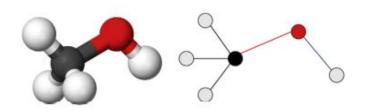
Graph Neural NETWORK (GNN)

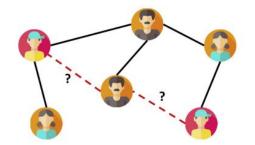
Zahra Akhlaghi

Graph Structured Data

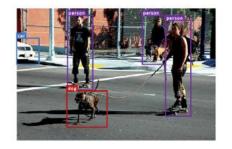
a) Molecule

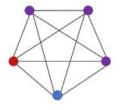


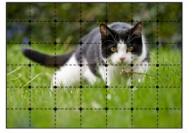
b) Social Network



b) Image

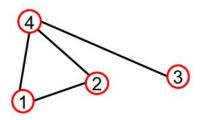


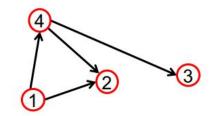






Representation Graph (Adjacency Matrix)





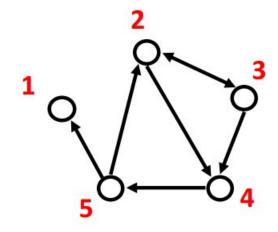
$$A_{ij} = 1$$
 if there is a link from node i to node j $A_{ij} = 0$ otherwise

$$A = \begin{pmatrix} 0 & 1 & 0 & 1 \\ 1 & 0 & 0 & 1 \\ 0 & 0 & 0 & 1 \\ 1 & 1 & 1 & 0 \end{pmatrix} \qquad A = \begin{pmatrix} 0 & 0 & 0 & 1 \\ 1 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \\ 0 & 1 & 1 & 0 \end{pmatrix}$$

$$A = \begin{pmatrix} 0 & 0 & 0 & 1 \\ 1 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \\ 0 & 1 & 1 & 0 \end{pmatrix}$$

Representation Graph (Edge List)

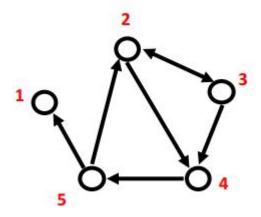
- **(2, 3)**
- **(2, 4)**
- **(3, 2)**
- **(3, 4)**
- **4**, 5)
- **(5, 2)**
- **(5, 1)**



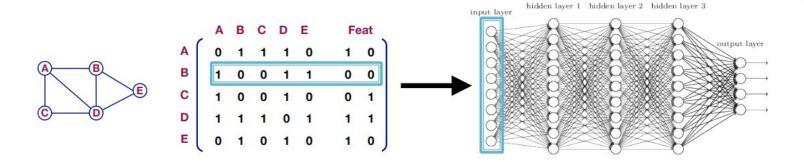
Representation Graph (Adjacency List)

Easier to work with if network is:

- Large
- Sparse
- 2: 3, 43: 2, 4



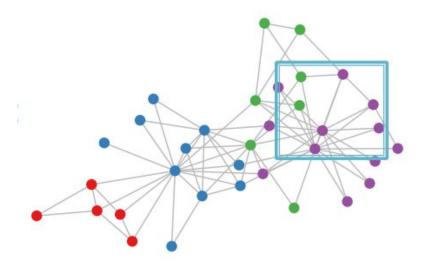
A Naive Approach



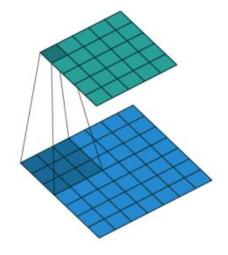
- O(|V|) parameters
- Not applicable to graphs of different sizes
- Sensitive to node ordering

Real-World Graphs

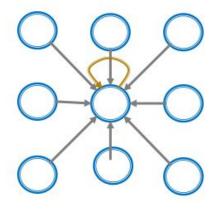
- There is no fixed notion of locality or sliding window on the graph
- Graph is permutation invariant



From Images to Graph

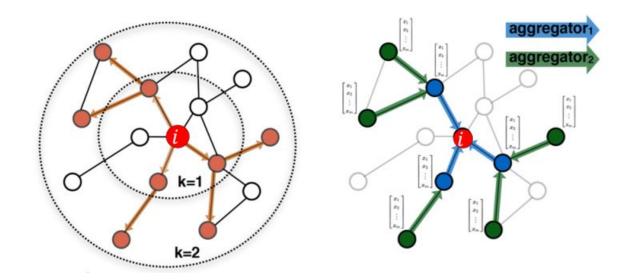


Images



Graph

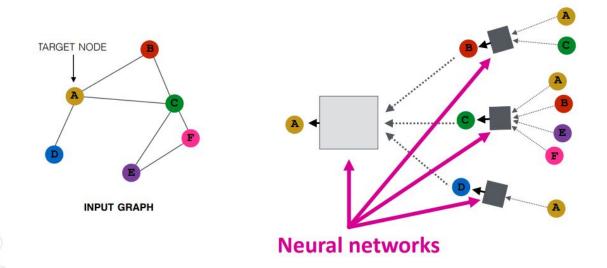
Graph Neural Network



Idea: Node's neighborhood defines a computation graph

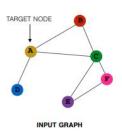
Idea: Aggregate Neighbors

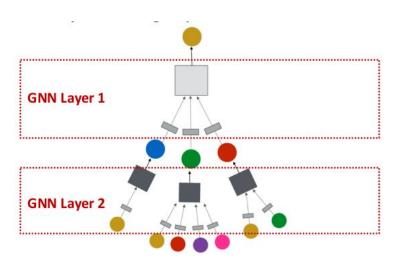
Intuition: Nodes aggregate information from their neighbors using neural networks



A General GNN Framework

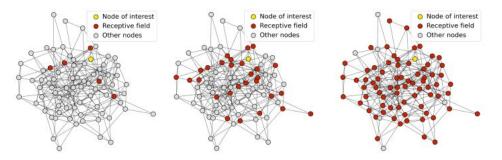
GNN Layer = Message + Aggregation





The Over-Smoothing Problem

- The Issue of stacking many GNN layers
 - GNN suffers from the over-smoothing problem
- The over-smoothing problem: all the node embeddings converge to the same value
 - This is bad because we want to use node embeddings to differentiate nodes



Why Manipulate Graph

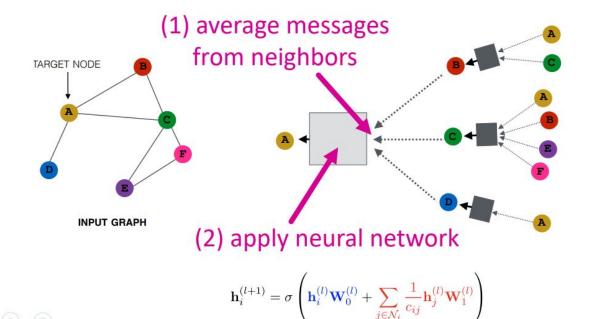
Raw input graph = computational graph

- Feature level:
 - The input graph lacks features → feature augmentation
- Structure level:
 - The graph is too sparse → inefficient message passing
 - The graph is too dense → message passing is too costly
 - The graph is too large → cannot fit the computational graph into a GPU

Graph Manipulation Approaches

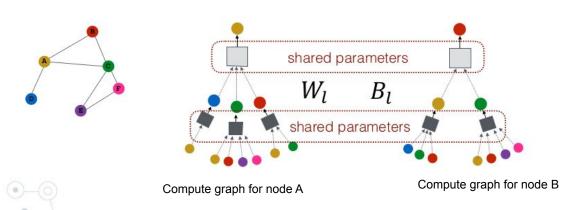
- Graph Feature manipulation
 - The input graph lacks features → feature augmentation
- Graph Structure manipulation
 - The graph is too sparse → Add virtual nodes / edges
 - The graph is too dense → Sample neighbors when doing message passing
 - The graph is too large → Sample subgraphs to compute embeddings

Graph Convolutional Networks



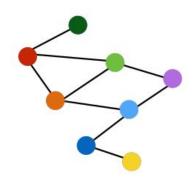
Inductive Capability

- The same aggregation parameters are shared for all nodes:
 - The number of model parameters is sublinear in |V| and we can generalize to unseen nodes!

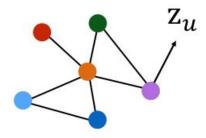


Inductive Capability: New Graphs

Inductive node embedding \rightarrow Generalize to entirely unseen graphs

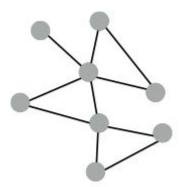


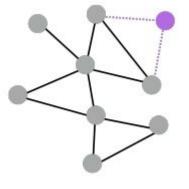
Train on one graph

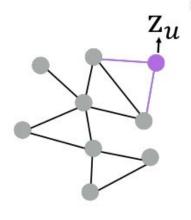


Generalize to new graph

Inductive Capability : New Nodes







Train with snapshot

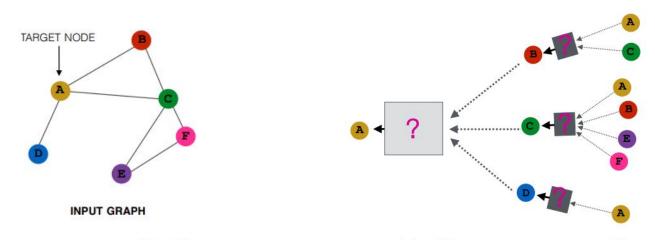
New node arrives

Generate embedding for new node



GraphSAGE (I)

Generalized neighborhood aggregation



$$\mathbf{h}_{v}^{(l+1)} = \sigma([\mathbf{W}_{l} \cdot \mathbf{AGG}\left(\left\{\mathbf{h}_{u}^{(l)}, \forall u \in N(v)\right\}\right), \mathbf{B}_{l}\mathbf{h}_{v}^{(l)}])$$

GraphSAGE (II)

- Neighbor Aggregation:
 - Mean: Take a weighted average of neighbors
 - Pool: Transform neighbor vectors and apply symmetric vector function
 - LSTM: Apply LSTM to reshuffled of neighbors
- L2 Normalization:
 - Apply L2 normalization to the embedding in each layer

Graph Attention Networks (I)

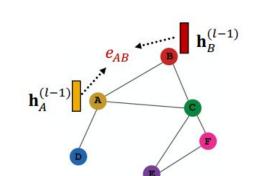
Not all node's neighbors are equally important

- Attention is inspired by cognitive attention.
- The attention focuses on the important parts of the input data and fades out the rest.
 - Idea: the NN should devote more computing power on that small but important part of the data.
 - Which part of the data is more important depends on the context and is learned through training.

Graph Attention Networks (II)

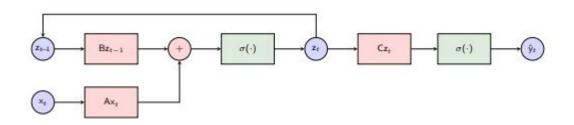
- Goal: Specify arbitrary importance to different neighbors of each node in the graph
- Idea: Compute embedding of each node in the graph following an attention strategy:
 - Nodes attend over their neighborhoods' message
 - Implicitly specifying different weights to different nodes in a neighborhood

$$e_{AB} = a(\mathbf{W}^{(l)}\mathbf{h}_A^{(l-1)}, \mathbf{W}^{(l)}\mathbf{h}_B^{(l-1)})$$

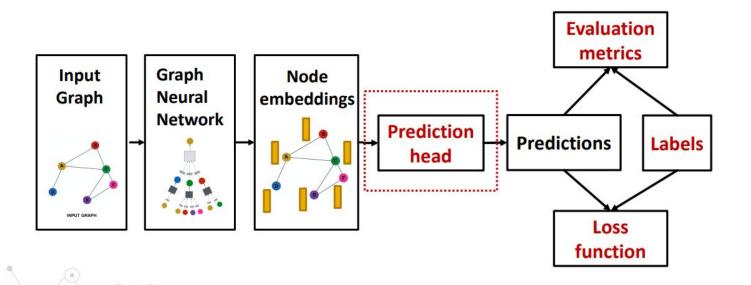


Graph Recurrent Neural Network

- A graph recurrent neural network (GRNN) combines:
 - GNN because xt is supported on a graph.
 - RNN because xt is a sequence



Prediction With GNN



Different prediction heads

- Node-level tasks: We can directly make prediction using node embeddings
- Edge-level tasks: Make prediction using pairs of node embeddings

O Graph-level tasks: Make prediction using pairs of node embeddings

References

- [1] Kipf, Thomas N., and Max Welling. "Semi-supervised classification with graph convolutional networks." arXiv preprint arXiv:1609.02907 (2016)
- [2] Hamilton, Will, Zhitao Ying, and Jure Leskovec. "Inductive representation learning on large graphs." *Advances in neural information processing systems* 30 (2017).
- [3] You, Jiaxuan, Zhitao Ying, and Jure Leskovec. "Design space for graph neural networks." *Advances in Neural Information Processing Systems* 33 (2020): 17009-17021.
- [4] Zhou, Jie, Ganqu Cui, Shengding Hu, Zhengyan Zhang, Cheng Yang, Zhiyuan Liu, Lifeng Wang, Changcheng Li, and Maosong Sun. "Graph neural networks: A review of methods and applications." *Al open* 1 (2020): 57-81.
- [5] CS224W: Machine Learning with Graphs (Stanford university)

THANK YOU FOR YOUR ATTENTION!!!



