

# 2010, PAPER 3, QUESTION 6 I

i.  
COLLISIONLESS BOLTZMANN EQUATION:

$$\frac{\partial f}{\partial t} + \underline{v} \cdot \nabla f - \nabla \Phi \frac{\partial f}{\partial v} = 0$$

FIRST MOMENT OF CBE:

$$\int_{\text{VELOCITY SPACE}} \left( \frac{\partial f}{\partial t} + v_i \frac{\partial f}{\partial x_i} - \frac{\partial \Phi}{\partial x_i} \frac{\partial f}{\partial v_i} \right) \cdot v_j d^3 \underline{v} = 0$$

CONSIDER:

$$\text{I) } \frac{\partial}{\partial t} (f v_j) = v_j \frac{\partial f}{\partial t} + f \frac{\partial v_j}{\partial t} = v_j \frac{\partial f}{\partial t} \quad \rightarrow = 0$$

$$\Rightarrow \int \frac{\partial f}{\partial t} v_j d^3 \underline{v} = \int \frac{\partial}{\partial t} (f v_j) d^3 \underline{v} = \frac{\partial}{\partial t} \int f v_j d^3 \underline{v}$$

II)  $\frac{\partial \Phi}{\partial x_i}$  DOES NOT HAVE  $\underline{v}$  DEPENDENCE

$$\text{I \& II} \Rightarrow \frac{\partial}{\partial t} \int f v_j d^3 \underline{v} + \int v_i v_j \frac{\partial f}{\partial x_i} d^3 \underline{v} - \frac{\partial \Phi}{\partial x_i} \int v_j \frac{\partial f}{\partial v_i} d^3 \underline{v} = 0$$

PROCEEDING TERM BY TERM:

$$\frac{\partial}{\partial t} \int f v_j d^3 \underline{v} = \frac{\partial}{\partial t} (S \langle v_j \rangle) = S \frac{\partial \langle v_j \rangle}{\partial t}$$

$$\int v_i v_j \frac{\partial f}{\partial x_i} d^3 \underline{v} = \frac{\partial}{\partial x_i} \int v_i v_j f d^3 \underline{v} = \frac{\partial}{\partial x_i} (S \langle v_i v_j \rangle)$$

$v_i v_j$  DOES  
NOT HAVE  
 $x_i$  DEP.

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$$\int v_j \frac{\partial \psi}{\partial x_i} d^3v = \left[ \psi v_j \right]_{-\infty}^{\infty} - \int \frac{\partial \psi}{\partial x_i} v_j d^3v = -\delta_{ij} \int \psi d^3v$$

→ 0  
AS WE WANT  
PHYSICAL BCs  
TO PREVAIL

COLLECT TERMS:

$$\int \frac{\partial \langle v_j \rangle}{\partial t} + \frac{\partial}{\partial x_i} \left( \int \langle v_i v_j \rangle \right) + \frac{\partial \Phi}{\partial x_j} \int \psi d^3v = 0 \quad (A)$$

RECALL (OR LOOK UP IN FORMULAE BOOKLET):

$$\frac{\partial S}{\partial t} + \frac{\partial (S \langle v_i \rangle)}{\partial x_i} = 0 \quad (B)$$

~~$$\frac{\partial S}{\partial t} + \frac{\partial (S \langle v_i \rangle)}{\partial x_i} + \frac{\partial \langle v_i \rangle}{\partial x_i} S = 0 \quad (B)$$~~

(A) - (B):

$$\int \frac{\partial \langle v_j \rangle}{\partial t} - \frac{\partial S}{\partial t} \langle v_j \rangle - \langle v_j \rangle \frac{\partial (S \langle v_i \rangle)}{\partial x_i} + \frac{\partial}{\partial x_i} (S \langle v_i v_j \rangle) + \int \frac{\partial \Phi}{\partial x_j} = 0$$

$$\int \frac{\partial \langle v_j \rangle}{\partial t} - \langle v_j \rangle \frac{\partial}{\partial x_i} (S \langle v_i \rangle) + \frac{\partial}{\partial x_i} (S \langle v_i v_j \rangle) = - \int \frac{\partial \Phi}{\partial x_j}$$

CONSIDER:

$$\sigma_{ij}^2 = \langle (v_i - \langle v_i \rangle)(v_j - \langle v_j \rangle) \rangle =$$

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$$= \langle v_i v_j - v_i \langle v_j \rangle - \langle v_i \rangle v_j + \langle v_i \rangle \langle v_j \rangle \rangle$$

$$= \langle v_i v_j \rangle - \langle v_i \rangle \langle v_j \rangle - \langle v_i \rangle \langle v_j \rangle + \langle v_i \rangle \langle v_j \rangle$$

$$= \langle v_i v_j \rangle - \langle v_i \rangle \langle v_j \rangle = \sigma_{ij}^2$$

$$\Rightarrow \langle v_i v_j \rangle = \sigma_{ij}^2 + \langle v_i \rangle \langle v_j \rangle$$

REWRITE EQUATION:

$$\int \frac{\partial \langle v_j \rangle}{\partial t} - \langle v_j \rangle \frac{\partial}{\partial x_i} \left( \int \langle v_i \rangle \right) + \frac{\partial}{\partial x_i} \left( \int \sigma_{ij}^2 \right) + \frac{\partial}{\partial x_i} \left( \int \langle v_i \rangle \langle v_j \rangle \right) = - \int \frac{\partial \Phi}{\partial x_j}$$

$$\Rightarrow \int \frac{\partial \langle v_j \rangle}{\partial t} - \langle v_j \rangle \frac{\partial}{\partial x_i} \left( \int \langle v_i \rangle \right) + \frac{\partial}{\partial x_i} \left( \int \langle v_i \rangle \langle v_j \rangle \right) = - \int \frac{\partial \Phi}{\partial x_j} - \frac{\partial}{\partial x_i} \left( \int \sigma_{ij}^2 \right)$$

$$- \langle v_j \rangle \frac{\partial}{\partial x_i} \left( \int \langle v_i \rangle \right) + \frac{\partial}{\partial x_i} \left( \int \langle v_i \rangle \langle v_j \rangle \right) + \frac{\partial}{\partial x_i} \left( \int \langle v_j \rangle \langle v_i \rangle \right)$$

$$\Rightarrow \int \frac{\partial \langle v_j \rangle}{\partial t} + \boxed{\int \langle v_i \rangle \frac{\partial \langle v_i \rangle}{\partial x_i}} = - \int \frac{\partial \Phi}{\partial x_j} - \frac{\partial}{\partial x_i} \left( \int \sigma_{ij}^2 \right)$$

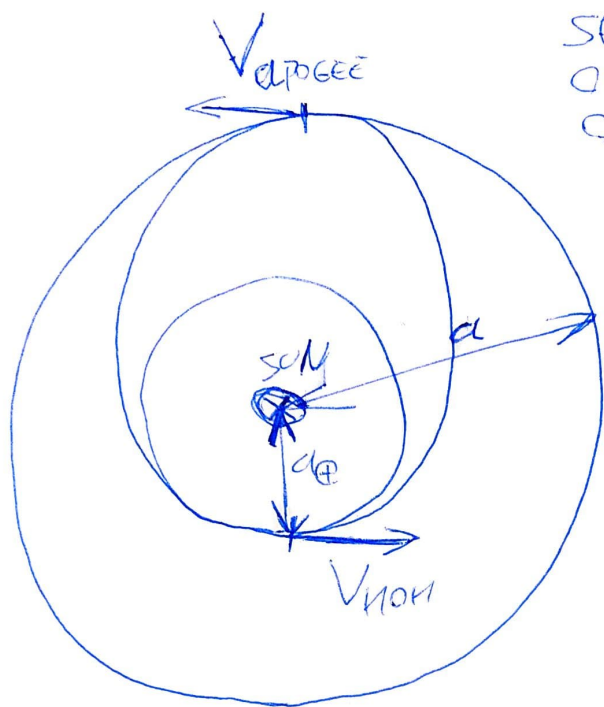
AS REQUIRED.



2010  
P3Q6 IV

KEPLER III:  $T^2 \propto a^3$

SEMI MAJOR AXIS  
OF TRANSFER  
ORBIT:  $\frac{a_{\oplus} + a}{2}$



$$\frac{T_{\text{FULL TRANSFER ORBIT}}^2}{T_{\text{EARTH 1 YR}}^2} = \frac{\left(\frac{a_{\oplus} + a}{2}\right)^3}{a_{\oplus}^3}$$

$$T_{\text{FTO}} = \left[ \frac{1}{2} \left( 1 + \frac{a}{a_{\oplus}} \right) \right]^{\frac{3}{2}} \text{ YR}$$

$$T = \frac{T_{\oplus} + T_{\text{FTO}}}{2} = \frac{1}{2} \left( \frac{1}{2} \right)^{\frac{3}{2}} \left( 1 + \frac{a}{a_{\oplus}} \right)^{\frac{3}{2}} = \frac{1}{2\sqrt{2}} \left( 1 + \frac{a}{a_{\oplus}} \right)^{\frac{3}{2}} \text{ YR}$$

→ (WE'RE ONLY  
GOING UP,  
NOT UP & DOWN)

$$= \frac{1}{4\sqrt{2}} \left( 1 + \frac{a}{a_{\oplus}} \right)^{\frac{3}{2}} \text{ YR}$$

AS PERUI  
RED.

ENERGY CONSERVATION:

$$\frac{1}{2} V_{\text{HOH}}^2 - \frac{GM}{a_{\oplus}} = \frac{1}{2} V_{\text{APOGEE}}^2 - \frac{GM}{a}$$

ANGULAR MOM CONSERVATION:

$$V_{\text{HOH}} a_{\oplus} = V_{\text{APOGEE}} a$$

$$\rightarrow \frac{1}{2} V_{\text{HOH}}^2 - \frac{GM}{a_{\oplus}} = \frac{1}{2} V_{\text{HOH}}^2 \left( \frac{a_{\oplus}}{a} \right)^2 - \frac{GM}{a}$$

2010  
P3Q6 V

$$\frac{1}{2} V_{\text{non}}^2 \left( 1 - \left( \frac{a_{\oplus}}{a} \right)^2 \right) = \cancel{GM} GM \left( \frac{1}{a_{\oplus}} - \frac{1}{a} \right)$$

$$V_{\text{non}}^2 = GM \cdot Z \cdot \frac{\frac{a - a_{\oplus}}{a a_{\oplus}}}{1 - \left( \frac{a_{\oplus}}{a} \right)^2}$$

$$= GM \cdot Z \cdot \frac{(a - a_{\oplus}) \left( \frac{a}{a_{\oplus}} \right)}{a^2 - a_{\oplus}^2} = \frac{\frac{a}{a_{\oplus}}}{a + a_{\oplus}} Z GM$$

EARTH CASE:

$$\frac{GM}{a_{\oplus}^2} = \frac{V_{\oplus}^2}{a_{\oplus}} \Rightarrow V_{\oplus}^2 = \frac{GM}{a_{\oplus}}$$

$$V_{\text{non}}^2 = \frac{a}{a + a_{\oplus}} Z \cdot \frac{GM}{a_{\oplus}}$$

$$= \frac{a}{a + a_{\oplus}} \cdot Z \cdot V_{\oplus}^2$$

$$\Rightarrow V_{\text{non}} = \sqrt{Z} \left( \frac{a}{a + a_{\oplus}} \right)^{\frac{1}{2}} V_{\oplus}$$

IE

$$V_{\text{ADD}} = V_{\text{non}} - V_{\oplus} = V_{\oplus} \left[ \sqrt{Z} \left( \frac{a}{a + a_{\oplus}} \right)^{\frac{1}{2}} - 1 \right]$$

~~AS REQUIRED~~  
AS REQUIRED.

~~APHELION DIST =  $a(1+e)$~~

APHELION DIST = SEMI-MAJOR AXIS  $\cdot (1+e)$

$$a = \frac{a + a_{\oplus}}{2} (1+e)$$

$$\frac{2a}{a + a_{\oplus}} - 1 = e$$

$$e = \frac{2 \cdot 1.525}{1.525 + 1} - 1 \approx \underline{\underline{0.21}}$$

$$T = \frac{1}{\sqrt{2}} \left( 1 + \frac{1.525}{1} \right)^{\frac{3}{2}} \approx \underline{\underline{0.71 \text{ YR}}}$$

$$V_{ADD} = V_{\oplus} \left( \sqrt{2} \left( \frac{a \cdot 1.525}{a + 1.525} \right)^{\frac{1}{2}} - 1 \right) \approx 0.10 V_{\oplus}$$



$$V_{\oplus} = \frac{150 \cdot 10^6 \cdot 10^3 \cdot 2\pi}{365 \cdot 24 \cdot 60 \cdot 60} = 4.8 \cdot 10^3 \frac{\text{m}}{\text{s}}$$

$$\Rightarrow V_{ADD} \approx 4.8 \cdot 10^2 \cdot 2\pi \approx \underline{\underline{3 \frac{\text{km}}{\text{s}}}}$$