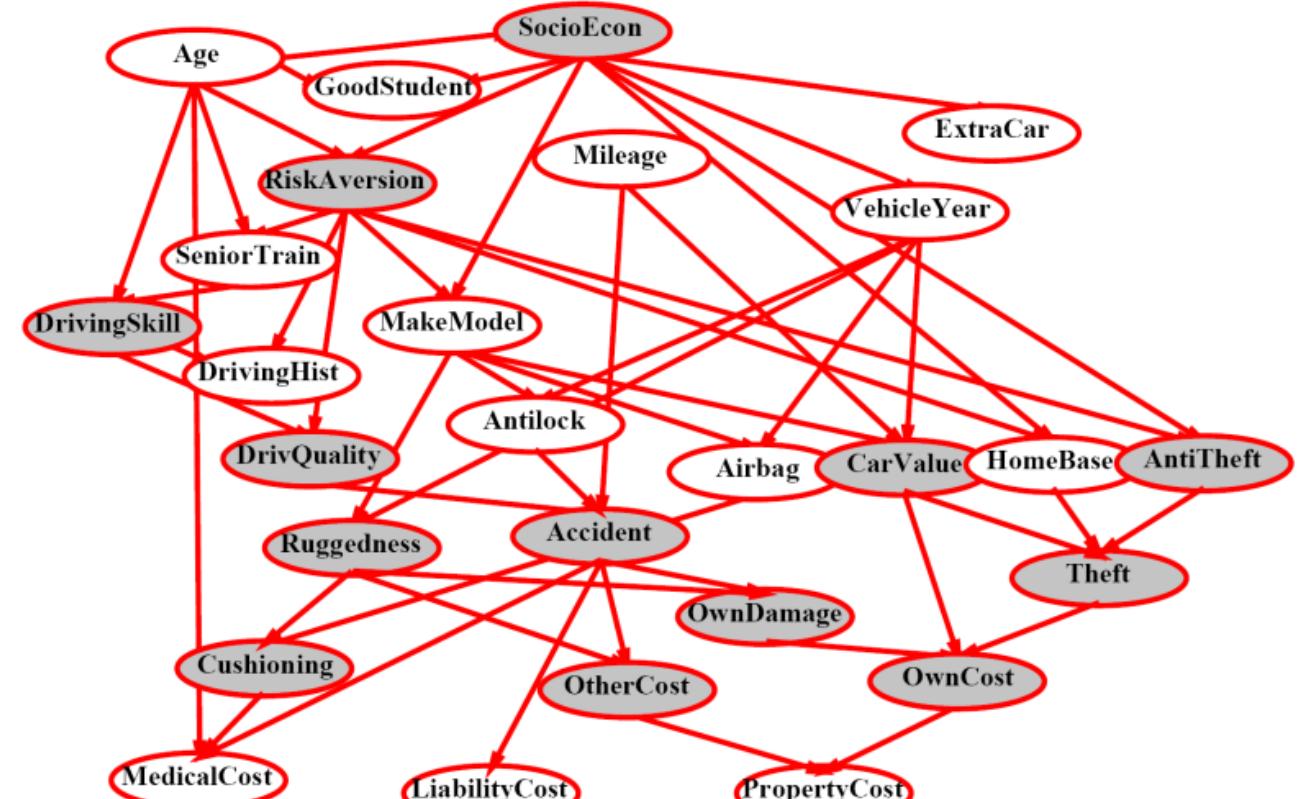


CSCI 3202: Intro to Artificial Intelligence

Lecture 15 & 16: Introduction to Bayesian Networks

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Uncertainty

Probabilistic reasoning gives us a framework for managing uncertain beliefs and knowledge.

In general:

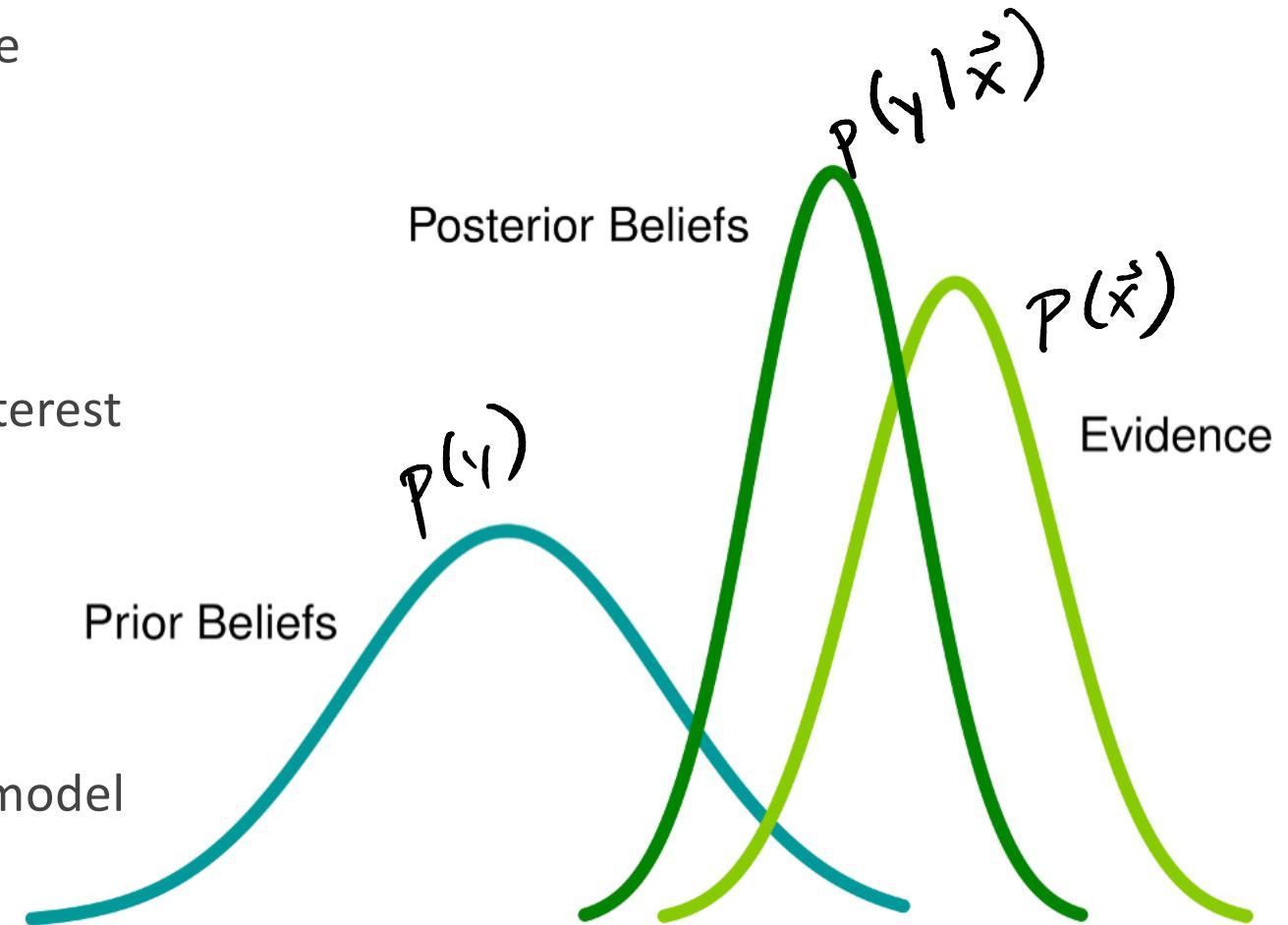
- **Observed variables (evidence):** Agent knows certain things about the state of the world (e.g. sensor readings or symptoms)
- **Unobserved variables:** Agent needs to reason about other aspects (e.g. where an object is or what disease is present)
- **Model:** Agent knows something about how the known variables relate to the unknown variables

Bayesian Network is a type of model.
→ specifically a type of graphical models.

Bayesian Reasoning

The whole Bayesian statistical framework can be summarized as follows:

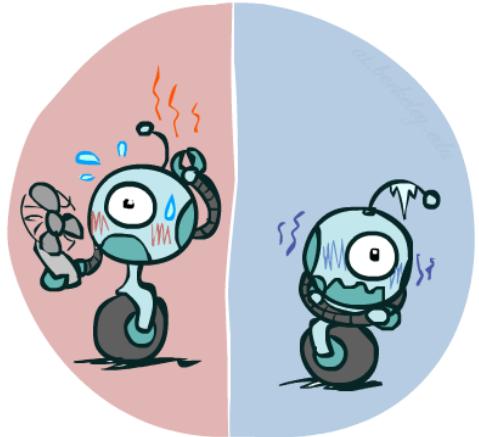
- What is your process of interest?
- Get **data** (evidence) for your process of interest
- Build a **model** $\eta(\theta)$ of this process
Depends on uncertain parameters θ
- Formalize your *a priori* knowledge of the model parameters θ in **prior distributions**, $P(\theta)$
- **Update** your prior knowledge using the match between your model and the data



Probability Distributions

- Associate a probability with each value

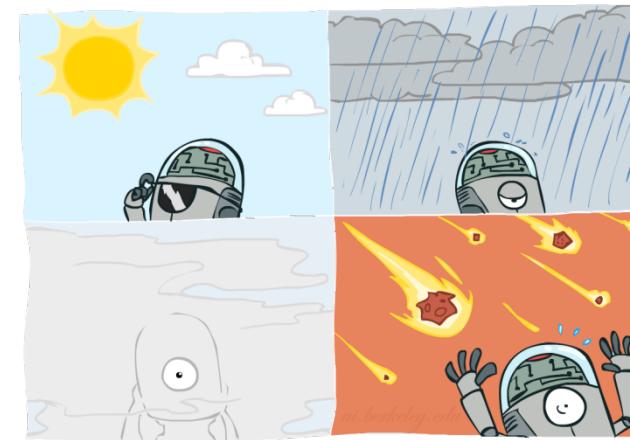
- Temperature:



$P(T)$

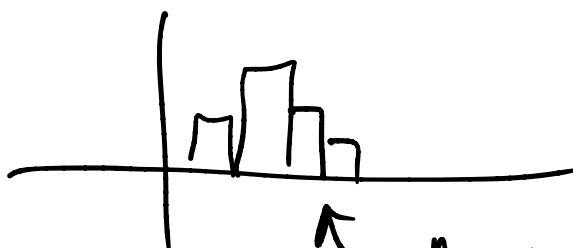
T	P
hot	0.5
cold	0.5

- Weather:



$P(W)$

W	P
sun	0.6
rain	0.1
fog	0.3
meteor	0.0



Area has to
 $= 1$

$$\sum_x f(x) = 1$$

And $P(x) \geq 0$

0.00001

↑

Joint Distributions

- A *joint distribution* over a set of random variables: X_1, X_2, \dots, X_n specifies a real number for each assignment (or *outcome*):

- $P(X_1 = x_1, X_2 = x_2, X_3 = x_3, \dots, X_n = x_n)$ or equivalently: $P(x_1, x_2, \dots, x_n)$

↑ ↑ ↑

★ $P(T, W)$

- Must obey: $P(x_1, x_2, \dots, x_n) \geq 0$ and

$$\sum_{(x_1, x_2, \dots, x_n)} P(x_1, x_2, \dots, x_n) = 1$$

- Size of distribution if n variables with domain sizes d ?

$\underbrace{d^n}$

- For all but the smallest distributions, impractical to write out!

T	W	P
hot	sun	0.4
hot	rain	0.1
cold	sun	0.2
cold	rain	0.3

$p(T = \text{hot}, W = \text{sun})$
 $= p(\text{hot} \cap \text{sun}) = 0.4$
 $= P(\text{hot, sun})$

Probability Models

- A probability model is a joint distribution over a set of random variables
- Probability models:
 - (Random) variables with domains
 - Assignments are called *outcomes*
 - Joint distributions: say whether assignments (outcomes) are likely
 - *Normalized*: sum to 1.0
 - *Ideally*, only certain variables directly interact

Joint
Distribution over T,W

T	W	P
hot	sun	0.4
hot	rain	0.1
cold	sun	0.2
cold	rain	0.3



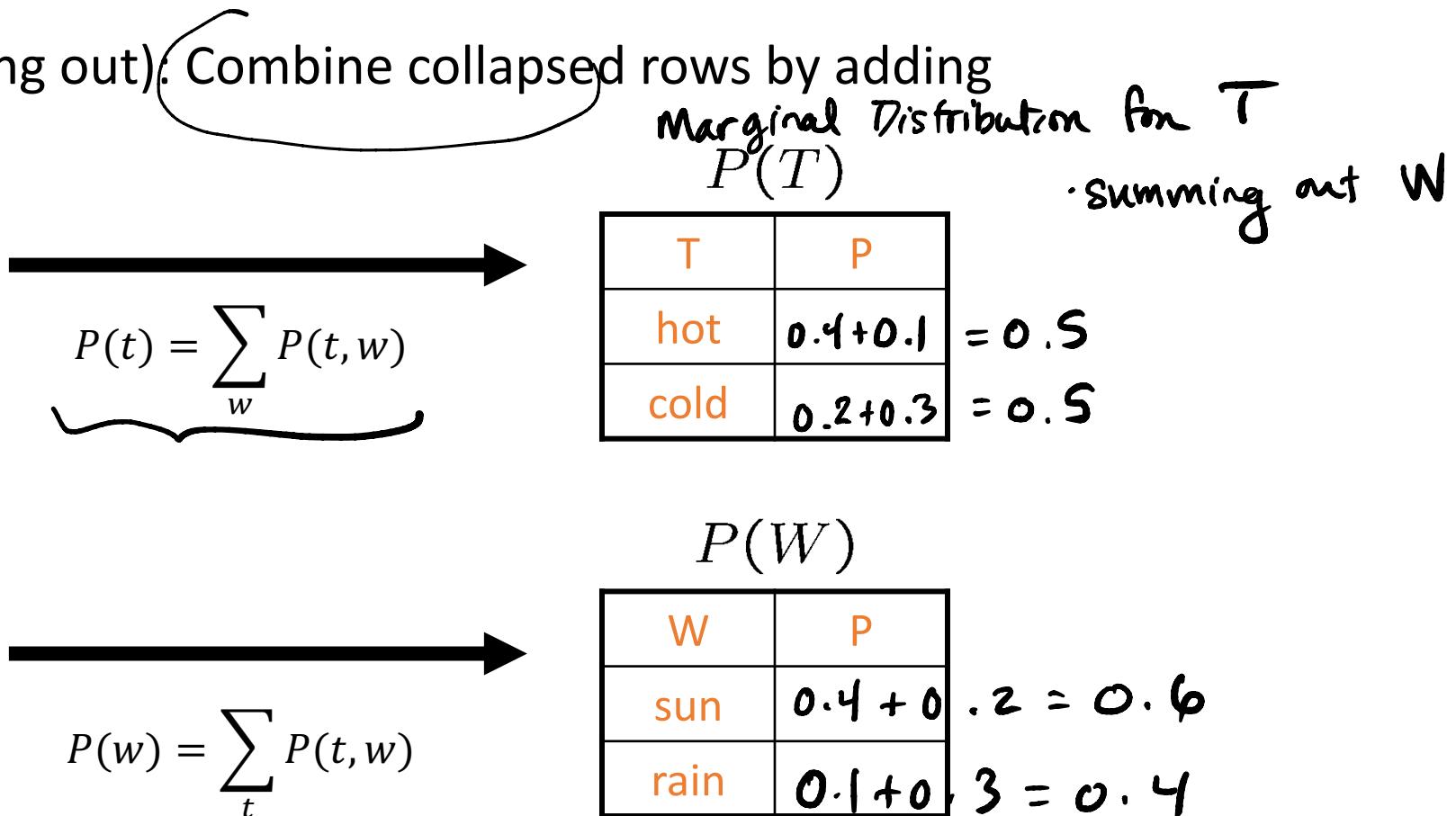
Marginal Distributions

- Marginal distributions are sub-tables which eliminate variables
- Marginalization (summing out): Combine collapsed rows by adding

Joint Distribution

$P(T, W)$

T	W	P
hot	sun	0.4
hot	rain	0.1
cold	sun	0.2
cold	rain	0.3



e.g. $P(X_1 = x_1) = \sum_{x_2} P(X_1 = x_1, X_2 = x_2)$

Independence (recall)
 $P(A \cap B) = P(A) \cdot P(B)$

Probability Models

Example:

- $P(+x, +y) ? = 0.2$

$$P(X, Y)$$

- $P(+x) ? = 0.2 + 0.3 = 0.5$

- $P(-y \text{ OR } +x) ? = 0.2 + 0.3 + 0.1 = 0.6$

X	Y	P
+x	+y	0.2
+x	-y	0.3
-x	+y	0.4
-x	-y	0.1

Marginal Distributions

$P(X, Y)$

X	Y	P
+x	+y	0.2
+x	-y	0.3
-x	+y	0.4
-x	-y	0.1

$$P(x) = \sum_y P(x, y)$$

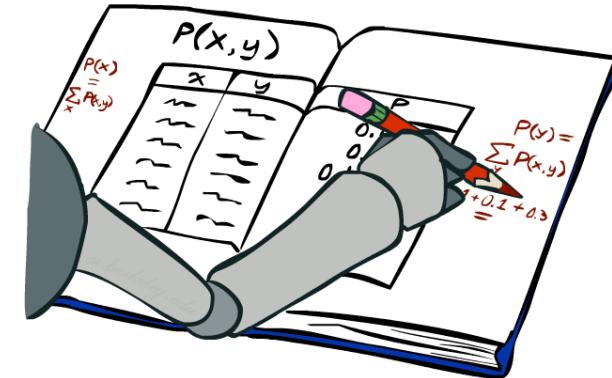
$$P(y) = \sum_x P(x, y)$$

$P(X)$

X	P
+x	0.5
-x	0.5

$P(Y)$

Y	P
+y	0.6
-y	0.4



Conditional Probabilities

def. of conditional probability,

Joint Probability distribution for X, Y
 $P(X, Y)$

X	Y	P
+x	+y	0.2
+x	-y	0.3
-x	+y	0.4
-x	-y	0.1

- $P(+x | +y) ? = \frac{P(+x, +y)}{P(+y)} = \frac{0.2}{0.2+0.4} = \boxed{\frac{1}{3}}$

- $P(-x | +y) ? = 1 - \frac{1}{3} = \frac{2}{3}$

OR

$$= \frac{P(-x, +y)}{P(+y)} = \frac{0.4}{0.2+0.4} = \boxed{\frac{2}{3}}$$

- $P(-y | +x) ?$

$$= \boxed{\frac{3}{5}}$$

Conditional Distributions

- Conditional distributions are probability distributions over some variables given fixed values of others

Conditional Distributions

$$P(W|T)$$
$$P(W|T = \text{hot})$$

W	P
sun	0.8
rain	0.2

$$P(W|T = \text{cold})$$

W	P
sun	0.4
rain	0.6

Joint Distribution

$$P(T, W)$$

T	W	P
hot	sun	0.4
hot	rain	0.1
cold	sun	0.2
cold	rain	0.3

$P(\text{sun} | \text{hot}) = \frac{P(\text{sun, hot})}{P(\text{hot})}$

$\frac{0.4}{0.5} = \frac{4}{5}$

$P(\text{sun} | \text{cold}) = \frac{P(\text{sun, cold})}{P(\text{cold})}$

$= \frac{0.2}{0.2+0.3} = \frac{2}{5}$

Independence

- Two variables are *independent* if:

$$\forall x, y : P(x, y) = P(x)P(y)$$

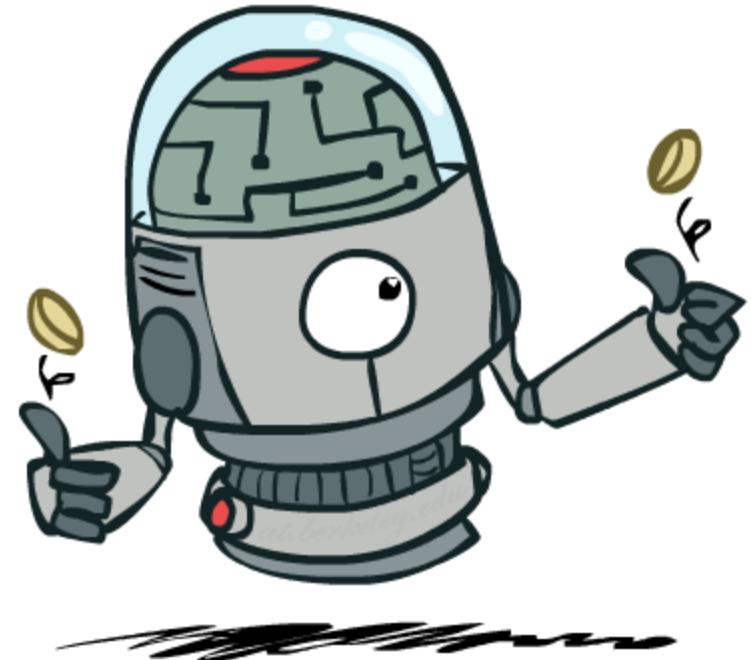
- This says that their joint distribution *factors* into a product two simpler distributions
- Another form:

$$\forall x, y : P(x|y) = P(x)$$

- Independence is a simplifying *modeling assumption*

- *Empirical* joint distributions: at best “close” to independent
- What could we assume for {Weather, Traffic, Cavity, Toothache}?

Weather, Traffic ↗
Cavity, toothache ↘



Independence

$P_1(T, W)$

T	W	P
hot	sun	0.4
hot	rain	0.1
cold	sun	0.2
cold	rain	0.3

$P(T)$

T	P
hot	0.5
cold	0.5

$P_2(T, W)$

T	W	P
hot	sun	0.3
hot	rain	0.2
cold	sun	0.3
cold	rain	0.2

$P(W)$

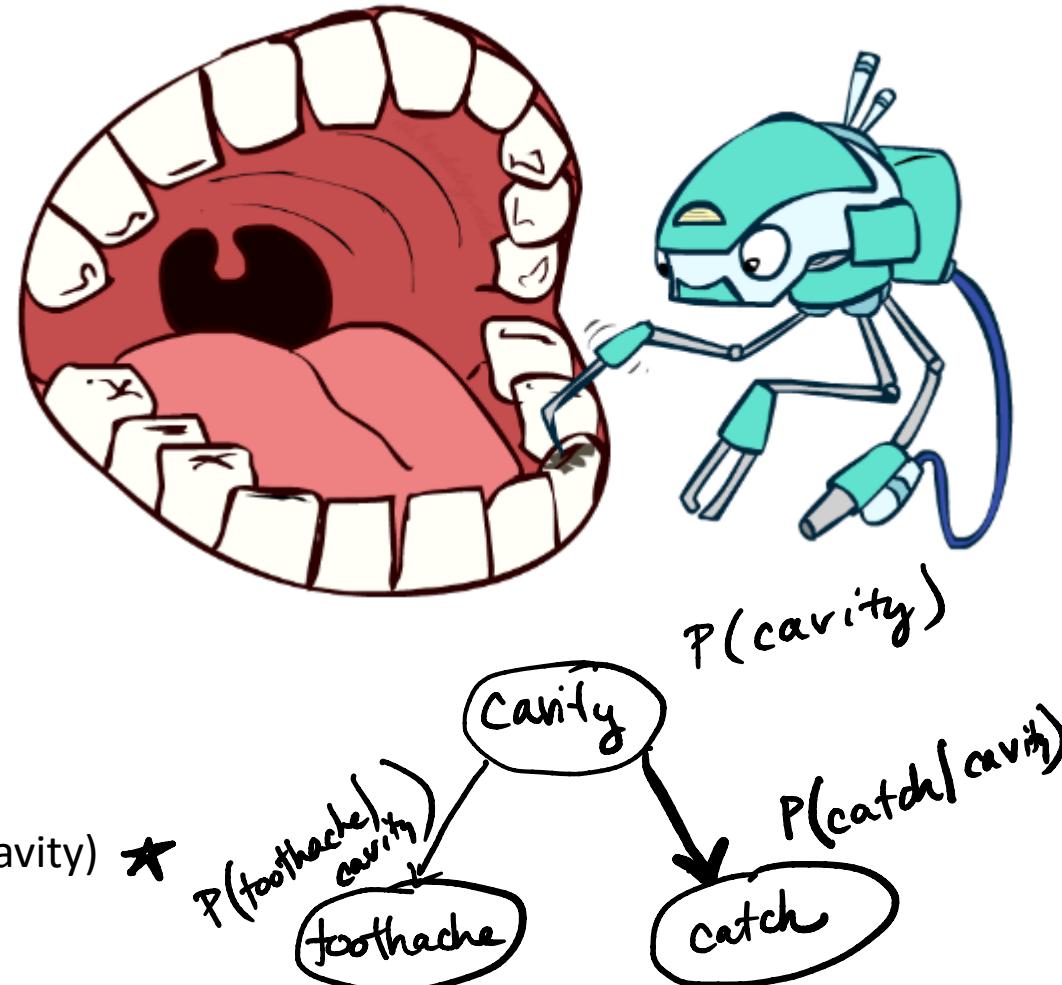
W	P
sun	0.6
rain	0.4

For independence to hold, we need $\forall t, w \quad P(t, w) = P(t)P(w)$

$P(\text{hot})P(\text{sun}) = (0.5)(0.6) = 0.3 \neq$
 $P(\text{hot, sun}) = 0.4$

Conditional Independence

- $P(\text{Toothache}, \text{Cavity}, \text{Catch})$
joint probability distribution
- If I have a cavity, the probability that the probe catches it doesn't depend on whether I have a toothache:
 - $P(+\text{catch} | +\text{toothache}, +\text{cavity}) = P(+\text{catch} | +\text{cavity})$
- The same independence holds if I don't have a cavity:
 - $P(+\text{catch} | +\text{toothache}, -\text{cavity}) = P(+\text{catch} | -\text{cavity})$
- Catch is *conditionally independent* of Toothache given Cavity:
 - $P(\text{Catch} | \text{Toothache}, \text{Cavity}) = P(\text{Catch} | \text{Cavity})$ *
- **Equivalent statements:**
 - $P(\text{Toothache} | \text{Catch}, \text{Cavity}) = P(\text{Toothache} | \text{Cavity})$ ↗
 - $P(\text{Toothache}, \text{Catch} | \text{Cavity}) = P(\text{Toothache} | \text{Cavity}) P(\text{Catch} | \text{Cavity})$ *
 - One can be derived from the other easily



Conditional Independence

- Unconditional (absolute) independence very rare (why?)
- *Conditional independence* is our most basic and robust form of knowledge about uncertain environments.
- X is conditionally independent of Y given Z

if and only if: $\forall x, y, z : P(x, y|z) = P(x|z)P(y|z)$

or, equivalently, if and only if $\forall x, y, z : P(x|z, y) = P(x|z)$

Bayesian Networks

$$\text{joint: } P(B, E, A, J, M)^*$$

The point of Bayes nets is to represent full joint probability distributions, and

to encode an interrelated set of conditional independence/probability statements

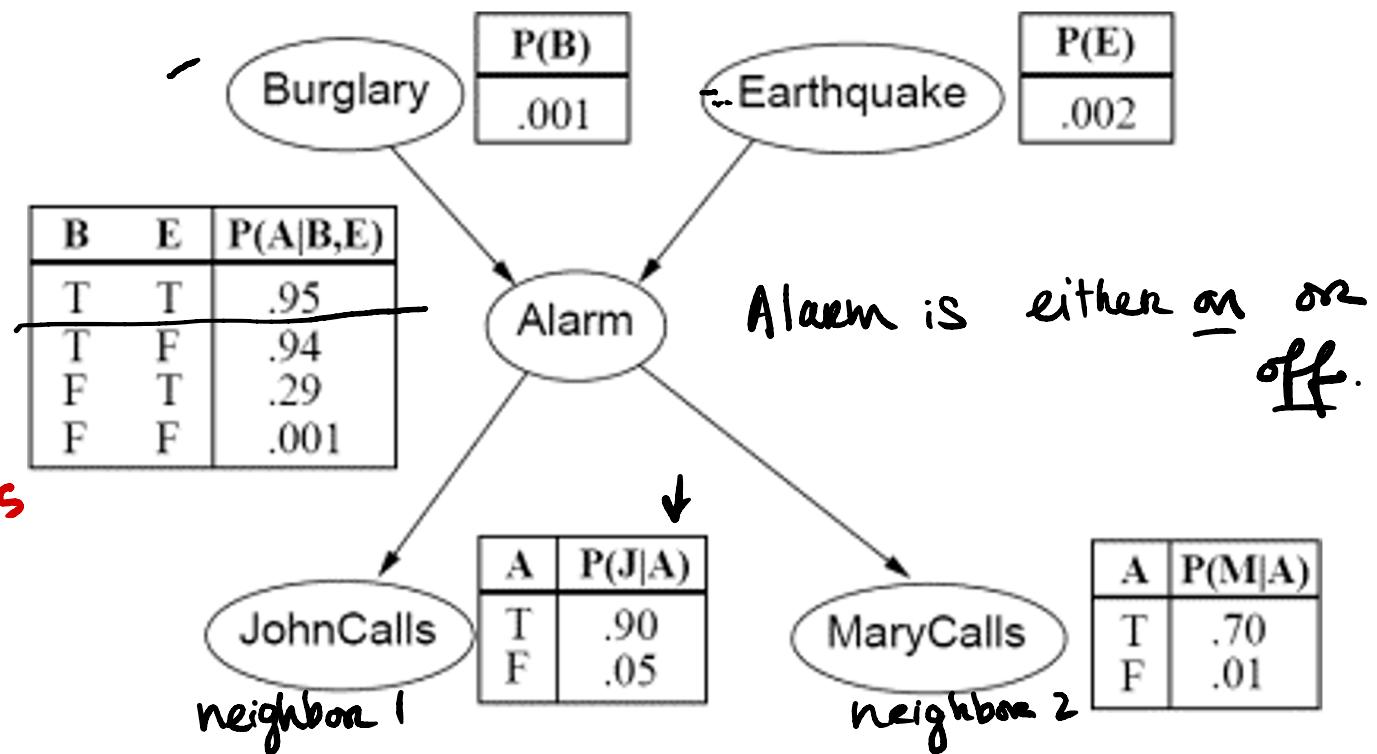
- **Directed Acyclic Graph (DAG)**

- Consists of **nodes** (events), and
- **conditional probability tables (CPTs)**, relating those events

- Describe how variables interact locally

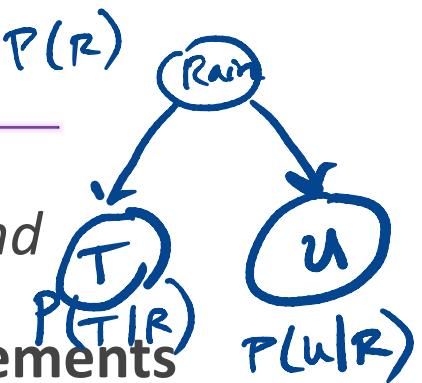
$$P(+A|+B, +E) = .95$$
$$P(-A|+B, +E) = .05$$

- Chain together local interactions to estimate **global, indirect** interactions



Bayesian Networks

The point of Bayes nets is to **represent full joint probability distributions**, and to encode an interrelated set of **conditional independence/probability statements**



Example: Represent the full joint distribution for $P(\text{Traffic}, \text{Rain}, \text{Umbrella})$

Trivial decomposition: $P(T, R, u) = P(u | T, R) \cdot P(T, R) = \underbrace{P(u | T, R)}_{\substack{\text{Chain} \\ \text{Rule}}} \cdot \underbrace{P(T | R) P(R)}_{\substack{\text{Chain} \\ \text{Rule}}}$

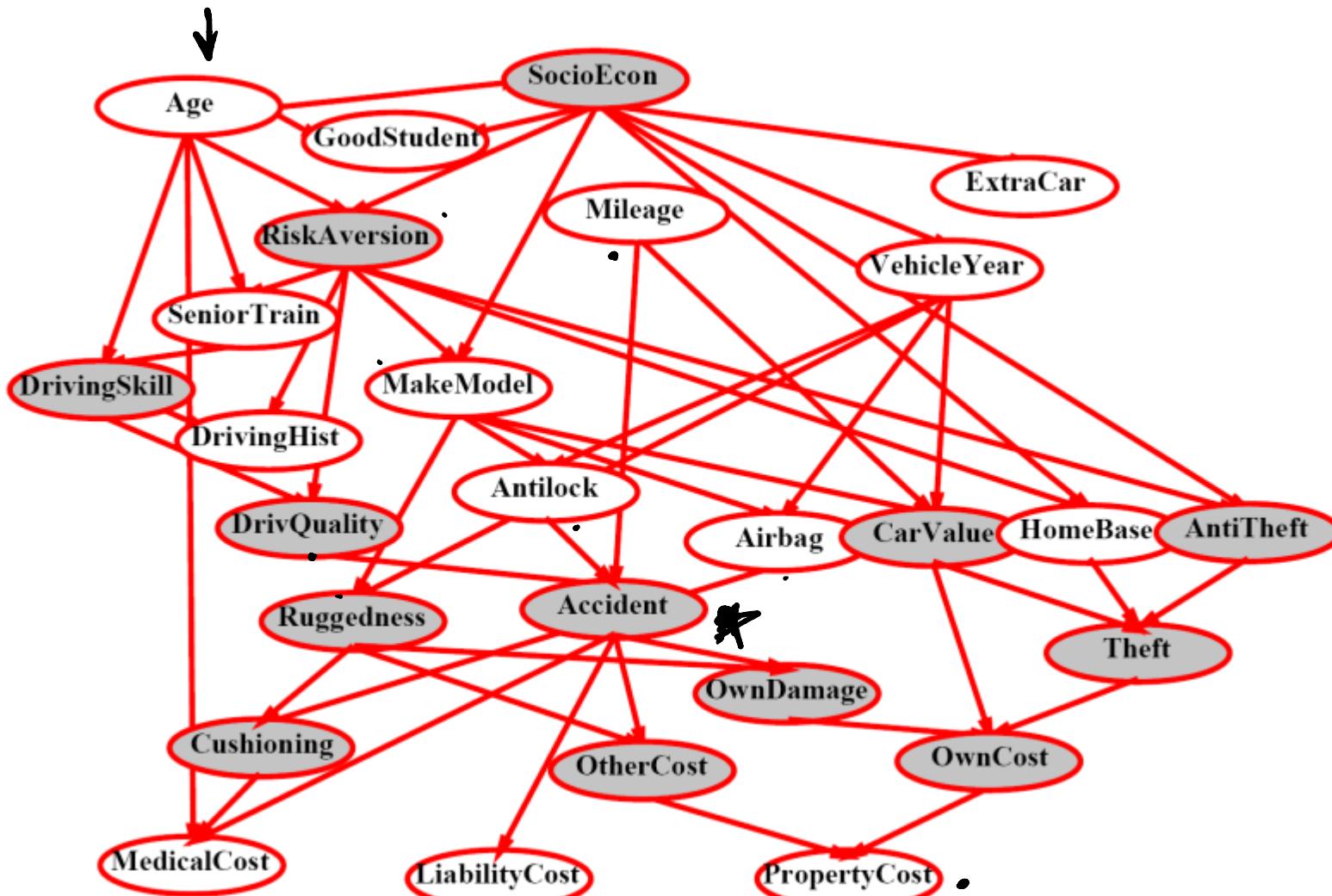
Conditional independence: We can make an assumption that Traffic and Umbrellas are conditionally independent given Rain.

$$P(u | T, R) = P(u | R) \quad \left\{ \begin{array}{l} * \\ P(T, R, u) = P(u | R) \cdot P(T | R) P(R) \end{array} \right.$$

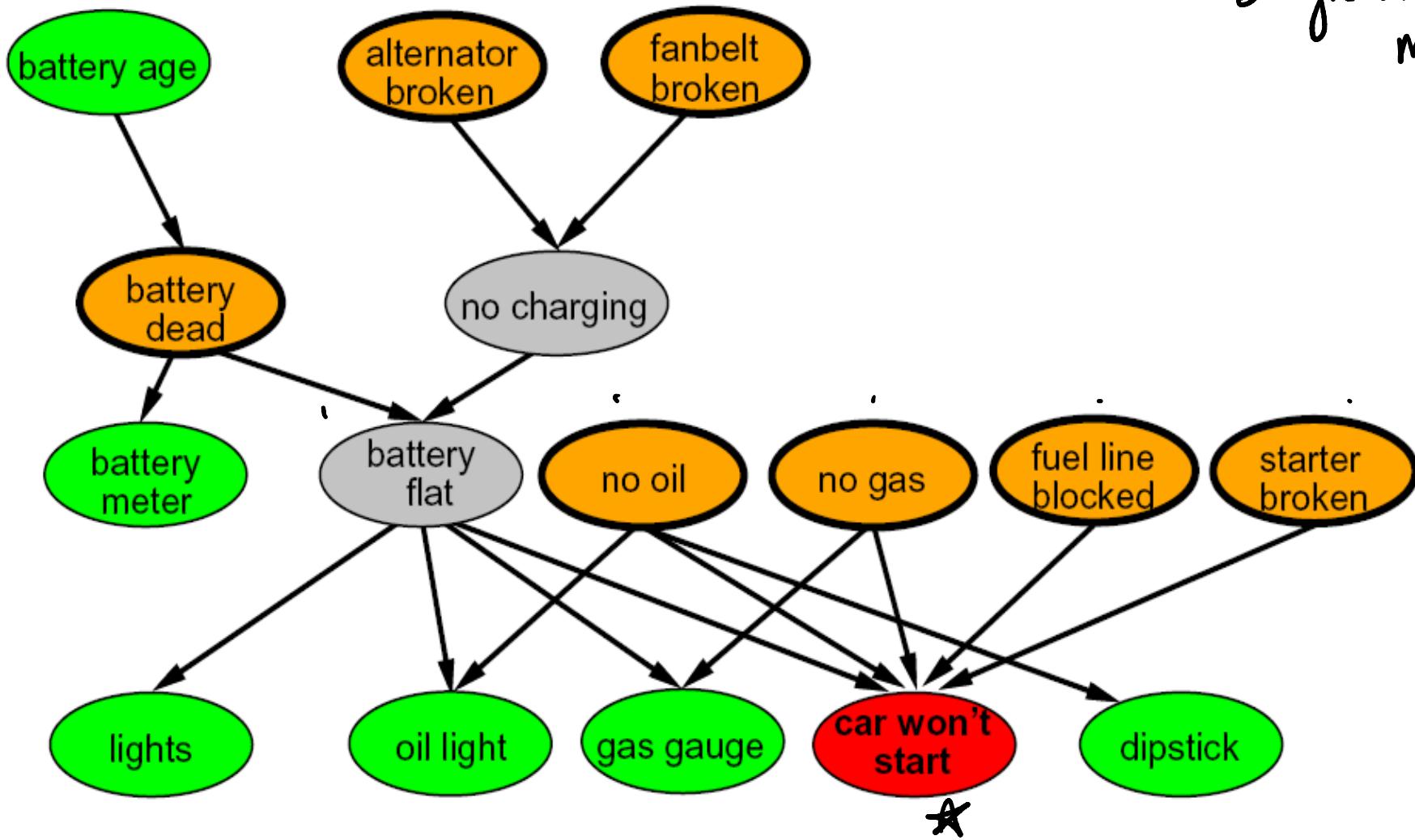
- ❖ Bayes nets (graphical models) help us compactly express conditional independence assumptions/relationships.

Graphical Model Notation

Vehicle
Insurance



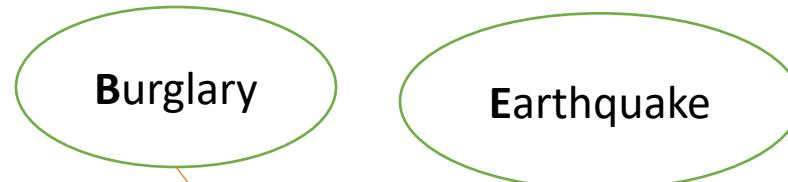
Graphical Model Notation



Bayesian Networks

P(B)	
true	false
0.001	0.999

1



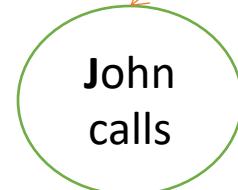
1

P(E)	
true	false
0.002	0.998



A	P(J A)	
	true	false
true	0.9	0.1
false	0.05	0.95

2



2

A	P(M A)	
	true	false
true	0.7	0.3
false	0.01	0.99

Number of free parameters in each CPT:

Parent domain sizes d_1, \dots, d_k

Child domain size d

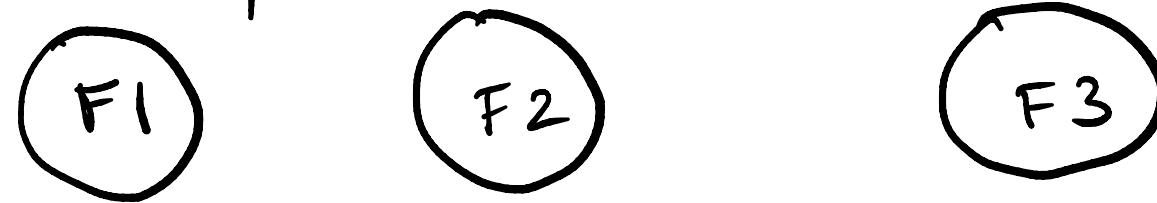
Each table row must sum to 1

$$(d-1) \prod_i d_i$$

Bayesian Networks

Example: Coin flips

Suppose we flip a coin 3 times



whenever you have a disconnected part of
a graph (in a Bayesian network) it
indicates independence

Bayesian Networks

Example: Coin flips

Reminder:

- X and Y are **independent** if $\underbrace{\forall x \forall y P(x, y) = P(x) P(y)}$,

$$X \perp\!\!\!\perp Y$$

- X and Y are **conditionally independent given Z** if $\forall x \forall y \forall z P(x, y | z) = P(x | z) P(y | z)$

$$X \perp\!\!\!\perp Y | Z$$

Bayesian Networks

Bayes nets implicitly encode joint distributions as a product of the local conditional distributions:

$$P(x_1, x_2, \dots, x_n) = ?$$

joint distribution entry

$$\begin{aligned} P(x_1, x_2, \dots, x_n) &= P(x_n | x_{n-1}, x_{n-2}, \dots, x_2, x_1) P(x_{n-1}, x_{n-2}, \dots, x_2, x_1) \\ &= P(x_n | x_{n-1}, x_{n-2}, \dots, x_2, x_1) P(x_{n-1} | x_{n-2}, \dots, x_2, x_1) P(x_{n-2}, \dots, x_2, x_1) \\ &= \dots \\ &= P(x_n | x_{n-1}, x_{n-2}, \dots, x_2, x_1) P(x_{n-1} | x_{n-2}, \dots, x_2, x_1) \dots \underbrace{P(x_3 | x_2, x_1) P(x_2 | x_1) P(x_1)}_{\curvearrowleft} \\ &= \prod_{i=1}^n P(x_i | x_{i-1}, x_{i-2}, \dots, x_2, x_1) \end{aligned}$$

Bayesian Networks

Bayes nets implicitly encode joint distributions as a product of the local conditional distributions:

$$P(x_1, x_2, \dots, x_n) = \prod_{i=1}^n P(x_i | x_{i-1}, x_{i-2}, \dots, x_2, x_1) = \dots ?$$

Node ordering: write in such a way that

→

$$\prod_{i=1}^n P(x_i | x_{i-1}, x_{i-2}, \dots, x_2, x_1)$$

entire chain rule

$$\text{parents}(X_i) \subseteq \{X_{i-1}, X_{i-2}, \dots, X_2, X_1\}$$

Simplifying assumption of conditional independence

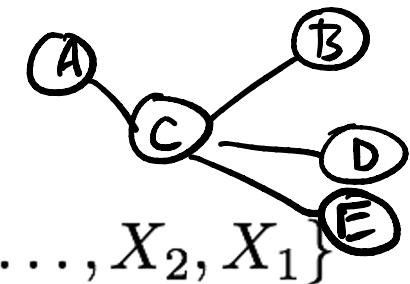
This statement:

$$P(X_i | X_{i-1}, X_{i-2}, \dots, X_2, X_1) = P(X_i | \text{parents}(X_i))$$

is key: each node is conditionally independent
of its other predecessors, given its parents



A, B, C, D, E



Bayesian Networks

Bayes nets implicitly encode joint distributions as a product of the local conditional distributions:

$$P(x_1, x_2, \dots, x_n) = \prod_{i=1}^n P(x_i \mid \text{parents}(X_i))$$

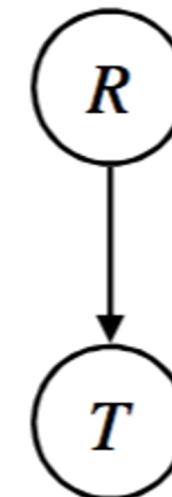
Example: Traffic

$$P(+r, -t) = ?$$

↑ this entry in the joint distribution

$$P(R, T) = P(T|R)P(R)$$

$$\begin{aligned} P(+r, -t) &= P(-t|+r)P(+r) \\ &= \frac{1}{4} \cdot \frac{1}{4} = \frac{1}{16} \end{aligned}$$



→

$P(R)$	
$+r$	$1/4$
$\neg r$	$3/4$

→

$P(T R)$	
$+r \rightarrow$	$+t$
$-r \rightarrow$	$+t$
$+r \rightarrow$	$\neg t$
$-r \rightarrow$	$\neg t$

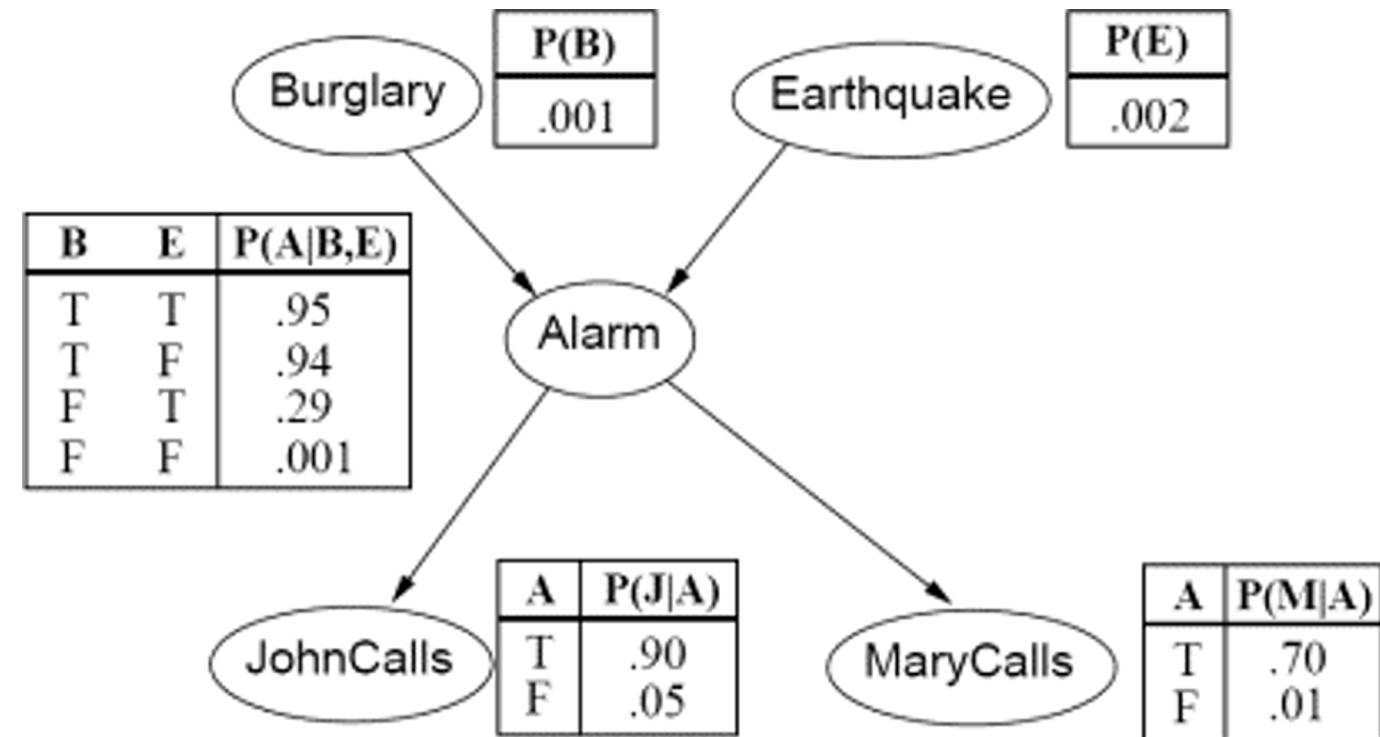
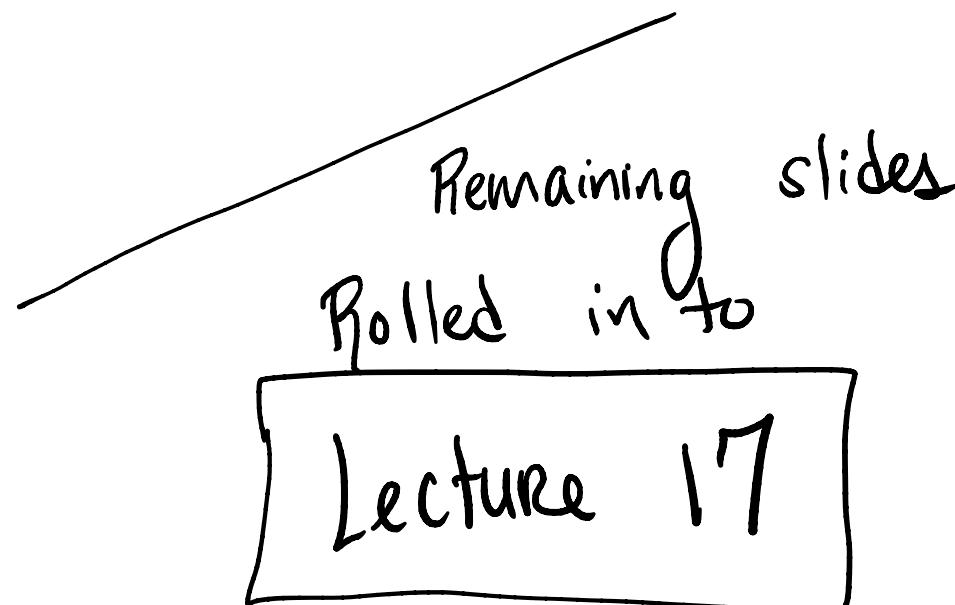
Bayesian Networks

Bayes nets implicitly encode joint distributions as a product of the local conditional distributions:

$$P(x_1, x_2, \dots, x_n) = \prod_{i=1}^n P(x_i \mid \text{parents}(X_i))$$

Example: Burglary or earthquake?

$$P(\neg j, \neg m, +a, +b, +e) = ?$$



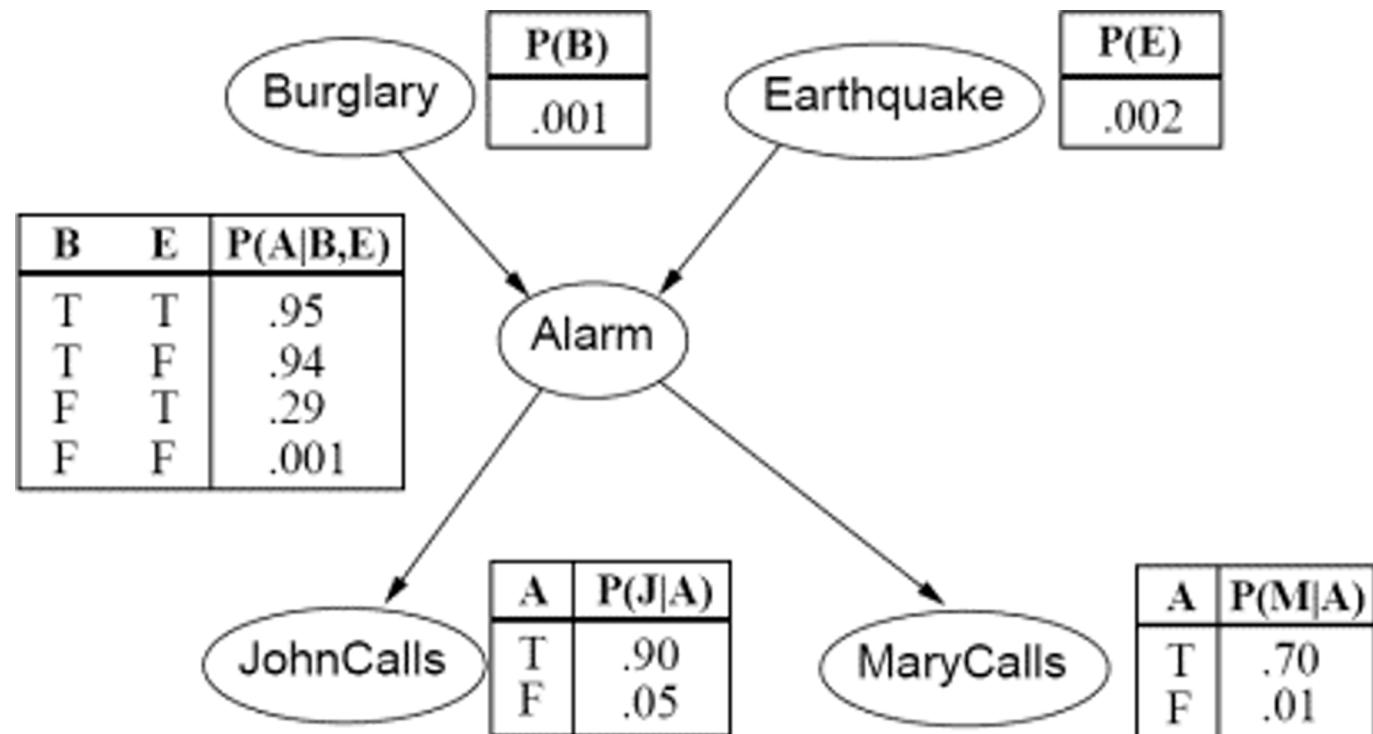
Bayesian Networks: Compactness

Full joint distribution for n Boolean nodes would require 2^n probabilities

- 5 nodes here $\rightarrow 2^5 = 32$

Bayes net representation:

- Permit $k = 2$ parents per node
- $n = 5$ nodes
- $5 \cdot 2^2 = 20$



Bayesian Networks: Compactness

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Bayes net representation:

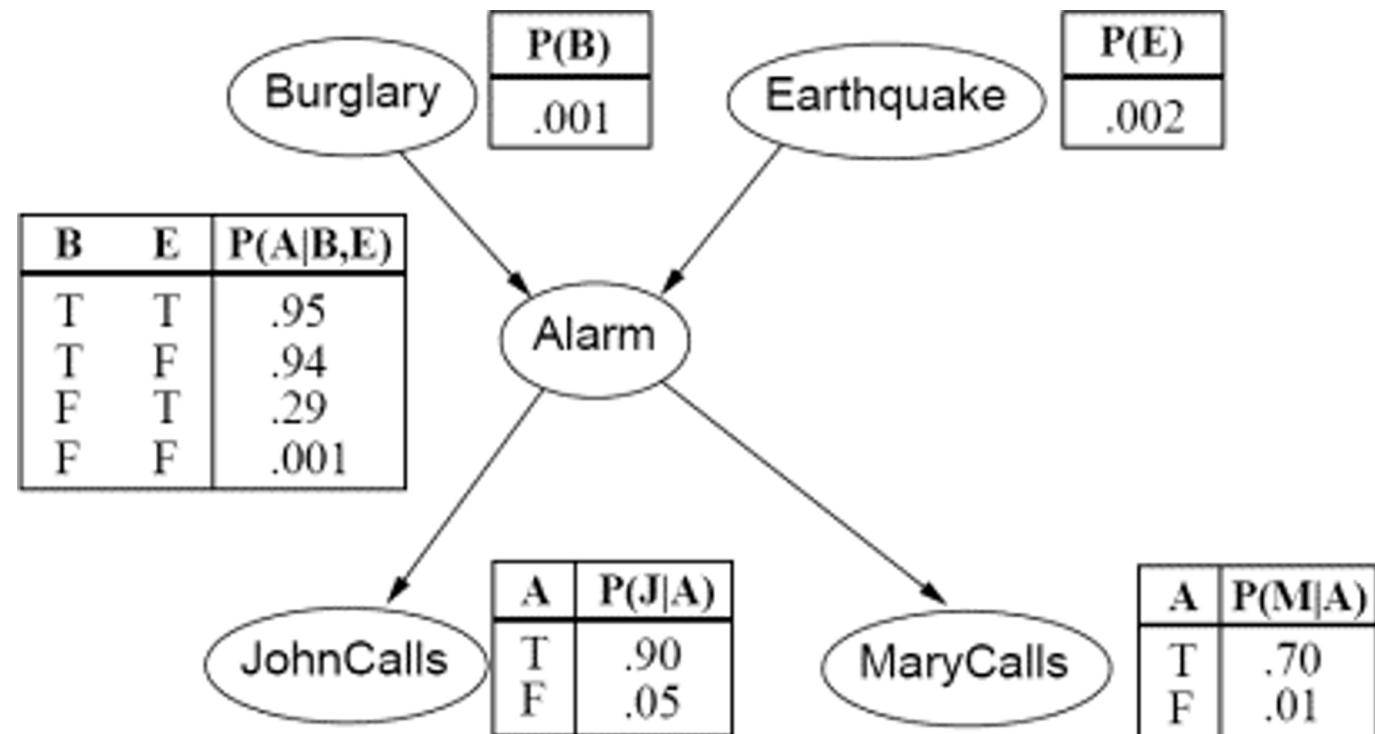
- Permit $k = 2$ parents per node
- $n = 5$ nodes
- $5 \cdot 2^2 = 20$

More extreme example:

With 5 parents per node and 30 nodes,
that's

$$\text{Bayes net: } n \cdot 2^k = 30 \cdot 2^5 = 960$$

$$\text{vs Naive: } 2^{30} \approx 1,000,000,000$$



Bayesian Networks: Construction

Show a “flow” from cause to effect: **Pearl’s Network Construction Algorithm**

Nodes: What is the set of variables we need to model?

Order them: $\{X_1, X_2, X_3, \dots, X_n\}$

Best if ordered such that **causes precede effects**

Links: For each node X_i , do:

- Choose a minimal set of parents $\text{parents}(X_i) \subseteq \{X_{i-1}, X_{i-2}, \dots, X_2, X_1\}$
such that $P(x_i | x_{i-1}, x_{i-2}, \dots, x_1) = P(x_i | \text{parents}(X_i))$
- For each parent, insert arcs (links) from parent to X_i
- Write down CPT $P(X_i | \text{parents}(X_i))$

Bayesian Networks: Construction

Example: Suppose we have an old motorcycle that might either blow a head gasket (H) or have a broken thermometer (T). Either one would cause the bike to overheat (O). If the bike overheats, then it might blow smoke (S) and/or run weak (W).

Construct a Bayesian network for this situation.



Bayesian Networks: Construction

Example: Suppose we have an old motorcycle that might either blow a head gasket (H) or have a broken thermometer (T). Either one would cause the bike to overheat (O). If the bike overheats, then it might blow smoke (S) and/or run weak (W).



Construct a Bayesian network for this situation.

1. Node ordering: {H, T, O, W, S}
2. Insert arcs

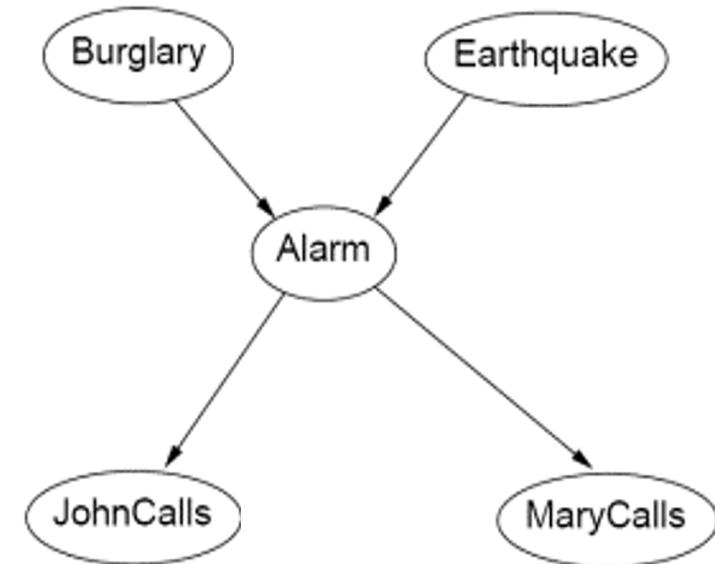
Bayesian Networks: Construction

Here, we chose to put the causes before effects:

{Burglary, Earthquake, Alarm, JohnCalls, MaryCalls}

What if instead we did the following?

{MaryCalls, JohnCalls, Alarm,
Burglary, Earthquake}

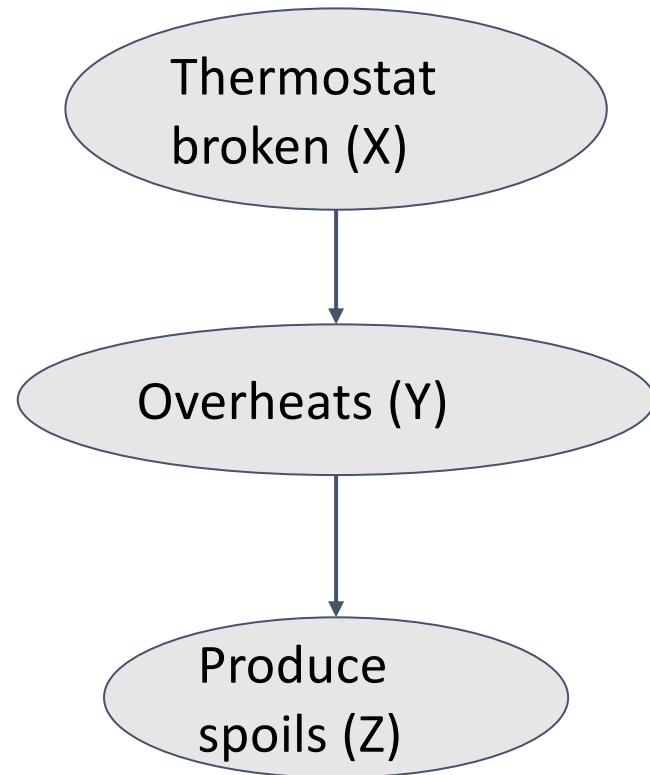


Bayesian Networks: Canonical Cases

Important Bayes net question: Are two nodes independent *given* certain evidence?

- If yes -- can prove using algebra
- If no -- can prove using a counterexample

Example: Are X and Z necessarily independent?



Bayesian Networks: Canonical Cases

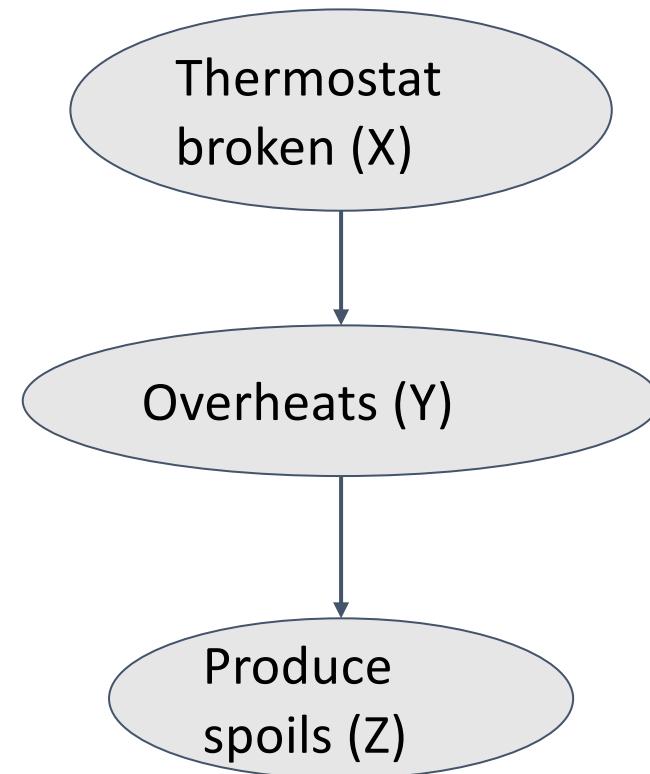
Important Bayes net question: Are two nodes independent *given* certain evidence?

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- If no -- can prove using a counterexample

Example: Are X and Z necessarily independent?

No!

- X certainly influences Y, which influences Z
- Also, knowledge of Z influences beliefs about X (through Y)



Bayesian Networks: Canonical Cases

Important Bayes net question: Are two nodes independent *given* certain evidence?

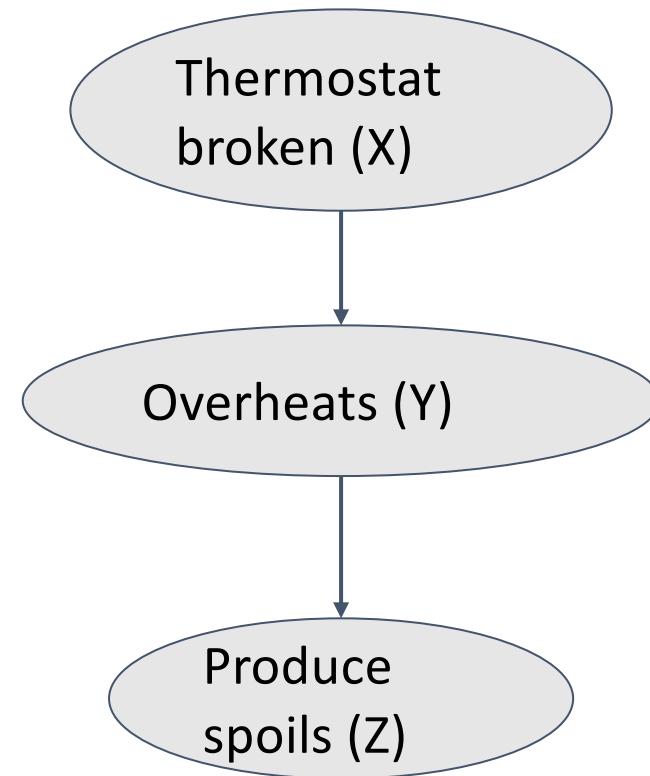
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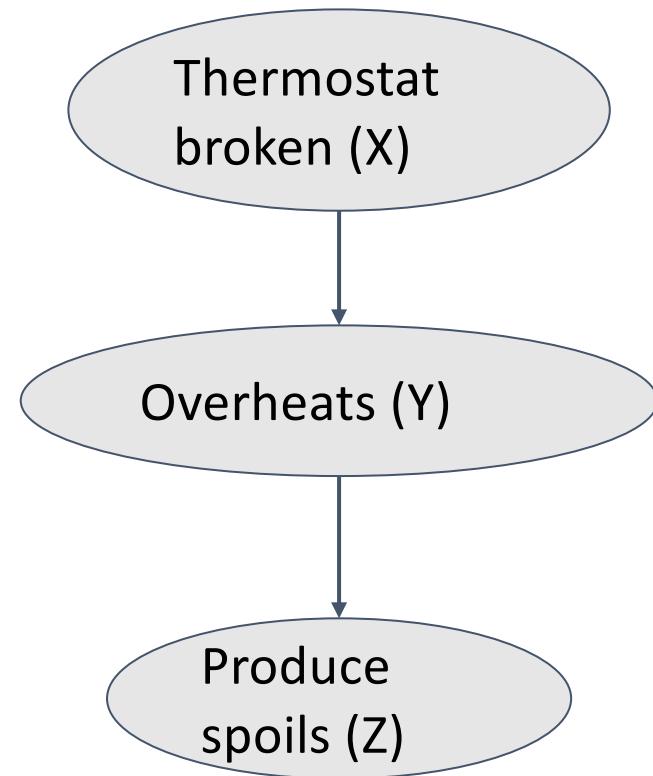
Example, rebooted: What about X and Z, *given* Y?



Bayesian Networks: Canonical Cases

Example, rebooted: What about X and Z, *given* Y?

This is a canonical case is called a **causal chain**



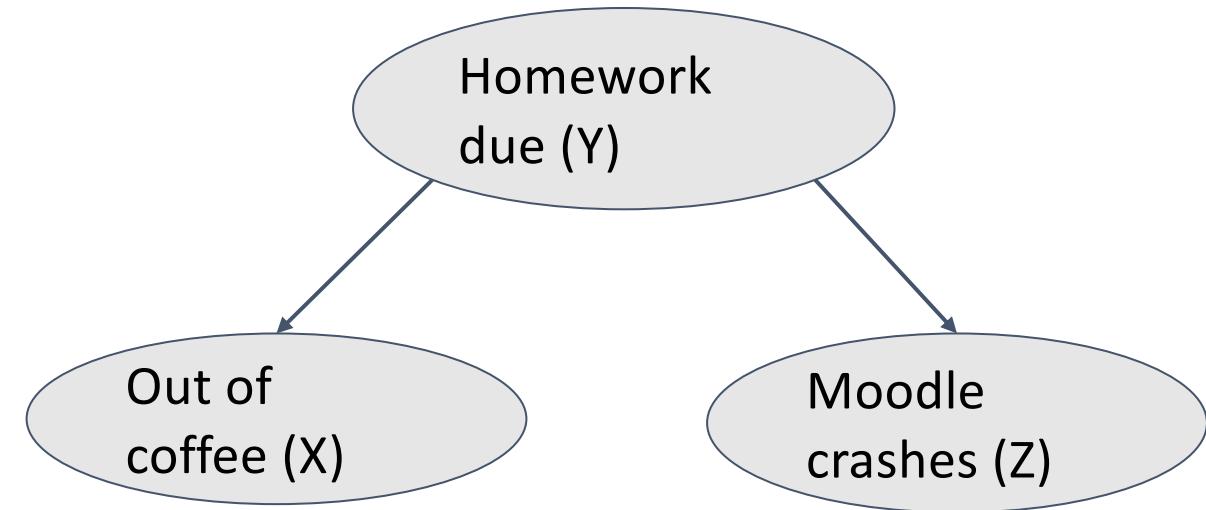
Bayesian Networks: Canonical Cases

Common cause is another canonical case.

→ Two effects, from the same cause

Example: Are X and Z independent?

Are X and Z independent *given* Y?



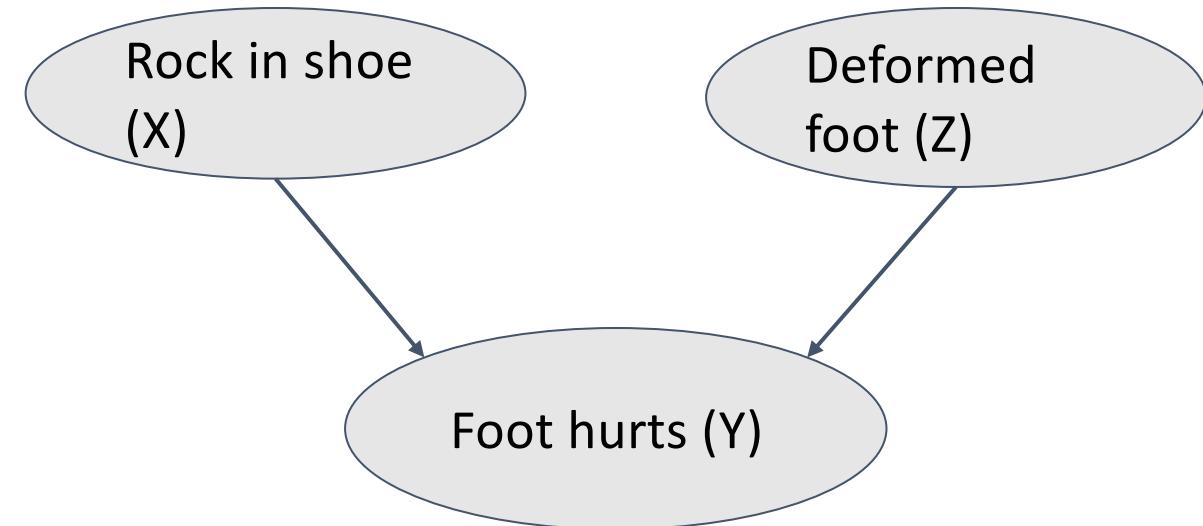
Bayesian Networks: Canonical Cases

Common effect is the third canonical case.

→ One effect, two possible causes

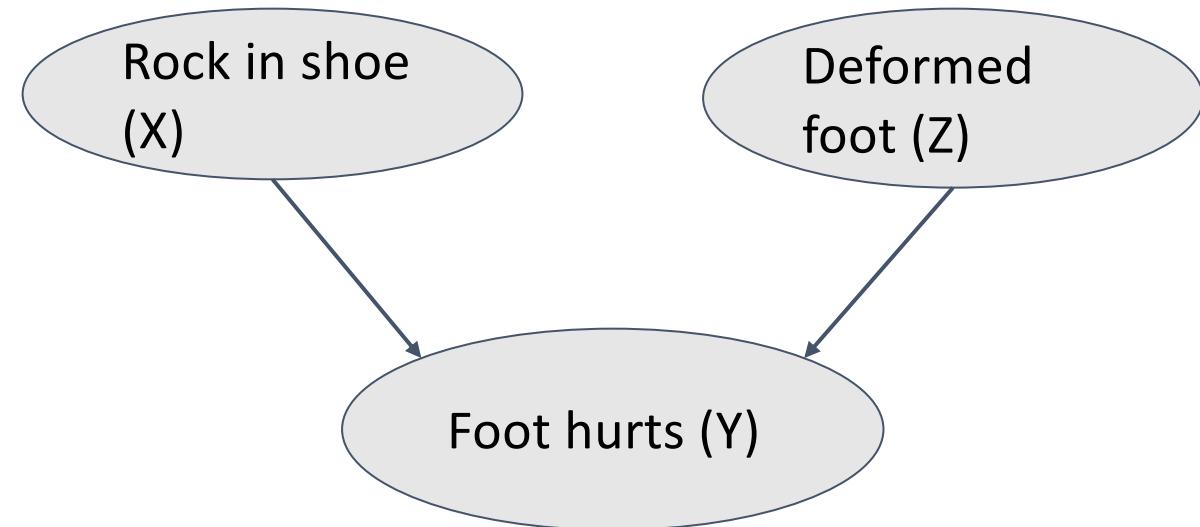
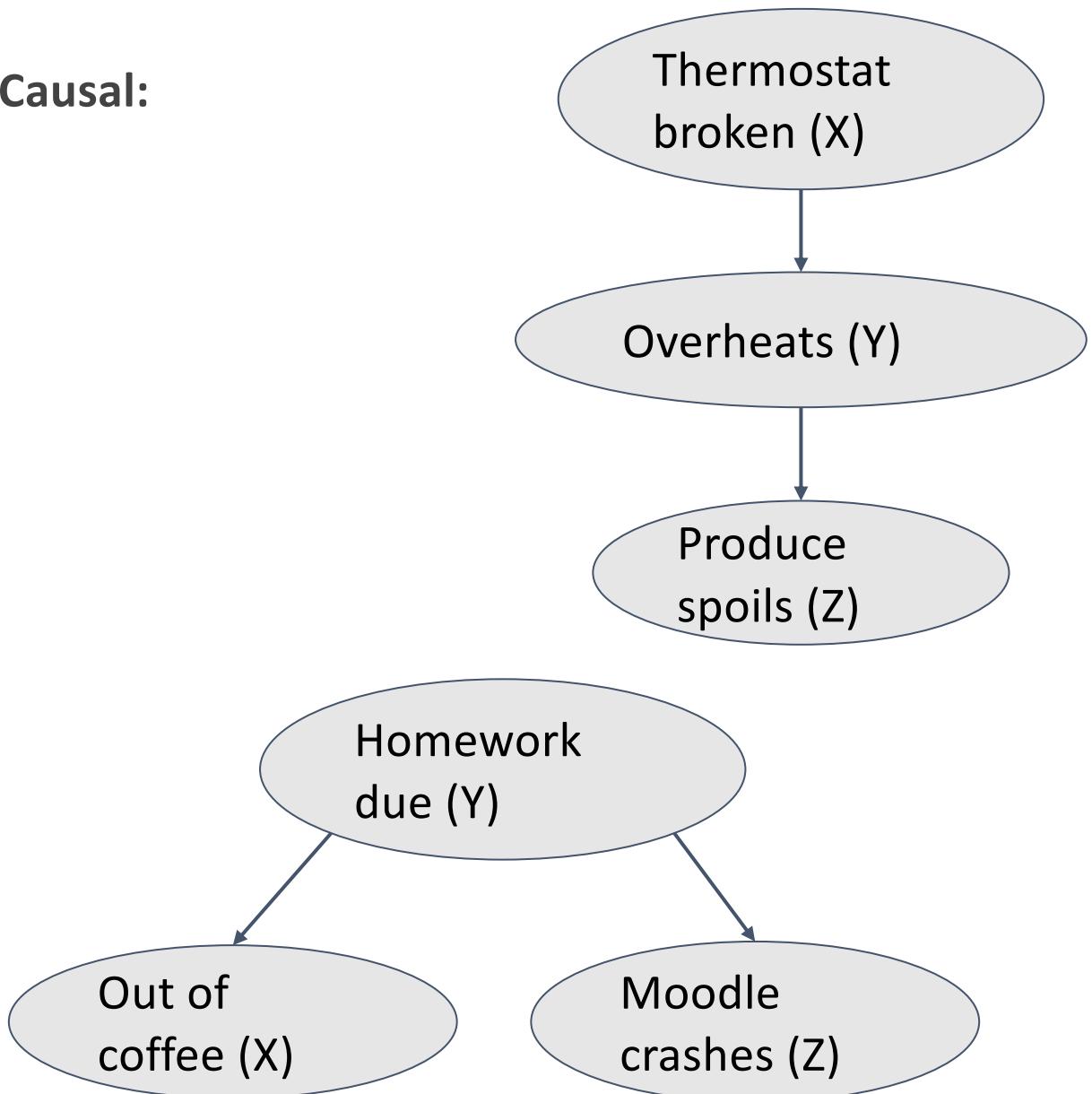
Example: Are X and Z independent?

Are X and Z independent *given* Y?



Causal vs Diagnostic Modeling

Causal:

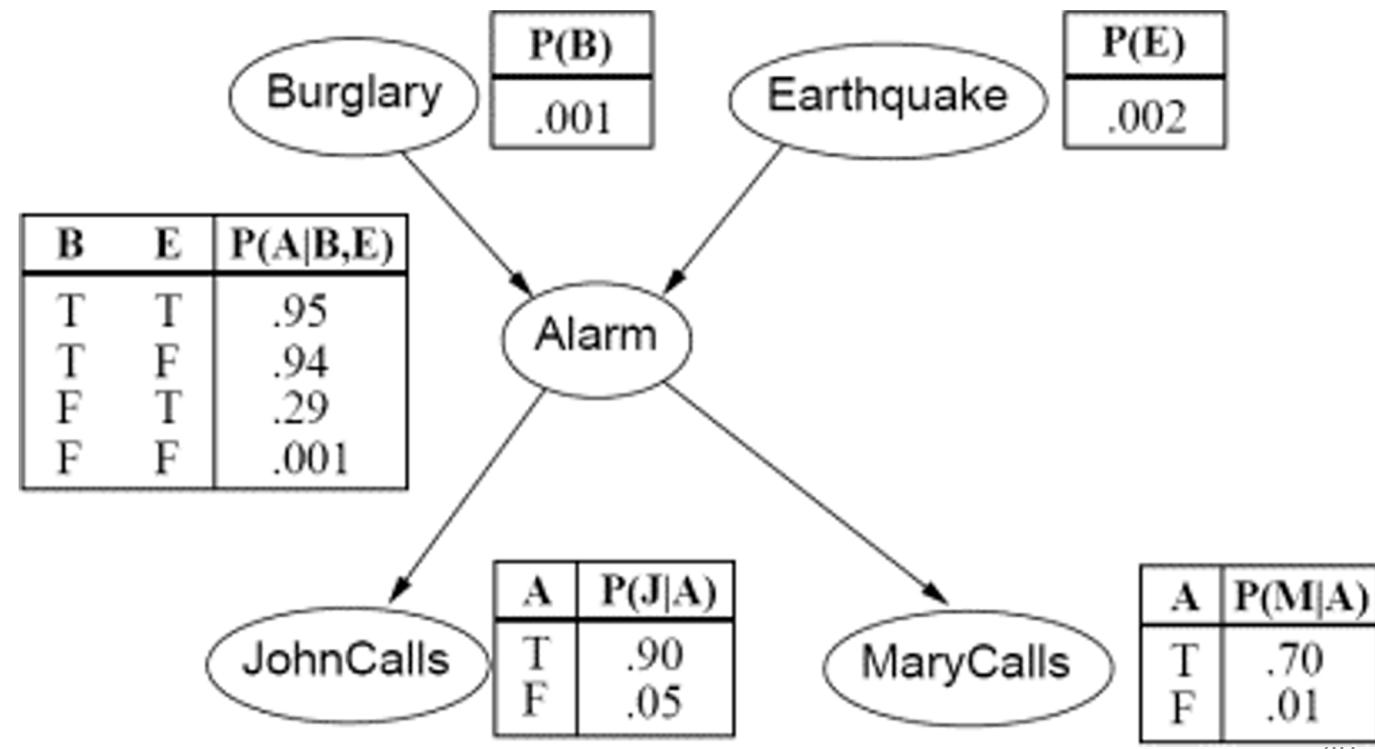


Diagnostic: observing an effect leads to competition between possible causes
→ *diagnose* which is most likely

Bayesian Networks: “Explaining Away”

Suppose we know that the alarm has gone off.

Suppose we find out later that we have been robbed



Next Time

- *Notebook Day on Monday*
- *Sampling using Bayesian networks
on Wednesday!*