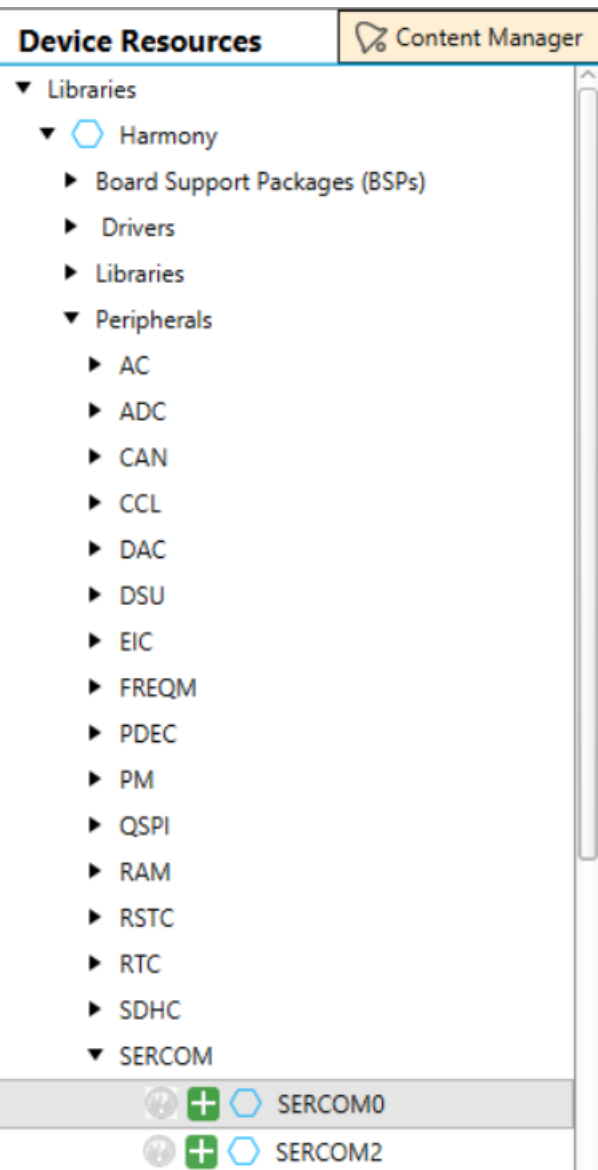
Martin Ruppert

OLED1 Xplained Pro - SSD1306



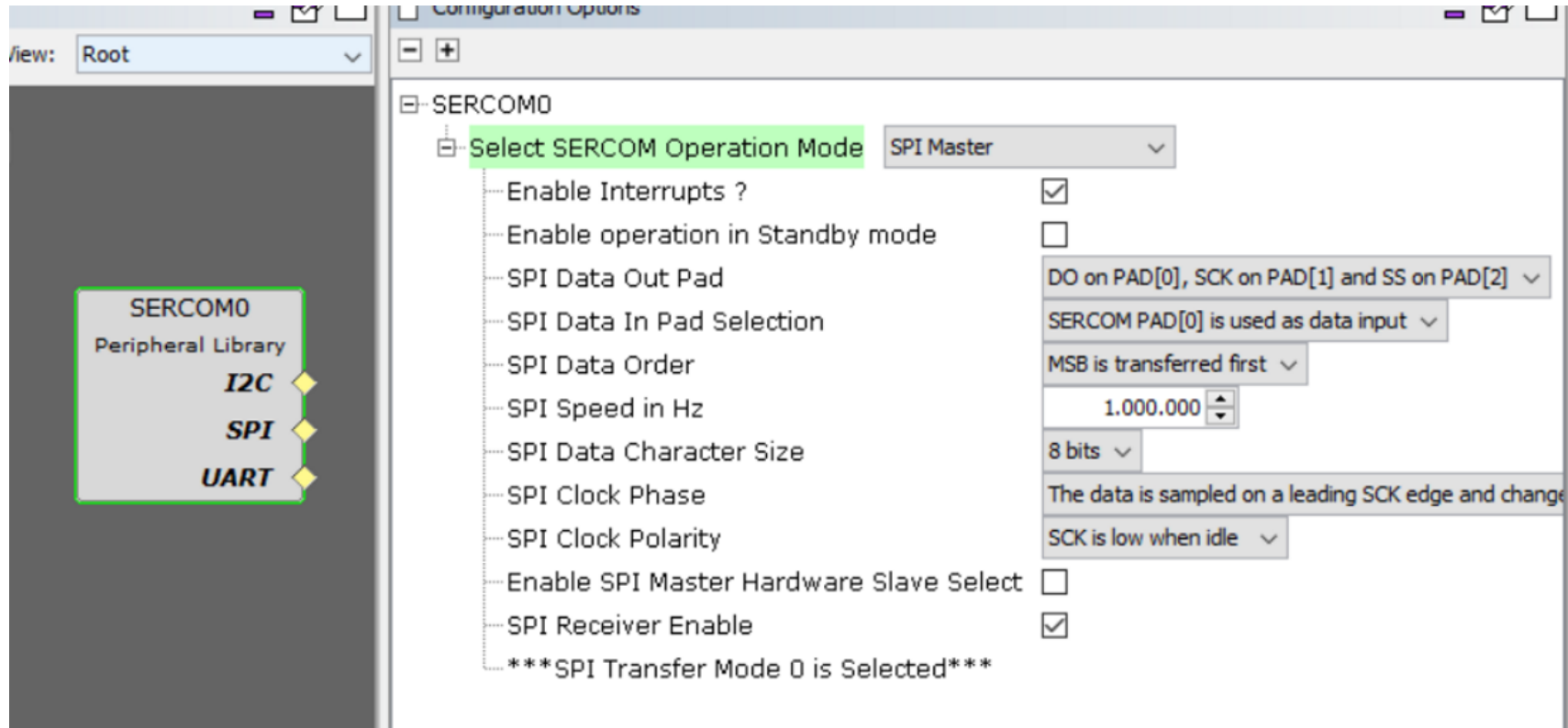
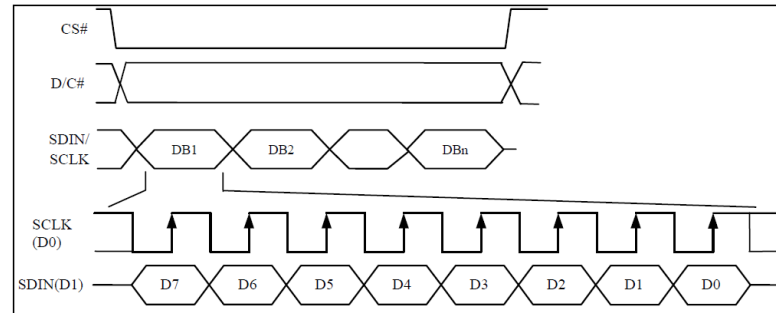
BUTTON2	3	PA08	
BUTTON3	4	PA09	
DATA_CMD_SEL	5	PD10	
LED3	6	PD12	
LED1	7	PB14	
LED2	8	PB15	
BUTTON1	9	PD11	
DISPLAY_RESET	10	PB28	
DISPLAY_SS_N	15	PC24	SPI0_SS_A
SPI_MOSI	16	PB24	SPI0_MOSI
SPI_SCK	18	PB25	SPI0_SCK





Configure the SERCOM0 with MCC

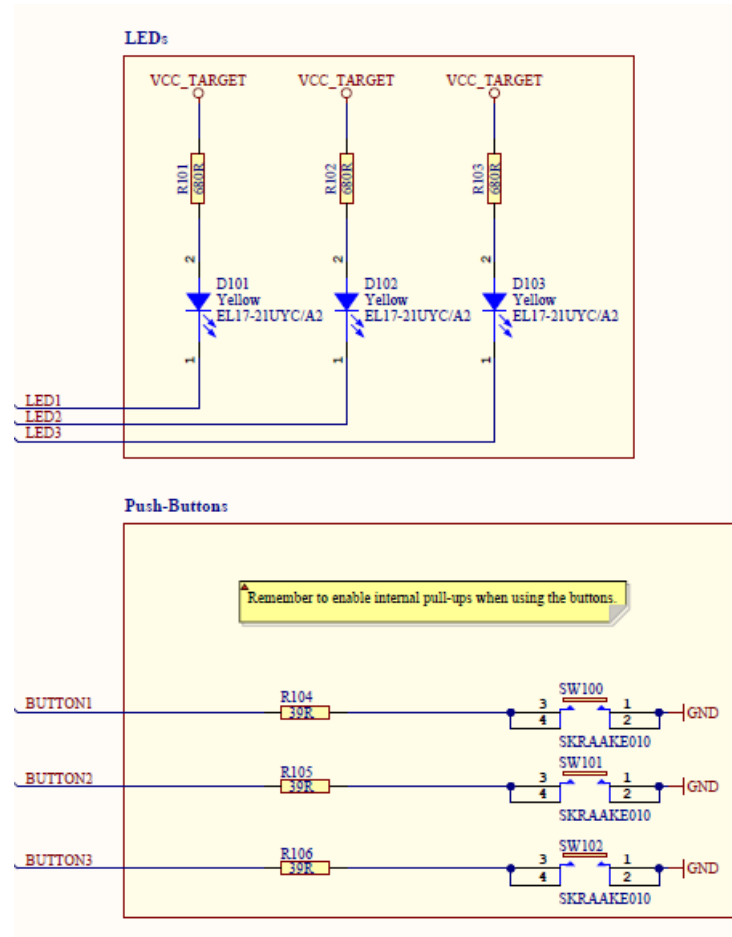
Figure 8-5 : Write procedure in 4-wire Serial interface mode



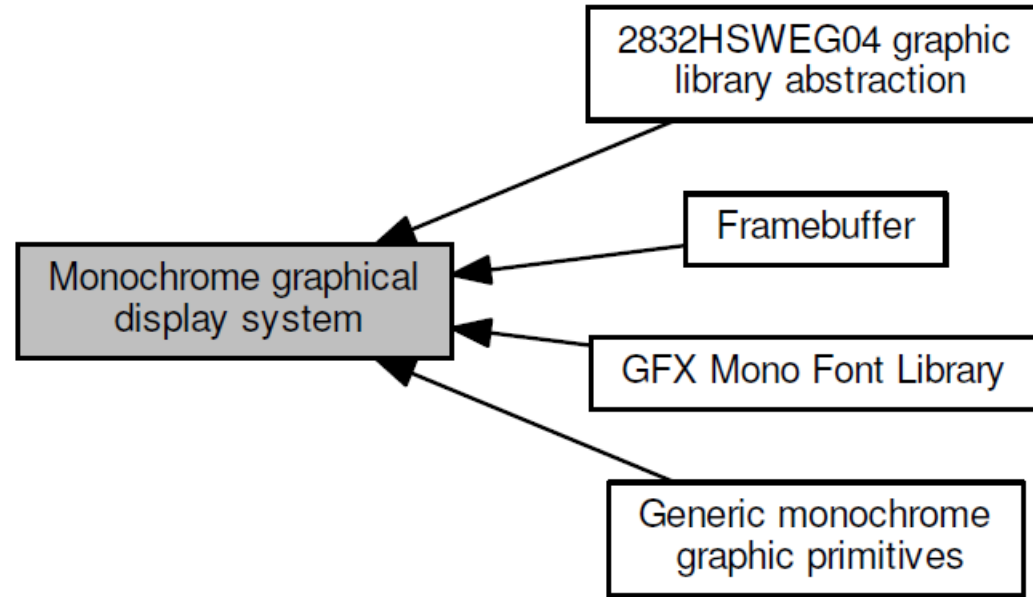
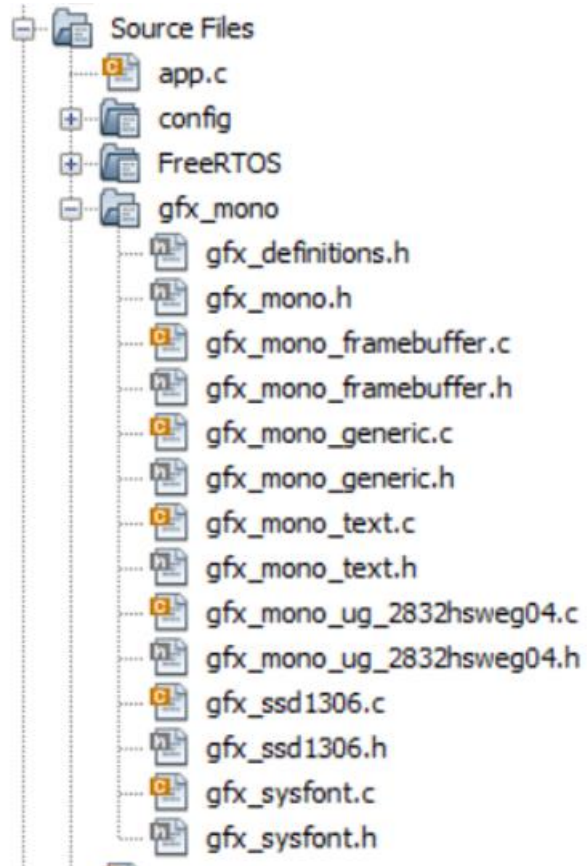
Configure Pins

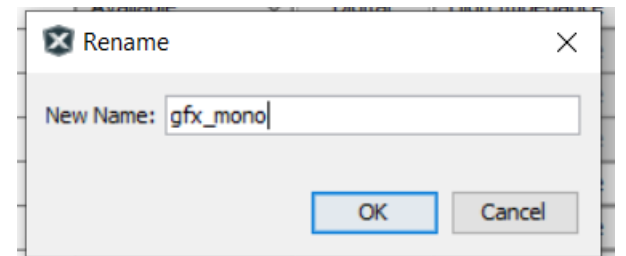
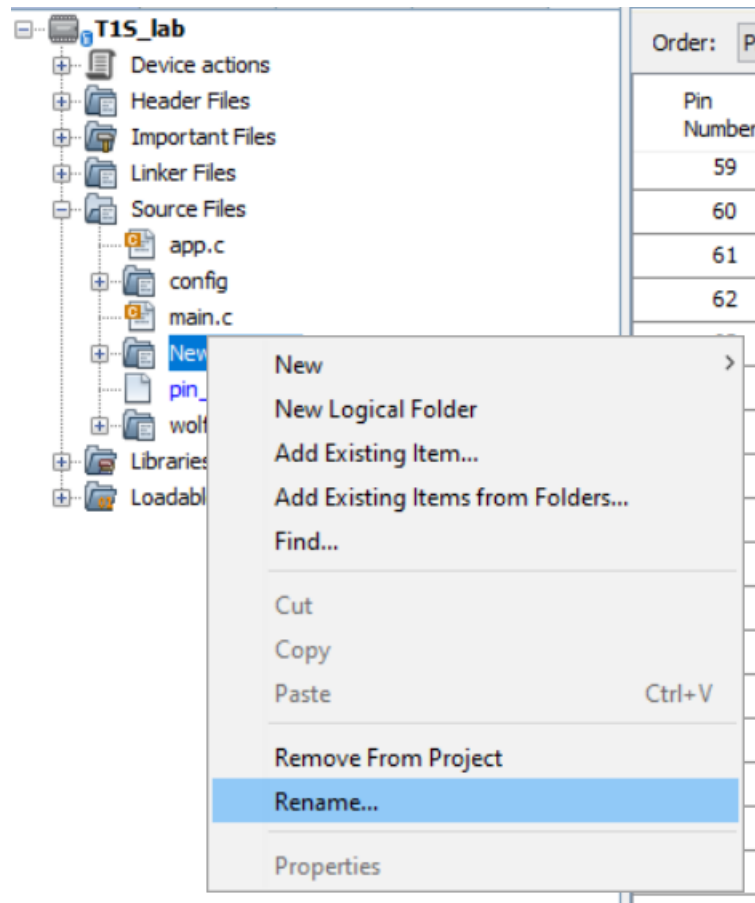
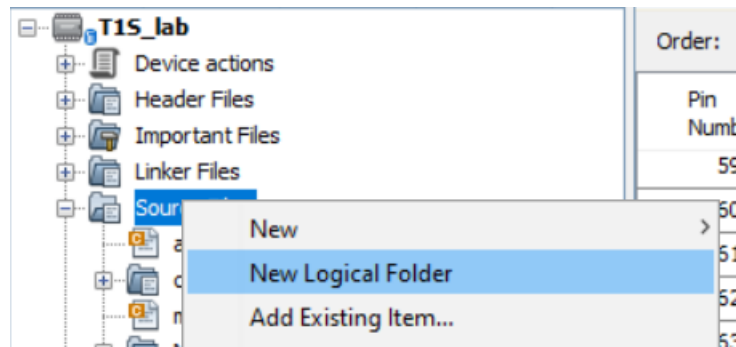
32	VDDIO		Available	Digital	High Impedance	Low	<input type="checkbox"/>	<input type="checkbox"/>	NORMAL
33	PA08	BUTTON2	GPIO	Digital	In	High	<input checked="" type="checkbox"/>	<input type="checkbox"/>	NORMAL
34	PA09	BUTTON3	GPIO	Digital	In	High	<input checked="" type="checkbox"/>	<input type="checkbox"/>	NORMAL
35	PA10		Available	Digital	High Impedance	Low	<input type="checkbox"/>	<input type="checkbox"/>	NORMAL
36	PA11		Available	Digital	High Impedance	Low	<input type="checkbox"/>	<input type="checkbox"/>	NORMAL
37	PA12		Available	Digital	High Impedance	Low	<input type="checkbox"/>	<input type="checkbox"/>	NORMAL
38	PA13		Available	Digital	High Impedance	Low	<input type="checkbox"/>	<input type="checkbox"/>	NORMAL
39	PA14		Available	Digital	High Impedance	Low	<input type="checkbox"/>	<input type="checkbox"/>	NORMAL
40	PA15		Available	Digital	High Impedance	Low	<input type="checkbox"/>	<input type="checkbox"/>	NORMAL
41	PA16		Available	Digital	High Impedance	Low	<input type="checkbox"/>	<input type="checkbox"/>	NORMAL
42	PA17		Available	Digital	High Impedance	Low	<input type="checkbox"/>	<input type="checkbox"/>	NORMAL
43	PB14	LED1	GPIO	Digital	Out	Low	<input type="checkbox"/>	<input type="checkbox"/>	NORMAL
44	PB15	LED2	GPIO	Digital	Out	Low	<input type="checkbox"/>	<input type="checkbox"/>	NORMAL
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46	PB17		Available	Digital	High Impedance	Low	<input type="checkbox"/>	<input type="checkbox"/>	NORMAL
47	PB18		Available	Digital	High Impedance	Low	<input type="checkbox"/>	<input type="checkbox"/>	NORMAL
48	PB19		Available	Digital	High Impedance	Low	<input type="checkbox"/>	<input type="checkbox"/>	NORMAL
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92	PD53		Available	Digital	High Impedance	Low	<input type="checkbox"/>	<input type="checkbox"/>	NORMAL
93	PD54		Available	Digital	High Impedance	Low	<input type="checkbox"/>	<input type="checkbox"/>	NORMAL
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98	PD59		Available	Digital	High Impedance	Low	<input type="checkbox"/>	<input type="checkbox"/>	NORMAL
99	PD60		Available	Digital	High Impedance	Low	<input type="checkbox"/>	<input type="checkbox"/>	NORMAL
100	PB24		SERCOM0_PAD0	Digital	High Impedance	n/a	<input type="checkbox"/>	<input type="checkbox"/>	NORMAL
101	PB25		SERCOM0_PAD1	Digital	High Impedance	n/a	<input type="checkbox"/>	<input type="checkbox"/>	NORMAL
102	PB26		Available	Digital	High Impedance	Low	<input type="checkbox"/>	<input type="checkbox"/>	NORMAL
103	PB27		Available	Digital	High Impedance	Low	<input type="checkbox"/>	<input type="checkbox"/>	NORMAL
104	PB28	DISPLAY_RESET	GPIO	Digital	Out	Low	<input type="checkbox"/>	<input type="checkbox"/>	NORMAL
105	PB29		Available	Digital	High Impedance	Low	<input type="checkbox"/>	<input type="checkbox"/>	NORMAL
106	GND		Available	Digital	High Impedance	Low	<input type="checkbox"/>	<input type="checkbox"/>	NORMAL
107	VDDIO		Available	Digital	High Impedance	Low	<input type="checkbox"/>	<input type="checkbox"/>	NORMAL
108	PC24	DISPLAY_SS_N	GPIO	Digital	Out	High	<input type="checkbox"/>	<input type="checkbox"/>	NORMAL
109	PC25		Available	Digital	High Impedance	Low	<input type="checkbox"/>	<input type="checkbox"/>	NORMAL

LED's and Buttons



GFX Mono Library





T1S_Lab > work > firmware > src >

^

Name

config

gfx_mono

packs

third_party

app

app

main

T1S_Lab > work > firmware > src > gfx_mono

^

gfxMonoDoc

Adobe Acrobat Document

gfx_mono_framebuffer

C File

gfx_mono_generic

C File

gfx_mono_text

C File

gfx_mono_ug_2832hsweg04

C File

gfx_ssd1306

C File

gfx_sysfont

C File

gfx_definitions

C Header Source File

gfx_mono

C Header Source File

gfx_mono_framebuffer

C Header Source File

gfx_mono_generic

C Header Source File

gfx_mono_text

C Header Source File

gfx_mono_ug_2832hsweg04

C Header Source File

gfx_ssd1306

C Header Source File


gfx_sysfont

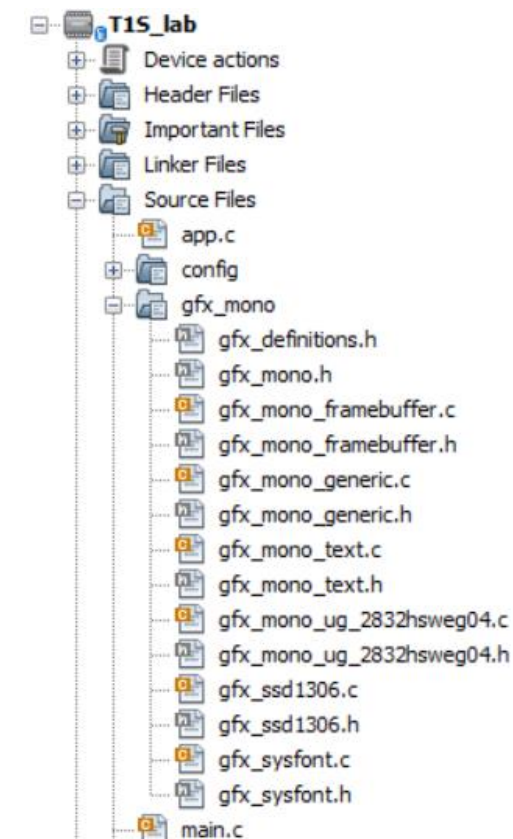
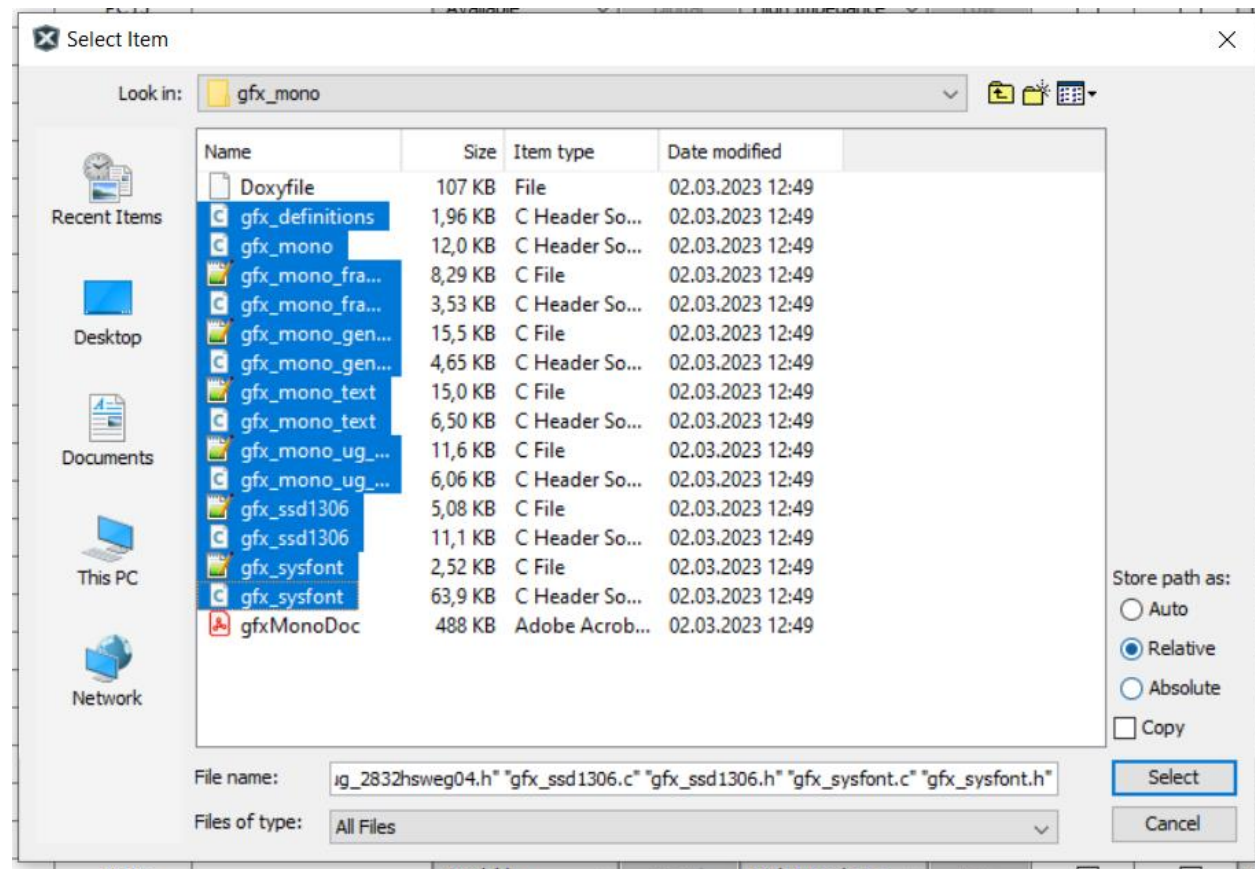
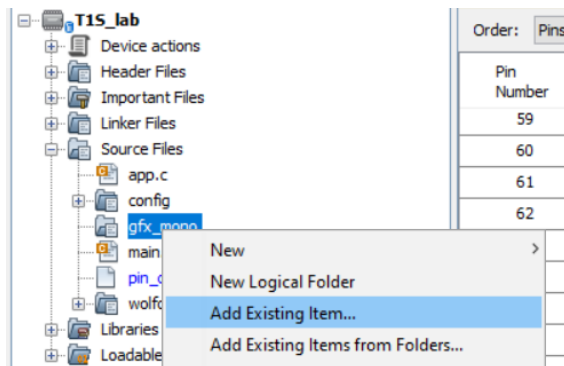
C Header Source File

Doxyfile

File

9


MICROCHIP



Add gxf_mono Glue

`\src\gxf_mono\gxf_definitions.h`

```
#include "../peripheral/port/plib_port.h"
#include "../peripheral/sercom/spi_master/plib_sercom0_spi_master.h"
#include "../system/time/sys_time.h"
```

```
#define GFX_DELAY_FUNCTION(x) \
{ \
    SYS_TIME_HANDLE tm_hdl; \
    SYS_TIME_DelayMS ( x, &tm_hdl ); \
    while(SYS_TIME_DelayIsComplete(tm_hdl) == false); \
}
```

```
#define GFX_SPI_WRITE_FUNCTION(x,y)    SERCOM0_SPI_Write(x,y)
#define GFX_SPI_IS_BUSY()              SERCOM0_SPI_IsBusy()
#define GFX_DISPLAY_RESET_CLEAR()      DISPLAY_RESET_Clear()
#define GFX_DISPLAY_RESET_SET()        DISPLAY_RESET_Set()
#define GFX_DISPLAY_SS_N_CLEAR()       DISPLAY_SS_N_Clear()
#define GFX_DISPLAY_SS_N_SET()         DISPLAY_SS_N_Set()
#define GFX_DATA_CMD_SEL_CLEAR()       DATA_CMD_SEL_Clear()
#define GFX_DATA_CMD_SEL_SET()         DATA_CMD_SEL_Set()
```

gfx_mono Initialization

Add GFX Init at the end of SYS_Initialize

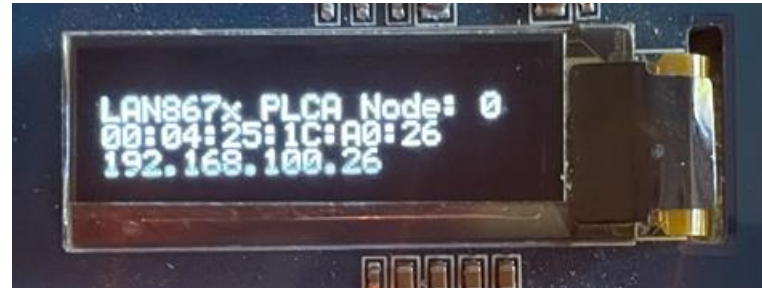
```
#include "peripheral/port/plib_port.h"  
#include "../gfx_mono/gfx_definitions.h"
```

```
void SYS_Initialize ( void* data )  
{  
    ...  
    init system function  
    ...
```

```
    APP_Initialize();  
    NVIC_Initialize();
```

```
    gfx_mono_ssd1306_init();  
    gfx_mono_print_scroll("LAN867x PLCA Node: %d",DRV_ETHPHY_PLCA_LOCAL_NODE_ID);  
    gfx_mono_print_scroll("%s",TCPIP_NETWORK_DEFAULT_MAC_ADDR_IDX0);  
    gfx_mono_print_scroll("%s",TCPIP_NETWORK_DEFAULT_IP_ADDRESS_IDX0);
```

```
}
```



Wait 1000 milli seconds

```
SYS_TIME_HANDLE tm_hdl;  
  
while(1){  
    SYS_TIME_DelayMS ( 1000, &tm_hdl );  
    while(SYS_TIME_DelayIsComplete(tm_hdl)==false);  
    LED3_Toggle();  
}
```

```
SYS_TIME_DelayMS ( 1000, &tm_hdl );  
while(1){  
    if(SYS_TIME_DelayIsComplete(tm_hdl)==true){  
        LED3_Toggle();  
        SYS_TIME_DelayMS ( 1000, &tm_hdl );  
    }  
}
```

Add Virtual UART Receive Function

„send to terminal commands from firmware“

```
\peripheral\sercom\usart\plib_sercom1_usart.c
```

```
void SERCOM1_USART_Virtual_Receive(char *str) {  
    while (*str!=0) {  
        if (SERCOM1_USART_RxPushByte(*str) == true) {  
            SERCOM1_USART_ReadNotificationSend();  
        }  
        str++;  
    }  
}
```

```
\peripheral\sercom\usart\plib_sercom1_usart.h
```

```
void SERCOM1_USART_Virtual_Receive(char *str);
```

Add Button Poll and Action

```
#include "config/default/peripheral/port/plib_port.h"
#include "config/default/peripheral/sercom/usart/plib_sercom1_usart.h"
#include "gfx_mono/gfx_definitions.h"

{
    static int old_but1 = 0;
    int temp_but1 = BUTTON1_Get();
    if (temp_but1 && !old_but1) {
        LED1_Set();
    }
    if (!temp_but1 && old_but1) {
        LED1_Clear();
        SERCOM1_USART_Virtual_Receive("iperf -s\n");
        gfx_mono_print_scroll("iperf TCP server");
    }
    old_but1 = temp_but1;
}
```

```
static int old_but2 = 0;
int temp_but2 = BUTTON2_Get();
if (temp_but2 && !old_but2) {
    LED2_Set();
}
if (!temp_but2 && old_but2) {
    LED2_Clear();
    SERCOM1_USART_Virtual_Receive("iperf -s -u\n");
    gfx_mono_print_scroll("iperf UDP server");
}
old_but2 = temp_but2;

static int old_but3 = 0;
int temp_but3 = BUTTON3_Get();
if (temp_but3 && !old_but3) {
    LED3_Set();
}
if (!temp_but3 && old_but3) {
    LED3_Clear();
    SERCOM1_USART_Virtual_Receive("iperfk\n");
    gfx_mono_print_scroll("iperf kill server");
}
old_but3 = temp_but3;
}
```

set programming speed up

