Solutions to Exercises

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Problem Set 2.7, page 117

$$\mathbf{1} \ A = \begin{bmatrix} 1 & 0 \\ 9 & 3 \end{bmatrix} \ \text{has} \ A^{\mathrm{T}} = \begin{bmatrix} 1 & 9 \\ 0 & 3 \end{bmatrix}, A^{-1} = \begin{bmatrix} 1 & 0 \\ -3 & 1/3 \end{bmatrix}, (A^{-1})^{\mathrm{T}} = (A^{\mathrm{T}})^{-1} = \begin{bmatrix} 1 & -3 \\ 0 & 1/3 \end{bmatrix};$$

$$A = \begin{bmatrix} 1 & c \\ c & 0 \end{bmatrix} \ \text{has} \ A^{\mathrm{T}} = A \ \text{and} \ A^{-1} = \frac{1}{c^2} \begin{bmatrix} 0 & c \\ c & -1 \end{bmatrix} = (A^{-1})^{\mathrm{T}}.$$

- **2** $(AB)^{\mathrm{T}} = \begin{bmatrix} 1 & 2 \\ 3 & 7 \end{bmatrix} = B^{\mathrm{T}}A^{\mathrm{T}}$. This answer is different from $A^{\mathrm{T}}B^{\mathrm{T}}$ (except when AB = BA and transposing gives $B^{\mathrm{T}}A^{\mathrm{T}} = A^{\mathrm{T}}B^{\mathrm{T}}$).
- **3** (a) $((AB)^{-1})^{\mathrm{T}} = (B^{-1}A^{-1})^{\mathrm{T}} = (A^{-1})^{\mathrm{T}}(B^{-1})^{\mathrm{T}}$. This is also $(A^{\mathrm{T}})^{-1}(B^{\mathrm{T}})^{-1}$. (b) If U is upper triangular, so is U^{-1} : then $(U^{-1})^{\mathrm{T}}$ is *lower* triangular.
- **4** $A = \begin{bmatrix} 0 & 1 \\ 0 & 0 \end{bmatrix}$ has $A^2 = 0$. But the diagonal of A^TA has dot products of columns of A with *themselves*. If $A^TA = 0$, zero dot products \Rightarrow zero columns $\Rightarrow A =$ zero matrix.

5 (a)
$$x^{T}Ay = \begin{bmatrix} 0 & 1 \end{bmatrix} \begin{bmatrix} 1 & 2 & 3 \\ 4 & 5 & 6 \end{bmatrix} \begin{bmatrix} 0 \\ 1 \\ 0 \end{bmatrix} = 5$$

- (b) This is the row $x^{\mathrm{T}}A = \begin{bmatrix} 4 & 5 & 6 \end{bmatrix}$ times y.
- (c) This is also the row x^{T} times $Ay = \begin{bmatrix} 2 \\ 5 \end{bmatrix}$.

6
$$M^{\mathrm{T}} = \begin{bmatrix} A^{\mathrm{T}} & C^{\mathrm{T}} \\ B^{\mathrm{T}} & D^{\mathrm{T}} \end{bmatrix}$$
; $M^{\mathrm{T}} = M$ needs $A^{\mathrm{T}} = A$ and $B^{\mathrm{T}} = C$ and $D^{\mathrm{T}} = D$.

- 7 (a) False: $\begin{bmatrix} 0 & A \\ A & 0 \end{bmatrix}$ is symmetric only if $A = A^{T}$.
 - (b) False: The transpose of AB is $B^{T}A^{T}=BA$. So $(AB)^{T}=AB$ needs BA=AB.

- (c) True: Invertible symmetric matrices have symmetric inverses! Easiest proof is to transpose $AA^{-1} = I$.
- (d) True: $(ABC)^{\mathrm{T}}$ is $C^{\mathrm{T}}B^{\mathrm{T}}A^{\mathrm{T}} (= CBA \text{ for symmetric matrices } A, B, \text{ and } C)$.
- **8** The 1 in row 1 has n choices; then the 1 in row 2 has n-1 choices ... (n!) overall).

$$\textbf{9} \ P_1 P_2 \ = \ \begin{bmatrix} 0 & 1 & 0 \\ 0 & 0 & 1 \\ 1 & 0 & 0 \end{bmatrix} \begin{bmatrix} 1 & 0 & 0 \\ 0 & 0 & 1 \\ 0 & 1 & 0 \end{bmatrix} = \begin{bmatrix} 0 & 0 & 1 \\ 0 & 1 & 0 \\ 1 & 0 & 0 \end{bmatrix} \text{ but } P_2 P_1 \ = \ \begin{bmatrix} 0 & 1 & 0 \\ 1 & 0 & 0 \\ 0 & 0 & 1 \end{bmatrix}.$$
 If P_3 and P_4 exchange $\emph{different}$ pairs of rows, $P_3 P_4 = P_4 P_3 = \text{both exchanges}.$

10 (3,1,2,4) and (2,3,1,4) keep 4 in place; 6 more even P's keep 1 or 2 or 3 in place; (2, 1, 4, 3) and (3, 4, 1, 2) and (4, 3, 2, 1) exchange 2 pairs. (1, 2, 3, 4) makes 12.

11
$$PA = \begin{bmatrix} 0 & 1 & 0 \\ 0 & 0 & 1 \\ 1 & 0 & 0 \end{bmatrix} \begin{bmatrix} 0 & 0 & 6 \\ 1 & 2 & 3 \\ 0 & 4 & 5 \end{bmatrix} = \begin{bmatrix} 1 & 2 & 3 \\ 0 & 4 & 5 \\ 0 & 0 & 6 \end{bmatrix}$$
 is upper triangular. Multiplying A

on the right by a permutation matrix P_2 exchanges the columns of A. To make this A lower triangular, we also need P_1 to exchange rows 2 and 3:

$$P_1AP_2 = \begin{bmatrix} 1 & & & \\ & & 1 \\ & 1 & \end{bmatrix} A \begin{bmatrix} & & 1 \\ & 1 & \\ 1 & & \end{bmatrix} = \begin{bmatrix} 6 & 0 & 0 \\ 5 & 4 & 0 \\ 3 & 2 & 1 \end{bmatrix}.$$

12 $(Px)^{\mathrm{T}}(Py) = x^{\mathrm{T}}P^{\mathrm{T}}Py = x^{\mathrm{T}}y$ since $P^{\mathrm{T}}P = I$. In general $Px \cdot y$

Non-equality where
$$P \neq P^{T}$$
:
$$\begin{bmatrix} 0 & 1 & 0 \\ 0 & 0 & 1 \\ 1 & 0 & 0 \end{bmatrix} \begin{bmatrix} 1 \\ 2 \\ 3 \end{bmatrix} \cdot \begin{bmatrix} 1 \\ 2 \\ 3 \end{bmatrix} \cdot \begin{bmatrix} 0 & 1 & 0 \\ 0 & 0 & 1 \\ 1 & 0 & 0 \end{bmatrix} \begin{bmatrix} 1 \\ 1 \\ 2 \end{bmatrix}.$$

13 A cyclic $P = \begin{bmatrix} 0 & 1 & 0 \\ 0 & 0 & 1 \\ 1 & 0 & 0 \end{bmatrix}$ or its transpose will have $P^3 = I: (1,2,3) \to (2,3,1) \to (2,3,1)$

$$(3,1,2) \to (1,2,3). \text{ The permutation } \widehat{P} = \begin{bmatrix} 1 & 0 \\ 0 & P \end{bmatrix} \text{ for the same } P \text{ has } \widehat{P}^4 = \widehat{P} \neq I.$$

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14 The "reverse identity" P takes $(1, \ldots, n)$ into $(n, \ldots, 1)$. When rows and also columns are reversed, the 1, 1 and n, n entries of A change places in PAP. So do the 1, n and n, 1 entries. In general $(PAP)_{ij}$ is $(A)_{n-i+1, n-j+1}$.

- **15** (a) If P sends row 1 to row 4, then P^{T} sends row 4 to row 1 (b) $P = \begin{bmatrix} E & 0 \\ 0 & E \end{bmatrix} = P^{\mathrm{T}}$ with $E = \begin{bmatrix} 0 & 1 \\ 1 & 0 \end{bmatrix}$ moves all rows: 1 and 2 are exchanged, 3 and 4 are exchanged.
- **16** $A^2 B^2$ and also ABA are symmetric if A and B are symmetric. But (A+B)(A-B) and ABAB are generally *not* symmetric.
- **17** (a) $S = \begin{bmatrix} 1 & 1 \\ 1 & 1 \end{bmatrix} = S^{\mathrm{T}}$ is not invertible (b) $S = \begin{bmatrix} 0 & 1 \\ 1 & 1 \end{bmatrix}$ needs row exchange (c) $S = \begin{bmatrix} 1 & 1 \\ 1 & 0 \end{bmatrix}$ has pivots $D = \begin{bmatrix} 1 & 0 \\ 0 & -1 \end{bmatrix}$: no real square root.
- **18** (a) 5+4+3+2+1=15 independent entries if $S=S^{T}$ (b) L has 10 and D has 5; total 15 in LDL^{T} (c) Zero diagonal if $A^{T}=-A$, leaving 4+3+2+1=10 choices.
- **19** (a) The transpose of $A^{\mathrm{T}}SA$ is $A^{\mathrm{T}}S^{\mathrm{T}}A^{\mathrm{T}} = A^{\mathrm{T}}SA = n$ by n when $S^{\mathrm{T}} = S$ (any m by n matrix A) (b) $(A^{\mathrm{T}}A)_{jj} = (\operatorname{column} j \text{ of } A) \cdot (\operatorname{column} j \text{ of } A) = (\operatorname{length squared of column } j) \geq 0$.
- $\mathbf{20} \begin{bmatrix} 1 & 3 \\ 3 & 2 \end{bmatrix} = \begin{bmatrix} 1 & 0 \\ 3 & 1 \end{bmatrix} \begin{bmatrix} 1 & 0 \\ 0 & -7 \end{bmatrix} \begin{bmatrix} 1 & 3 \\ 0 & 1 \end{bmatrix}; \quad \begin{bmatrix} 1 & b \\ b & c \end{bmatrix} = \begin{bmatrix} 1 & 0 \\ b & 1 \end{bmatrix} \begin{bmatrix} 1 & 0 \\ 0 & c b^2 \end{bmatrix} \begin{bmatrix} 1 & b \\ 0 & 1 \end{bmatrix}$ $\begin{bmatrix} 2 & -1 & 0 \\ -1 & 2 & -1 \\ 0 & -1 & 2 \end{bmatrix} = \begin{bmatrix} 1 & 0 \\ -\frac{1}{2} & 1 \\ 0 & -\frac{2}{3} & 1 \end{bmatrix} \begin{bmatrix} 2 & 0 \\ \frac{3}{2} & \frac{4}{3} \end{bmatrix} \begin{bmatrix} 1 & -\frac{1}{2} & 0 \\ 1 & -\frac{2}{3} & 1 \end{bmatrix} = \mathbf{LDL}^{\mathrm{T}}.$
- 21 Elimination on a symmetric 3 by 3 matrix leaves a symmetric lower right 2 by 2 matrix.

$$\begin{bmatrix} 2 & 4 & 8 \\ 4 & 3 & 9 \\ 8 & 9 & 0 \end{bmatrix} \text{ and } \begin{bmatrix} 1 & b & c \\ b & d & e \\ c & e & f \end{bmatrix} \text{ lead to } \begin{bmatrix} -5 & -7 \\ -7 & -32 \end{bmatrix} \text{ and } \begin{bmatrix} d - b^2 & e - bc \\ e - bc & f - c^2 \end{bmatrix} \text{: symmetric!}$$

$$\mathbf{22} \begin{bmatrix} 1 \\ 1 \\ 1 \end{bmatrix} A = \begin{bmatrix} 1 \\ 0 & 1 \\ 2 & 3 & 1 \end{bmatrix} \begin{bmatrix} 1 & 0 & 1 \\ & 1 & 1 \\ & & -1 \end{bmatrix}; \begin{bmatrix} 1 \\ & 1 \\ 1 \end{bmatrix} A = \begin{bmatrix} 1 \\ 1 & 1 \\ 2 & 0 & 1 \end{bmatrix} \begin{bmatrix} 1 & 2 & 0 \\ & -1 & 1 \\ & & 1 \end{bmatrix}$$

23
$$A = \begin{bmatrix} 0 & 0 & 0 & 1 \\ 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 \end{bmatrix} = P \text{ and } L = U = I.$$
 Elimination on this $A = P$ exchanges rows 1-2 then rows 2-3 then rows 3-4.

24
$$PA = LU$$
 is $\begin{bmatrix} 1 \\ 1 \\ 1 \end{bmatrix} \begin{bmatrix} 0 & 1 & 2 \\ 0 & 3 & 8 \\ 2 & 1 & 1 \end{bmatrix} = \begin{bmatrix} 1 \\ 0 & 1 \\ 0 & 1/3 & 1 \end{bmatrix} \begin{bmatrix} 2 & 1 & 1 \\ 3 & 8 \\ & -2/3 \end{bmatrix}$. If we wait to exchange and a_{12} is the pivot, $A = L_1 P_1 U_1 = \begin{bmatrix} 1 \\ 3 & 1 \\ & 1 \end{bmatrix} \begin{bmatrix} 1 \\ 1 \\ 1 \end{bmatrix} \begin{bmatrix} 2 & 1 & 1 \\ 0 & 1 & 2 \\ 0 & 0 & 2 \end{bmatrix}$.

wait to exchange and
$$a_{12}$$
 is the pivot, $A=L_1P_1U_1=\begin{bmatrix}1\\3&1\\1\end{bmatrix}\begin{bmatrix}1\\1\\1\end{bmatrix}\begin{bmatrix}2&1&1\\0&1&2\\0&0&2\end{bmatrix}.$

25 One way to decide even vs. odd is to count all pairs that P has in the wrong order. Then P is even or odd when that count is even or odd. Hard step: Show that an exchange always switches that count! Then 3 or 5 exchanges will leave that count odd.

26 (a)
$$E_{21} = \begin{bmatrix} 1 \\ -3 & 1 \\ \end{bmatrix}$$
 puts 0 in the 2, 1 entry of $E_{21}A$. Then $E_{21}AE_{21}^{T} = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 2 & 4 \\ 0 & 4 & 9 \end{bmatrix}$ is still symmetric, with zero also in its 1, 2 entry. (b) Now use $E_{32} = \begin{bmatrix} 1 \\ 1 \\ -2 & 1 \end{bmatrix}$

is still symmetric, with zero also in its 1, 2 entry. (b) Now use
$$E_{32}=\begin{bmatrix} 1 & & & \\ & 1 & & \\ & -2 & 1 & \\ & & \end{bmatrix}$$

to make the 3, 2 entry zero and $E_{32}E_{21}AE_{21}^{\mathrm{T}}E_{32}^{\mathrm{T}}=D$ also has zero in its 2, 3 entry Key point: Elimination from both sides (rows + columns) gives the symmetric LDL^{T} .

27
$$A = \begin{bmatrix} 0 & 1 & 2 & 3 \\ 1 & 2 & 3 & 0 \\ 2 & 3 & 0 & 1 \\ 3 & 0 & 1 & 2 \end{bmatrix} = A^{\mathrm{T}} \text{ has } 0, 1, 2, 3 \text{ in every row. I don't know any rules for a}$$

symmetric construction like this "Hankel matrix" with constant antidiagonals.

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28 Reordering the rows and/or the columns of $\begin{bmatrix} a & b \\ c & d \end{bmatrix}$ will move the entry **a**. So the result cannot be the transpose (which doesn't move **a**).

- **29** (a) Total currents are $A^{T}y = \begin{bmatrix} 1 & 0 & 1 \\ -1 & 1 & 0 \\ 0 & -1 & -1 \end{bmatrix} \begin{bmatrix} y_{BC} \\ y_{CS} \\ y_{BS} \end{bmatrix} = \begin{bmatrix} y_{BC} + y_{BS} \\ -y_{BC} + y_{CS} \\ -y_{CS} y_{BS} \end{bmatrix}.$
 - (b) Either way $(A\boldsymbol{x})^{\mathrm{T}}\boldsymbol{y} = \boldsymbol{x}^{\mathrm{T}}(A^{\mathrm{T}}\boldsymbol{y}) = x_By_{BC} + x_By_{BS} x_Cy_{BC} + x_Cy_{CS} x_Sy_{CS} x_Sy_{BS}$. Six terms.

$$\mathbf{30} \begin{bmatrix} 1 & 50 \\ 40 & 1000 \\ 2 & 50 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \end{bmatrix} = A\mathbf{x}; \ A^{\mathrm{T}}\mathbf{y} = \begin{bmatrix} 1 & 40 & 2 \\ 50 & 1000 & 50 \end{bmatrix} \begin{bmatrix} 700 \\ 3 \\ 3000 \end{bmatrix} = \begin{bmatrix} 6820 \\ 188000 \end{bmatrix} \ 1 \ \text{truck}$$

- **31** $Ax \cdot y$ is the cost of inputs while $x \cdot A^T y$ is the value of outputs.
- **32** $P^3 = I$ so three rotations for 360° ; P rotates every v around the (1, 1, 1) line by 120° .
- 33 $\begin{bmatrix} 1 & 2 \\ 4 & 9 \end{bmatrix} = \begin{bmatrix} 1 & 0 \\ 2 & 1 \end{bmatrix} \begin{bmatrix} 1 & 2 \\ 2 & 5 \end{bmatrix} = EH =$ (elementary matrix) times (symmetric matrix).
- **34** $L(U^{\mathrm{T}})^{-1}$ is lower triangular times lower triangular, so *lower triangular*. The transpose of $U^{\mathrm{T}}DU$ is $U^{\mathrm{T}}D^{\mathrm{T}}U^{\mathrm{T}} = U^{\mathrm{T}}DU$ again, so $U^{\mathrm{T}}DU$ is *symmetric*. The factorization multiplies lower triangular by symmetric to get LDU which is A.
- **35** These are groups: Lower triangular with diagonal 1's, diagonal invertible D, permutations P, orthogonal matrices with $Q^{\mathrm{T}} = Q^{-1}$.
- 36 Certainly B^{T} is northwest. B^2 is a full matrix! B^{-1} is southeast: $\begin{bmatrix} 1 & 1 \\ 1 & 0 \end{bmatrix}^{-1} = \begin{bmatrix} 0 & 1 \\ 1 & -1 \end{bmatrix}$. The rows of B are in reverse order from a lower triangular L, so B = PL. Then $B^{-1} = L^{-1}P^{-1}$ has the *columns* in reverse order from L^{-1} . So B^{-1} is *southeast*. Northwest B = PL times southeast PU is (PLP)U = upper triangular.
- 37 There are n! permutation matrices of order n. Eventually two powers of P must be the same permutation. And if $P^r = P^s$ then $P^{r-s} = I$. Certainly $r s \le n!$

$$P = \begin{bmatrix} P_2 & \\ & P_3 \end{bmatrix} \text{ is 5 by 5 with } P_2 = \begin{bmatrix} 0 & 1 \\ 1 & 0 \end{bmatrix} \text{ and } P_3 = \begin{bmatrix} 0 & 1 & 0 \\ 0 & 0 & 1 \\ 1 & 0 & 0 \end{bmatrix} \text{ and } P^6 = I.$$

- **38** To split the matrix M into (symmetric S) + (anti-symmetric A), the only choice is $S=\frac{1}{2}(M+M^{\rm T})$ and $A=\frac{1}{2}(M-M^{\rm T}).$
- **39** Start from $Q^{\mathrm{T}}Q=I$, as in $\begin{bmatrix} & \boldsymbol{q}_1^{\mathrm{T}} & \\ & \boldsymbol{q}_2^{\mathrm{T}} & \end{bmatrix} \begin{bmatrix} \boldsymbol{q}_1 & \boldsymbol{q}_2 \end{bmatrix} = \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix}$
 - (a) The diagonal entries give ${m q}_1^{
 m T}{m q}_1=1$ and ${m q}_2^{
 m T}{m q}_2=1$: unit vectors
 - (b) The off-diagonal entry is $\, {m q}_1^{\rm T} {m q}_2 = 0$ (and in general ${m q}_i^{\rm T} {m q}_j = 0$)
 - (c) The leading example for Q is the rotation matrix $\begin{bmatrix} \cos \theta & -\sin \theta \\ \sin \theta & \cos \theta \end{bmatrix}.$