

**iSpy: Detection of Signals in Noise**  
**(EECE4688)**  
**Spring 2019**

**Homework 5**  
**(Assigned Feb.14, 2019; due Feb.20, 2019 in class.)**

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**Objective:** The objective of this exercise is to experiment with binary hypothesis testing using multiple observations.

**Task:** The Matlab file `hwk5.mat` contains  $N = 1000$  realizations of a random vector  $\mathbf{Y}$ . Each realization (each vector  $\mathbf{y}$ ) has  $M = 16$  elements corresponding to multiple observations. Your task is to design the detector, and make  $N = 1000$  decisions, one for each realization  $\mathbf{y}$ . A decision is either 1, corresponding to “signal present,” or 0, corresponding to “signal absent.”

The detection problem is specified as follows:

$$\begin{aligned} H_0 : \mathbf{Y} &= \mathbf{Z} \\ H_1 : \mathbf{Y} &= A\mathbf{s} + \mathbf{Z} \end{aligned}$$

The noise is circularly symmetric complex Gaussian,  $\mathbf{Z} \sim \mathcal{CN}(\mathbf{0}, \sigma_{Z_1}^2 \mathbf{I})$ . In other words, each element of  $\mathbf{Z}$  consists of independent zero-mean Gaussian real/imaginary parts of variance  $\sigma_{Z_1}^2/2$ . The elements (different noise observations) are uncorrelated, as evident from the diagonal structure of the covariance matrix  $\mathbf{C}_Z = E\{\mathbf{Z}\mathbf{Z}'\} = \sigma_{Z_1}^2 \mathbf{I}$ . The amplitude  $A$  is real-valued and constant, and the vector  $\mathbf{s}$  is defined as through a phase  $\phi$  as

$$\mathbf{s} = \begin{bmatrix} 1 \\ e^{-j\phi} \\ e^{-j2\phi} \\ \vdots \\ e^{-j(M-1)\phi} \end{bmatrix} \quad (1)$$

This type of problem is found in radar/sonar, or any type of sounding or probing, when an array of  $M$  receivers is used to detect presence/absence of a signal. If the array receivers are separated by a distance  $d$ , and the signal of wavelength  $\lambda$  (frequency  $f = c/\lambda$ ) arrives to the array from direction  $\theta$ , the phase  $\phi$  is given by

$$\phi = 2\pi \frac{d}{\lambda} \sin \theta \quad (2)$$

In the present problem, the direction of arrival is  $\theta = 20^\circ$ , and  $d = \frac{\lambda}{2}$ . The variance of the noise is  $\sigma_{Z_1}^2 = 1$ .

- 1) Specify the relevant probability density functions  $f_0(\mathbf{y})$  and  $f_1(\mathbf{y})$ .
- 2) State the likelihood ratio test (LRT).
- 3) Show that the LRT reduces to  $\frac{1}{M} \underset{H_0}{\underset{H_1}{Re\{\mathbf{s}'\mathbf{y}\}}} \gtrless \gamma$ . (Prime here denotes conjugate transpose.)
- 4) Determine the threshold  $\gamma$  so as to ensure probability of false alarm equal to  $P_{fa}^* = 10\%$ .
- 5) Apply the resulting Neuman-Pearson detection rule to the data stored in `hwk5.mat`. How many “signal present” decisions have you made?
- 6) Imagine that a genie comes to you after you’ve done all this work, and tells you that the signal was actually present in 8 out of 1000 realizations; specifically, in realizations 148 607 624 626 645 711 727 and 780. Did you have any missed detections? If so, in which realizations did they occur?

**Reporting:** Your report should be typed, and not exceed two single-sided pages. It should be written in a professional manner. Figures and mathematical expressions should be used whenever meaningful. Figures should always have axes labeled in appropriate units (e.g. time [s], time [ms], frequency [Hz], frequency [kHz], SNR or SNR [dB], etc.). Include any Matlab code as an appendix. Please put your name on top of the report.