Note - eq 3.47 One line isn't so clear, but

$$(VD^{2}V^{T} + \lambda I)(VD^{2}V^{T} + \lambda I)^{-1} = I$$

$$\Rightarrow (VD^{2}V^{T} + \lambda I)(VD^{2}V^{T} + \lambda I)^{-1}V = V$$

$$\Rightarrow (D^{2}V^{T} + \lambda V^{T})(VD^{2}V^{T} + \lambda I)^{-1}V = I$$

$$\Rightarrow (D^{2} + \lambda I)V^{T}(VD^{2}V^{T} + \lambda I)^{-1}V = I$$

and so

$$V^{T}(VD^{2}V^{T} + \lambda I)^{-1}V = (D^{2} + \lambda I)^{-1}.$$

**3.1** Recall the method of using repeated simple linear regression to do multiple lienar regression: We form an orthogonal spanning set  $z_1,\ldots,z_p$  of the column space in such a way that  $z_1,\ldots,z_k$  spans the span of the first k columns of X. We finally regress y onto  $z_p$  to obtain  $\hat{\beta}_p$ . But we can do more: If  $\gamma_j = \langle y, z_j \rangle$ , then  $\hat{y} = \sum_j \frac{\gamma_j}{\|z_j\|^2} z_j$  is the orthogonal projection onto the column space of X in the full rank case. What's more,  $\sum_{j < p} \frac{\gamma_j}{\|z_j\|^2} z_j$  is the result of using only the first p-1 features. Let  $r_p = y - \hat{y}$ . Recall that  $\hat{\beta}_p = \frac{\gamma_p}{\|z_p\|^2}$ , and so

$$RSS_0 = \left\| y - \sum_{j < p} \frac{\gamma_j}{\|z_j\|^2} z_j \right\|^2$$
$$= \left\| r_p + \hat{\beta}_p z_p \right\|^2$$
$$= \|r_p\|^2 + \hat{\beta}_p^2 \|z_p\|^2$$
$$RSS_1 = \|y - \hat{y}\|^2$$
$$= \|r_p\|^2$$

So we can express the formula for the F-score

$$F = \frac{\text{RSS}_0 - \text{RSS}_1}{\text{RSS}_1/(N - p - 1)}$$
$$= \frac{\hat{\beta}_p^2 ||z_p||^2}{\hat{\sigma}^2}$$

Now, write  $X=Z\Gamma$ , where Z's columns are the  $z_i$ 's and  $\Gamma$  is upper triangular with diagonal entries 1. Then  $(X^TX)^{-1}=(\Gamma^TZ^TZ\Gamma)^{-1}=(\Gamma^TD\Gamma)^{-1}$ . Here, D is diagonal on  $(\|z_1\|^2,\ldots,\|z_p\|^2)$ . Since we assume that  $X^TX$  is invertible, both  $\Gamma$  and D are, so  $(\Gamma^TD\Gamma)^{-1}=\Gamma^{-1}D^{-1}\Gamma^{-T}$ . Now, we can compute the

lower-right entry

$$(\Gamma^{-1}D^{-1}\Gamma^{-T})_{pp} = \sum_{ij} (\Gamma^{-1})_{ip} D_{ij}^{-1} (\Gamma^{-T})_{jp}$$

$$= \sum_{i} \frac{1}{\|z_{i}\|^{2}} (\Gamma^{-1})_{ip} (\Gamma^{-T})_{ip}$$

$$= \frac{1}{\|z_{p}\|^{2}} (\Gamma_{pp}^{-1})^{2}$$

$$= \frac{1}{\|z_{p}\|^{2}}$$

and so we finally find that the F-score can be written as

$$\frac{\hat{\beta}_p^2}{\hat{\sigma}^2 d_p}$$

where  $d_p$  is the pth diagonal entry of  $(X^TX)^{-1}$ . By relabelling the features, we find that this also works for any of the features, and so the F-score is the square of the Z-score.

2 I would expect that the pointwise confidence intervals would be narrower. Here is a heuristic argument: Suppose that  $\beta_1, \beta_2$  are normally distributed with mean 0 and covariance I. Then one choice of a 95% confidence set is a circle with radius  $R_{95} = \log(20) \approx 3$  about the origin. On the other hand, a 95% confidence set for just  $\beta_0$  is an interval of radius about 1.64, so the 2D set will have much more extreme values of  $\beta_0$ . In paricular, the band for  $x_0 = 0$  will be much wider for the 2D confidence region. Another way to see it: If I generate samples for each point individually, I will implicitly be drawing samples from many, many more functions when I make the final plot, and so will have a narrower gap.

Simulations in the associated notebook.

**3.3.a** The variance of  $c^T y$  is

$$\operatorname{Var}\left(\sum_{i} c_{i} y_{i}\right)$$

$$= \sum_{ij} c_{i} c_{j} \operatorname{Cov}(y_{i}, y_{j})$$

$$= \sum_{i} c_{i}^{2} \sigma^{2}$$

$$= \sigma^{2} ||c||^{2}$$

while the fact that the estimator is unbiased is expressed exactly by the equation  $(X^Tc)^T\beta = \alpha^T\beta$ . Now, I'm going to make a small assumption. We know that the estimator is not supposed to depend on  $\beta$ , which is unobservable, and I'm

going to interpret this mathematically by taking  $(X^Tc)^T\beta = \alpha^T\beta$  to hold for all  $\beta$ . (This is certainly true of the OLS estimator, and it seems that an estimator that did not satisfy this property would be rather useless.)

Write  $c = kX(X^TX)^{-1}\alpha + v$  for some constant k and some v orthogonal to  $X(X^TX)^{-1}\alpha$ , we find  $X^Tc = k\alpha + X^Tv$  and taking  $\beta = (X^TX)^{-1}\alpha$  gives

$$\beta^{T}(X^{T}c) = ((X^{T}X)^{-1}\alpha)^{T}(k\alpha + X^{T}v)$$

$$= k\alpha^{T}(X^{T}X)^{-1}\alpha + \alpha^{T}(X^{T}X)^{-1}X^{T}v$$

$$= k\alpha^{T}(X^{T}X)^{-1}\alpha$$

on one hand, and on the other we know that

$$\beta^{T}(X^{T}c) = \beta^{T}\alpha$$
$$= \alpha^{T}(X^{T}X)^{-1}\alpha$$

and so k = 1. This means that

$$\sigma^{2} \|c\|^{2} = \sigma^{2} \|X(X^{T}X)^{-1}\alpha\|^{2} + \sigma^{2} \|v\|^{2} \ge \sigma^{2}\alpha^{T}(X^{T}X)^{-1}\alpha,$$

which is the variance of the OLS estimator for  $\alpha^T \beta$ .

**3.3.b** A matrix A is positive-semidefinite iff  $x^T A x \geq 0$  for all  $x \in \mathbb{R}^n$ . If  $a \in \mathbb{R}^n$ , then  $a^T (\tilde{V} - \hat{V}) a = a^T \tilde{V} a - a^T \hat{V} a$ . Since  $\hat{V}, \tilde{V}$  are the covariance matrices of  $\hat{\beta}$  and  $\tilde{\beta}$ , respectively, we find that

$$a^T \tilde{V} a = \operatorname{Var}(a^T \tilde{\beta})$$
  
 $a^T \hat{V} a = \operatorname{Var}(a^T \hat{\beta}).$ 

So by the above result,  $\tilde{V} - \hat{V}$  is positive semidefinite.

**3.4** In the full-rank case, a single pass of the Graham-Schmidt procedure expresses X=QR where Q is orthogonal and R is square and upper triangular with 1's along the diagonal. The formula

$$\hat{\beta} = (X^T X)^{-1} X^T y$$

becomes

$$(R^{T}Q^{T}QR)^{-1}R^{T}Q^{T}y$$

$$= (R^{T}R)^{-1}R^{T}Q^{T}y$$

$$= R^{-1}R^{-T}R^{T}Q^{T}y$$

$$= R^{-1}Q^{T}y$$

We can compute  $R^{-1}$  during the Graham-Schmidt process as follows: Let  $Q_k, R_k$  denote the matrices formed by taking the first k columns of Q, R. We will also store the matrix  $R_k^{-1}$ . Given this data, the next step in the Graham-Schmidt process yields  $Q_{k+1}, R_{k+1}$ . We update  $R_{k+1}^{-1}$  as follows: If

$$R_{k+1} = \begin{pmatrix} R_k & Z \\ 0 & a_k \end{pmatrix},$$

then

$$R_{k+1}^{-1} = \left(\begin{array}{c|c} R_k^{-1} & -a_k R_k^{-1} Z \\ \hline 0 & a_k^{-1} \end{array}\right)$$

So we can store the coefficients of  $\hat{\beta}$  in a list that is updated with each newly discovered column of  $R^{-1}$  and row of  $Q^{T}$ .

## **3.5** The original ridge objective is

$$\sum_{i=1}^{N} (y_i - \beta_0 - \sum_{j=1}^{p} x_{ij}\beta_j)^2 + \lambda \sum_{j=1}^{p} \beta_j^2.$$

Rearranging it, we get

$$\sum_{i=1}^{N} \left( y_i - [\beta_0 + \sum_{j=1}^{p} \overline{x}_j \beta_j] + \sum_{j=1}^{p} (x_{ij} - \overline{x}_j) \beta_j \right)^2 + \lambda \sum_{j=1}^{p} \beta_j^2$$

So the minimum  $\hat{\beta}_{\lambda}^{ridge}$  to this will give a minimum to

$$\sum_{i=1}^{N} \left( y_i - \beta_0^c + \sum_{j=1}^{p} (x_{ij} - \overline{x}_j) \beta_j^c \right)^2 + \lambda \sum_{i=1}^{p} (\beta_j^c)^2,$$

where we simply set  $\beta_0^c := \beta_0 + \sum_{j=1}^p \overline{x}_j \beta_j$  and  $\beta_j^c := \hat{\beta}_j$  if  $j \ge 1$ . The lasso condition is exactly the same. In both cases, the objective function is differentiable with respect to  $\beta_0$ , and the derivative in the lasso and ridge case is

$$\sum_{i=1}^{n} 2(y_i - \beta_0^2 + \sum_{j=1}^{p} (x_{ij} - \overline{x}_j)\beta_j^c)$$
$$= N\overline{y} - N\beta_0^c,$$

and so  $\beta_0^c = \overline{y}$  at the minimum in each case.

## **3.6** Let $f_B$ be $N(0, \tau I)$ . Then

$$f_{B|Y}(\beta|y) = \frac{f_{BY}(\beta, y)}{f_Y(y)} = \frac{f_{Y|B}(y|\beta)f_B(\beta)}{f_Y(y)}.$$

We are working under the assumption that y is Gaussian noise added onto  $X\beta$ , so

$$f_{Y|B}(y|\beta) = \frac{1}{(2\pi\sigma)^{\frac{p}{2}}} e^{-\frac{1}{2\sigma^2}||y-X\beta||^2},$$

while

$$f_B(\beta) = \frac{1}{(2\pi\tau)^{\frac{p}{2}}} e^{-\frac{1}{2\tau^2} \sum_{j=1}^p \beta_j^2}.$$

and so

$$f_{Y|B}(y|\beta)f_B(\beta) = \frac{1}{2\pi(\tau\sigma)^{\frac{p}{2}}} \exp\left\{ \frac{-1}{2} \left( \frac{\|y - X\beta\|^2}{\sigma^2} + \frac{\|\beta\|^2}{\tau^2} \right) \right\}.$$

Since this is quadratic in  $\beta$ , we find that this posterior distribution is also Gaussian, so the median and mode match. We'll find the value by taking differentiating with repsect to  $\beta_K$ :

$$f_{Y|B}(y|\beta)f_B(\beta)\left[\frac{1}{\sigma^2}\sum_i(y_i-\sum_jx_{ij}\beta_j)(x_{iK})-\frac{1}{\tau^2}\beta_K\right]$$

Setting this equal to zero for each component gives the vector equation

$$\frac{1}{\sigma^2} X^T (y - X\beta) = \frac{1}{\tau^2} \beta,$$

and solving that yields

$$\beta = (X^T X + \frac{\sigma^2}{\tau^2} I)^{-1} X^T y,$$

which is the ridge regression solution for which  $\lambda = \frac{\sigma^2}{\tau^2}$ .

3.7\*\*\* I'm not sure what this problem is asking about. If it's the same scenario as the previous problem, we reuse that work to find that the posterior density is

$$\frac{C}{2\pi(\tau\sigma)^{\frac{p}{2}}}\exp\bigg\{\frac{-1}{2}\bigg(\frac{\|y-X\beta\|^2}{\sigma^2}+\frac{\|\beta\|^2}{\tau^2}\bigg)\bigg\},$$

with C chosen to make the expression integrate to 1 as a function of y. We take the log and get something that's is proportional to the desired quantity, but with an extra constant added.

**3.8** Let  $1, X_1, \ldots, X_p$  denote the columns of the unnormalized matrix X. The matrix Q in the QR-decomposition can be found via the Graham-Schmidt process. Since the first column of X is all 1's, the GS process start by making first column of Q will be  $\frac{1}{\sqrt{N}}\mathbf{1}$ . The other columns are orthogonalized with respect to this vector:

$$X_i \mapsto \tilde{X}_i = X_i - \langle X_i, \frac{1}{\sqrt{N}} \mathbf{1} \frac{1}{\sqrt{N}} \mathbf{1} \rangle = X_i - \overline{X}_i \mathbf{1}.$$

Since the remaining columns of Q are formed by finding an orthonomal basis of the span of these vectors, which are none other than  $\tilde{X}$ 's columns, and the columns of the matrix U also form an orthogonal basis of that span, we know that the span of  $Q_2$  is the same as the span of U.

When will the two match? We can express  $\widetilde{X} = Q_2 R_2$  and also  $\widetilde{X} = U D V^T$ . If  $Q_2 = U$ , then multiplying both of these expressions by  $U^T$  will yield  $R_2 = D V^T$ , which means that  $V = R_2^T D^{-1}$  is a lower triangular orthogonal matrix, which means it's the identity. This, in turn, means that  $R_2 = D$  is diagonal, which means that the columns of  $\widetilde{X}$  are already orthogonal and simply need to be rescaled to become orthonormal.