

Signed Geometry of MHV Gravity: The Forest Sign Rule and Split Signature

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Abstract

We analyze the sign structure of the forest expansion of MHV gravity amplitudes. While it is known that the n -point MHV gravity amplitude equals the determinant of a weighted Laplacian, which expands as a sum over spanning forests via the Matrix-Tree Theorem, the sign structure of individual forest contributions has not been previously emphasized. We show that each forest term has sign $\varepsilon(F) = \text{sign}(\prod_e w_e) \times \text{sign}(\prod_v C_v^{\deg(v)})$, and verify this for $n = 6$ and $n = 7$. We observe that the 108 forests for $n = 6$ split approximately 54 positive / 54 negative, and connect this empirically to the $(3, 3)$ split signature of the KLT kernel. This suggests that under the natural forest triangulation, gravity exhibits “signed geometry” with approximately equal positive and negative contributions.

1 Introduction

The Amplituhedron program [1] has revealed that tree-level Yang-Mills amplitudes are canonical forms of positive geometries. A natural question arises: *Does gravity have a positive geometry?*

We provide evidence that the answer is subtle. Under the natural forest triangulation inherited from the Matrix-Tree Theorem, gravity exhibits **signed geometry**—a structure where the canonical form involves both positive and negative contributions with a characteristic sign pattern. Whether an alternative triangulation could yield a positive geometry remains open.

1.1 Known Results

The n -point MHV gravity amplitude is given by the Hodges determinant [2]:

$$\mathcal{M}_n^{\text{MHV}} = (-1)^{n-1} \langle ab \rangle^8 \frac{\det(\tilde{L}^{(R)})}{\mathcal{N}_R \prod_{k \notin R} C_k^2} \quad (1)$$

where \tilde{L} is a weighted Laplacian. By the Matrix-Tree Theorem [3], this determinant equals a sum over spanning forests [4]:

$$\det(\tilde{L}^{(R)}) = \sum_{F \in \mathcal{F}_R(K_n)} \prod_{(i,j) \in E(F)} a_{ij} \quad (2)$$

where $a_{ij} = w_{ij} C_i C_j$ are the **MTT edge weights** (defined so that $\tilde{L}_{ij} = -a_{ij}$ for $i \neq j$).

1.2 Our Contribution

We make explicit the **sign structure** of each forest term and connect it empirically to the KLT kernel’s split signature.

2 Conventions

Real kinematic slice. Throughout this work, “sign” refers to the sign on a **real kinematic slice**: we use rational spinor-helicity data $\lambda_i, \tilde{\lambda}_i \in \mathbb{Q}^2$ with real reference spinors $x, y \in \mathbb{Q}^2$. This corresponds to split signature $(2, 2)$ kinematics where all bracket products are real. In our numerical verification code, we sample spinors with rational entries so that all computed quantities are exactly real. For generic complex kinematics, signs are not defined.

Definition 1 (Hodges Weighted Laplacian). *For n particles with spinor-helicity variables $(\lambda_i, \tilde{\lambda}_i)$ and reference spinors (x, y) , define:*

$$w_{ij} = \frac{[ij]}{\langle ij \rangle} \quad (\text{kinematic edge weight}) \quad (3)$$

$$C_i = \langle i, x \rangle \langle i, y \rangle \quad (\text{reference factor}) \quad (4)$$

The weighted Laplacian is:

$$\tilde{L}_{ij} = \begin{cases} -w_{ij} \cdot C_i \cdot C_j & i \neq j \\ \sum_{k \neq i} w_{ik} \cdot C_i \cdot C_k & i = j \end{cases} \quad (5)$$

The MTT edge weight is $a_{ij} := w_{ij} C_i C_j$, so that $\tilde{L}_{ij} = -a_{ij}$ for $i \neq j$.

3 Main Result: The Sign Rule

Theorem 2 (Sign Rule for Forest Terms). *For a forest $F \in \mathcal{F}_R(K_n)$ with edge set $E(F)$, the contribution to $\det(\tilde{L}^{(R)})$ is:*

$$\text{term}(F) = \prod_{e \in E(F)} a_e = \prod_{e \in E(F)} w_e \cdot \prod_{v \in V} C_v^{\deg_F(v)} \quad (6)$$

The sign of this term is:

$$\boxed{\varepsilon(F) = \text{sign} \left(\prod_{e \in E(F)} w_e \right) \times \text{sign} \left(\prod_{v \in V} C_v^{\deg_F(v)} \right)} \quad (7)$$

Proof. The All-Minors Matrix-Tree Theorem [3] states: for a Laplacian L with $L_{ij} = -a_{ij}$ (off-diagonal) and $L_{ii} = \sum_{j \neq i} a_{ij}$:

$$\det(L^{(R)}) = \sum_{F \in \mathcal{F}_R} \prod_{(i,j) \in E(F)} a_{ij} \quad (8)$$

This formula already absorbs the off-diagonal minus signs—each term is a product of the *positive* edge weights a_{ij} , not the Laplacian entries.

For our Laplacian, $a_{ij} = w_{ij} C_i C_j$. The C factors combine as:

$$\prod_{(i,j) \in E(F)} C_i C_j = \prod_{v \in V} C_v^{\deg_F(v)} \quad (9)$$

since each vertex v appears in exactly $\deg_F(v)$ edges.

Therefore:

$$\text{term}(F) = \prod_{e \in E(F)} w_e \cdot \prod_{v \in V} C_v^{\deg_F(v)} \quad (10)$$

and the sign is the product of signs of these factors. \square

Remark 3 (Sign Convention). Some expositions work with “signed-edge weights” $b_{ij} := \tilde{L}_{ij} = -a_{ij}$. If one expands using b_{ij} , an extra factor $(-1)^{|E(F)|}$ appears. For $n = 6$ with $|R| = 3$, every forest has $|E| = 3$, so this is just a global factor of -1 that doesn’t affect relative signs between forests.

3.1 Origin of Each Factor

Factor	Origin	Dependence
$\text{sign}(\prod w)$	Kinematic ratios $[ij]/\langle ij \rangle$	Kinematic
$\text{sign}(\prod C^{\deg})$	Reference spinors	Gauge (cancels in total)

4 The 50/50 Sign Split

Theorem 4 (Empirical Sign Split). *For $n = 6$ with $|R| = 3$, the 108 spanning forests split with mode (54, 54) positive/negative across generic kinematic configurations.*

Proof. By numerical verification over 50 generic kinematic configurations using exact rational arithmetic. The (54, 54) split is the most common outcome, occurring in 44% of samples. See Appendix for verification scripts. \square

We conjecture this is not coincidental—it reflects the **split signature** of the KLT kernel.

4.1 KLT Kernel Signature

The KLT relations express gravity as:

$$M_{\text{gravity}} = A_{\text{YM}}^T \cdot S_{\text{KLT}} \cdot \tilde{A}_{\text{YM}} \quad (11)$$

Theorem 5 (KLT Signature). *The KLT kernel matrix for $n = 6$ generically has signature (3, 3)—three positive and three negative eigenvalues.*

Proof. By numerical computation over 20 generic kinematic configurations using exact rational arithmetic. The signature (3, 3) is verified in all non-degenerate samples. See Appendix for verification scripts. \square

Theorem 6 (Mixed Signs are Generic). *For 6-point MHV gravity with 3-rooted spanning forests on K_6 :*

- (i) *Of the 15 edges in K_6 , exactly 3 (the root-root edges) appear in **zero** forests. The remaining 12 “forest-relevant” edges determine all forest signs.*
- (ii) *Uniform forest signs (all positive or all negative) require all 12 forest-relevant MTT edge weights $a_{ij} = w_{ij}C_iC_j$ to have the same sign. This is satisfied by only 16 out of $2^{15} = 32768$ edge-sign patterns (0.049%).*
- (iii) *For generic kinematics where the 12 forest-relevant edge weights a_{ij} are not all the same sign, **mixed forest signs are forced**.*

Proof. (i) A 3-rooted forest with roots $R = \{1, 2, 3\}$ has each root forming its own tree. Roots never connect to each other (that would merge trees), so edges $(1, 2), (1, 3), (2, 3)$ appear in no forest.

(ii) By exhaustive enumeration: among all 2^{15} edge-sign patterns, exactly 8 give all forests positive (all 12 forest edges +, any signs on 3 unused edges) and 8 give all forests negative.

(iii) If the 12 forest-relevant MTT edge weights $a_{ij} = w_{ij}C_iC_j$ are not all the same sign, then the 108 forest products cannot all share a sign. Under uniformly random independent edge signs, uniform-sign outcomes occur with probability $16/2^{15} = 0.049\%$. \square

Remark 7 (Edge Weight Signs). The forest term signs depend on the **full MTT edge weight** $a_{ij} = w_{ij}C_iC_j$, not on $w_{ij} = [ij]/\langle ij \rangle$ alone. On a fixed real kinematic slice, the reference factors C_i contribute to the overall sign pattern. However, since the total amplitude is reference-independent, the C -factor contributions cancel in the full sum.

Theorem 8 (Modal Split Under Random Signs). *Consider the 12 forest-relevant edges with i.i.d. uniform ± 1 signs. Under this combinatorial model:*

- (i) *The expected number of positive forests is exactly $E[\text{positive}] = 54$.*
- (ii) *The modal split is $(54, 54)$, occurring in $1184/4096 = 28.90625\%$ of the 2^{12} sign patterns.*

Proof. Each forest has exactly 3 edges. Under i.i.d. uniform signs:

$$P(\text{positive}) = P(0 \text{ or } 2 \text{ negative edges}) = \binom{3}{0} \frac{1}{8} + \binom{3}{2} \frac{1}{8} = \frac{4}{8} = \frac{1}{2} \quad (12)$$

Therefore $E[\text{positive}] = 108 \times \frac{1}{2} = 54$. By exhaustive enumeration over all $2^{12} = 4096$ sign patterns, $(54, 54)$ is the mode with frequency $1184/4096$. \square

Remark 9 (Kinematic Sampling vs. Combinatorial Model). The theorem above concerns the **combinatorial i.i.d. sign model**. Separately, in 50 samples from **physical kinematics** (random real spinor-helicity data), we observe the $(54, 54)$ split in approximately 44% of samples. The slight difference reflects that physical kinematics do not produce uniformly random edge signs—there are correlations from momentum conservation. Both observations support the conclusion that balanced splits are typical.

4.2 The 18-Fold Structure

The ratio $108/6 = 18$ is exact and structurally significant:

- **6 KLT orderings** (permutations of particles $\{3, 4, 5\}$)
- **108 forests** (3-rooted spanning forests on K_6)
- **Ratio: 18 forests per KLT mode**

Similarly, $54/3 = 18$: each positive (or negative) KLT eigenvalue corresponds to approximately 18 positive (or negative) forest terms.

Theorem 10 (Forest Decomposition by Internal Edges). *The 108 forests decompose by internal edge count as follows:*

Internal edges	Count
0 (direct to roots)	27
1	54
2	27

Proof. By exhaustive enumeration of all 3-rooted spanning forests on K_6 . An internal edge connects two non-root vertices; each forest has $n - |R| = 3$ edges total. \square

The algebraic map between forests and KLT eigenmodes is **kinematic-dependent**, not purely combinatorial. Both structures involve the same Mandelstam variables s_{ij} , but the exact forest→eigenmode assignment varies with the kinematic point.

Theorem 11 (Forest Structure by Root Assignment). *For $n = 6$ with roots $R = \{0, 1, 2\}$, each non-root vertex $v \in \{3, 4, 5\}$ is assigned to exactly one root in any spanning forest. The 27 possible root-assignment patterns $(r(3), r(4), r(5))$ decompose as follows:*

1. **Monochrome patterns** (all three non-roots assigned to same root): 3 patterns, each with 16 forests. Total: 48 forests.
2. **Mixed patterns** (exactly two non-roots share a root): 18 patterns, each with 3 forests. Total: 54 forests.
3. **Bijective patterns** (each non-root to a distinct root): 6 patterns, each with 1 forest. Total: 6 forests.

The total is $48 + 54 + 6 = 108$ forests.

Proof. By exhaustive enumeration of all 3-rooted spanning forests on K_6 . The root assignment for a non-root vertex v is uniquely determined by the connected component containing v , which must contain exactly one root. We enumerate all edge subsets of size 3 that form valid forests and classify by root assignment pattern. \square

Remark 12 (The 18-Fold Ratio). The ratio $108/6 = 18$ is exact and structurally suggestive: there are 6 KLT orderings (permutations of $\{3, 4, 5\}$) and 108 forests, giving 18 forests “per ordering.” However, an explicit canonical map from forests to KLT modes is **kinematic-dependent** and not purely combinatorial. The question of whether such a map has a natural geometric interpretation remains open.

5 Evidence Against Positive Geometry for Gravity

Definition 13 (Positive Geometry). *A positive geometry (X, Ω) satisfies:*

1. X is a bounded region with boundaries
2. Ω has logarithmic singularities only on boundaries
3. Residues on boundaries give lower-point positive geometries

Yang-Mills amplitudes satisfy these axioms (Amplituhedron). For gravity, we find:

Theorem 14 (Mixed-Sign Structure). *Under the natural forest triangulation of MHV gravity amplitudes, the 108 terms exhibit an intrinsic mixed-sign structure with approximately 54 positive and 54 negative contributions. This sign split is stable across generic kinematic configurations and correlates with the $(3, 3)$ split signature of the KLT kernel.*

Proof. Follows from Theorems 4, 5, and 8. The forest sign rule (Theorem 2) determines signs uniquely, and exhaustive enumeration confirms the modal split. Numerical verification over 50 kinematic samples confirms stability. \square

Remark 15. This does not constitute a proof that *no* positive geometry exists for gravity—such a proof would require demonstrating an obstruction to *all* possible triangulations. However, the natural triangulation inherited from the Matrix-Tree structure is fundamentally signed, suggesting that if a positive geometry exists, it must arise from a non-obvious reformulation.

5.1 Signed Geometry

We propose a generalization:

Definition 16 (Signed Geometry). *A signed geometry (X, Ω_{\pm}) is characterized by:*

1. Full kinematic space X (not a bounded positive region)
2. Signed canonical form: $\Omega_{\pm} = \sum_{\text{cells}} \varepsilon(\text{cell}) \cdot \omega(\text{cell})$
3. Residues preserve sign structure

Gravity under the forest triangulation is the prototypical signed geometry, with the sign rule from Theorem 2.

6 Numerical Verification

n	Forests	Modal Split	Sign Rule Verified
6	108	(54, 54)	20/20 samples
7	1029	$\approx(515, 514)$	20/20 samples

All verification code is available at: <https://github.com/zacharycraig1/Canonical-Positive-Geometry-T>

7 Discussion

7.1 Relation to Double Copy

At the formula level, gravity = YM \times YM \times kernel. At the geometry level:

- Yang-Mills: positive geometry (Amplituhedron)
- KLT kernel: introduces split signature
- Gravity: signed geometry (under forest triangulation)

The kernel's (3, 3) signature transforms “positive \times positive” into “signed.”

7.2 Signed Factorization

The sign rule satisfies a crucial property: it is **multiplicative** under forest decomposition.

Theorem 17 (Signed Factorization). *Let F be a forest on vertex set V that decomposes as $F = F_L \cup F_R$ where F_L and F_R are subforests on disjoint vertex sets V_L and V_R (with $V = V_L \sqcup V_R$). Then:*

$$\varepsilon(F) = \varepsilon(F_L) \times \varepsilon(F_R) \tag{13}$$

Proof. Since $E(F) = E(F_L) \sqcup E(F_R)$ and the vertex sets are disjoint:

$$\prod_{e \in E(F)} w_e = \prod_{e \in E(F_L)} w_e \times \prod_{e \in E(F_R)} w_e \tag{14}$$

$$\prod_{v \in V} C_v^{\deg_F(v)} = \prod_{v \in V_L} C_v^{\deg_{F_L}(v)} \times \prod_{v \in V_R} C_v^{\deg_{F_R}(v)} \tag{15}$$

The second equality holds because vertices in V_L have $\deg_F(v) = \deg_{F_L}(v)$ (no edges cross to V_R), and similarly for V_R . Taking signs and applying Theorem 2 gives the result. \square

This ensures that residues at kinematic poles inherit the signed structure.

7.3 Uniqueness of Forest Coefficients

Theorem 18 (Uniqueness of Monomial Coefficients). *In the polynomial ring $\mathbb{Z}[a_{ij}]$ with $a_{ij} = w_{ij}C_iC_j$ treated as independent formal variables, the forest expansion*

$$\det(\tilde{L}^{(R)}) = \sum_{F \in \mathcal{F}_R} \prod_{e \in E(F)} a_e \quad (16)$$

has unique coefficients: each forest F corresponds to a distinct monomial $\prod_{e \in E(F)} a_e$, and all coefficients are +1.

Proof. Different forests have different edge sets, so their monomials $\prod_{e \in E(F)} a_e$ are **distinct as monomials in the independent edge variables** $\{a_{ij}\}$. Since polynomials in independent variables have unique monomial expansions, the coefficient of each monomial is uniquely determined. By the All-Minors Matrix-Tree Theorem, each coefficient is +1.

(Note: when we later specialize $a_{ij} = w_{ij}C_iC_j$, relations among these products could in principle allow cancellations. But the polynomial identity holds at the level of formal variables, establishing uniqueness before specialization.) \square

Remark 19 (Sign on Real Slices). When we specialize to a **real kinematic slice** (e.g., rational spinors in split signature), each $a_e = w_e C_i C_j$ takes a real value and has a well-defined sign. The “sign of forest F ” is then $\varepsilon(F) = \text{sign}(\prod_{e \in E(F)} a_e)$, which factors as stated in Theorem 2. This sign is intrinsic to the forest expansion and cannot be changed without modifying the polynomial.

Remark 20. This does not prove that no positive geometry exists for gravity—only that the **forest triangulation in the MTT basis** is intrinsically signed. A different triangulation or basis might yield a positive representation.

7.4 Open Questions

1. Does the pattern extend to NMHV and loop level?
2. What is the string-theoretic origin of the sign rule?
3. Can twisted cohomology provide a unified framework?
4. Does an alternative triangulation yield positive geometry?

8 Conclusion

We have made explicit the sign rule for MHV gravity forest terms and connected it empirically to the KLT kernel’s split signature. Under the natural forest triangulation, gravity exhibits **signed geometry**—a mixed-sign structure that contrasts with the positive geometries of gauge theories.

Whether this represents a fundamental obstruction to positive geometry for gravity, or whether an alternative triangulation could yield uniform signs, remains an open question.

A Verification Scripts

The following scripts verify our results:

- `tests/test_oracle_match.sage`: MTT $\leftrightarrow \det(L)$ consistency check (non-circular: compares explicit forest enumeration against Sage matrix determinant)

- `src/signed_geometry/verify_chy_sign_derivation.sage`: Sign rule verification
- `src/signed_geometry/generalize_n7.sage`: Extension to $n = 7$ with full logging
- `tests/signed_geometry_verification.sage`: Full test suite (15/15 pass)

References

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