# Connectionist Computing COMP 30230/41390

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#### **Credits**

- Geoffrey Hinton, University of Toronto.
  - borrowed some of his slides for "Neural Networks" and "Computation in Neural Networks" courses.



- slides from his CS4018.
- Paolo Frasconi, University of Florence.
  - slides from tutorial on Machine Learning for structured domains.



#### Lecture notes on Brightspace

- Strictly confidential...
- Slim PDF version will be uploaded later, typically the same day as the lecture.
- If there is demand, I can upload onto Brightspace last year's narrated slides.. (should be very similar to this year's material)

Connectionist Computing COMP 30230

#### **Books**

- No book covers large fractions of this course.
- Parts of chapters 4, 6, (7), 13 of Tom Mitchell's "Machine Learning"
- Parts of chapter V of Mackay's "Information Theory, Inference, and Learning Algorithms", available online at:

http://www.inference.phy.cam.ac.uk/mackay/itprnn/book.html

 Chapter 20 of Russell and Norvig's "Artificial Intelligence: A Modern Approach", also available at:

http://aima.cs.berkeley.edu/newchap20.pdf

More materials later...

### Marking

- 3 landmark papers to read, and submit a 10-line summary on Brightspace about: each worth 6-7%
- a connectionist model to build and play with on some sets, write a report: 30%
- Final Exam in the RDS (50%)

### **Assignment 1**

- Read the first section of the following article by Marvin Minsky:
- http://web.media.mit.edu/~minsky/papers/SymbolicVs.Connectionist.html
- down to ".. we need more research on how to combine both types of ideas."
- Submit through BrightSpace a 250 word MAX summary by October 2<sup>nd</sup> at 23:59, any time zone of your choice (Baker Island?).
- One third of a grade down every 2 days late, that is: if you deserve an A and you're 1-2 days late you get an A-, 3-4 days late a B+, etc.
- Make sure it's gone through!

Connectionist Computing COMP 30230

# From Hopfield nets to Boltzmann machine

Hopfield nets (attempt to) minimise an energy function:

$$E(y) = -\frac{1}{2} \sum_{i,j} w_{ij} y_i y_j = -\frac{1}{2} \mathbf{y}^{\mathbf{T}} \mathbf{W} \mathbf{y}$$

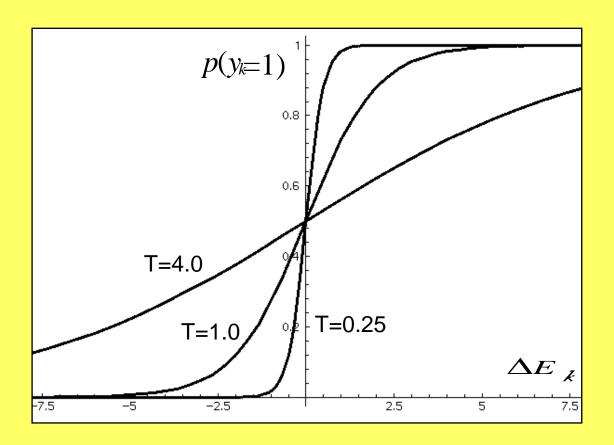
$$\mathbf{y} = (y_1, ..., y_m)^T$$

$$\mathbf{W} = \begin{pmatrix} w_{11} & \dots & w_{1i} & \dots & w_{1n} \\ w_{j1} & \dots & w_{ji} & \dots & w_{jn} \\ w_{m1} & \dots & w_{mi} & \dots & w_{mn} \end{pmatrix}$$

#### Stochastic units

 The probability that a given unit is switched on is a function of the amount of energy that its change of state would contribute to the network's overall energy, and the "temperature" T.

$$\frac{exp(z_i/T)}{exp(z_i/T) + exp(-z_i/T)} = \frac{1}{1 + exp(-2z_i/T)}$$



Connectionist Computing COMP 30230

# Implementing a probability distribution

 It can be shown that the Boltzmann machine generates configurations according to the distribution:

$$P(\mathbf{y}|\mathbf{W}) = \frac{1}{Z(\mathbf{W})} exp(\frac{1}{2}\mathbf{y^T}\mathbf{W}\mathbf{y})$$

· Where:

$$Z(\mathbf{W}) = \sum_{\mathbf{y}} exp(\frac{1}{2}\mathbf{y}^{\mathbf{T}}\mathbf{W}\mathbf{y})$$

# Learning in the Boltzmann machine

 Working on the probability distribution it is possible to devise the following learning rule:

$$\Delta w_{ij} = \eta \sum_{p=1}^{P} \left[ y_i^{(p)} y_j^{(p)} - \sum_{\mathbf{y}} y_i y_j P(\mathbf{y} | \mathbf{W}) \right]$$

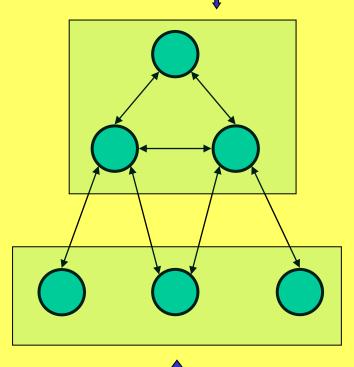
#### Interpretation of learning terms

- First term: the network is awake and measures the correlations in the real world.
- Second term: the network sleeps and dreams about the world using the model it has of it.
- Once dream and reality coincide learning reaches an end. It is interesting to notice that the network unlearns its dreams.

# Hidden units for Hopfield nets/Boltzmann machines

- Instead of using the net just to store memories, use it to construct interpretations of the input.
  - The input is represented by the visible units.
  - The interpretation is represented by the states of the hidden units.
- Higher order correlations can be represented by hidden units.
- More powerful model, but even harder to train.

Hidden units. Used to represent an interpretation of the inputs



Visible units. Used to represent the inputs

# Learning in the Boltzmann machine with hidden units

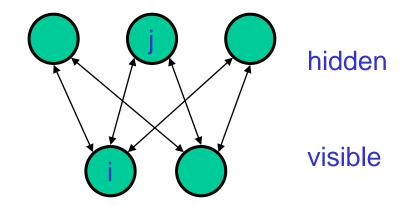
- Even in this case we have two terms in Δw<sub>ij</sub>.
- The first term is the correlation between neurons i and j when the visible units are clamped to the examples.
- The second is the correlation between neurons i and j when the system is let evolve freely.

# Learning in the Boltzmann machine with hidden units

- In this case both terms must be estimated by letting the network evolve many times until equilibrium, in one case with the visible units clamped, in the other freely.
- Not only: the missing units need to be estimated separately for each example.
- Can be computationally very expensive

# Restricted Boltzmann Machines (RBM)

- We restrict the connectivity to make inference and learning easier.
  - Only one layer of hidden units.
  - No connections between hidden units.
- It only takes one step to reach equilibrium when the visible units are clamped..



#### **Example 1: no hidden units**

- Only two examples:
- (-1, -1, -1, -1, -1)
- (1, 1, 1, 1, 1, 1)

 Train a Boltzmann machine without hidden units on them.

### **Example 1: BM learning**

#### **Iterate:**

- First step: increase (i,j) connection strength by an amount proportional to the correlation between bits i and j of the examples:
- Second step: let the BM machine run many times until equilibrium, measure the correlation between bits i and j of the final BM states and decrease (i,j) connection strength by an amount proportional to it.

- Correlations in:
- (-1,-1,-1,-1,-1) and (1,1,1,1,1,1)

All the w<sub>ij</sub> are 2η

 NOTE: We can compute these at the beginning: they don't change.

#### **Learning parameters:**

- Learning rate η=0.1
- Temperature T=1

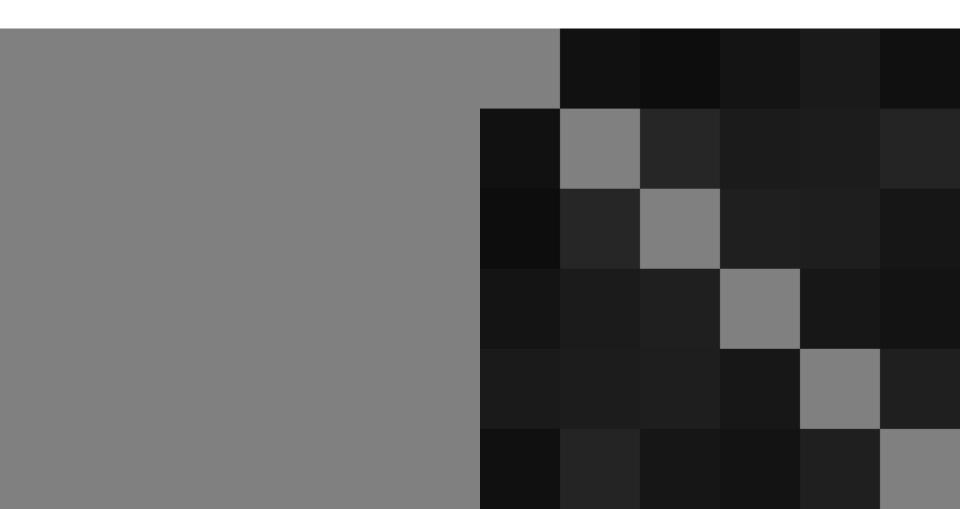
"let the BM machine run many times until equilibrium":

- many times = 1000
- until equilibrium = 600 neuron flips

Summary

- Iterate:
  - 1) change all weights by +2η
  - 2) let the BM run from random starts 1000 times until it settles into y, decrease all weights by  $\eta$  times the correlations between the bits of y.
- until no change

Reality



Reality



Reality



Reality



Reality



Reality



Reality

Reality

- What happens if we let the trained BM evolve from random starts now?
- -1 -1 -1 -1 -1 -1
- -1 1 1 1 1 1
- 1 1 1 1 1 1
- 1 1 1 1 1 1
- 1 1 1 1 1 1
- 1 1 -1 1 1 1
- -1 -1 -1 -1 -1 -1
- 1 1 1 1 1 1
- 1 1 1 1 1 1

- 1 1 1 1 1 1
- -1 -1 -1 -1 -1
- 1 1 1 1 1 1
- -1 1 -1 -1 -1 -1
- 1 1 1 1 1 1
- -1 -1 -1 -1 -1
- -1 -1 -1 -1 -1
- -1 -1 -1 -1 -1 -1
- 1 1 1 1 1 1
- 1 1 1 1 1 1
- -1 -1 -1 -1 -1

#### **Example 2: still no HU**

- Three examples now:
- (1 -1 -1 1 1 1)
- (-1 1 -1 1 1 1)
- (-1 -1 1 1 1 1)

Train a BM on them

#### **Correlations in the examples:**

- (1 -1 -1 1 1 1)
- (-1 1 -1 1 1 1)
- (-1 -1 1 1 1 1)

#### This is what we get:

```
 0.3 -0.1 -0.1 -0.1 -0.1
```

$$\bullet$$
 -0.1 -0.1 0.3 -0.1 -0.1 -0.1

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Xη

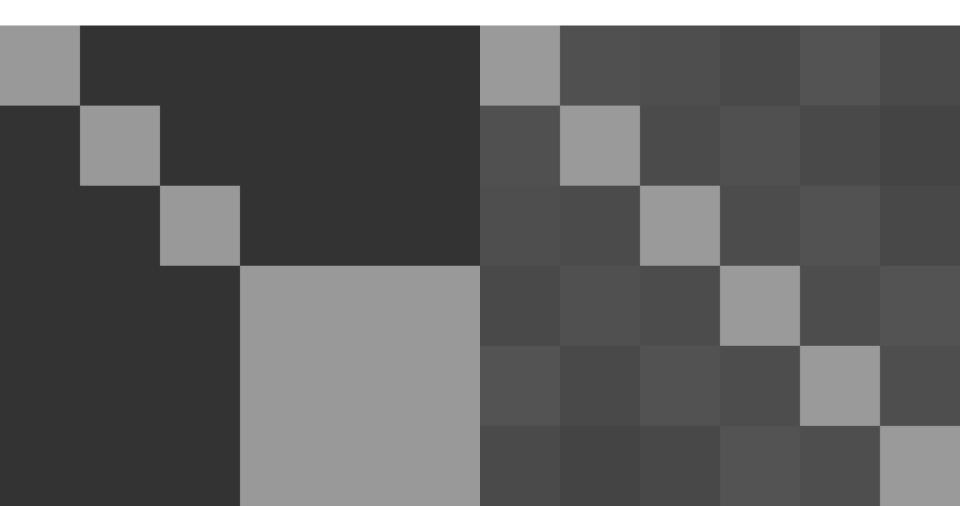
Learning parameters, same as in example 1:

- Learning rate η=0.1
- Temperature T=1

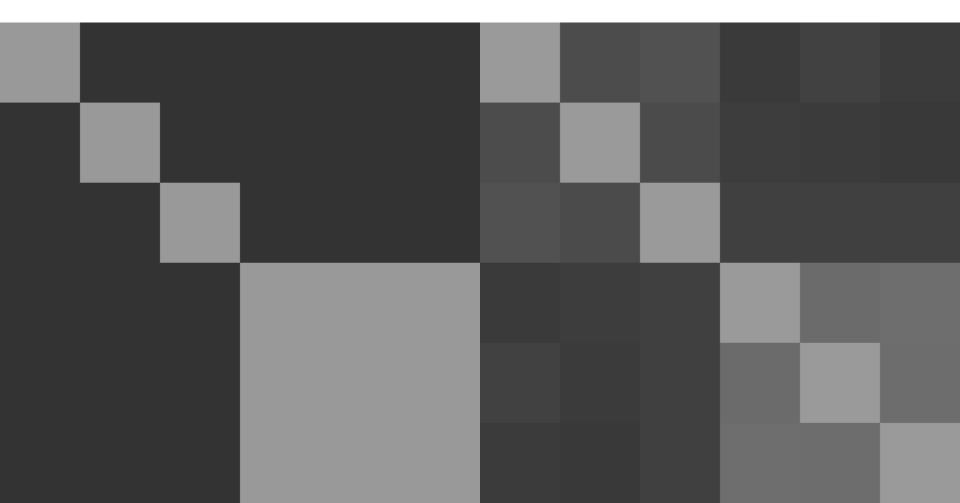
"let the BM machine run many times until equilibrium":

- many times = 1000
- until equilibrium = 600 neuron flips

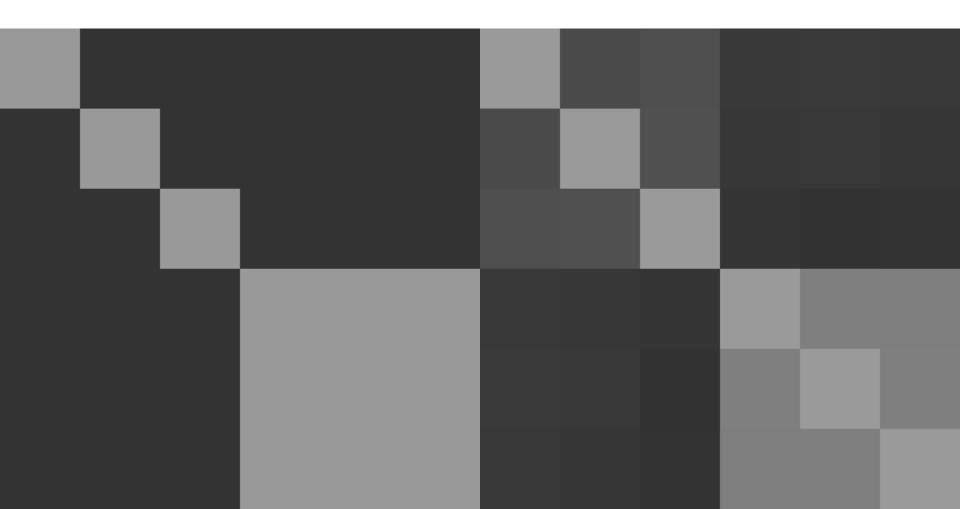
Reality



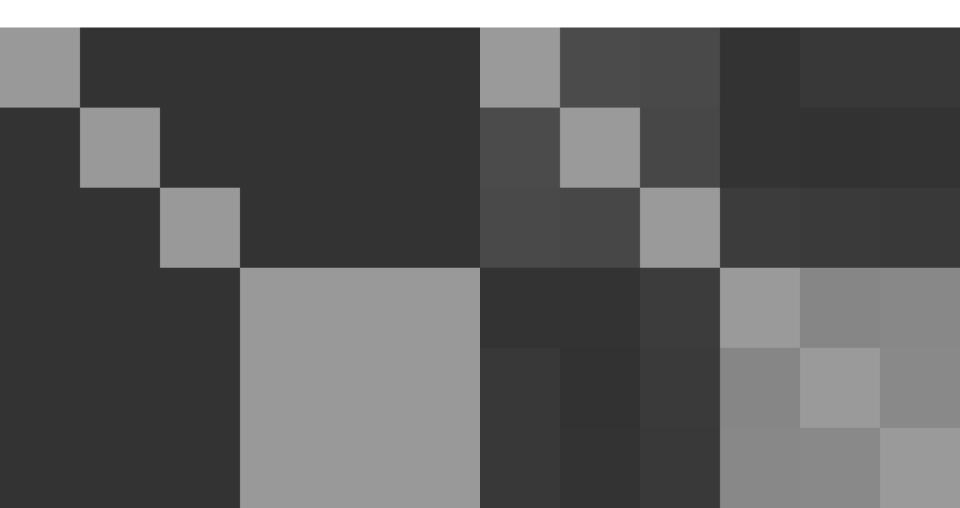
Reality



Reality



Reality



Reality



Reality



Reality



Reality



Reality



Reality



- $\cdot (1 -1 -1 1 1 1)$
- · (-1 1 -1 1 1 1)

### Example 2 $\frac{1}{1-1} \frac{1}{1-1} \frac{1}{1-1} \frac{1}{1-1} \frac{1}{1-1}$

- We now let the BM converge from random points:
- -1 1 1 -1 -1 -1
- -1 1 -1 1 1 1
- -1 1 1 -1 -1 -1
- 1 -1 1 -1 -1
- · -1 1 -1 1 1 1
- 1 -1 1 -1 -1 -1
- -1 -1 1 1 1 1
- -1 -1 1 1 1 1
- -1 -1 1 -1 -1 -1

- -1 1 1 -1 -1 -1
- 1 1 -1 -1 -1 -1
- 1 -1 1 -1 -1
- 1 1 -1 -1 -1
- -1 1 1 -1 -1 -1
- 1 1 -1 1 1 1
- 1 -1 1 -1 -1 -1
- · -1 -1 1 1 1 1
- 1 -1 1 -1 -1
- -1 1 1 -1 -1 -1
- 1 1 -1 -1 -1 -1

- $\cdot (1 -1 -1 1 1 1)$
- (-1 1 -1 1 1 1)

### Example 2 $\begin{pmatrix} 1 & 1 & 1 & 1 & 1 \\ 1 & 1 & 1 & 1 & 1 \end{pmatrix}$

- We now let the BM converge from random points:
- -1 1 1 -1 -1 -1
- -1 1 -1 1 1 1
- -1 1 1 -1 -1 -1
- 1 -1 1 -1 -1
- · -1 1 -1 1 1 1
- 1 -1 1 -1 -1
- -1 -1 1 1 1 1
- · -1 -1 1 1 1 1
- -1 -1 1 -1 -1 -1

- -1 1 1 -1 -1 -1
- 1 1 -1 -1 -1 -1
- 1 -1 1 -1 -1
- 1 1 -1 -1 -1
- -1 1 1 -1 -1 -1
- 1 1 -1 1 1 1
- 1 -1 1 -1 -1 -1
- -1 -1 1 1 1 1
- 1 -1 1 -1 -1
- -1 1 1 -1 -1 -1
- 1 1 -1 -1 -1 -1

Just a few right ones

- · (1 -1 -1 1 1 1)
- · (-1 1 -1 1 1 1)
- (-1 -1 1 1 1 1)

### Example 2

- We now let the BM converge from random points:
- -1 1 1 -1 -1 -1
- -1 1 -1 1 1 1
- -1 1 1 -1 -1 -1
- 1 -1 1 -1 -1 -1
- -1 1 -1 1 1 1
- 1 -1 1 -1 -1 -1
- -1 -1 1 1 1 1
- · -1 -1 1 1 1 1
- -1 -1 1 -1 -1 -1

- -1 1 1 -1 -1 -1
- 1 1 -1 -1 -1 -1
- 1 -1 1 -1 -1 -1
- 1 1 -1 -1 -1
- -1 1 1 -1 -1 -1
- 1 1 -1 1 1 1
- 1 -1 1 -1 -1
- -1 -1 1 1 1 1
- 1 -1 1 -1 -1 -1
- -1 1 1 -1 -1 -1
- 1 1 -1 -1 -1

A good few opposites

- $\cdot (1 -1 -1 1 1 1)$
- · (-1 1 -1 1 1 1)
- (-1 -1 1 1 1 1)

### Example 2

- We now let the BM converge from random points:
- -1 1 1 -1 -1 -1
- -1 1 -1 1 1 1
- -1 1 1 -1 -1 -1
- 1 -1 1 -1 -1 -1
- -1 1 -1 1 1 1
- 1 -1 1 -1 -1 -1
- -1 -1 1 1 1 1
- · -1 -1 1 1 1 1
- -1 -1 1 -1 -1 -1

- -1 1 1 -1 -1 -1
- 1 1 -1 -1 -1 -1
- 1 -1 1 -1 -1 -1
- 1 1 -1 -1 -1
- -1 1 1 -1 -1 -1
- 1 1 -1 1 1 1
- 1 -1 1 -1 -1
- -1 -1 1 1 1 1
- 1 -1 1 -1 -1 -1
- -1 1 1 -1 -1 -1
- 1 1 -1 -1 -1

Rebels

#### Example 2

- Problem here: second order relations are just not enough to model even this simple problem.
- Need hidden units?

#### **Hidden Units**

- Hidden Units take time to be trained, and it is problematic to run a machine with them in any realistic case using the standard algorithm on a CPU.
- Later in the course I'll talk about ways to overcome the issue.

#### Learning

- We will need concepts of learning theory.
- What is learning exactly, after all?

### Types of learning task

#### Supervised learning:

 learning to predict output when examples of input and corresponding output are available.

#### Reinforcement learning:

 no real supervision, only occasional payoff: e.g. I don't know if a chess move is correct but I know if I win.

#### Unsupervised learning:

I want to create an internal representation of the data,
 e.g. in form of clusters, extract relevant features for further tasks, etc.

### Supervised learning

- A set of examples: <x,f(x)>
  - x is some object (instance)  $\in \mathcal{X}$  (instance space)
  - $f(\cdot)$  is an *unknown* function
- Learning algorithm will guess  $h(\cdot) \approx f(\cdot)$
- Inductive learning hypothesis
  - Any  $h(\cdot)$  that approximates  $f(\cdot)$  well on training examples will also approximate  $f(\cdot)$  well on new (unseen) instances x. This isn't necessarily true, of course..

# Types of supervised learning task

- f(x) is a real value/an array of real values: regression
- f(x) is a discrete value; f(x)∈{y₁ ..yκ}:
  classification
  - if K=2, binary classification

#### **Example**

- Medical diagnosis (classification)
  - x: set of properties for a patient (symptoms, lab tests, previous diseases)
  - f(x): disease
  - <x,f(x)>: Database of past medical records
  - Type of x: a fixed-length array (attribute/value representation), maybe with missing attributes
  - Type of f(x): a discrete value or a fixed-width array

#### **Example**

- Making a computer read (classification?)
  - x: letters of sentences in some language
  - f(x): corresponding sound features (in context)
  - <x,f(x)>: Database of texts/corresponding sound features extracted from humans reading.
  - Type of x: a fixed-length array
  - Type of f(x): a fixed-length array

#### Supervised learning

- Training examples: <x,f(x)>
- Hypothesis space: set H of functions that (hopefully) contains the target function f(·)
- Result of learning: a function h(·)∈H approximating f(·)
- Examples are used to guide the algorithm to choose a good h(·)∈H

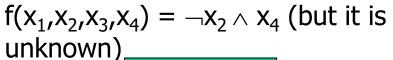
#### Supervised learning

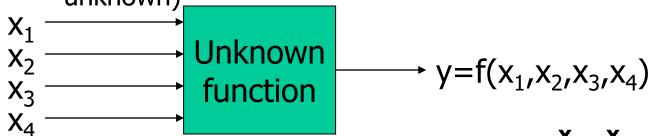
- h(·) is called a consistent hypothesis if it agrees with f(·) on all training examples
  - After observing the data, only some hypotheses in H are consistent. They form the so called version space : {h(·)∈H : h(x)=f(x) ∀ example x}
- A consistent learner always outputs a consistent hypothesis (i.e., it is 100% accurate on the training set)
- The empirical error is the fraction of training examples such that h(x)≠f(x) (0% in a consistent learner)

### **Example (boolean functions)**

Four boolean variables as input features:

$$x=(x_1,x_2,x_3,x_4)\in\{0,1\}^4$$





Training examples

$\mathbf{X}_{1}$	$\mathbf{X_2}$	$X_3$	$X_4$	у
0	0	1	1	1
1	0	0	1	1 1 0
1	0	1	1	1
1	1	0	0	0
1	1	1	0	0

#### **Hypothesis space 1**

 $X_4$ 

0

 $X_3$ 

 $X_2$ 

0

0

0

0

0

 No knowledge: H is the set of all boolean functions on 4 variables. |H|=2<sup>16</sup>≈64×10<sup>3</sup>

abies.	0	1	0	1	?
:2 <sup>16</sup> ≈64×10 <sup>3</sup>	0	1	1	0	?
	0	1	1	1	?
	1	0	0	0	?
	1	0	0	1	?
	1	0	1	0	?
	1	0	1	1	?
	4	4	^	^	

### **Hypothesis space 1**

- After observing 5
   examples we are left
   with
   2<sup>16-5</sup>=2<sup>11</sup>=2048
   consistent
   hypotheses
- A randomly-picked consistent h(·) is unlikely to approximate f(·) well...
- What is wrong?

<b>X</b> <sub>1</sub>	$\mathbf{X_2}$	$X_3$	$X_4$	<u> </u>
	<b>x</b> <sub>2</sub> <b>0</b>		<b>X</b> <sub>4</sub>	?
0	0	0 0	1	?
0	0	1	0	?
0	0	1	1	1
0	1	0	0	?
0	1	0 0	1 0 1 0 1 0	?
0	1	1	0	?
0	1	1	1	?
1	0	0	0	?
1	0	<b>0</b> 0	1	1
1	0	1	0	?
1	0	1	1	1
1	1	0 <b>0</b>	0	0
0 0 0 0 0 0 0 1 1 1 1 1 1	1	0	0 1 0 1	? ? ? ? ? ? 1 ? 1 0 ? 0 ?
1	1	1	0	0
1	1	1	1	?

#### **Hypothesis space 2**

- A literal is a variable x<sub>i</sub> or its negation ¬x<sub>i</sub>
- A term is the conjunction of literals
- H=  $\{\text{terms over } x_1, x_2, x_3, x_4\}$
- |H|=3<sup>4</sup>=81 (each variable is affirmed, is negated, isn't present)
- Learning algorithm:
  - Initial  $h(\cdot)$  = conjunction of all possible literals
  - Remove literals associated with inconsistent positive examples

### Learning conjunctions

- 1.  $h = -x_1x_1 x_2x_2 x_3x_3 x_4x_4$
- 2. Observe 1<sup>st</sup> training example, remove literals  $x_1, x_2, \neg x_3$ , and  $\neg x_4$   $h = \neg x_1 \neg x_2 x_3 x_4$
- 3. Observe  $2^{nd}$  training example, remove literals  $\neg x_1$  and  $x_3$   $h = \neg x_2 x_4$
- 4. Observe  $3^{rd}$  training example: nothing to do (h =  $\neg x_2 x_4$ )
- 5. No more positive training examples Output  $h = \neg x_2 x_4$