

# MA 16200: Plane Analytic Geometry and Calculus II

## Lecture 2: Dot and Cross Products

# §13.3 The Dot Product

## Definition

### Definition 1 (Dot Product)

Let  $\vec{u} = \langle u_1, u_2, \dots, u_n \rangle$  and  $\vec{v} = \langle v_1, v_2, \dots, v_n \rangle$  be vectors. The **dot product** of  $\vec{u}$  and  $\vec{v}$  is:

$$\vec{u} \cdot \vec{v} \stackrel{\text{def}}{=} \sum_{i=1}^n u_i v_i = u_1 v_1 + u_2 v_2 + \dots + u_n v_n$$

In 2-Dimensions ( $n = 2$ ):

$$\vec{u} \cdot \vec{v} = \langle u_1, u_2 \rangle \cdot \langle v_1, v_2 \rangle = u_1 v_1 + u_2 v_2$$

In 3-Dimensions ( $n = 3$ ):

$$\vec{u} \cdot \vec{v} = \langle u_1, u_2, u_3 \rangle \cdot \langle v_1, v_2, v_3 \rangle = u_1 v_1 + u_2 v_2 + u_3 v_3$$

## Examples

### Problem 2

Compute the following:

- $\langle 1, 2 \rangle \cdot \langle 3, 4 \rangle$
- $\langle 8, 2 \rangle \cdot \langle 0, -2 \rangle$
- $\langle 4, -1, 1 \rangle \cdot \langle 1, 4, 0 \rangle$

Sol

①  $\langle 1, 2 \rangle \cdot \langle 3, 4 \rangle = 1(3) + 2(4) = 3 + 8 = \boxed{11}$

②  $\langle 8, 2 \rangle \cdot \langle 0, -2 \rangle = 8(0) + 2(-2) = \boxed{-4}$

③  $\langle 4, -1, 1 \rangle \cdot \langle 1, 4, 0 \rangle = 4(1) + (-1)(4) + 1(0)$   
 $= \boxed{0}$

# Extra Space

# Properties Of Dot Products

## Theorem 3

Let  $\vec{u}$ ,  $\vec{v}$ , and  $\vec{w}$  be vectors and  $c$  a scalar:

1  $\vec{0} \cdot \vec{u} = 0$

2  $\vec{u} \cdot \vec{u} = |\vec{u}|^2$

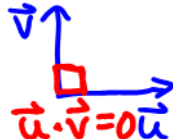
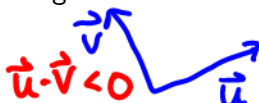
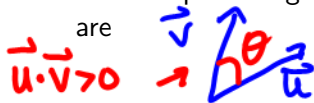
$$\sqrt{\langle x, y \rangle \cdot \langle x, y \rangle} = \sqrt{x^2 + y^2}$$

3  $\vec{u} \cdot \vec{v} = \vec{v} \cdot \vec{u}$  (Commutative Property)

4  $c(\vec{u} \cdot \vec{v}) = (c\vec{u}) \cdot \vec{v} = \vec{u} \cdot (c\vec{v})$  (Associative Property)

5  $\vec{u} \cdot (\vec{v} + \vec{w}) = \vec{u} \cdot \vec{v} + \vec{u} \cdot \vec{w}$  (Distributive Property)

The dot product gives a rough idea of how “aligned” two vectors are



... can we be more precise than this?

# Physics Definition of The Dot Product

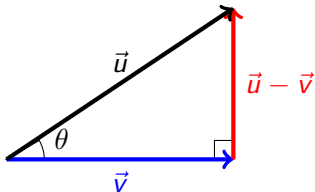
## Theorem 4

If  $\vec{u}$  and  $\vec{v}$  are **non-zero** vectors, then:

$$\vec{u} \cdot \vec{v} = |\vec{u}| |\vec{v}| \cos \theta$$

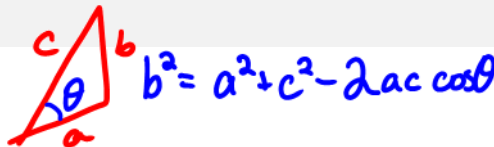
where  $\theta$  is the angle between  $\vec{u}$  and  $\vec{v}$

Why? By properties of the dot product:



$$\begin{aligned} |\vec{u} - \vec{v}|^2 &= (\vec{u} - \vec{v}) \cdot (\vec{u} - \vec{v}) \\ &= \vec{u} \cdot \vec{u} - \vec{u} \cdot \vec{v} - \vec{v} \cdot \vec{u} + \vec{v} \cdot \vec{v} \\ &= |\vec{u}|^2 - 2\vec{u} \cdot \vec{v} + |\vec{v}|^2 \\ &= |\vec{u}|^2 - 2(\vec{u} \cdot \vec{v}) + |\vec{v}|^2 \end{aligned}$$

## Extra Space



Now by the Law of Cosines:

$$\begin{aligned} |\vec{u} - \vec{v}|^2 &= |\vec{u}|^2 + |\vec{v}|^2 - 2|\vec{u}| |\vec{v}| \cos \theta \\ |\vec{u}|^2 - 2(\vec{u} \cdot \vec{v}) + |\vec{v}|^2 &= |\vec{u}|^2 + |\vec{v}|^2 - 2|\vec{u}| |\vec{v}| \cos \theta \\ -2(\vec{u} \cdot \vec{v}) &= -2|\vec{u}| |\vec{v}| \cos \theta \\ \vec{u} \cdot \vec{v} &= |\vec{u}| |\vec{v}| \cos \theta \end{aligned}$$



## Angle Between Vectors

### Definition 5

- 1 Solving for  $\theta$  we get the **angle between two vectors**  $\vec{u}$  and  $\vec{v}$ :

$$\theta = \cos^{-1} \left( \frac{\vec{u} \cdot \vec{v}}{|\vec{u}| |\vec{v}|} \right)$$

$$\begin{aligned} \vec{u} \cdot \vec{v} &= |\vec{u}| |\vec{v}| \cos \theta \\ \cos \theta &= \frac{\vec{u} \cdot \vec{v}}{|\vec{u}| |\vec{v}|} \end{aligned}$$

If either  $\vec{u} = \vec{0}$  or  $\vec{v} = \vec{0}$ , then  $\theta$  is undefined. Note that

$$0 \leq \theta \leq \pi.$$

- 2 If  $\vec{u} \cdot \vec{v} = 0$  (equivalently  $\theta = \frac{\pi}{2}$ ), we say  $\vec{u}$  and  $\vec{v}$  are **orthogonal**.

In 2 and 3 dimensions, “orthogonal” and “perpendicular” mean the same thing.



## Examples

$$\vec{i} = \langle 1, 0, 0 \rangle \quad \vec{j} = \langle 0, 1, 0 \rangle \quad \vec{k} = \langle 0, 0, 1 \rangle$$

## Problem 6

Use the dot product to show:

- 1  $2\vec{i} + 2\vec{j} - \vec{k}$  and  $5\vec{i} - 4\vec{j} + 2\vec{k}$  are orthogonal;
- 2  $\langle 2, 1 \rangle$  is parallel to  $\langle 10, 5 \rangle$ .

$$\begin{aligned} \textcircled{1} \quad \langle 2, 2, -1 \rangle \cdot \langle 5, -4, 2 \rangle &= \\ 2(5) + 2(-4) + (-1)(2) &= 10 - 8 - 2 = \boxed{0} \\ \theta &= \cos^{-1}\left(\frac{0}{\|\vec{u}\|\|\vec{v}\|}\right) = \cos^{-1}(0) = \frac{\pi}{2} \\ \textcircled{2} \quad \text{Show } \theta &= 0 \text{ [or } \pi] \end{aligned}$$

Extra Space

$$\vec{u} = \langle 2, 1 \rangle$$
$$\vec{v} = \langle 10, 5 \rangle$$

$$\vec{u} \cdot \vec{v} = \langle 2, 1 \rangle \cdot \langle 10, 5 \rangle = 2(10) + 1(5) = 25$$

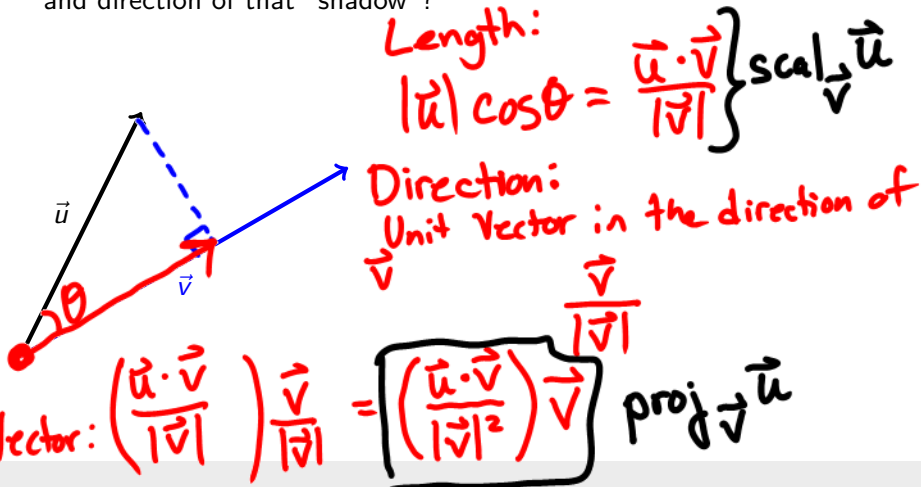
$$|\vec{u}| = \sqrt{2^2 + 1^2} = \sqrt{5}$$

$$|\vec{v}| = \sqrt{10^2 + 5^2} = \sqrt{125} = 5\sqrt{5}$$

$$\theta = \cos^{-1}\left(\frac{\vec{u} \cdot \vec{v}}{|\vec{u}| |\vec{v}|}\right) = \cos^{-1}\left(\frac{25}{\sqrt{5}(5\sqrt{5})}\right) = \cos^{-1}(1)$$
$$= 0$$

## Projecting Onto Other Vectors

Vectors can “cast a shadow” on another vector, what is the length and direction of that “shadow”?



# Components and Projections

## Definition 7

- 1 For a vector  $\vec{u}$  and a non-zero vector  $\vec{v}$ , the scalar component of  $\vec{u}$  in the direction of  $\vec{v}$  is:

$$\text{scal}_{\vec{v}} \vec{u} = |\vec{u}| \cos \theta = \frac{\vec{u} \cdot \vec{v}}{|\vec{v}|}$$

- 2 The (orthogonal) projection of  $\vec{u}$  onto  $\vec{v}$  is:

$$\text{proj}_{\vec{v}} \vec{u} = [\text{scal}_{\vec{v}} \vec{u}] \frac{\vec{v}}{|\vec{v}|} = \left( \frac{\vec{u} \cdot \vec{v}}{|\vec{v}|^2} \right) \vec{v}$$



## Example

## Problem 8

Find  $\text{scal}_{\vec{v}}\vec{u}$  and  $\text{proj}_{\vec{v}}\vec{u}$  for  $\vec{u} = -4\vec{i} - 3\vec{j}$  and  $\vec{v} = \vec{i} - \vec{j}$ .

$$\begin{aligned}\text{scal}_{\vec{v}}\vec{u} &= \frac{\vec{u} \cdot \vec{v}}{|\vec{v}|} = \frac{\langle -4, -3 \rangle \cdot \langle 1, -1 \rangle}{\sqrt{1^2 + (-1)^2}} \\ &= \frac{(-4)(1) + (-3)(-1)}{\sqrt{2}} = \boxed{\frac{-1}{\sqrt{2}}}\end{aligned}$$
$$\begin{aligned}\text{proj}_{\vec{v}}\vec{u} &= [\text{scal}_{\vec{v}}\vec{u}] \frac{\vec{v}}{|\vec{v}|} \\ &= \left(\frac{-1}{\sqrt{2}}\right) \frac{1}{\sqrt{2}} \langle 1, -1 \rangle = \boxed{\langle -\frac{1}{2}, \frac{1}{2} \rangle}\end{aligned}$$

# Orthogonal Decompositions

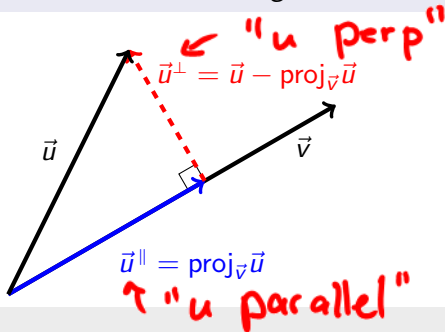
## Theorem 9

For a vector  $\vec{u}$  and a non-zero vector  $\vec{v}$ ,  $\vec{u}$  can be written as the sum of two vectors:

$$\vec{u} = \vec{u}^{\parallel} + \vec{u}^{\perp}$$

where  $\vec{u}^{\parallel}$  is parallel to  $\vec{v}$  and  $\vec{u}^{\perp}$  is orthogonal to  $\vec{v}$ .

Why?

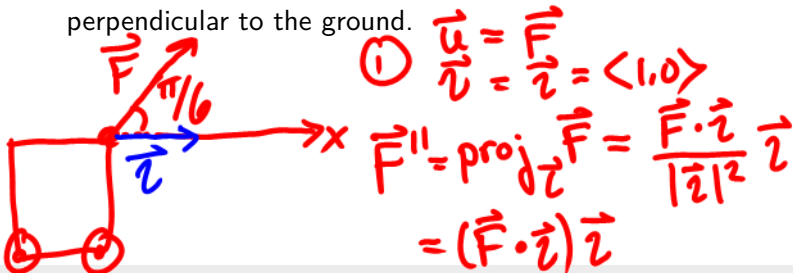


## Application: Work

### Problem 10

A wagon is pulled a distance of 100m along a horizontal path by a constant force of 50N. The handle of the wagon is held at an angle of  $30^\circ$  above the horizontal.

1) Express the force vector  $\vec{F} = 50\langle \cos \frac{\pi}{6}, \sin \frac{\pi}{6} \rangle = \langle 25\sqrt{3}, 25 \rangle$  as the sum of two vectors: one parallel to the ground and one perpendicular to the ground.





$$[\langle 25\sqrt{3}, 25 \rangle \cdot \langle 1, 0 \rangle] \langle 1, 0 \rangle = 25\sqrt{3} \langle 1, 0 \rangle$$

$$\vec{F}'' = \langle 25\sqrt{3}, 0 \rangle$$

$$\vec{F}^\perp = \vec{F} - \text{proj}_{\vec{L}} \vec{F} = \langle 25\sqrt{3}, 25 \rangle - \langle 25\sqrt{3}, 0 \rangle$$

$$= \langle 0, 25 \rangle$$

$$\vec{F} = \underbrace{\langle 25\sqrt{3}, 0 \rangle}_{\text{Parallel to } \vec{L}} + \underbrace{\langle 0, 25 \rangle}_{\text{Perpendicular to } \vec{L}}$$

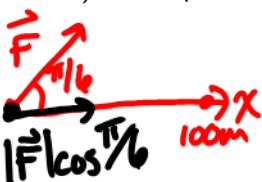
## Work Definition

### Definition 11

Given a force vector  $\vec{F}$  and displacement vector  $\vec{D}$ , the **work (W)** done by the force is defined as:

$$W \stackrel{\text{def}}{=} (\text{Force})(\text{Distance}) = \underbrace{(|\vec{F}| \cos \theta)}_{\text{scal } \vec{D}} |\vec{D}| = \vec{F} \cdot \vec{D}$$

2) In the previous problem, how much work was done?


$$\begin{aligned} W &= \vec{F} \cdot \vec{D} = |\vec{F}| |\vec{D}| \cos \theta \\ &= 50 \cdot 100 \cdot \cos \pi/6 \\ &= 50 \cdot 100 \cdot \frac{\sqrt{3}}{2} = 2500\sqrt{3} \text{ Nm} \end{aligned}$$



## §13.4 The Cross Product

## Review of Determinants

A **2-by-2 determinant** is defined by:

$$\begin{vmatrix} a & b \\ c & d \end{vmatrix} = ad - bc$$

A **3-by-3 determinant** is defined using 2-by-2 determinants:

$$\begin{vmatrix} a_1 & a_2 & a_3 \\ b_1 & b_2 & b_3 \\ c_1 & c_2 & c_3 \end{vmatrix} = a_1 \begin{vmatrix} b_2 & b_3 \\ c_2 & c_3 \end{vmatrix} - a_2 \begin{vmatrix} b_1 & b_3 \\ c_1 & c_3 \end{vmatrix} + a_3 \begin{vmatrix} b_1 & b_2 \\ c_1 & c_2 \end{vmatrix}$$

Notice the negative sign next to the  $a_2$ .

Compute

$$\begin{vmatrix} 1 & -2 & 3 \\ 2 & 0 & 3 \\ 1 & 5 & 4 \end{vmatrix} = \underset{\substack{\uparrow \\ \text{Row 1} \\ \text{Col 1}}}{(1)} \begin{vmatrix} 0 & 3 \\ 5 & 4 \end{vmatrix} - \underset{\substack{\uparrow \\ \text{Row 1} \\ \text{Col 2}}}{(-2)} \begin{vmatrix} 2 & 3 \\ 1 & 4 \end{vmatrix} + \underset{\substack{\uparrow \\ \text{Row 1} \\ \text{Col 3}}}{(3)} \begin{vmatrix} 2 & 0 \\ 1 & 5 \end{vmatrix}$$

$$= \underbrace{1(0(4) - (5)(3))}_{-15} + \underbrace{2(2(4) - (3)(1))}_{10} + \underbrace{3(2(5) - 0(1))}_{30}$$

$$= \boxed{25}$$

## Cross Product Definition

### Definition 12

If  $\vec{u} = \langle u_1, u_2, u_3 \rangle$  and  $\vec{v} = \langle v_1, v_2, v_3 \rangle$ , then the **cross product** of  $\vec{u}$  and  $\vec{v}$  is:

$$\begin{aligned}\vec{u} \times \vec{v} &\stackrel{\text{def}}{=} \begin{vmatrix} \vec{i} & \vec{j} & \vec{k} \\ u_1 & u_2 & u_3 \\ v_1 & v_2 & v_3 \end{vmatrix} \\ &= (u_2 v_3 - u_3 v_2) \vec{i} + (u_3 v_1 - u_1 v_3) \vec{j} + (u_1 v_2 - u_2 v_1) \vec{k}\end{aligned}$$

Notice how  $\vec{u} \times \vec{v}$  is a **vector** and is only defined in 3-dimensions.

# Examples

## Problem 13

Compute  $\vec{u} \times \vec{v}$  for:

1  $\vec{u} = \langle 1, 2, 0 \rangle, \vec{v} = \langle 0, 3, 1 \rangle$

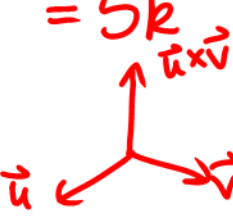
2  $\vec{u} = \langle 1, 1, 0 \rangle, \vec{v} = \langle -2, 3, 0 \rangle$

①  $\vec{u} \times \vec{v} = \begin{vmatrix} \vec{i} & \vec{j} & \vec{k} \\ 1 & 2 & 0 \\ 0 & 3 & 1 \end{vmatrix} = \vec{i} \begin{vmatrix} 2 & 0 \\ 3 & 1 \end{vmatrix} - \vec{j} \begin{vmatrix} 1 & 0 \\ 0 & 1 \end{vmatrix} + \vec{k} \begin{vmatrix} 1 & 2 \\ 0 & 3 \end{vmatrix}$   
 $= (2-0)\vec{i} - (1-0)\vec{j} + (3-0)\vec{k} = 2\vec{i} - \vec{j} + 3\vec{k}$   
 $= \langle 2, -1, 3 \rangle$

Extra Space

$$\begin{aligned} \textcircled{2} \vec{u} \times \vec{v} &= \begin{vmatrix} \vec{i} & \vec{j} & \vec{k} \\ 1 & 1 & 0 \\ -2 & 3 & 0 \end{vmatrix} = \begin{vmatrix} 1 & 0 \\ 3 & 0 \end{vmatrix} \vec{i} - \begin{vmatrix} 1 & 0 \\ -2 & 0 \end{vmatrix} \vec{j} + \begin{vmatrix} 1 & 1 \\ -2 & 3 \end{vmatrix} \vec{k} \\ &= (0-0)\vec{i} - (0-0)\vec{j} + (3-(-2))\vec{k} \\ &= 5\vec{k} \end{aligned}$$

$\vec{u} \times \vec{v} : \langle 0, 0, 5 \rangle \cdot \vec{u} = 0$   
 $\langle 0, 0, 5 \rangle \cdot \vec{v} = 0$   
 $(\vec{u} \times \vec{v}) \cdot \vec{u} = \langle 0, 0, 5 \rangle \cdot \langle 1, 1, 0 \rangle = 0$





Note The cross product is not commutative

$$\vec{u} \times \vec{v} \neq \vec{v} \times \vec{u}$$

$$\vec{i} \times \vec{j} = \begin{vmatrix} \vec{i} & \vec{j} & \vec{k} \\ 1 & 0 & 0 \\ 0 & 1 & 0 \end{vmatrix} = \begin{vmatrix} 0 & 0 \\ 1 & 0 \end{vmatrix} \vec{i} - \begin{vmatrix} 1 & 0 \\ 0 & 0 \end{vmatrix} \vec{j} + \begin{vmatrix} 1 & 0 \\ 0 & 1 \end{vmatrix} \vec{k} \\ = \vec{k}$$

$$\vec{j} \times \vec{i} = \begin{vmatrix} \vec{i} & \vec{j} & \vec{k} \\ 0 & 1 & 0 \\ 1 & 0 & 0 \end{vmatrix} = \begin{vmatrix} 1 & 0 \\ 0 & 0 \end{vmatrix} \vec{i} - \begin{vmatrix} 0 & 0 \\ 1 & 0 \end{vmatrix} \vec{j} + \begin{vmatrix} 0 & 1 \\ 1 & 0 \end{vmatrix} \vec{k} \\ = (0 - 1) \vec{k} \\ = -\vec{k}$$

## Properties of Cross Products

### Theorem 14

$\vec{u} \times \vec{v}$  is orthogonal to **both**  $\vec{u}$  and  $\vec{v}$ .

Check

$$(\vec{u} \times \vec{v}) \cdot \vec{u} = (\vec{u} \times \vec{v}) \cdot \vec{v} = 0$$

### Theorem 15

Let  $\vec{u}$ ,  $\vec{v}$ , and  $\vec{w}$  be vectors and  $c$  a scalar:

1  $\vec{u} \times \vec{u} = \vec{0}$

→ Any parallel vectors will have a cross product of  $\vec{0}$

2  $\vec{u} \times \vec{v} = -(\vec{v} \times \vec{u})$  (**anti-commutativity**)

3  $(c\vec{u}) \times \vec{v} = \vec{u} \times (c\vec{v}) = c(\vec{u} \times \vec{v})$

4  $\vec{u} \times (\vec{v} + \vec{w}) = \vec{u} \times \vec{v} + \vec{u} \times \vec{w}$

5  $(\vec{u} + \vec{v}) \times \vec{w} = \vec{u} \times \vec{w} + \vec{v} \times \vec{w}$

6  $\vec{u} \cdot (\vec{v} \times \vec{w}) = (\vec{u} \times \vec{v}) \cdot \vec{w}$

7  $\vec{u} \times (\vec{v} \times \vec{w}) = (\vec{u} \cdot \vec{w})\vec{v} - (\vec{u} \cdot \vec{v})\vec{w}$

## Physics Definition of Cross Product

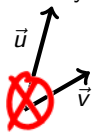
### Theorem 16

Given two **non-zero** 3-dimensional vectors  $\vec{u}$  and  $\vec{v}$ :

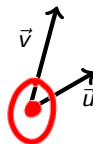
$$|\vec{u} \times \vec{v}| = |\vec{u}| |\vec{v}| \sin \theta$$

where  $0 \leq \theta \leq \pi$  is the angle between  $\vec{u}$  and  $\vec{v}$ .

The direction of  $\vec{u} \times \vec{v}$  is given by the **right-hand rule**: Line up the tails of  $\vec{u}$  and  $\vec{v}$ . Curl your right hand from  $\vec{u}$  to  $\vec{v}$ , then  $\vec{u} \times \vec{v}$  points in the same direction as your thumb. If  $\vec{u}$  or  $\vec{v}$  is  $\vec{0}$ , the direction is undefined.



⊗ = Vector  
Pointing Into  
the page



⊙ = Vector  
Pointing  
out of  
the page

## Why?

$$\begin{aligned} |\vec{u} \times \vec{v}|^2 &= (u_2 v_3 - u_3 v_2)^2 + (u_3 v_1 - u_1 v_3)^2 + (u_1 v_2 - u_2 v_1)^2 \\ &= u_2^2 v_3^2 - 2u_2 u_3 v_2 v_3 + u_3^2 v_2^2 + u_3^2 v_1^2 - 2u_1 u_3 v_1 v_3 + u_1^2 v_3^2 \\ &\quad + u_1^2 v_2^2 - 2u_1 u_2 v_1 v_2 + u_2^2 v_1^2 \\ &= (u_1^2 + u_2^2 + u_3^2) (v_1^2 + v_2^2 + v_3^2) - (u_1 v_1 + u_2 v_2 + u_3 v_3)^2 \\ &= |\vec{u}|^2 |\vec{v}|^2 - (\vec{u} \cdot \vec{v})^2 \\ &= |\vec{u}|^2 |\vec{v}|^2 - |\vec{u}|^2 |\vec{v}|^2 \cos^2 \theta \\ &= |\vec{u}|^2 |\vec{v}|^2 (1 - \cos^2 \theta) \\ &= |\vec{u}|^2 |\vec{v}|^2 \sin^2 \theta \end{aligned}$$

Since  $\sin \theta \geq 0$  for  $0 \leq \theta \leq \pi$  we have  $\sqrt{\sin^2 \theta} = \sin \theta$ , so take the square root of both sides to get  $|\vec{u} \times \vec{v}| = |\vec{u}| |\vec{v}| \sin \theta$

## Test for Parallel Vectors

### Corollary 17

- 1  $\vec{u}$  and  $\vec{v}$  are parallel if and only if  $\vec{u} \times \vec{v} = \vec{0}$
- 2 Three points  $A, B$ , and  $C$  are collinear if and only if  $\vec{AB} \times \vec{AC} = \vec{0}$

Why?  $\vec{u} \times \vec{v} = \vec{0} \Rightarrow \underbrace{|\vec{u} \times \vec{v}|}_{0} = |\vec{u}| |\vec{v}| \sin \theta$   
 $\Rightarrow \theta = \sin^{-1}\left(\frac{0}{|\vec{u}| |\vec{v}|}\right) = \sin^{-1}(0)$   
 $\Rightarrow \theta = 0 \text{ or } \pi$

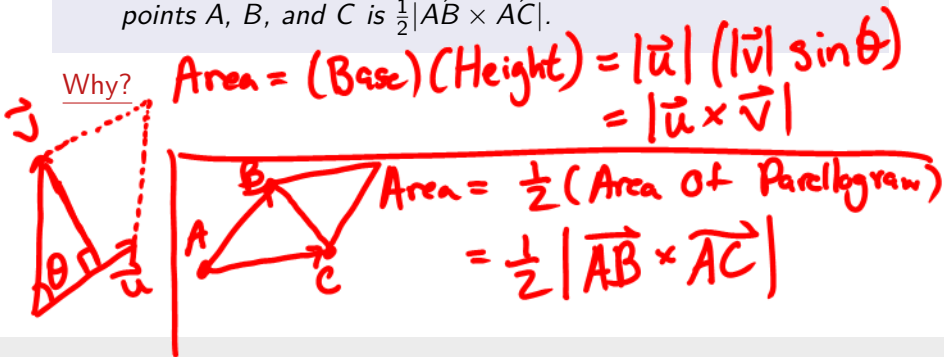


Example: The points  $A(-2, -4, 1)$ ,  $B(1, 3, 7)$ , and  $C(4, 10, 13)$  are collinear.

# Calculating Areas and Volumes

## Theorem 18

- 1 The area of the parallelogram determined by  $\vec{u}$  and  $\vec{v}$  is  $|\vec{u} \times \vec{v}|$ ;
- 2 The area of the triangle determined by the non-collinear points  $A$ ,  $B$ , and  $C$  is  $\frac{1}{2}|\vec{AB} \times \vec{AC}|$ .



## Examples

### Problem 19

- 1 Determine the area of the parallelogram with adjacent sides  $\vec{u} = -4\vec{i} + 3\vec{k}$  and  $\vec{v} = \vec{i} + \vec{j} + 2\vec{k}$ .
- 2 Determine the area of the triangle with vertices  $(0, 1)$ ,  $(-1, 1)$ , and  $(1, -1)$

① Need to compute  $|\vec{u} \times \vec{v}|$

$$\begin{aligned}\vec{u} \times \vec{v} &= \begin{vmatrix} \vec{i} & \vec{j} & \vec{k} \\ -4 & 0 & 3 \\ 1 & 1 & 2 \end{vmatrix} = \begin{vmatrix} 0 & 3 \\ 1 & 2 \end{vmatrix} \vec{i} - \begin{vmatrix} -4 & 3 \\ 1 & 2 \end{vmatrix} \vec{j} + \begin{vmatrix} -4 & 0 \\ 1 & 1 \end{vmatrix} \vec{k} \\ &= (0-3)\vec{i} - (-8-3)\vec{j} + (-4-0)\vec{k} \\ &= -3\vec{i} + 11\vec{j} - 4\vec{k}\end{aligned}$$

Extra Space

$$|\vec{u} \times \vec{v}| = \sqrt{(-3)^2 + 1^2 + (-4)^2} = \sqrt{146}$$

②

$$A(0,1) ; B(1,-1) ; C(-1,1)$$

$$\vec{AB} = \langle 1, -1 \rangle - \langle 0, 1 \rangle = \langle 1, -2 \rangle$$

$$\vec{AC} = \langle -1, 1 \rangle - \langle 0, 1 \rangle = \langle -1, 0 \rangle$$

$$\vec{AB} \times \vec{AC} = \begin{vmatrix} \vec{i} & \vec{j} & \vec{k} \\ 1 & -2 & 0 \\ -1 & 0 & 0 \end{vmatrix} = \begin{vmatrix} -2 & 0 \\ 0 & 0 \end{vmatrix} \vec{i} - \begin{vmatrix} 1 & 0 \\ -1 & 0 \end{vmatrix} \vec{j} + \begin{vmatrix} 1 & -2 \\ -1 & 0 \end{vmatrix} \vec{k}$$

$$\text{Area} = \frac{1}{2}(2) = 1$$

$$= (0 - 2)\vec{k} = -2\vec{k}$$

$$= (1(0) - (-1)(-2)) = -2\vec{k}$$



# The Triple Scalar Product

## Theorem 20

The volume of the parallelepiped determined by vectors  $\vec{u}$ ,  $\vec{v}$ , and  $\vec{w}$  is the *absolute value of the triple scalar product*:

$$\vec{u} \cdot (\vec{v} \times \vec{w}) = \begin{vmatrix} u_1 & u_2 & u_3 \\ v_1 & v_2 & v_3 \\ w_1 & w_2 & w_3 \end{vmatrix}$$

Why? This is a HW Problem.

$$V = (\text{Base}) (\text{Height}) \\ = |\vec{v} \times \vec{w}| |\vec{u}| \cos \theta$$

## Example

### Problem 21

Are the vectors  $\vec{u} = \langle 1, 4, -7 \rangle$ ,  $\vec{v} = \langle 2, -1, 4 \rangle$ , and  $\vec{w} = \langle 0, -9, 18 \rangle$  coplanar?

Check  $\vec{u} \cdot (\vec{v} \times \vec{w}) = 0$

$$\begin{aligned} \text{Volume} &= \begin{vmatrix} 1 & 4 & -7 \\ 2 & -1 & 4 \\ 0 & -9 & 18 \end{vmatrix} = (-18 + 36) - 4(36) - 7(-18) \\ &= 18 - 144 + 126 \\ &= 0 \end{aligned}$$

## Application: Torque

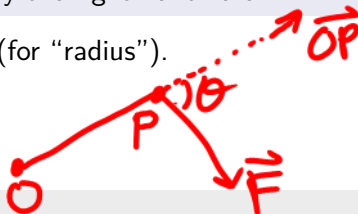
### Definition 22

Applying a force  $\vec{F}$  at a point  $P$ , the twisting effect (or **torque**) about a point  $O$  is a vector  $\vec{\tau}$  with:

$$|\vec{\tau}| = |\vec{OP} \times \vec{F}|$$

The direction of  $\vec{\tau}$  is governed by the right hand rule.

It is common to write  $\vec{OP}$  as  $\vec{r}$  (for “radius”).

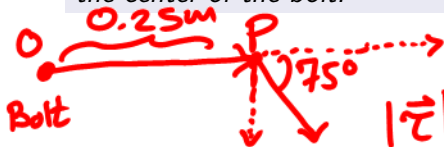


## Torque Example

$$|\vec{u} \times \vec{v}| = |\vec{v} \times \vec{u}|$$

## Problem 23

A bolt is tightened by applying a 40-N force to a 0.25-m wrench at a  $75^\circ$  angle. Find the magnitude and direction of the torque about the center of the bolt.



$$\begin{aligned} |\vec{\tau}| &= |\vec{OP} \times \vec{F}| = |\vec{OP}| \cdot |\vec{F}| \sin 75^\circ \\ &= 40(0.25) \sin 75^\circ \\ &= 10 \sin 75^\circ \approx 9.66 \text{ Nm} \end{aligned}$$

Direction :  $\vec{n}$  = Unit Vector Pointing into the page

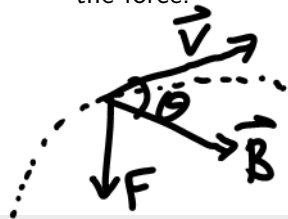
## Application: Magnetism

### Definition 24

A point charge  $q$  experiences a force  $\vec{F}$  when it moves through a magnetic field  $\vec{B}$  with velocity  $\vec{v}$  governed by the equation:

$$\vec{F} = q(\vec{v} \times \vec{B})$$

Notice whether  $q$  is positive or negative influences the direction of the force.



$$|\vec{F}| = |q| |\vec{v}| |\vec{B}| \sin \theta$$

## Example

### Problem 25

An electron ( $q = -1.6 \times 10^{-19} \text{ C}$ ) enters a magnetic field  $\vec{B} = \vec{i} + \vec{j}$  with velocity  $\vec{v} = (2 \times 10^5 \text{ m/s})\vec{k}$ .

- 1 Determine the magnitude and direction of the force.
- 2 Make a rough sketch of  $\vec{v}$ ,  $\vec{B}$ , and  $\vec{F}$ .

①  $|F| = |q| |\vec{v}| |\vec{B}| \sin \theta$

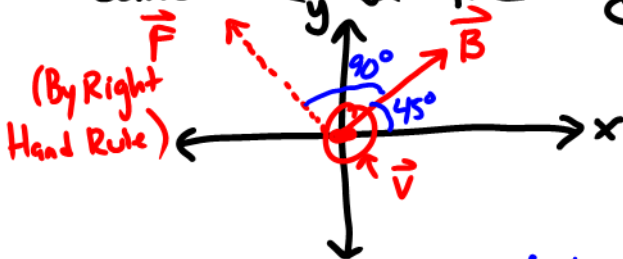
Absolute value  $\rightarrow |-1.6 \times 10^{-19}| (2 \times 10^5) (\sqrt{2}) (1)$

$= (3.2 \times 10^{-14}) \sqrt{2} \text{ Newtons}$

$\vec{B}, \vec{v}$  orthogonal  
 $\theta = \frac{\pi}{2}$

Extra Space

Direction:  $\vec{F} \cdot \vec{B} = 0$  and  $\vec{F} \cdot \vec{v} = 0$ , so  $\vec{F}$  lies  
Somewhere in the  $xy$ -plane



The Direction is  $135^\circ$  with respect to positive  
 $x$ -axis

② See Diagram Above