

A decorative graphic on the left side of the slide consisting of two overlapping parallelograms. The front one is blue and the back one is a light green. They are positioned diagonally, with the blue one partially covering the green one.

Determining whether Two Devices are on the Same Person using Accelerometers

Final Presentation

Zachary Stence and Torry Johnson



Purpose and Objective

- Producers of wearable devices skimp on security and authentication to cut costs
- Increasing prevalence of wearable devices in our society, has potential to cause great harm
- Reliably determine whether two readings came from the same person or different people
- Could later be used as a framework for providing authentication techniques
- Accelerometers are very cheap sensors already present in most devices today

Features

Mean

Standard deviation

Variance

Power

Interquartile Range

Energy

Mean absolute deviation

Models Used

k-Nearest Neighbors

Random Forest

Support Vector
Machine

Gradient Boosting
Classifier

Decision Tree

Neural Network

Processing/Labelling Data

Acceleration Data from Walking
(time vs. acceleration)



$F_1 = \{f_1, f_2, f_3, \dots\}$ $F_2 = \{f_1, f_2, f_3, \dots\}$ $F_3 = \{f_1, f_2, f_3, \dots\}$
 feature vectors



$$A = \begin{bmatrix} \vdots & \vdots & \vdots \\ F_1 & F_2 & F_3 & \dots \end{bmatrix}$$

$$B = \begin{bmatrix} \vdots & \vdots & \vdots \\ F_1 & F_2 & F_3 & \dots \end{bmatrix}$$

$$\text{magnitude} = \sqrt{x^2 + y^2 + z^2}$$

1. Split a magnitude stream into windows of length w .
2. Extract a feature vector from each window.
3. Combine the feature vectors to form a feature matrix, A .
4. Repeat steps 1-3 with another magnitude stream to obtain a feature matrix, B .
5. Calculate the normalized coherence of each feature of A and B across a window c to obtain a coherence matrix.
6. Split this coherence matrix into rows and label them corresponding to where the original magnitude streams came from.

labelled data

$$\begin{bmatrix} C(f_{A_1}^{1\dots 1+c}, f_{B_1}^{1\dots 1+c}) & \dots \\ C(f_{A_1}^{2\dots 2+c}, f_{B_1}^{2\dots 2+c}) & \dots \\ \vdots \end{bmatrix} \begin{bmatrix} 0 \text{ or } 1 \\ 0 \text{ or } 1 \\ 0 \text{ or } 1 \end{bmatrix}$$

Generated
datasets

$$\begin{bmatrix} [C_1, C_2, \dots, C_7], 0 \text{ or } 1 \\ [C_1, C_2, \dots, C_7], 0 \text{ or } 1 \\ \vdots \end{bmatrix}$$

Splitting into
Training and
Testing Data

$$\begin{bmatrix} [C_1, C_2, \dots, C_7], 0 \text{ or } 1 \\ \vdots \end{bmatrix} \xrightarrow{\text{random 80\%}} \begin{bmatrix} [C_1, C_2, \dots, C_7], 0 \text{ or } 1 \\ \vdots \end{bmatrix} \xrightarrow{\text{random 20\%}} \begin{bmatrix} [C_1, C_2, \dots, C_7], 0 \text{ or } 1 \\ \vdots \end{bmatrix}$$

$$\begin{matrix} X_{\text{train}} & y_{\text{train}} \\ \begin{bmatrix} [C_1, C_2, \dots, C_7], \\ [C_1, C_2, \dots, C_7], \\ \vdots \end{bmatrix} & \begin{bmatrix} 0 \text{ or } 1, \\ 0 \text{ or } 1, \\ \vdots \end{bmatrix} \end{matrix}$$

$$\begin{matrix} X_{\text{test}} & y_{\text{test}} \\ \begin{bmatrix} [C_1, C_2, \dots, C_7], \\ [C_1, C_2, \dots, C_7], \\ \vdots \end{bmatrix} & \begin{bmatrix} 0 \text{ or } 1, \\ 0 \text{ or } 1, \\ \vdots \end{bmatrix} \end{matrix}$$



Results

- We achieved roughly the same results with both sets of data.
- around 72% success when classifying accelerometer streams. These results aren't bad, but could definitely be improved.

UniMiB-SHAR	
Accuracy	0.716
Precision	0.678
F1 Score	0.748
Train Time (s)	0.004
Test Time (s)	0.003

Confusion matrix		Predicted	
		T	F
Actual	T	118	78
	F	27	172

Our data	
Accuracy	0.729
Precision	0.725
F1 Score	0.730
Train Time (s)	0.082
Test Time (s)	0.193

Confusion matrix		Predicted	
		T	F
Actual	T	3564	1365
	F	1297	3598



Conclusion

- Our program can classify two accelerometer streams as same body or different body reasonably accurately
- Parameters play a huge role in the performance of the models (window length, coherence window length, etc)
- Better accuracy can be achieved with other models, but there is a tradeoff with time
- In the future...
 - A more carefully collected dataset with more people
 - Higher quality accelerometers could be used
 - Different features could be used and optimized
- This seems to be a very promising way of authenticating users without requiring new sensors or complicated systems



References

1. Daniela Micucci, Marco Mobilio, Paolo Napoletano. “UniMiB SHAR: A Dataset for Human Activity Recognition Using Acceleration Data from Smartphones.” *Applied Sciences*, vol. 7, no. 10, 24 Oct. 2017. *Applied Sciences*, doi:10.3390/app7101101.
2. Cory T Cornelius, David F Kotz. “Recognizing Whether Sensors Are on the Same Body.” *Pervasive and Mobile Computing*, vol. 8, no. 6, Dec. 2012, pp. 822–836. *ScienceDirect*, doi:10.1016/j.pmcj.2012.06.005.
3. “Scikit-Learn: Machine Learning in Python.” *Scikit-Learn*, Oct. 2017, scikit-learn.org/stable/index.html.