

2010, PAPER 3, QUESTION 6 I

COLLISIONLESS BOLTZMANN EQUATION:

$$\frac{\partial f}{\partial t} + \underline{v} \cdot \nabla f - \nabla \Phi \frac{\partial f}{\partial v} = 0$$

FIRST MOMENT OF BE:

$$\int_{\text{VELOCITY SPACE}} \left(\frac{\partial f}{\partial t} + v_i \frac{\partial f}{\partial x_i} - \frac{\partial \Phi}{\partial x_i} \frac{\partial f}{\partial v_i} \right) \cdot v_j d^3 \underline{v} = 0$$

CONSIDER:

$$I) \frac{\partial}{\partial t} (f v_j) = v_j \frac{\partial f}{\partial t} + f \underbrace{\frac{\partial v_j}{\partial t}}_{=0} = v_j \frac{\partial f}{\partial t}$$

$$\Rightarrow \int \frac{\partial f}{\partial t} v_j d^3 \underline{v} = \int \frac{\partial}{\partial t} (f v_j) d^3 \underline{v} = \frac{\partial}{\partial t} \int f v_j d^3 \underline{v}$$

$$II) \frac{\partial \Phi}{\partial x_i} \text{ DOES NOT HAVE } \underline{v} \text{ DEPENDENCE}$$

$$I \& II \Rightarrow \frac{\partial}{\partial t} \int f v_j d^3 \underline{v} + \int v_i v_j \frac{\partial f}{\partial x_i} d^3 \underline{v} - \frac{\partial \Phi}{\partial x_i} \int v_j \frac{\partial f}{\partial v_i} d^3 \underline{v} = 0$$

PROCEEDING TERM BY TERM:

$$\frac{\partial}{\partial t} \int f v_j d^3 \underline{v} = \frac{\partial}{\partial t} \left(S \langle v_j \rangle \right) = S \frac{\partial \langle v_j \rangle}{\partial t}$$

$$\int v_i v_j \frac{\partial f}{\partial x_i} d^3 \underline{v} = \frac{\partial}{\partial x_i} \int v_i v_j f d^3 \underline{v} = \frac{\partial}{\partial x_i} \left(S \langle \underline{v}_i \underline{v}_j \rangle \right)$$

$v_i v_j$ DOES
NOT HAVE
 x_i DEP.

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$$\int v_j \frac{\partial f}{\partial x_i} d^3v = [\cancel{f v_j}]_{-\infty}^{\infty} - \int \frac{\partial v_j}{\partial x_i} f d^3v = -\delta_{ij} \int f d^3v$$

$\Rightarrow 0$
AS WE WANT
PHYSICAL BCS
TO PREVAIL

COLLECT TERMS:

$$S \frac{\partial \langle v_j \rangle}{\partial t} + \frac{\partial}{\partial x_i} \left(S \langle v_i v_j \rangle \right) + \underbrace{\frac{\partial \Phi}{\partial x_j}}_S \int f d^3v = 0 \quad (A)$$

RECALL (OR LOOK UP IN FORMULAE BOOKLET):

$$\cancel{\frac{\partial S}{\partial t}} + \frac{\partial (S \langle v_i \rangle)}{\partial x_i} = 0 \quad (B)$$

$$\cancel{\frac{\partial S}{\partial t}} + \cancel{\frac{\partial S \langle v_i \rangle}{\partial x_i}} + \frac{\partial \langle v_i \rangle}{\partial x_i} S = 0 \quad (\text{crossed out})$$

(A) - (B):

$$S \frac{\partial \langle v_j \rangle}{\partial t} - \cancel{\frac{\partial S \langle v_j \rangle}{\partial t}} - \langle v_j \rangle \frac{\partial}{\partial x_i} (S \langle v_i \rangle) + \\ + \frac{\partial}{\partial x_i} (S \langle v_i v_j \rangle) + S \frac{\partial \Phi}{\partial x_j} = 0$$

$$S \frac{\partial \langle v_j \rangle}{\partial t} - \langle v_j \rangle \frac{\partial}{\partial x_i} (S \langle v_i \rangle) + \frac{\partial}{\partial x_i} (S \langle v_i v_j \rangle) = -S \frac{\partial \Phi}{\partial x_j}$$

CONSIDER:

$$\sigma_{ij}^2 = \langle (v_i - \langle v_i \rangle)(v_j - \langle v_j \rangle) \rangle =$$

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$$\begin{aligned}
 &= \langle v_i, v_j \rangle - v_i \langle v_j \rangle \cancel{\#} \langle v_i \rangle v_j + \langle v_i \rangle \langle v_j \rangle \\
 &= \langle v_i, v_j \rangle - \cancel{\langle v_i \rangle \langle v_j \rangle} \cancel{\#} \langle v_i \rangle \langle v_j \rangle + \cancel{\langle v_i \rangle \langle v_j \rangle} \\
 &= \langle v_i, v_j \rangle \cancel{\#} \langle v_i \rangle \langle v_j \rangle = \sigma_{ij}^2 \\
 \Rightarrow \langle v_i, v_j \rangle &= \sigma_{ij}^2 + \langle v_i \rangle \langle v_j \rangle
 \end{aligned}$$

REWRITE EQUATION:

$$\begin{aligned}
 S \frac{\partial \langle v_i \rangle}{\partial t} - \langle v_j \rangle \cancel{\frac{\partial}{\partial x_i}} \cancel{\left(S \langle v_i \rangle \right)} + \cancel{\frac{\partial}{\partial x_i}} \left(S \sigma_{ij}^2 \right) + \cancel{\frac{\partial}{\partial x_i}} \left(S \langle v_i \rangle \langle v_j \rangle \right) = \\
 = -S \frac{\partial \Phi}{\partial x_j}
 \end{aligned}$$

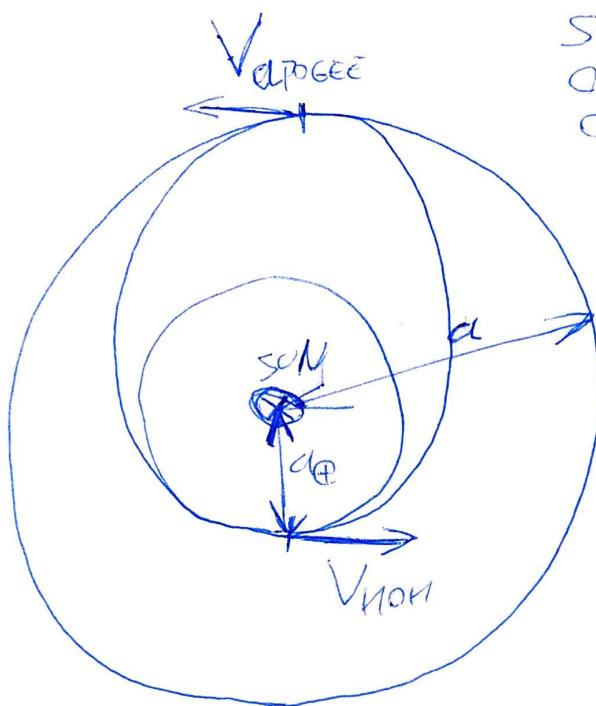
$$\begin{aligned}
 \Rightarrow S \frac{\partial \langle v_i \rangle}{\partial t} - \cancel{\langle v_j \rangle \frac{\partial}{\partial x_i} \left(S \langle v_i \rangle \right)} + \cancel{\frac{\partial}{\partial x_i} \left(S \langle v_i \rangle \langle v_j \rangle \right)} \\
 = -S \frac{\partial \Phi}{\partial x_j} - \cancel{\frac{\partial}{\partial x_i} \left(S \sigma_{ij}^2 \right)} \\
 \cancel{- \langle v_j \rangle \frac{\partial}{\partial x_i} \left(S \langle v_i \rangle \right) + \cancel{\frac{\partial}{\partial x_i} \left(S \langle v_i \rangle \langle v_j \rangle \right)} + \cancel{\frac{\partial}{\partial x_i} \left(S \langle v_j \rangle \langle v_i \rangle \right)}}
 \end{aligned}$$

$$\begin{aligned}
 \Rightarrow S \frac{\partial \langle v_i \rangle}{\partial t} + \cancel{S \langle v_i \rangle \frac{\partial}{\partial x_i} \langle v_i \rangle} = \\
 = -S \frac{\partial \Phi}{\partial x_j} - \cancel{\frac{\partial}{\partial x_i} \left(S \sigma_{ij}^2 \right)}
 \end{aligned}$$

N/A REQUIRED.

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KEPLER III: $T^2 \propto a^3$



SEMI MAJOR AXIS
OF TRANSFER
ORBIT: $\frac{a_{\oplus} + a}{2}$

$$\frac{T_{\text{FULL TRANSFER}}^2}{T_{\text{EARTH}}^2} = \frac{\left(\frac{a_{\oplus} + a}{2}\right)^3}{a_{\oplus}^3}$$

$$T_{\text{FTO}} = \left[\frac{1}{2} \left(1 + \frac{a}{a_{\oplus}} \right) \right]^{\frac{3}{2}} \text{ yr}$$

$$T = \frac{T_{\oplus \text{TO}}}{2} = \frac{1}{2} \left(\frac{1}{2} \right)^{\frac{3}{2}} \left(1 + \frac{a}{a_{\oplus}} \right)^{\frac{3}{2}} = \frac{1}{2\sqrt{2}} \left(1 + \frac{a}{a_{\oplus}} \right)^{\frac{3}{2}} \text{ yr}$$

\hookrightarrow (WE'RE ONLY
GOING UP,
NOT UP & DOWN)

$$= \frac{1}{4\sqrt{2}} \left(1 + \frac{a}{a_{\oplus}} \right)^{\frac{3}{2}} \text{ yr}$$

AS REQUIRED.

ENERGY CONSERVATION:

$$\frac{1}{2} V_{\text{PERIGEE}}^2 - \frac{GM}{a_{\oplus}} = \frac{1}{2} V_{\text{APOGEE}}^2 - \frac{GM}{a}$$

ANGULAR MOM CONSERVATION:

$$V_{\text{PERIGEE}} a_{\oplus} = V_{\text{APOGEE}} a$$

$$\Rightarrow \frac{1}{2} V_{\text{PERIGEE}}^2 - \frac{GM}{a_{\oplus}} = \frac{1}{2} V_{\text{PERIGEE}}^2 \left(\frac{a_{\oplus}}{a} \right)^2 - \frac{GM}{a}$$

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$$\frac{1}{2} V_{\text{non}}^2 \left(1 - \left(\frac{a_{\oplus}}{a} \right)^2 \right) = GM \left(\frac{1}{a_{\oplus}} - \frac{1}{a} \right)$$

$$V_{\text{non}}^2 = GM \cdot Z \cdot \frac{\frac{a - a_{\oplus}}{aa_{\oplus}}}{1 - \left(\frac{a_{\oplus}}{a} \right)^2}$$

$$= GM \cdot Z \cdot \frac{\frac{(a - a_{\oplus}) \left(\frac{a}{a_{\oplus}} \right)}{a^2 - a_{\oplus}^2}}{\frac{a}{a_{\oplus}}} = \frac{\frac{a}{a_{\oplus}}}{a + a_{\oplus}} \cdot 2GM$$

EARTH CASE:

$$\frac{GM}{a_{\oplus}^2} = \frac{V_{\oplus}^2}{a_{\oplus}} \Rightarrow V_{\oplus}^2 = \frac{GM}{a_{\oplus}}$$

$$V_{\text{non}}^2 = \frac{a}{a + a_{\oplus}} \cdot Z \cdot \frac{GM}{a_{\oplus}}$$

$$= \frac{a}{a + a_{\oplus}} \cdot Z \cdot V_{\oplus}^2$$

$$\Rightarrow V_{\text{non}} = \sqrt{Z} \left(\frac{a}{a + a_{\oplus}} \right)^{\frac{1}{2}} V_{\oplus}$$

(E)

$$V_{\text{ADD}} = V_{\text{non}} - V_{\oplus} = V_{\oplus} \left[\sqrt{Z} \left(\frac{a}{a + a_{\oplus}} \right)^{\frac{1}{2}} - 1 \right]$$

AS REQUIRED.

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~~APHELION DIST = $a(1+\epsilon)$~~

APHELION DIST = SEMI-MAJOR AXIS - ($1-\epsilon$)

$$a = \frac{a + a_{\oplus}}{2} (1 - \epsilon)$$

$$\frac{2a}{a + a_{\oplus}} - 1 = \epsilon$$

$$\epsilon = \frac{2 \cdot 1.524}{1.524 + 1} - 1 \approx \underline{\underline{0.21}}$$

$$T = \frac{1}{\sqrt[3]{2}} \left(1 + \frac{1.524}{T} \right)^{\frac{3}{2}} \approx \underline{\underline{0.71 \text{ yr}}}$$

$$V_{ADD} = V_{\oplus} \left(\sqrt{2} \left(\frac{a(1.524)}{a(1+1.524)} \right)^{\frac{1}{2}} - 1 \right) \approx 0.10 V_{\oplus}$$

~~V_{\oplus}~~
$$V_{\oplus} = \frac{150 \cdot 10^6 \cdot 10^3 \cdot 2\pi}{365 \cdot 24 \cdot 60 \cdot 60} = 4.8 \cdot 10^3 \frac{\text{m}}{\text{s}}$$

$$\Rightarrow V_{ADD} \approx 4.8 \cdot 10^2 \cdot 2\pi \approx \underline{\underline{3 \frac{\text{km}}{\text{s}}}}$$