

# ZACH BELLAY

[/zachbellay](https://github.com/zachbellay)[zbellay@scu.edu](mailto:zbellay@scu.edu)

(425) 444-7070

[/in/zachbellay](https://www.linkedin.com/in/zachbellay)

**Objective:** Masters Computer Engineering student looking for full-time positions in computer vision or machine learning starting after June 2020.

## EXPERIENCE

### FORD MOTOR COMPANY | PRODUCT DEVELOPMENT INTERN

Jun 2019 - Sep 2019 | Palo Alto, CA

- Developed and deployed small sensor network from scratch using Kubernetes, Docker, InfluxDB, Flask, Unicorn, LoRa, Arduino, The Things Network, LoRaWAN, and Fusion 360.

### ONEPOINTONE | COMPUTER VISION INTERN

Jan 2018 - Mar 2019 | San Jose, CA

- Created multi-camera IoT array to capture images of plants growing on a vertical plane.
- Developed image processing pipeline to remove lens distortion and to perform image stitching.

### FORD MOTOR COMPANY | PRODUCT DEVELOPMENT INTERN

Jun 2018 - Sep 2018 | Palo Alto, CA

- Developed applications for Ford's "Arduino for cars."
- Created vehicle crash data marketplace proof of concept using Ethereum blockchain and InterPlanetary File System.

### SCU ROBOTIC SYSTEMS LAB | SOFTWARE ENGINEERING INTERN

Jan 2017 - Sep 2017 | Santa Clara, CA

- Built system to control indoor vertical farming prototype using JSON-based Raspberry Pi to Arduino serial protocol, secure RESTful API with Python Flask via TLS, and web interface for API.
- Prototype was used in a pitch that resulted in \$1.4M seed funding.

## PROJECTS

### ROBUST MOVING OBJECT DETECTION

June 2018 - May 2019

- Developed and implemented robust moving object detection algorithm with Python for senior design project.
- Paper accepted at SPIE Defense + Commercial Sensing Conference.

### FINGERPRINT MATCHING

May 2019

- Compared SIFT, SURF, and CNN feature extraction methods for fingerprint matching on the SOCOFing fingerprint dataset.

### "SELF DRIVING" FISH TANK

June 2017 - Present

- Designed omnidirectional robot with mounted fish bowl in Fusion 360.
- Developing drivers to capture goldfish position with OpenCV and translate into commands to drive robot.

## AWARDS

2019	2 <sup>nd</sup> Place	Ford Summer Intern Hackathon
2019	Best in Session	Senior Design Conference
2018	1 <sup>st</sup> Place	Ford Summer Intern Hackathon
2018	2 <sup>nd</sup> Place	Hack for Humanity
2016	2 <sup>nd</sup> Place	Google Games

## EDUCATION

### SANTA CLARA UNIVERSITY

Santa Clara, CA | June 2020

M.S. in Computer Engineering  
Pursuing thesis in GANs  
GPA: 3.400/4.0

### SANTA CLARA UNIVERSITY

Santa Clara, CA | June 2019

B.S. in Computer Engineering  
GPA: 3.257/4.0

## COURSEWORK

### GRADUATE

Computer Vision I, II  
Digital Signal Processing  
ML & DSP on FPGA  
Computational Creativity  
Adv. Operating Systems  
Adv. Computer Architecture

### UNDERGRADUATE

Data Science  
Applied Machine Learning  
Theory of Algorithms  
Software Engineering  
Computer Networks  
Operating Systems  
Computer Architecture  
Web Infrastructure

## SKILLS

### LANGUAGES

Python • C • C++ • MATLAB  
JavaScript • HTML/CSS • Bash

### MACHINE LEARNING & COMPUTER VISION

Keras • Scikit-learn • OpenCV  
Numpy • Pandas • Jupyter  
Notebook • Matplotlib

### BACKEND & CLOUD

Docker • Kubernetes • Helm  
MongoDB • MySQL • InfluxDB  
AWS EC2 • Unicorn • Flask

### HARDWARE

Raspberry Pi • Jetson Nano  
Teensy 3.2/3.6 • Arduino  
Uno/Mega Soldering

### CAD

Fusion 360 • Blender • 3D Printing