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1 $\begin{bmatrix} 1 & 1 & 1 \\ 0 & 1 & 1 \\ 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} c_1 \\ c_2 \\ c_3 \end{bmatrix} = 0$ gives $c_3 = c_2 = c_1 = 0$. So those 3 column vectors are

independent. But $\begin{bmatrix} 1 & 1 & 1 & 2 \\ 0 & 1 & 1 & 3 \\ 0 & 0 & 1 & 4 \end{bmatrix} \begin{bmatrix} c \\ c \\ c \\ c \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix}$ is solved by $\mathbf{c} = (1, 1, -4, 1)$. Then $\mathbf{v}_1 + \mathbf{v}_2 - 4\mathbf{v}_3 + \mathbf{v}_4 = \mathbf{0}$ (dependent).

2 $\mathbf{v}_1, \mathbf{v}_2, \mathbf{v}_3$ are independent (the -1 's are in different positions). All six vectors in \mathbf{R}^4 are on the plane $(1, 1, 1, 1) \cdot \mathbf{v} = 0$ so no four of these six vectors can be independent.

3 If $a = 0$ then column 1 = $\mathbf{0}$; if $d = 0$ then $b(\text{column 1}) - a(\text{column 2}) = \mathbf{0}$; if $f = 0$ then all columns end in zero (they are all in the xy plane, they must be dependent).

4 $U\mathbf{x} = \begin{bmatrix} a & b & c \\ 0 & d & e \\ 0 & 0 & f \end{bmatrix} \begin{bmatrix} x \\ y \\ z \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix}$ gives $z = 0$ then $y = 0$ then $x = 0$ (by back substitution). A square triangular matrix has independent columns (invertible matrix) when its diagonal has no zeros.

5 (a) $\begin{bmatrix} 1 & 2 & 3 \\ 3 & 1 & 2 \\ 2 & 3 & 1 \end{bmatrix} \rightarrow \begin{bmatrix} 1 & 2 & 3 \\ 0 & -5 & -7 \\ 0 & -1 & -5 \end{bmatrix} \rightarrow \begin{bmatrix} 1 & 2 & 3 \\ 0 & -5 & -7 \\ 0 & 0 & -18/5 \end{bmatrix}$: invertible \Rightarrow independent columns.

(b) $\begin{bmatrix} 1 & 2 & -3 \\ -3 & 1 & 2 \\ 2 & -3 & 1 \end{bmatrix} \rightarrow \begin{bmatrix} 1 & 2 & -3 \\ 0 & 7 & -7 \\ 0 & -7 & 7 \end{bmatrix} \rightarrow \begin{bmatrix} 1 & 2 & -3 \\ 0 & 7 & -7 \\ 0 & 0 & 0 \end{bmatrix}$; $A \begin{bmatrix} 1 \\ 1 \\ 1 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix}$ columns add to $\mathbf{0}$.

6 Columns 1, 2, 4 are independent. Also 1, 3, 4 and 2, 3, 4 and others (but not 1, 2, 3). Same column numbers (not same columns!) for A . This is because $EA = U$ for the matrix E that subtracts 2 times row 1 from row 4. So A and U have the same nullspace (same dependencies of columns).

- 7** The sum $v_1 - v_2 + v_3 = \mathbf{0}$ because $(w_2 - w_3) - (w_1 - w_3) + (w_1 - w_2) = \mathbf{0}$. So the differences are *dependent* and the difference matrix is singular: $A = \begin{bmatrix} 0 & 1 & 1 \\ 1 & 0 & -1 \\ -1 & -1 & 0 \end{bmatrix}$.
- 8** If $c_1(w_2 + w_3) + c_2(w_1 + w_3) + c_3(w_1 + w_2) = \mathbf{0}$ then $(c_2 + c_3)w_1 + (c_1 + c_3)w_2 + (c_1 + c_2)w_3 = \mathbf{0}$. Since the w 's are independent, $c_2 + c_3 = c_1 + c_3 = c_1 + c_2 = 0$. The only solution is $c_1 = c_2 = c_3 = 0$. Only this combination of v_1, v_2, v_3 gives $\mathbf{0}$.
(changing -1 's to 1 's for the matrix A in solution **7** above makes A invertible.)
- 9** (a) The four vectors in \mathbf{R}^3 are the columns of a 3 by 4 matrix A . There is a nonzero solution to $Ax = \mathbf{0}$ because there is at least one free variable. (b) Two vectors are dependent if $[v_1 \ v_2]$ has rank 0 or 1. (OK to say "they are on the same line" or "one is a multiple of the other" but *not* " v_2 is a multiple of v_1 " —since v_1 might be $\mathbf{0}$.) (c) A nontrivial combination of v_1 and $\mathbf{0}$ gives $\mathbf{0}$: $0v_1 + 3(0, 0, 0) = \mathbf{0}$.
- 10** The plane is the nullspace of $A = [1 \ 2 \ -3 \ -1]$. Three free variables give three independent solutions $(x, y, z, t) = (2, -1, 0, 0)$ and $(3, 0, 1, 0)$ and $(1, 0, 0, 1)$. Combinations of those special solutions give more solutions (all solutions).
- 11** (a) Line in \mathbf{R}^3 (b) Plane in \mathbf{R}^3 (c) All of \mathbf{R}^3 (d) All of \mathbf{R}^3 .
- 12** b is in the column space when $Ax = b$ has a solution; c is in the row space when $A^T y = c$ has a solution. *False*. The zero vector is always in the row space.
- 13** The column space and row space of A and U all have the same dimension $= 2$. *The row spaces of A and U are the same*, because the rows of U are combinations of the rows of A (and vice versa!).
- 14** $v = \frac{1}{2}(v + w) + \frac{1}{2}(v - w)$ and $w = \frac{1}{2}(v + w) - \frac{1}{2}(v - w)$. The two pairs *span* the same space. They are a basis when v and w are *independent*.
- 15** The n independent vectors span a space of dimension n . They are a *basis* for that space. If they are the columns of A then m is *not less* than n ($m \geq n$). *Invertible* if $m = n$.

- 16** These bases are not unique! (a) $(1, 1, 1, 1)$ for the space of all constant vectors (c, c, c, c) (b) $(1, -1, 0, 0), (1, 0, -1, 0), (1, 0, 0, -1)$ for the space of vectors with sum of components = 0 (c) $(1, -1, -1, 0), (1, -1, 0, -1)$ for the space perpendicular to $(1, 1, 0, 0)$ and $(1, 0, 1, 1)$ (d) The columns of I are a basis for its column space, the empty set is a basis (by convention) for $N(I) = Z = \{\text{zero vector}\}$.
- 17** The column space of $U = \begin{bmatrix} 1 & 0 & 1 & 0 & 1 \\ 0 & 1 & 0 & 1 & 0 \end{bmatrix}$ is \mathbf{R}^2 so take any bases for \mathbf{R}^2 ; (row 1 and row 2) or (row 1 and row 1 + row 2) or (row 1 and - row 2) are bases for the row space of U .
- 18** (a) The 6 vectors *might not* span \mathbf{R}^4 (b) The 6 vectors *are not* independent (c) Any four *might be* a basis.
- 19** n independent columns \Rightarrow rank n . Columns span $\mathbf{R}^m \Rightarrow$ rank m . Columns are basis for $\mathbf{R}^m \Rightarrow \text{rank} = m = n$. The rank counts the number of *independent* columns.
- 20** One basis is $(2, 1, 0), (-3, 0, 1)$. A basis for the intersection with the xy plane is $(2, 1, 0)$. The normal vector $(1, -2, 3)$ is a basis for the line perpendicular to the plane.
- 21** (a) The only solution to $Ax = 0$ is $x = 0$ because *the columns are independent* (b) $Ax = b$ is solvable because *the columns span* \mathbf{R}^5 . Key point: A basis gives exactly one solution for every b .
- 22** (a) True (b) False because the basis vectors for \mathbf{R}^6 might not be in S .
- 23** Columns 1 and 2 are bases for the (**different**) column spaces of A and U ; rows 1 and 2 are bases for the (**equal**) row spaces of A and U ; $(1, -1, 1)$ is a basis for the (**equal**) nullspaces.
- 24** (a) *False* $A = \begin{bmatrix} 1 & 1 \end{bmatrix}$ has dependent columns, independent row (b) *False* Column space \neq row space for $A = \begin{bmatrix} 0 & 1 \\ 0 & 0 \end{bmatrix}$ (c) *True*: Both dimensions = 2 if A is invertible, dimensions = 0 if $A = 0$, otherwise dimensions = 1 (d) *False*, columns may be dependent, in that case not a basis for $C(A)$.

25 A has rank 2 if $c = 0$ and $d = 2$; $B = \begin{bmatrix} c & d \\ d & c \end{bmatrix}$ has rank 2 except when $c = d$ or $c = -d$.

26 (a) Basis for all diagonal matrices: $\begin{bmatrix} 1 & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{bmatrix}, \begin{bmatrix} 0 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 0 \end{bmatrix}, \begin{bmatrix} 0 & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 1 \end{bmatrix}$

(b) Add $\begin{bmatrix} 0 & 1 & 0 \\ 1 & 0 & 0 \\ 0 & 0 & 0 \end{bmatrix}, \begin{bmatrix} 0 & 0 & 1 \\ 0 & 0 & 0 \\ 1 & 0 & 0 \end{bmatrix}, \begin{bmatrix} 0 & 0 & 0 \\ 0 & 0 & 1 \\ 0 & 1 & 0 \end{bmatrix}$ = basis for symmetric matrices.

(c) $\begin{bmatrix} 0 & 1 & 0 \\ -1 & 0 & 0 \\ 0 & 0 & 0 \end{bmatrix}, \begin{bmatrix} 0 & 0 & 1 \\ 0 & 0 & 0 \\ -1 & 0 & 0 \end{bmatrix}, \begin{bmatrix} 0 & 0 & 0 \\ 0 & 0 & 1 \\ 0 & -1 & 0 \end{bmatrix}$.

These are simple bases (among many others) for (a) diagonal matrices (b) symmetric matrices (c) skew-symmetric matrices. The dimensions are 3, 6, 3.

27 $I, \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 2 \end{bmatrix}, \begin{bmatrix} 1 & 0 & 0 \\ 0 & 2 & 0 \\ 0 & 0 & 1 \end{bmatrix}, \begin{bmatrix} 1 & 1 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix}, \begin{bmatrix} 1 & 0 & 1 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix}, \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 1 \\ 0 & 0 & 1 \end{bmatrix};$

echelon matrices do *not* form a subspace; they *span* the upper triangular matrices (not every U is an echelon matrix).

28 $\begin{bmatrix} 1 & 0 & 0 \\ -1 & 0 & 0 \end{bmatrix}, \begin{bmatrix} 0 & 1 & 0 \\ 0 & -1 & 0 \end{bmatrix}, \begin{bmatrix} 0 & 0 & 1 \\ 0 & 0 & -1 \end{bmatrix}; \begin{bmatrix} 1 & -1 & 0 \\ -1 & 1 & 0 \end{bmatrix}$ and $\begin{bmatrix} 1 & 0 & -1 \\ -1 & 0 & 1 \end{bmatrix}$.

29 (a) The invertible matrices span the space of all 3 by 3 matrices (b) The rank one matrices also span the space of all 3 by 3 matrices (c) I by itself spans the space of all multiples cI .

30 $\begin{bmatrix} -1 & 2 & 0 \\ 0 & 0 & 0 \end{bmatrix}, \begin{bmatrix} -1 & 0 & 2 \\ 0 & 0 & 0 \end{bmatrix}, \begin{bmatrix} 0 & 0 & 0 \\ -1 & 2 & 0 \end{bmatrix}, \begin{bmatrix} 0 & 0 & 0 \\ -1 & 0 & 2 \end{bmatrix}$. **Dimension = 4.**

31 (a) $y(x) = \text{constant } C$ (b) $y(x) = 3x$. (c) $y(x) = 3x + C = y_p + y_n$ solves $y' = 3$.

32 $y(0) = 0$ requires $A + B + C = 0$. One basis is $\cos x - \cos 2x$ and $\cos x - \cos 3x$.

- 33** (a) $y(x) = e^{2x}$ is a basis for all solutions to $y' = 2y$ (b) $y = x$ is a basis for all solutions to $dy/dx = y/x$ (First-order linear equation \Rightarrow 1 basis function in solution space).
- 34** $y_1(x), y_2(x), y_3(x)$ can be $x, 2x, 3x$ (dim 1) or $x, 2x, x^2$ (dim 2) or x, x^2, x^3 (dim 3).
- 35** Basis $1, x, x^2, x^3$, for cubic polynomials; basis $x - 1, x^2 - 1, x^3 - 1$ for the subspace with $p(1) = 0$.
- 36** Basis for **S**: $(1, 0, -1, 0), (0, 1, 0, 0), (1, 0, 0, -1)$; basis for **T**: $(1, -1, 0, 0)$ and $(0, 0, 2, 1)$; **S** \cap **T** = multiples of $(3, -3, 2, 1)$ = nullspace for 3 equations in \mathbf{R}^4 has dimension 1.
- 37** The subspace of matrices that have $AS = SA$ has dimension *three*. The 3 numbers a, b, c can be chosen independently in A .
- 38** (a) No, 2 vectors don't span \mathbf{R}^3 (b) No, 4 vectors in \mathbf{R}^3 are dependent (c) Yes, a basis (d) No, these three vectors are dependent
- 39** If the 5 by 5 matrix $[A \ b]$ is invertible, b is not a combination of the columns of A : no solution to $Ax = b$. If $[A \ b]$ is singular, and the 4 columns of A are independent (rank 4), b is a combination of those columns. In this case $Ax = b$ has a solution.
- 40** (a) The functions $y = \sin x, y = \cos x, y = e^x, y = e^{-x}$ are a basis for solutions to $d^4y/dx^4 = y(x)$.
- (b) A particular solution to $d^4y/dx^4 = y(x) + 1$ is $y(x) = -1$. The complete solution is $y(x) = -1 + c_1 \sin x + c_2 \cos x + c_3 e^x + c_4 e^{-x}$ (or use another basis for the nullspace of the 4th derivative).
- 41**
$$I = \begin{bmatrix} & 1 \\ 1 & \\ & \\ & 1 \end{bmatrix} - \begin{bmatrix} & 1 \\ & \\ 1 & \\ & \end{bmatrix} + \begin{bmatrix} & 1 \\ & 1 \\ 1 & \\ & \end{bmatrix} + \begin{bmatrix} 1 & \\ & 1 \\ & 1 \\ & \end{bmatrix} - \begin{bmatrix} & 1 \\ 1 & \\ & 1 \\ & \end{bmatrix}.$$
 The six P 's are dependent.
Those five are independent: The 4th has $P_{11} = 1$ and cannot be a combination of the others. Then the 2nd cannot be (from $P_{32} = 1$) and also 5th ($P_{32} = 1$). Continuing, a nonzero combination of all five could not be zero. Further challenge: How many independent 4 by 4 permutation matrices?

- 42** The dimension of \mathcal{S} spanned by all rearrangements of \mathbf{x} is (a) zero when $\mathbf{x} = \mathbf{0}$
 (b) one when $\mathbf{x} = (1, 1, 1, 1)$ (c) three when $\mathbf{x} = (1, 1, -1, -1)$ because all rearrangements of this \mathbf{x} are perpendicular to $(1, 1, 1, 1)$ (d) four when the \mathbf{x} 's are not equal and don't add to zero. **No \mathbf{x} gives $\dim \mathcal{S} = 2$.** I owe this nice problem to Mike Artin—the answers are the same in higher dimensions: $0, 1, n - 1, n$.

- 43** The problem is to show that the \mathbf{u} 's, \mathbf{v} 's, \mathbf{w} 's together are independent. We know the \mathbf{u} 's and \mathbf{v} 's together are a basis for \mathbf{V} , and the \mathbf{u} 's and \mathbf{w} 's together are a basis for \mathbf{W} . Suppose a combination of \mathbf{u} 's, \mathbf{v} 's, \mathbf{w} 's gives $\mathbf{0}$. **To be proved:** All coefficients = zero.

Key idea: In that combination giving $\mathbf{0}$, the part \mathbf{x} from the \mathbf{u} 's and \mathbf{v} 's is in \mathbf{V} . So the part from the \mathbf{w} 's is $-\mathbf{x}$. This part is now in \mathbf{V} and also in \mathbf{W} . But if $-\mathbf{x}$ is in $\mathbf{V} \cap \mathbf{W}$ it is a combination of \mathbf{u} 's only. Now the combination giving $\mathbf{0}$ uses only \mathbf{u} 's and \mathbf{v} 's (independent in \mathbf{V} !) so all coefficients of \mathbf{u} 's and \mathbf{v} 's must be zero. Then $\mathbf{x} = \mathbf{0}$ and the coefficients of the \mathbf{w} 's are also zero.

- 44** The inputs to multiplication by an m by n matrix fill \mathbf{R}^n : dimension n . The outputs (column space!) have dimension r . The nullspace has $n - r$ special solutions. The formula becomes $r + (n - r) = n$.

- 45** If the left side of $\dim(\mathbf{V}) + \dim(\mathbf{W}) = \dim(\mathbf{V} \cap \mathbf{W}) + \dim(\mathbf{V} + \mathbf{W})$ is greater than n , then $\dim(\mathbf{V} \cap \mathbf{W})$ must be greater than zero. So $\mathbf{V} \cap \mathbf{W}$ contains nonzero vectors.

Oh here is a more basic approach: Put a basis for \mathbf{V} and then a basis for \mathbf{W} in the columns of a matrix A . Then A has more columns than rows and there is a nonzero solution to $A\mathbf{x} = \mathbf{0}$. That \mathbf{x} gives a combination of the \mathbf{V} columns = a combination of the \mathbf{W} columns.

- 46** If $A^2 = \text{zero matrix}$, this says that each column of A is in the nullspace of A . If the column space has dimension r , the nullspace has dimension $10 - r$. So we must have $r \leq 10 - r$ and this leads to $r \leq 5$.