## (\*Math 227A Homework 2\*)

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Due October 7 2016*)

In[191]:= (*Part 1A*)

In[192]:= Plot[2y-2y^3, {y, -2, 2}]

6
4
2
-2
-4
-4
-6
```

(\*Evident from graph as well as fact that  $f'(y) = 2-6y^2$  so that f'(1) = f'(-1) = -4 < 0 so those are stable and f'(0) = 2 > 0 so that one is unstable\*)

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ln[194]: (*I will choose the following initial values for the sample solutions:
          Initial Value 1 is y(0) = 1.5
          Initial Value 2 is y(0) = 0.5
              Initial Value 3 is y(0) = -0.5
            Initial Value 4 is y(0) = -1.5 *
In[195]:= prob1Ainit1 = NDSolveValue[{y'[t] == 2y[t] - 2y[t] ^3, y[0] == 1.5}, y, {t, 0, 20}];
In[196]:= prob1Ainit2 = NDSolveValue[{y'[t] == 2y[t] - 2y[t] ^3, y[0] == .5}, y, {t, 0, 20}];
log[197] = prob1Ainit3 = NDSolveValue[{y'[t] == 2y[t] - 2y[t]^3, y[0] == -.5}, y, {t, 0, 20}];
IN[198]:= prob1Ainit4 = NDSolveValue[{y'[t] == 2y[t] - 2y[t] ^3, y[0] == -1.5}, y, {t, 0, 20}];
In[199]:= (*Here is the graph of sample solutions*)
In[200]:= Plot[{prob1Ainit1[t], prob1Ainit2[t], prob1Ainit3[t], prob1Ainit4[t]}, {t, 0, 1.5}]
       1.5
       1.0
       0.5
Out[200]=
                                    0.8
                             0.6
                                          1.0
                                                        1.4
      -0.5
      -1.0
In[201]:= (*Problem 1B*)
       (*Steady state if e^{(-y)} = 0 or sin(y) = 0
           First condition will never happen
           sin(y) = 0 if y=n*Pi for any integer n*)
       (*It holds that f'(y) = e^{(-y)}(\cos(y) - \sin(y)) *)
       (*Here is verification*)
      D[Exp[-y] * Sin[y], y]
Out[201]= e^{-y} Cos[y] - e^{-y} Sin[y]
In[202]:= (*Steady states occur at n*Pi
          e^(-y)>0 everywhere so we care about the sign of the other term
          If y=
       2*n*Pi for integer n then cos(y) = 1 so f'(y) > 0 making those steady states unstable
            If y=(2*n+1)*Pi for integer n then cos(y)=
           -1 so f'(y)<0 making those steady states stable *)</pre>
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In[203]:= (*Here are the initial values that I chose:
          y(0) = Pi/4
          y(0) = 5Pi/4
           y(0) = -Pi/4

y(0) = -5Pi/4*)
ln[204] = prob1Binit1 = NDSolveValue[{y'[t] == Exp[-y[t]] * Sin[y[t]], y[0] == Pi/4}, y, {t, 0, 40}];
In[205]:= prob1Binit2 =
         NDSolveValue[\{y'[t] = Exp[-y[t]] * Sin[y[t]], y[0] = 5 * Pi/4\}, y, \{t, 0, 40\}];
ln[206] = prob1Binit3 = NDSolveValue[{y'[t] == Exp[-y[t]] * Sin[y[t]], y[0] == -Pi/4}, y, {t, 0, 40}];
In[207]:= prob1Binit4 =
         NDSolveValue[\{y'[t] = Exp[-y[t]] * Sin[y[t]], y[0] = -5 * Pi/4\}, y, \{t, 0, 40\}];
In[208]:= (*Here is the log linear graph of sample solutions*)
In[209]:= LogLinearPlot[{prob1Binit1[t], prob1Binit2[t], prob1Binit3[t], prob1Binit4[t]}, {t, 0, 40}]
Out[209]=
              0.10
                           0.50
         0.05
       -2
```

```
(*Problem 2*)
  (*Need a function with zeros at 0,1,2,3. For simplicity I will try a polynomial*)
  (*One possibility is the form f(y) = Ky(y-1)(y-2)(y-3) *)
  (*Here I am computing f'(y) to get info about steady states*)
  Expand[D[KK * y (y-1) (y-2) (y-3), y]]

Out[210]= -6 KK + 22 KK y - 18 KK y² + 4 KK y³

In[211]= fPrime[y_] := -6 KK + 22 KK y - 18 KK y² + 4 KK y³

In[212]= (*Here I am computing f'(y) at the steady state points*)

In[213]= {fPrime[0], fPrime[1], fPrime[2], fPrime[3]}

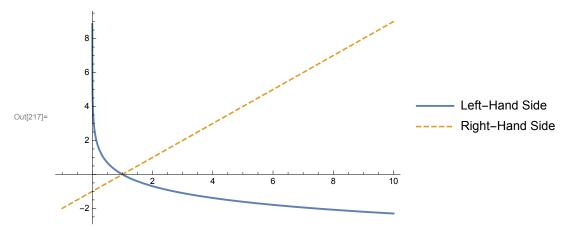
Out[213]= {-6 KK, 2 KK, -2 KK, 6 KK}

In[214]= (*As long as K>0 the properties are satified, thus every function f(y) = Ky(y-1) (y-2) (y-3) where K>0 satisfies our requirements*)
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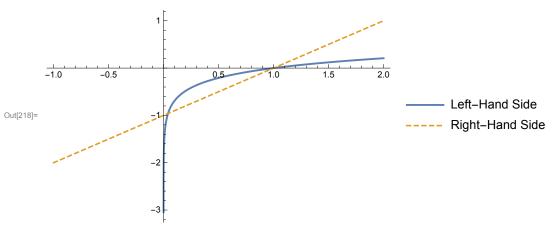
## In[215]:= (\*Problem 3A\*)

In[216]:= (\*Here are four graphs showing both functions\*)

 $\label{eq:local_$ PlotStyle  $\rightarrow$  {Thick, Dashed}] (\* r=-1 \*)



 $\label{eq:local_$ PlotStyle  $\rightarrow$  {Thick, Dashed}] (\* r=0.3 \*)



```
log(219) = Plot[\{log[y], y-1\}, \{y, -1, 2\}, PlotLegends \rightarrow \{"Left-Hand Side", "Right-Hand Side"\}, 
                            PlotStyle \rightarrow {Thick, Dashed}] (* r=1 *)

    Left-Hand Side

Out[219]=
                                                                                                                                                                                                                                                       -- Right-Hand Side
  \label{eq:local_local_local_local_local_local_local_local_local_local_local_local_local_local_local_local_local_local_local_local_local_local_local_local_local_local_local_local_local_local_local_local_local_local_local_local_local_local_local_local_local_local_local_local_local_local_local_local_local_local_local_local_local_local_local_local_local_local_local_local_local_local_local_local_local_local_local_local_local_local_local_local_local_local_local_local_local_local_local_local_local_local_local_local_local_local_local_local_local_local_local_local_local_local_local_local_local_local_local_local_local_local_local_local_local_local_local_local_local_local_local_local_local_local_local_local_local_local_local_local_local_local_local_local_local_local_local_local_local_local_local_local_local_local_local_local_local_local_local_local_local_local_local_local_local_local_local_local_local_local_local_local_local_local_local_local_local_local_local_local_local_local_local_local_local_local_local_local_local_local_local_local_local_local_local_local_local_local_local_local_local_local_local_local_local_local_local_local_local_local_local_local_local_local_local_local_local_local_local_local_local_local_local_local_local_local_local_local_local_local_local_local_local_local_local_local_local_local_local_local_local_local_local_local_local_local_local_local_local_local_local_local_local_local_local_local_local_local_local_local_local_local_local_local_local_local_local_local_local_local_local_local_local_local_local_local_local_local_local_local_local_local_local_local_local_local_local_local_local_local_local_local_local_local_local_local_local_local_local_local_local_local_local_local_local_local_local_local_local_local_local_local_local_local_local_local_local_local_local_local_local_local_local_local_local_local_local_local_local_local_local_local_local_local_local_local_local_local_local_local_local_local_local_local_local_local_local_local_local_local_local_local_local_local_local_local_local_local_local_
                            PlotStyle → {Thick, Dashed}] (* r=2 *)

    Left-Hand Side

Out[220]=
                                                                                                                                                                                                                                         ---- Right-Hand Side
                                                     -2
  In[221]:= (* At the points where the two graphs intersect,
                        it holds that y'=0 so the intersection points
                                will be the steady states and that holds for any value of r *)
                         (*It appears for large r, there are two steady states.
                                     At r=1 there is one steady state.
                                         Between 0 and 1 there appear to be two steady states.
                                         For r<0 there appears to be one steady state.
```

This is Saddle Node Bifurcation\*)

ln[222]:= (\*If y=1, the ln(y)=0 so the value of r is irrelevant\*)

```
(*Problem 3B*)
     (*Equation is now the following
       u'=-r \ln(u+1) + u
     (*Problem 3C*)
     (* If we assume that ln(u+1) =
      u - (1/2)u^2 then when expanding the part b equation using that assumption we have
         u' = -r (u - (1/2)u^2) + u
          u' = -r*u + (1/2)r*u^2 + u (1)
           When you expand the part c equation you end up with
            u' = (r/2)u(-2 + 2/r + u)
           u' = u(-r + 1 + r*u/2)
            u' = -r*u + u + r*u^2/2
              Equation (1) matches equation (2) above so the given equation for u' is valid*)
\ln[224]:= (*Since (-r+1)*(2/r) is a constant just like mu,
     our system will have very similar behavior around r=1.
        At r=1 and mu=
        0 the only difference is a constant factor. They both have a single steady state.
            For r>1 the zeros are at 0 and a positive number, just like for mu<0.
       For r<1 the zeros are at 0 and a negative number, just like for mu>0.
       Both also have a parabolic shape pointing upward, so the first zero is
      a stable steady state and the second zero is an unstable steady state*)
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In[225]:= (*Problem 4*)
      (-r-sqrt(r^2-4))/2 and (-r+sqrt(r^2-4))/2
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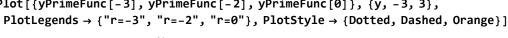
In[226]:= (\*For large positive and negative values, y' will be positive. The quadratic equation  $1+r*y+y^2$  has a discriminant of  $r^2-4$ 

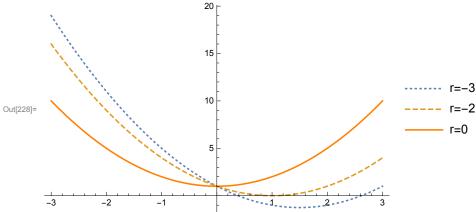
Meaning that if |r| < 2 there are no real roots so y' is positive everywhere.

2 or r=-2 then there is one unstable steady state at y=-1 and y=1 respectively If |r|>2 there are two steady states at

The first one is stable and the second one is unstable respectively This is an example of Saddle Node Bifurcation\*)

In[227]:= yPrimeFunc[r\_] := 1 + r \* y + y^2; In[228]:= (\*This shows the phase diagram for r=-3 (two steady states), r=-2 (one steady state), and r=2 (no steady states)\*) Plot[{yPrimeFunc[-3], yPrimeFunc[-2], yPrimeFunc[0]}, {y, -3, 3},





```
ln[229]:= (*It holds that f'(y)=r+2y]
         For a given r value, the two steady state y values are described by
       y1(r) = (-r+sqrt(r^2-4))/2
        y2(r) = (-r-sqrt(r^2-4))/2
```

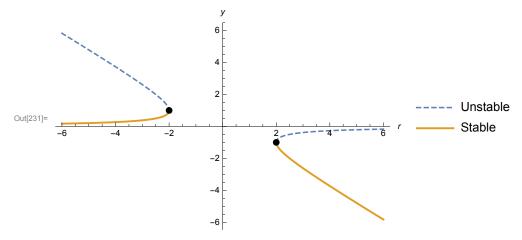
For y1 it holds that  $r+2y = sqrt(r^2-4) \ge 0$  so that branch is unstable For y2 it holds that  $r+2y = -sqrt(r^2-4) \le 0$  so that branch is stable

The bifurcation points occur when r+2y= 0 thus (r,y) is equal to (-2,1) and (2,-1)

The plot below shows the stable and unstable branches as well as the bifurcation points as black dots\*)

 $ln[230] = prob4Plot = Plot[{(-r + Sqrt[r^2 - 4])/2, (-r - Sqrt[r^2 - 4])/2}, {r, -6, 6},$  $PlotStyle \rightarrow \{Dashed, Thick\}, AxesLabel \rightarrow \{r, y\}, PlotLegends \rightarrow \{"Unstable", "Stable"\}];$ 

In[231]:= Show[prob4Plot, Graphics[{PointSize[0.02], Point[{-2, 1}]}], Graphics[{PointSize[0.02], Point[{2, -1}]}]]



```
In[232]:= (*Problem 5*)
ln[233]:= prob5Func[r_] := y * (r - Exp[y])
ln[234]:= (*For large positive values of y it holds that r won't matter as -
        y∗e^(y) will be a large negative number
         For large negative values of y it holds that e^{(y)}
         is near zero thus the graph will be similar to r*y
          So it r<0 and y negative then y' will be positive,
      but if r>0 and y negative then y' will be negative *)
In[235]:= (*The steady states will occur when y=0 or r=e^y
            If r≤0 then there will only be one steady state at y=0 and it will be stable
             If r>0 then there will be two steady states at y=
           0 and y=ln(r). The lower one is unstable and the higher value is stable.
                In the case of r=1 there is one steady state at y=1 and it is unstable.*)
In[236]:= (*This is Transcritical Bifurcation*)
ln[237] = Plot[{prob5Func[-2], prob5Func[1], prob5Func[5]}, {y, -2, 2},
       PlotLegends \rightarrow {"r=-2", "r=1", "r=5"}, PlotStyle \rightarrow {Dotted, Dashed, Orange}]
                                                               ----- r=-2
                                                                ---- r=1
Out[237]=
                                                                    r=5
                               -10
                               -15
                               -20 <sup>L</sup>
```

```
ln[238] = (*It holds that f'(y) = y(-e^y) + (r-e^y) = r - e^y - y*e^y
             For the y=0 bifurcation branch it holds that f'(y)=r-1
                 so f'(y) < 0 for r < 1 (stable part) and f'(y) \ge 0 for r \ge 1 (unstable part)
                For the r=e<sup>y</sup> branch it tholds that f'(y) = -y \cdot e^y so since e^y > 0 for all values,
       it holds that f'(y) < 0 for y > 0 (stable part) and f'(y) \ge 0 for y < 0 (unstable part)
         The Bifurcation Point occurs when
          (r,y) is equal to (1,0) and is given a black dot below*)
In[239]:= prob5Plot =
         Plot[\{Piecewise[\{\{0, r < 1\}, \{Log[r], r \ge 1\}\}], Piecewise[\{\{Log[r], r < 1\}, \{0, r \ge 1\}\}]\},
           \{r, -5, 5\}, AxesLabel \rightarrow \{r, y\}, PlotLegends \rightarrow \{\text{"Stable"}, \text{"Unstable"}\},
           PlotStyle → {Thickness[0.025], {Thickness[0.015], Dashed}}];
In[240]:= Show[prob5Plot, Graphics[{PointSize[0.04], Point[{1, 0}]}]]
                                 1.5
                                 1.0
                                 0.5
                                                                           Stable
Out[240]=

    Unstable

                                 -0.5
```

```
In[241]:= (*Problem 6*)
```

ln[242]:= (\*It holds that our equation is  $y(1 + r/(1+y^2)) = 0$  so either y = 0 or  $1 + r/(1+y^2) = 0$ . In the later case we can manipulate it to be  $y^2 = -(r+1)$  so it must hold that r < -1 for a root to exist.

For r<-1 we have three roots:

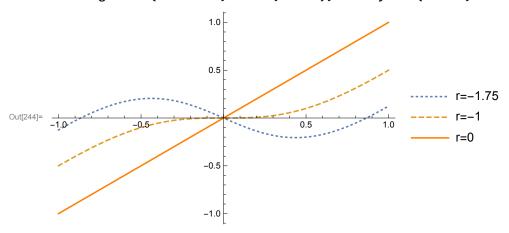
y =

-sqrt(-r-1) 0 sqrt(-r-1) and they are unstable stable and unstable respectively For  $r \ge -1$  we have an unstable root at y=0

This is Pitch Fork Bifurcation\*)

 $ln[243]:= prob6Func[r_] := y + r * y / (1 + y^2)$ 

 $\label{eq:local_prob} $$ \inf[244]:= Plot[\{prob6Func[-1.75], prob6Func[-1], prob6Func[0]\}, \{y, -1, 1\}, $$ PlotLegends $\to \{"r=-1.75", "r=-1", "r=0"\}, PlotStyle $\to \{Dotted, Dashed, Orange\}]$$ $$$ 



In[245]:=

$$\begin{aligned} & & \text{In}[246] \text{:= } & D \left[ y + r * y / \left( 1 + y^2 \right) , y \right] \\ & & \text{Out}[246] \text{= } & 1 - \frac{2 r y^2}{\left( 1 + y^2 \right)^2} + \frac{r}{1 + y^2} \end{aligned}$$

 $ln[247] = (*It thus holds that f'(y) = 1-r((y^2-1) / (1+y^2)^2) *)$ 

ln[248]:= (\* The branches of the graph are y=0 and y^2=-(r+1)

If y=

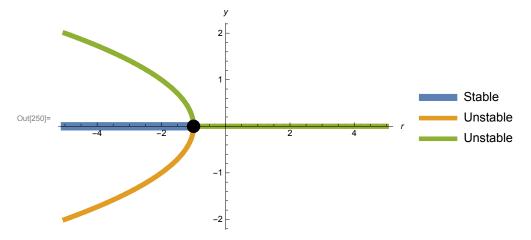
0 then f'(y)=1+r so if r<-1 the branch is stable but if  $r\geq -1$  the branch is unstable

If  $y^2 = -(r+1)$  then  $f'(y) = 1 - r((-r-2)/r^2) = 1 + (r+2)/r = 2(r+1)/r$ , thus since  $r \le -1$  it holds that  $f'(y) \ge 0$  hence the branches are unstable

f'(y) = 0 in our branches only when r=-1 thus the Bifurcation Point is (r,y) = (-1,0)which is given a black dot below\*)

 $ln[249]= prob6Plot = Plot[{Piecewise[{0, r < -1}, {Sqrt[-(r+1)], r \ge -1}}],$ Piecewise  $[\{-Sqrt[-(r+1)], r < -1\}, \{0, r \ge -1\}\}],$ Piecewise  $\left[\left\{\left\{Sqrt\left[-\left(r+1\right)\right], r<-1\right\}\right\}\right]\right\}$ ,  $\{r, -5, 5\}$ , AxesLabel  $\rightarrow \{r, y\}$ , PlotLegends → {"Stable", "Unstable", "Unstable"}, PlotStyle → {Thickness[0.025], {Thickness[0.015], Dashed}, {Thickness[0.015], Dashed}}];

In[250]:= Show[prob6Plot, Graphics[{PointSize[0.04], Point[{-1, 0}]}]]



```
In[251]:= (*Extra Problem*)
ln[252]:= (*Show that y' = y^(1/3) and y(0)=0 has more than one solution*)
In[253]:= (*After doing separation of variables,
     we have y^{-1/3} dy = dt. After integrating we have
         (3/2) y^{(2/3)} = t + C
           If we assume y(0) = 0 then it holds that C=0.
            After rearranging our solution is
            y^2 = (2t/3)^3
            The positive and negative square root of the right hand side are both solutions,
     hence there is more than one solution*)
      (*Additionally,
     the function y(t)=0 satisfies both properties and is thus an additional solution*)
```