

## PCA

have data set  $\vec{x}_1, \dots, \vec{x}_n \quad x_i \in \mathbb{R}^d$

$$X = \begin{pmatrix} \vec{x}_1 \\ \vdots \\ \vec{x}_n \end{pmatrix}$$

assume mean 0  $(\sum_{i=1}^n x_i = 0)$

### Examples

n images	& pixels each
n measurements	& sensors
n docs	& words
n people	& movies
n customers	& products

### Fix K

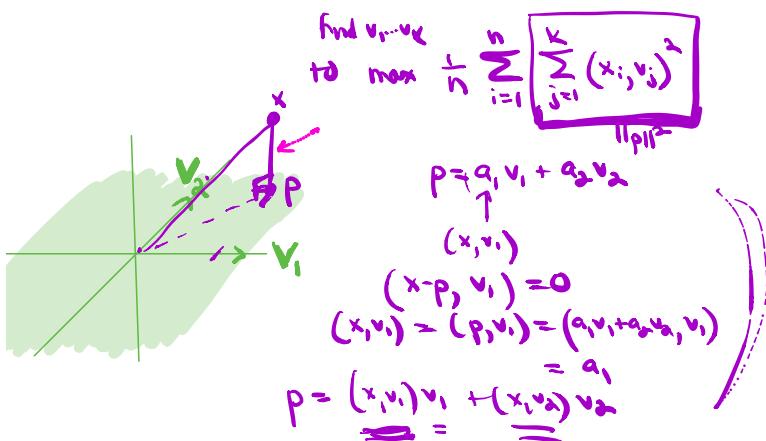
Find k-dimensional subspace (defined by orthonormal vectors  $\vec{v}_1, \vec{v}_2, \dots, \vec{v}_k$ )

so as to minimize  $\frac{1}{n} \sum_{i=1}^n \text{distance}(x_i \rightarrow \underset{\substack{\text{subspace} S \\ \vec{v}_1, \vec{v}_2, \dots, \vec{v}_k}}{\text{spanned by}})$

$\equiv$  maximizing  $\frac{1}{n} \sum_{i=1}^n \sum_{j=1}^k (x_i, v_j)^2$   
variance of projected pts

projecting  $x_i \rightarrow S$

$$\sum_{j=1}^k (x_i, v_j) v_j$$



$$\text{maximizing } \frac{1}{n} \sum_{i=1}^n \sum_{j=1}^k (x_i \cdot v_j)^2 = \sum_{j=1}^k (x \cdot v_j)^T x \cdot v_j = \frac{1}{n} \sum_{j=1}^k v_j^T X^T X v_j$$

How to find  $\vec{v}_1, \dots, \vec{v}_k$

① Compute eigendecomposition of empirical covariance matrix  $X^T X$

$$A := X^T X = Q D Q^T$$

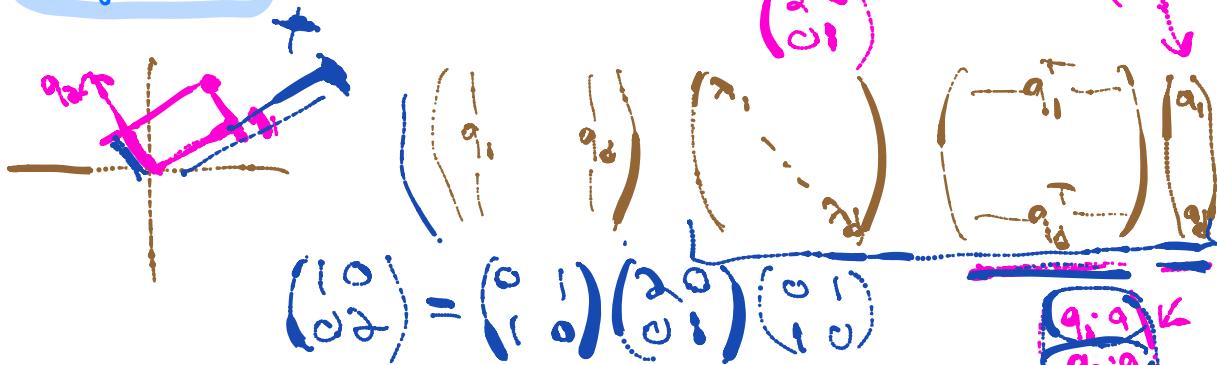
$$D = \begin{pmatrix} \lambda_1 & & \\ & \lambda_2 & \\ & & \ddots \\ & & 0 \end{pmatrix}$$

$\lambda_1 \geq \lambda_2 \geq \dots \geq \lambda_n$   
all eigenvalues  $\geq 0$

$$A q_i = \lambda_i q_i \quad \forall i$$

$$Q = \begin{pmatrix} | & & | \\ q_1 & \cdots & q_n \\ | & & | \end{pmatrix}$$

$q_1, \dots, q_n$  orthonormal  
 $Q^T Q = Q^T Q = I$   
 $\forall w \quad \|Qw\| = \|w\|$



② Set  $v_1 := q_1$   
 $v_2 := q_2$   
 $\vdots$   
 $v_k := q_k$

New coordinates of  $x_i$

are  $(x_i \cdot v_1), (x_i \cdot v_2), \dots, (x_i \cdot v_k)$

low dimensional representation

$$g_i \vec{x}_i$$

$$\Sigma = A A^T$$

$$\Sigma = Q D Q^T = \begin{pmatrix} q_1, q_2 \\ \vdots \\ q_k \end{pmatrix} \begin{pmatrix} \lambda_1 & & \\ & \lambda_2 & \\ & & \ddots \\ & & 0 \end{pmatrix} \begin{pmatrix} q_1^T \\ q_2^T \\ \vdots \\ q_k^T \end{pmatrix}$$

$$\begin{pmatrix} Q & D \\ Q^T & I \end{pmatrix} \quad \begin{pmatrix} Q & D \\ Q^T & I \end{pmatrix}^T$$

1. Find the top component,  $\mathbf{v}_1$ , using power iteration.
2. Project the data matrix orthogonally to  $\mathbf{v}_1$ :

$$\begin{bmatrix} \mathbf{x}_1 \\ \mathbf{x}_2 \\ \vdots \\ \mathbf{x}_m \end{bmatrix} \mapsto \begin{bmatrix} (\mathbf{x}_1 - \langle \mathbf{x}_1, \mathbf{v}_1 \rangle \mathbf{v}_1) \\ (\mathbf{x}_2 - \langle \mathbf{x}_2, \mathbf{v}_1 \rangle \mathbf{v}_1) \\ \vdots \\ (\mathbf{x}_m - \langle \mathbf{x}_m, \mathbf{v}_1 \rangle \mathbf{v}_1) \end{bmatrix}.$$

This corresponds to subtracting out the variance of the data that is already explained by the first principal component  $\mathbf{v}_1$ .

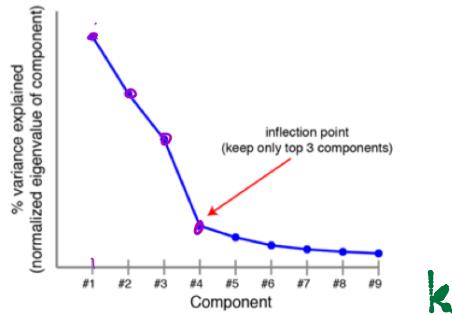
3. Recurse by finding the top  $k-1$  principal components of the new data matrix.

## Applications

- ① Visualization    ② Compression    ③ Learning

## How to choose $k$ ?

- For visualization: a few
- compression: Look at eigenvalues.  
As soon as small enough; happy.



**Scree plot.** Principal components are ranked by the amount of variance they capture in the original dataset, a scree plot can provide some sense of how many components are needed.

## Singular Value Decomposition (SVD)

gives us best way to approximate a matrix with a "low rank" matrix rating

$$\text{movies} \begin{bmatrix} 7 & ? & ? \\ ? & 8 & ? \\ ? & 12 & 6 \\ ? & ? & 2 \\ 21 & 6 & ? \end{bmatrix}.$$

**Motivation:** can we reconstruct missing entries?

Suppose I told you  
that all rows are multiples  
of each other

1 2 3

$$\begin{array}{c|ccc} 1 & 7 & 2 & 1 \\ 2 & 28 & 8 & 4 \\ 3 & 42 & 12 & 6 \\ 4 & 14 & 4 & 2 \\ 5 & 21 & 6 & 3 \end{array} = \begin{array}{l} 1 \cdot (7 \ 2 \ 1) \\ 4 \cdot (7 \ 2 \ 1) \\ 6 \cdot (7 \ 2 \ 1) \\ 2 \cdot (7 \ 2 \ 1) \\ 3 \cdot (7 \ 2 \ 1) \end{array}$$

$$\begin{pmatrix} 1 \\ 4 \\ 6 \\ 2 \\ 3 \end{pmatrix} \cdot (7 \ 2 \ 1)$$

Rank 0 all 0 matrix

Rank 1

$$A = uv^T = \begin{bmatrix} u_1 v^T & \cdot \\ u_2 v^T & \cdot \\ \vdots & \cdot \\ u_m v^T & \cdot \end{bmatrix} = \begin{bmatrix} | & | & & | \\ v_1 u & v_2 u & \cdots & v_n u \\ | & | & & | \end{bmatrix}$$

Rank 2

$$A = uv^T + wz^T = \begin{bmatrix} u_1 v^T + w_1 z^T & \cdot \\ u_2 v^T + w_2 z^T & \cdot \\ \vdots & \cdot \\ u_m v^T + w_m z^T & \cdot \end{bmatrix} = \begin{bmatrix} | & | & | \\ u & w & \\ \text{up!} & \text{up!} & \end{bmatrix} \cdot \begin{bmatrix} v^T & w^T \\ z^T & z^T \end{bmatrix}$$

$u_i v_j + w_i z_j$

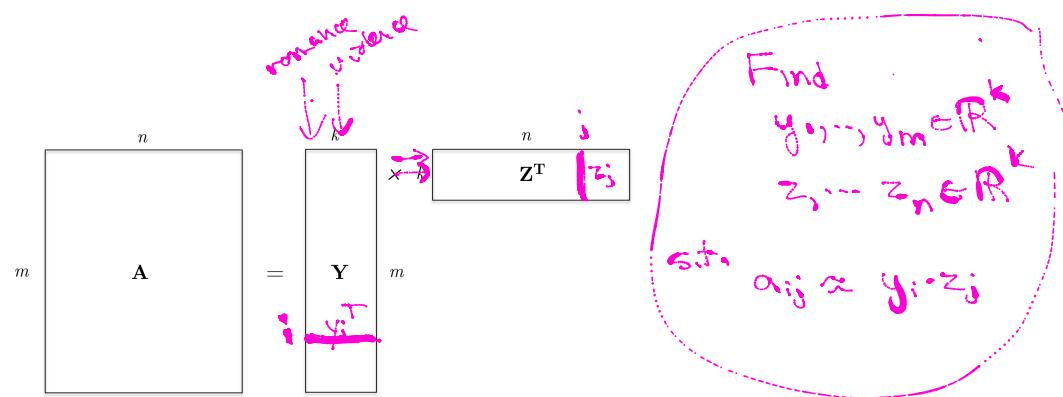


Figure 1: Any matrix  $A$  of rank  $k$  can be decomposed into a long and skinny matrix times a short and long one.

Why might a matrix be approximately low rank?

Example: movie ratings

- Suppose each movie characterized by relatively small # of attributes
  - e.g. romance, violence, comedy, ...
- and each person characterized by their preferences on each of these

# Singular Value Decomposition (SVD)

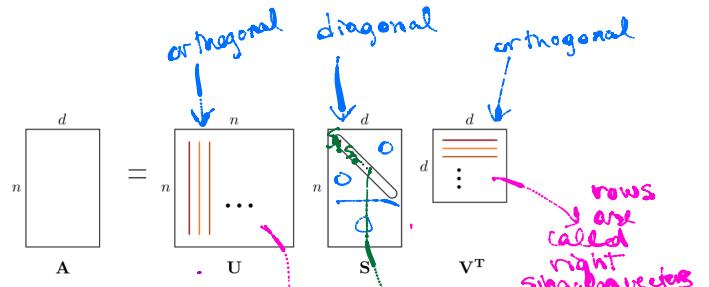


Figure 2: The singular value decomposition (SVD). Each singular value in  $S$  has an associated left singular vector in  $U$ , and right singular vector in  $V$ .

$$UU^T = U^TU = I$$

cols called  
left singular vectors

$$VV^T = V^TV = I$$

$s_1 \geq s_2 \geq \dots \geq s_{\min(n,d)} \geq 0$   
called  
singular values.

Running time to compute

$$\min [O(n^2d), O(d^2n)]$$

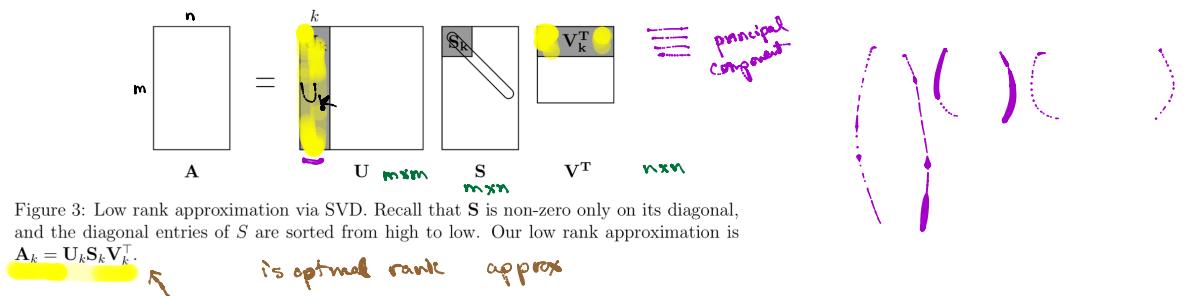


Figure 3: Low rank approximation via SVD. Recall that  $S$  is non-zero only on its diagonal, and the diagonal entries of  $S$  are sorted from high to low. Our low rank approximation is  $A_k = U_k S_k V_k^T$ .

Claim: If  $m \times n$  matrix  $A$  and rank target  $k$ , and rank  $k$  matrix  $B$

$$\|A - A_k\|_F^2 \leq \|A - B\|_F^2$$

$$\|M\|_F^2 = \sum_{i,j} m_{ij}^2$$

Exercise: knowing that  $v_1$  (first row)  
is first principal component  
prove this theorem for  $k=1$

## Relationship between SVD and PCA

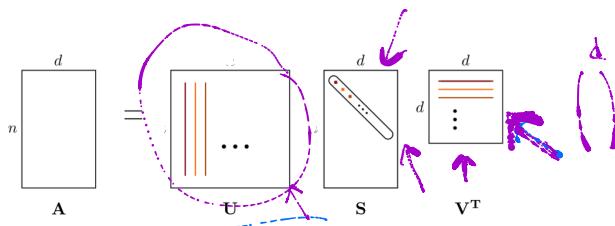


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$$\text{PCA}$$

$$X^T X = Q D Q^T$$

SVD

$$X = U S V^T$$

$n \times d$

$$X^T X = (U S V^T)^T U S V^T$$

$$= V S^T U^T U S V^T$$

$$= V S^2 V^T$$

$$Q = V$$

$$D = S^2$$

eigenvalues of  $X^T X$  are  
squares of singular values.

$$X X^T = U \underline{S^2} U^T$$

products

customers

$X^T X$  covariance for products

$X X^T$  covariance for customers

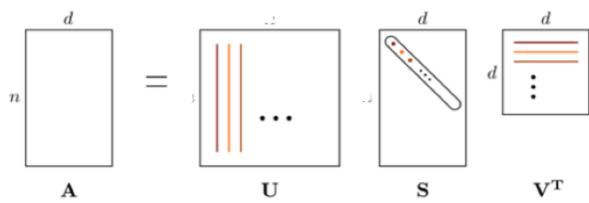


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## Application 1: Denoising

Suppose matrix  $A$  is noisy version of rank  $k$  matrix

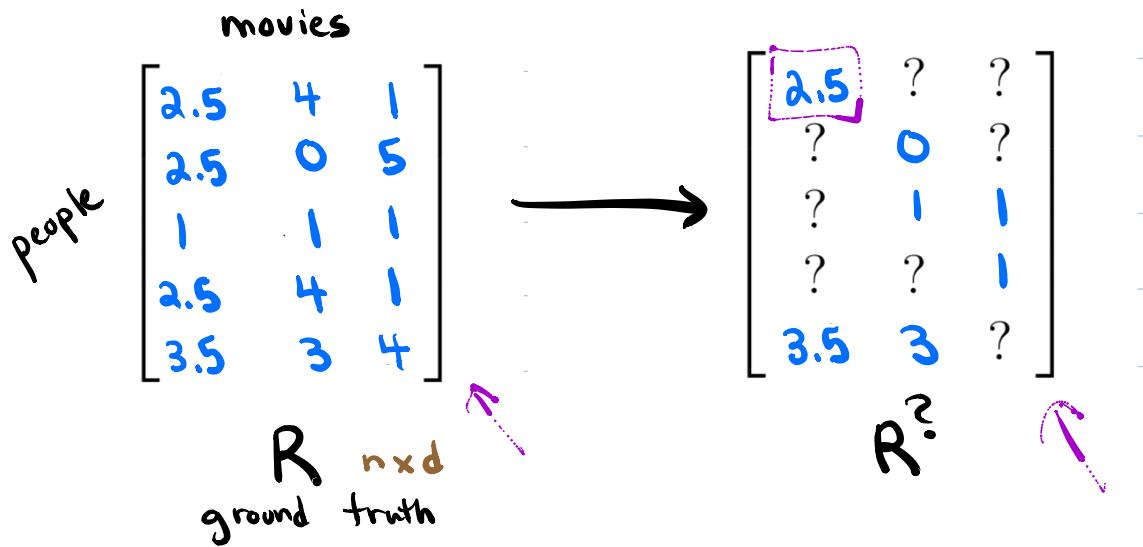
$$A = \underbrace{C}_{\text{rank } k} + \underbrace{N}_{\text{noise}}$$

can "reconstruct  $C$ " by taking  $A_k$

## Collaborative Filtering

recommendations: which movies to see, which products to buy

Model:



Assumptions:

$R$  is low rank  
e.g. rank  $k$

example:  
humor, violence,  
romance

$$\min \sum_{(i,j) \in R^*} (R_{ij} - a_i \cdot b_j)^2$$

( $i, j$  have entry)

The matrix completion problem:

$$R? = \begin{pmatrix} & \overset{k}{\underset{i=1}{\mid}} & \overset{d}{\underset{j=1}{\mid}} & \dots \\ \underset{i=1}{\overset{n}{\mid}} & a_i & b_j & \dots \\ & \ddots & \ddots & \ddots \end{pmatrix}$$

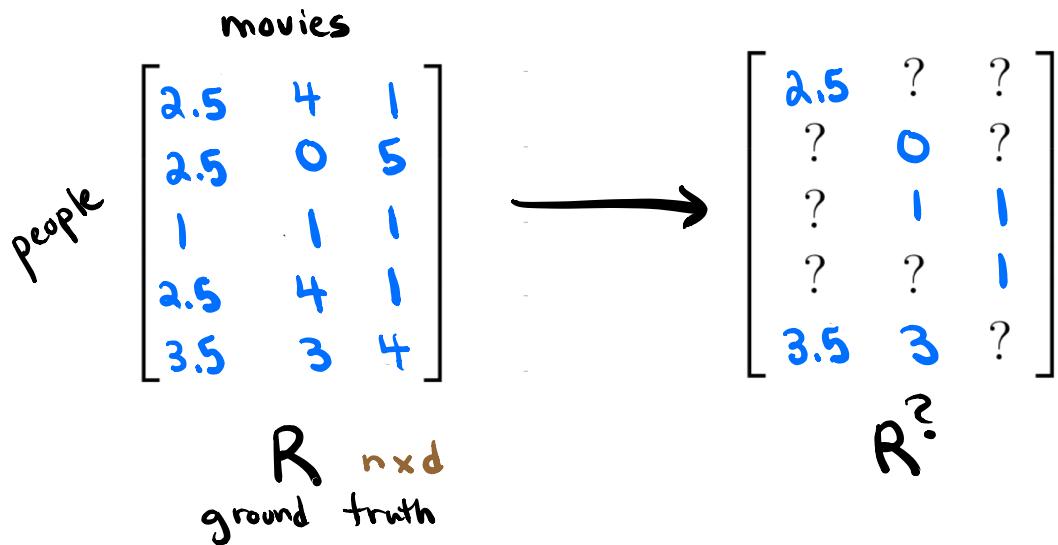
Find  $a_i$ ,  $b_j$   $i=1..n$ ,  $j=1..d$

s.t. if  $R_{ij}$  is present  
 $R_{ij} \approx a_i \cdot b_j$

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## The matrix completion problem:

fill in the missing entries.

Theorem  $\hat{A}$   $n \times d$  matrix of indep. r.v.s, each with variance bounded by  $\sigma^2$

If  $\underline{A} = \underline{E(\hat{A})}$  is rank  $k$

then with high probability

$$\|\underline{A} - \hat{A}_k\|_F^2 \text{ is } O(k\sigma^2(n+d))$$

avg per elt error  $O\left(\frac{k\sigma^2(n+d)}{nd}\right) = o(1)$

Suppose  $\underline{A}$  rank  $k$ .  
entry  $(ij)$  present with prob  $p_{ij}$   
 $\begin{pmatrix} ? & ? & ? \\ ? & ? & ? \\ ? & ? & ? \end{pmatrix}$   
Let  $\hat{A}_{ij} = \begin{cases} \hat{A}_{ij} & \text{if entry present} \\ 0 & \text{o.w.} \end{cases}$

$A$   $\rightarrow$   $\hat{A}$   
 $A_{ij}$  rank  
entry  $(ij)$  survives with prob  $p_{ij}$

$$E(\hat{A}_{ij}) = \frac{\hat{A}_{ij}}{p_{ij}} \cdot p_{ij} + 0$$

$$= \boxed{A_{ij}}$$

(1)

$$\begin{bmatrix} 2.5 & ? & ? \\ ? & 0 & ? \\ ? & 1 & 1 \\ ? & ? & 1 \\ 3.5 & 3 & ? \end{bmatrix} \xrightarrow{\hspace{1cm}} \begin{bmatrix} & & \\ & & \\ & & \\ & & \\ & & \end{bmatrix}$$

$R^?$

$M$