Differentiation

Imagine a bug that moves with constant speed on a circular path of radius r around the origin. The angle of the bug's position vector with the +x axis can be written as

$$\theta = \omega t + a$$
.

Assume a = 0, so that the bug is on the +x axis at time 0. Then the position vector of the bug is

$$X(t) = (r\cos(\omega t), r\sin(\omega t)).$$

Now imagine the bug lives in \mathbb{R}^3 with

$$X(t) = (\cos(t), \sin(t), t).$$

This lifts the circular path into a helix.

In general, a **parametrized curve** $X:I\to\mathbb{R}^n$ is a vector-valued function that maps points from an interval I into n-space. In the examples above, I is the entire real line \mathbb{R} (which we consider to be an interval). We can write X(t) as its individual coordinate functions

$$X(t) = (x_1(t), \dots, x_n(t)).$$

Just as with ordinary real-valued function, we can take derivatives by looking at the limit

$$\lim_{h \to 0} \frac{X(t+h) - X(t)}{h}.$$

Here, dividing by h really means scaling the vector by 1/h. Writing out components, this is simply

$$\lim_{h \to 0} \frac{(x_1(t+h) - x_1(t), \dots, x_n(t+h) - x_n(t))}{h}.$$

If the individual components are all differentiable, we obtain a new vector-valued function

$$X'(t) = (x'_1(t), \dots, x'_n(t)).$$

X'(t) is called the **derivative** or **velocity** of X(t).

So for the example $X(t) = (\cos(t), \sin(t), t)$, we have

$$X'(t) = (-\sin(t), \cos(t), 1).$$

The velocity is parallel to the direction of instantaneous motion.

Example. Find a parametric equation of the tangent line to the curve $X(t) = (\sin t, \cos t)$ at $t = \pi/3$.

We need two pieces of information: a point on the line, and a direction vector of the line. These are supplied by $X(\pi/3)$ and $X'(\pi/3)$ respectively. The tangent line L(t) can

thus be written

$$L(s)|_{t=\pi/3} = X(\pi/3) + sX'(\pi/3)$$
$$= \left(\frac{\sqrt{3}}{2} + \frac{1}{2}s, \frac{1}{2} - \frac{\sqrt{3}}{2}s\right).$$

We used the parameter s for the line to avoid confusion with the already defined X(t) above. The **speed** of the curve X(t), denoted v(t), is defined to be

$$v(t) = ||X'(t)||.$$