## 3.5°

## **Internal Interrupts**



Timers are one of the most essential parts in every microcontroller unit. By utilizing them the designers can perform time sensitive operations such as creating PWM signals or executing a critical code on a regular basis. ATMEGA328p (Arduino Uno's microcontroller) contains three timers labeled as TIMER0, TIMER1 and TIMER2. TIMER0 and TIMER 2 are 8-bit timers and TIMER1 is a 16-bit timer.

In this experiment we want to use TIMER1 to generate a PWM signal on pin 4. This pins is not connected to any hardware PWM generation unit thus we can't use analogWrite() function in order to generate PWM signal on this pin.

TIMER1 has three different operating modes: CTC, Fast PWM and Phase corrected PWM. As mentioned, pin 4 is not connected to hardware PWM unit so we cannot use the timer in the PWM mode, and we should set the timer's operating mode to CTC. In this mode the timer starts to count from zero and is incremented on each timer's cycle. The value of timer counter register (TCNT) is then compared to a compare register (OCR) and if it matches the value stored in this register, it will trigger a compare match interrupt. By setting the appropriate registers we can register an ISR for servicing the interrupt (Refer to the device datasheet for further reading).

The last thing we need to configure is the timer's prescaler. The prescaler simply determines the counting frequency of the timer. For example, if the prescaler is set to one, the timer counts on each microcontrollers' clock cycle and if it is set to 1/8, it counts with 1/8 speed of the microcontroller clock speed.

For this experiment we set the timer to CTC mode with the prescaler value of 1/8 and write an ISR to switch pin 4 in a manner that creates a PWM signal with adjustable duty cycle between 10% and 90%. The PWM resolution should be 10-bits and the duty cycle should be adjusted using a potentiometer. we can monitor the generated signal using an oscilloscope in Proteus. Arduino configures the timer configuration registers on boot and it needs to be reseted before applying our own settings.

Components used in proteus:

SIMULINO UNO, POT-HG, oscilloscope



