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```
% Zain Bhaila
% Math 240 Fall 2018 Project 3
% Section 0132
clc
```

Problem 0

```
format rat
clock
```

ans =

Columns 1 through 5

2018	10	29	15	1
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Column 6

2188/99

Problem 1

```
format short

% Problem 1(a)
A = [1 cos(0) cos(0).^2 cos(0).^3 ; 1 cos(0.1) cos(0.1).^2 cos(0.1).^3 ;
     1 cos(0.2) cos(0.2).^2 cos(0.2).^3 ; 1 cos(0.3) cos(0.3).^2 cos(0.3).^3]

% Problem 1(b)
rref(A)
det(A)

% Problem 1(c)
% The rref shows that Ax = 0 has only the trivial solution
% and the detA /= 0, so A is invertible.

% Problem 1(d)
A = [1 cos(0) cos(0).^2 cos(0).^3 ; 1 cos(1) cos(1).^2 cos(1).^3 ;
```

```
1 cos(0.2) cos(0.2).^2 cos(0.2).^3 ; 1 cos(0.5) cos(0.5).^2 cos(0.5).^3]
det(A)
```

```
% Problem 1(e)
% sin^2 + cos^2 = 1, so since 1 can be written as a linear
% combination of sin^2 and cos^2, the set is linearly dependent
```

A =

1.0000	1.0000	1.0000	1.0000
1.0000	0.9950	0.9900	0.9851
1.0000	0.9801	0.9605	0.9414
1.0000	0.9553	0.9127	0.8719

ans =

1	0	0	0
0	1	0	0
0	0	1	0
0	0	0	1

ans =

6.5176e-11

A =

1.0000	1.0000	1.0000	1.0000
1.0000	0.5403	0.2919	0.1577
1.0000	0.9801	0.9605	0.9414
1.0000	0.8776	0.7702	0.6759

ans =

1.7052e-05

Problem 2

```
format rat
A = [0 -9 -3 -1 ; 2 -1 -1 -2 ; 1 13 4 2 ; 9 -3 -4 -9 ; 1 -2 -1 -1]
```

```
% Problem 2(a)
rank(A)
```

```
% Problem 2(b)
% rankA = dimColA = dimRowA = 3
% dimNulA = n - rankA = 4-3 = 1
```

```
% Problem 2(c)
```

```
rref(A)
N = [1/3 ; -1/3 ; 0 ; 0] % NulA
C = [0 -9 -1 ; 2 -1 -2 ; 1 13 2 ; 9 -3 -9 ; 1 -2 -1] % ColA
R = [0 2 1 ; -9 -1 -13 ; -3 -1 4 ; -1 -2 2] % RowA
```

A =

0	-9	-3	-1
2	-1	-1	-2
1	13	4	2
9	-3	-4	-9
1	-2	-1	-1

ans =

3

ans =

1	0	-1/3	0
0	1	1/3	0
0	0	0	1
0	0	0	0
0	0	0	0

N =

1/3
-1/3
0
0

C =

0	-9	-1
2	-1	-2
1	13	2
9	-3	-9
1	-2	-1

R =

0	2	1
-9	-1	-13
-3	-1	4
-1	-2	2

Problem 3

```

% Problem 3(a)
v1 = [2;1;3;1]
v2 = [3;4;7;3]
v3 = [1;-3;8;5]
v4 = [0;5;5;3]
v5 = [-1;2;1;1]

% Problem 3(b)
A = [v1 v2 v3 v4 v5]
rref(A) % columns with pivots form a basis for ColA
B = [v1 v2 v3] % basis for the span

% Problem 3(c)
% basis of W = {p1, p2, p3}, dimW = 3

% Problem 3(d)
% W  $\neq$  P3 because W must have 4 linearly independent
% vectors to span P3, and it has 3 since dimW = 3

```

v1 =

2
1
3
1

v2 =

3
4
7
3

v3 =

1
-3
8
5

v4 =

0
5
5
3

v5 =

-1
2

1
1

A =

2	3	1	0	-1
1	4	-3	5	2
3	7	8	5	1
1	3	5	3	1

ans =

1	0	0	-3	-2
0	1	0	2	1
0	0	1	0	0
0	0	0	0	0

B =

2	3	1
1	4	-3
3	7	8
1	3	5

Problem 4

```
% Problem 4(a)
v1 = [2;2;-2;3;-12;1]
v2 = [4;1;2;-2;-3;2]
v3 = [0;2;1;-3;-4;0]
v4 = [4;-2;-1;5;0;2]

% Problem 4(b)
A = [v1 v2 v3 v4]
rref(A)
% v4 can be written as a linear combination of the other 3

% Problem 4(c)
% -2/5 * A1 + -4/5 * A2 + 9/5 * A3 = A4
```

v1 =

2
2
-2
3
-12
1

v2 =

4
1
2
-2
-3
2

v3 =

0
2
1
-3
-4
0

v4 =

4
-2
-1
5
0
2

A =

2	4	0	4
2	1	2	-2
-2	2	1	-1
3	-2	-3	5
-12	-3	-4	0
1	2	0	2

ans =

1	0	0	2/5
0	1	0	4/5
0	0	1	-9/5
0	0	0	0
0	0	0	0
0	0	0	0

Problem 5

```
% Problem 5(a)
P = [1 0 0 0 ; 1 2 0 0 ; 2 -1 3 0 ; 4 -1 0 1] % B -> e
Q = [1 0 0 0 ; 1 2 0 0 ; 2 -1 3 0 ; 4 -1 0 1] % C -> e
```

```
% Problem 5(b)
R = inv(Q) * P

% Problem 5(c)
x = Q * [0;0;0;1]

% Problem 5(d)
b = [0;3;2;1]
c = R * b
```

P =

1	0	0	0
1	2	0	0
2	-1	3	0
4	-1	0	1

Q =

1	0	0	0
1	2	0	0
2	-1	3	0
4	-1	0	1

R =

1	0	0	0
0	1	0	0
0	0	1	0
0	0	0	1

x =

0
0
0
1

b =

0
3
2
1

c =

0
3
2

