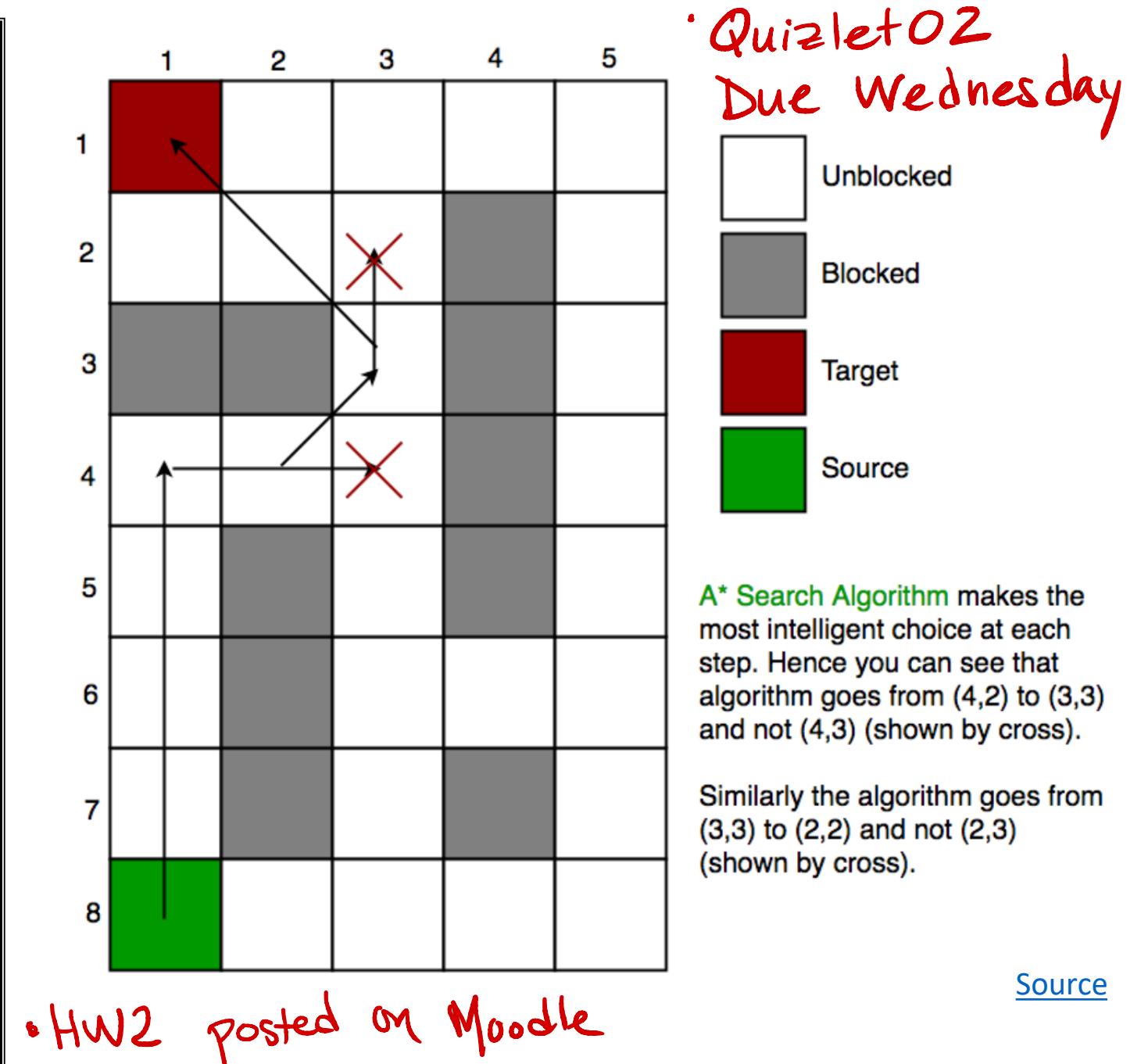


# CSCI 3202: Intro to Artificial Intelligence

## Lecture 7: A\* Search and Heuristics

Rachel Cox  
Department of Computer Science



## Review: Uniform-cost Search (UCS)

- Expand out in contours, where least cost dictates which nodes we explore.
- Eventually, we will find a path to the goal - but the search is not directed



# Search Algorithms

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- ❖ Search algorithms are fundamentally the same except for their frontier strategies.

## Uninformed Search: e.g. Uniform Cost Search

- the good: UCS is complete and optimal → if a solution exists, it will find it with the least cost path
- the bad: explores in every direction

## \* Informed Search: include information about where the goal is

- what do we need to have? A heuristic.

heuristic: A function that estimates how close a state is to a goal.

# Greedy best-first search

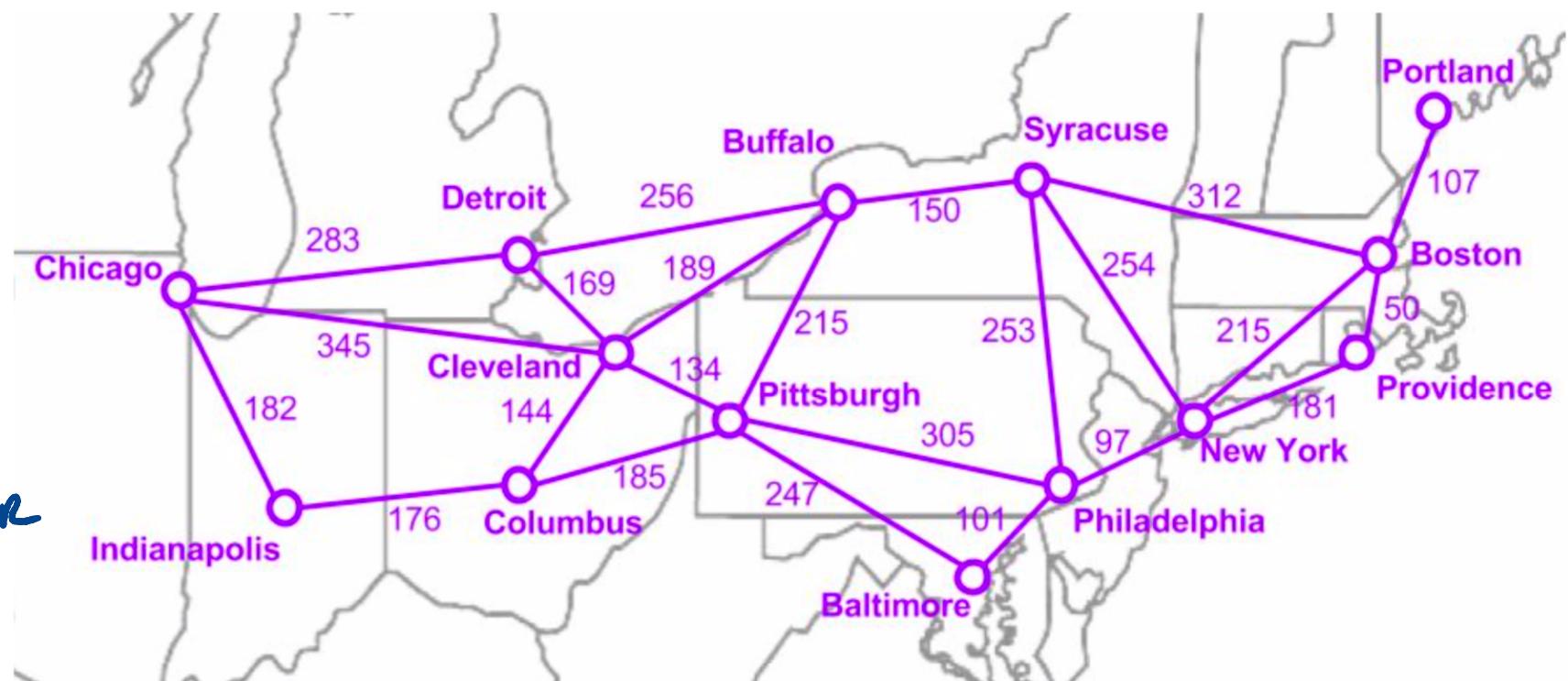
- ❖ First expand the path that's closest to the goal.

To determine what's closest to the goal, we need to define a heuristic function.

**Example:** For the traveling in the northeast problem, let's estimate the distance to the goal as the straight-line distance between city and the goal city.

↑  
this is our  
heuristic  
function

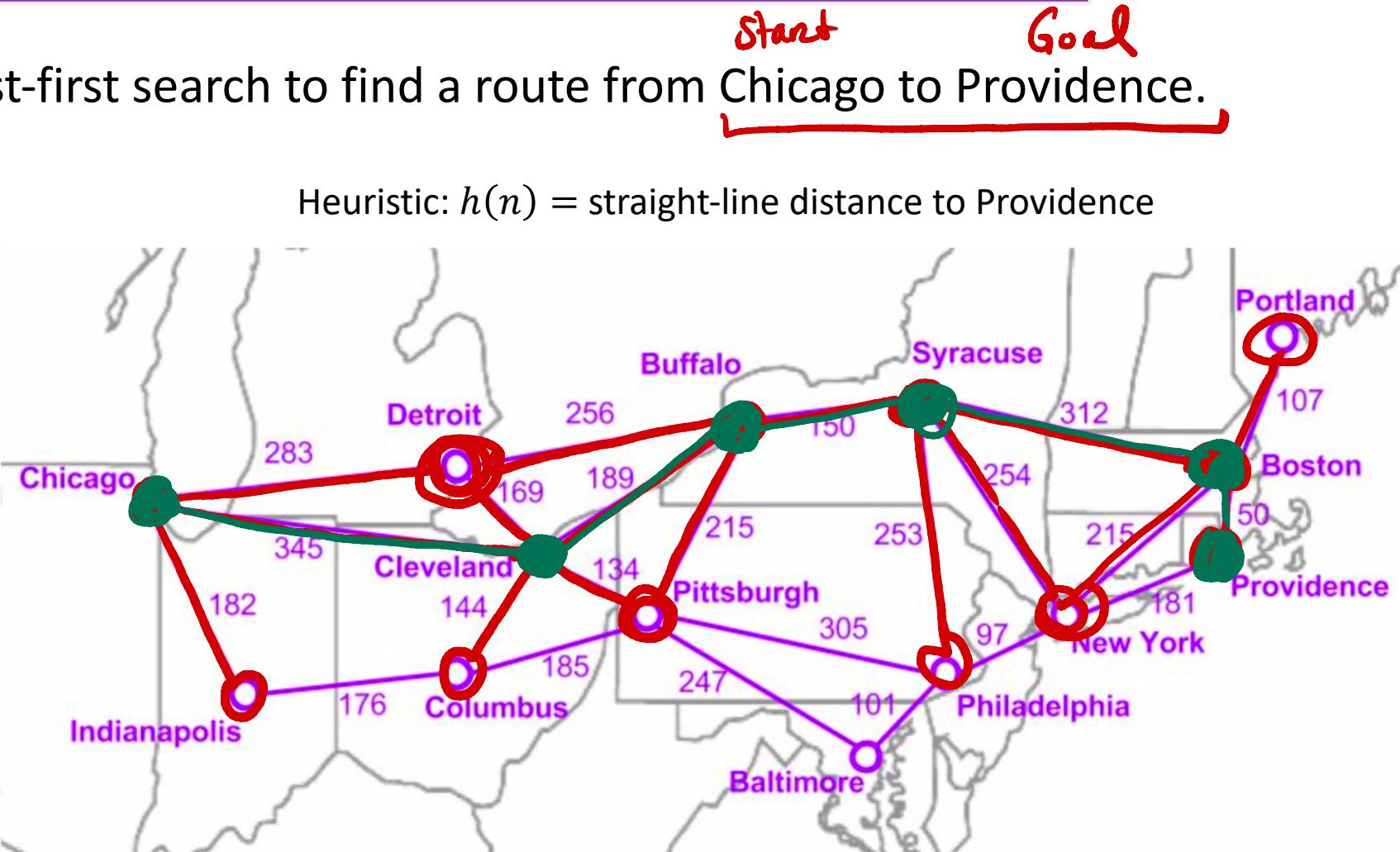
Step costs: miles between cities along major highways



# Greedy best-first search

Example: Use the greedy best-first search to find a route from Chicago to Providence.

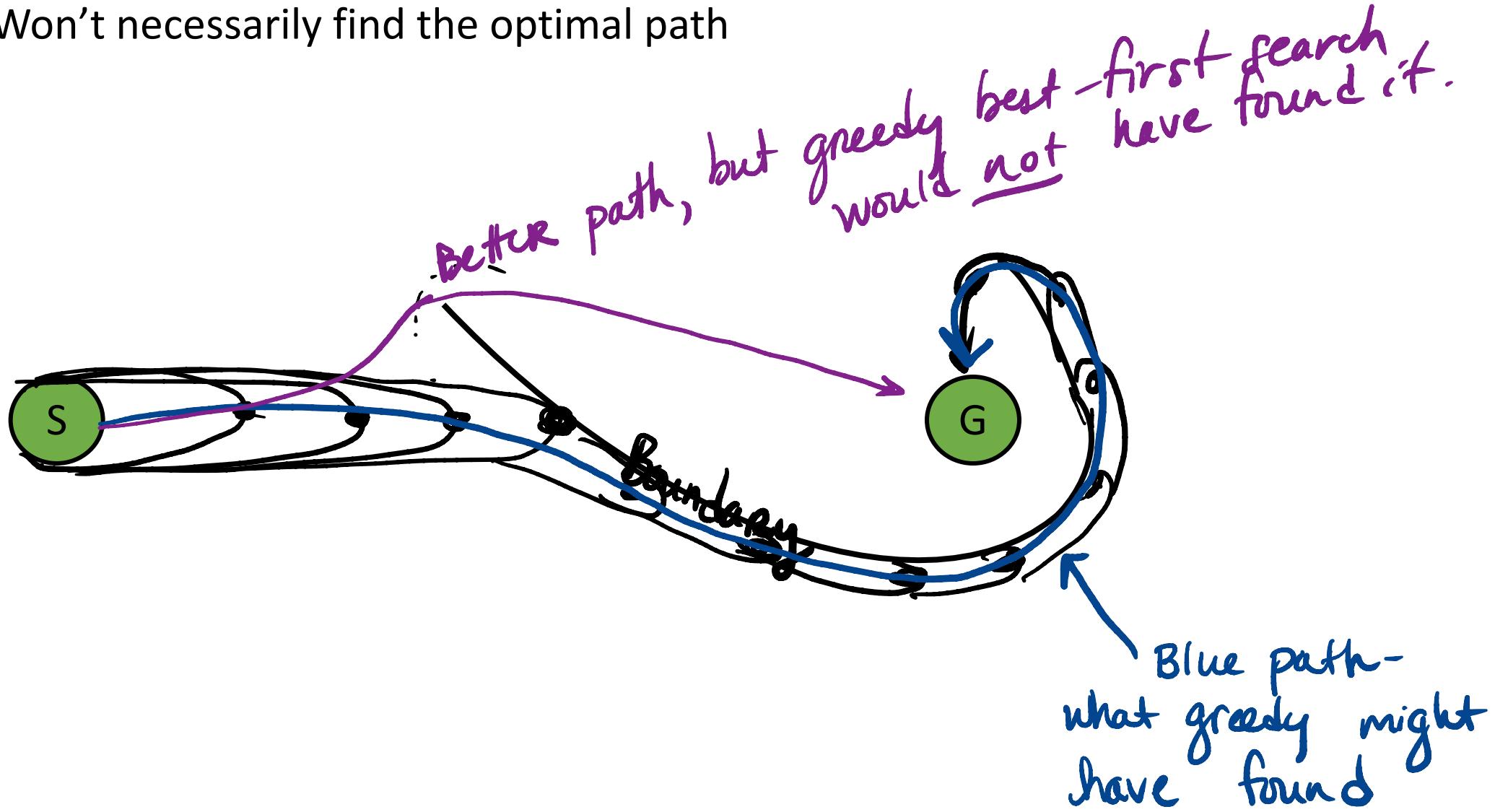
Chicago → Providence	833 miles
Detroit → Providence	597 miles
Indianapolis → Providence	783 miles
Cleveland → Providence	530 miles
Columbus → Providence	618 miles
Buffalo → Providence	388 miles
Pittsburgh → Providence	456 miles
Baltimore → Providence	324 miles
Syracuse → Providence	256 miles
Philadelphia → Providence	235 miles
New York → Providence	155 miles
Portland → Providence	140 miles
Boston → Providence	41 miles



"heuristic function"

# Greedy best-first search

Possible Issue: Won't necessarily find the optimal path



# A\* Search

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**Uniform-cost search:**

$$f(n) = g(n) \quad (\text{cost to get to } n)$$

**Greedy:**

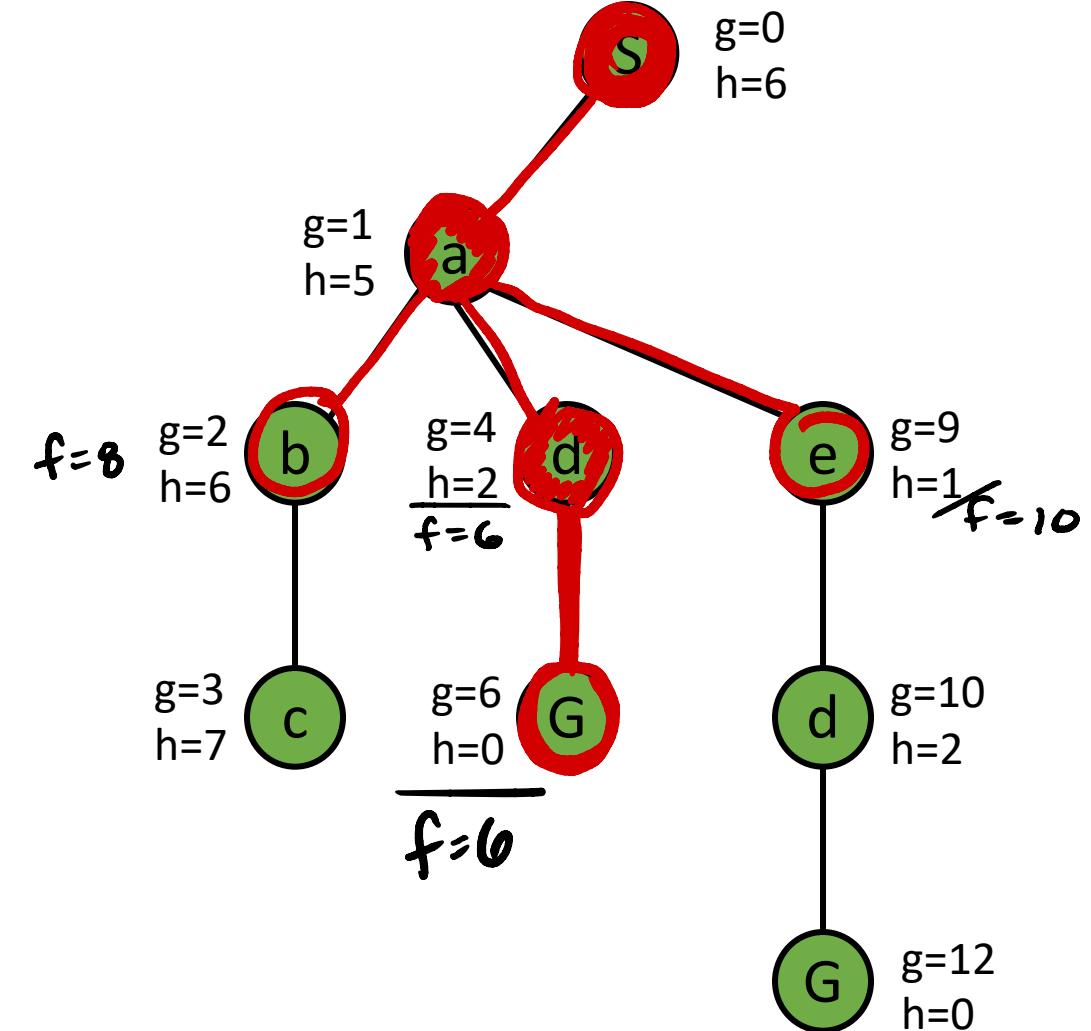
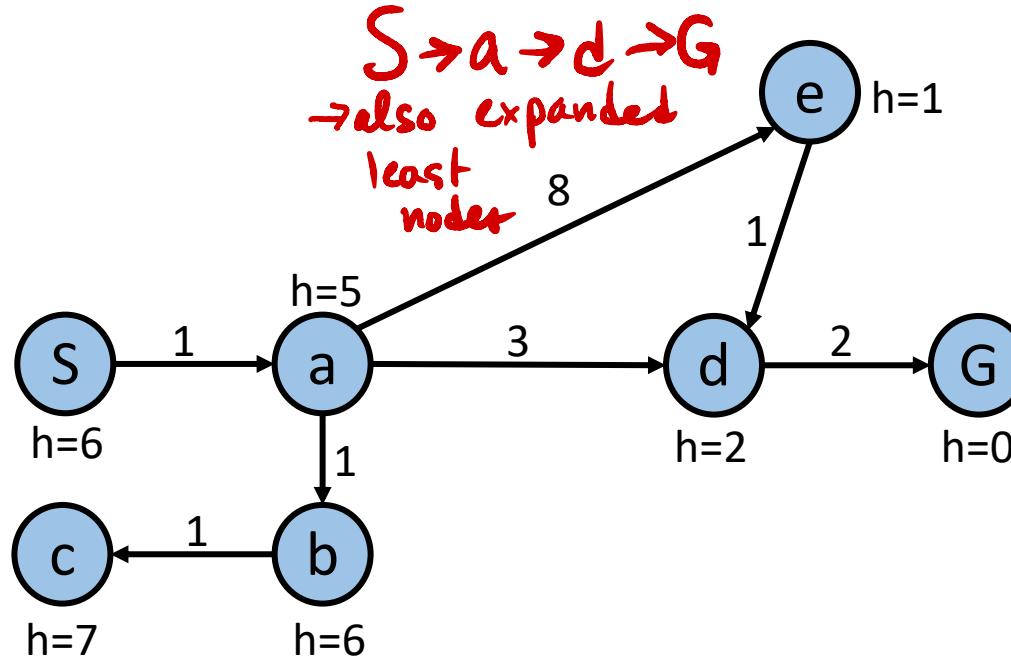
$$f(n) = h(n) \quad (\text{estimated cost to get from } n \text{ to goal})$$

**A\*:**

$$f(n) = g(n) + h(n) \quad (\text{estimated total cost of cheapest solution through } n)$$

# A\* Search

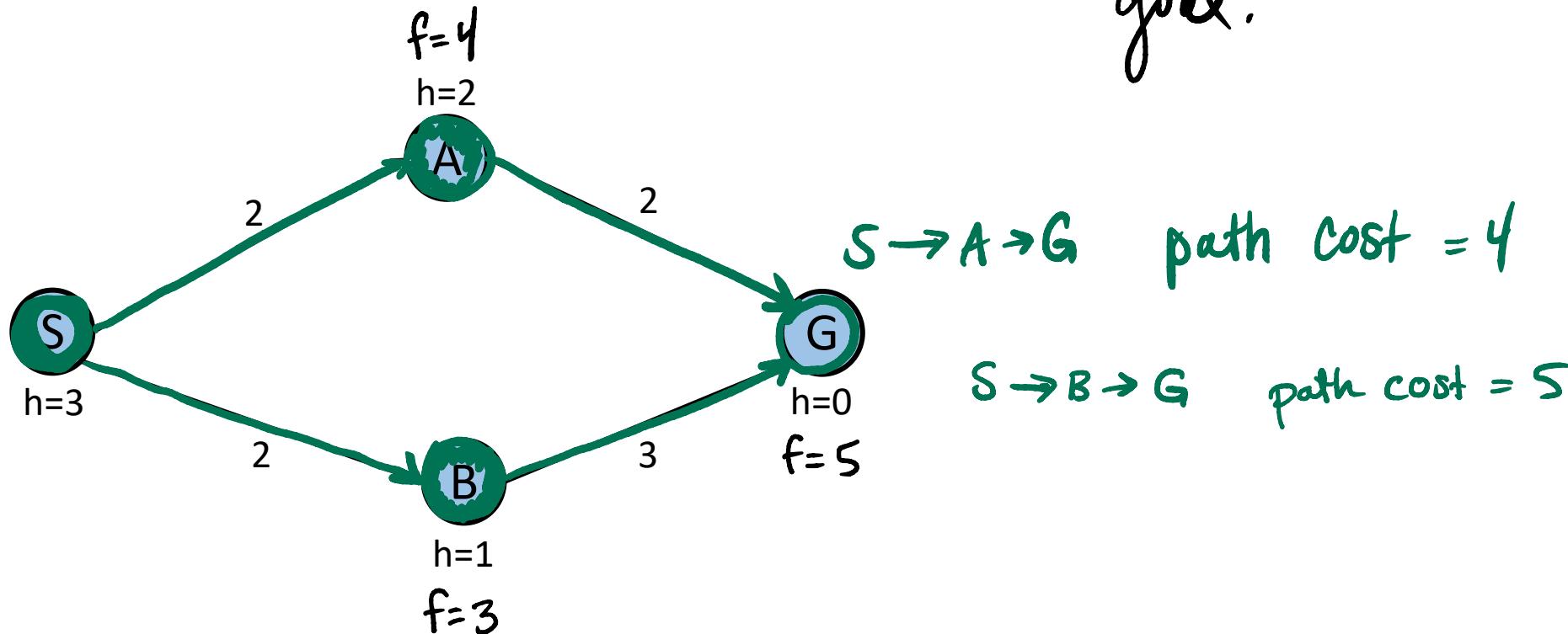
Example: Compare Uniform Cost, Greedy Search, and A\* on the graph below.



# A\* Search

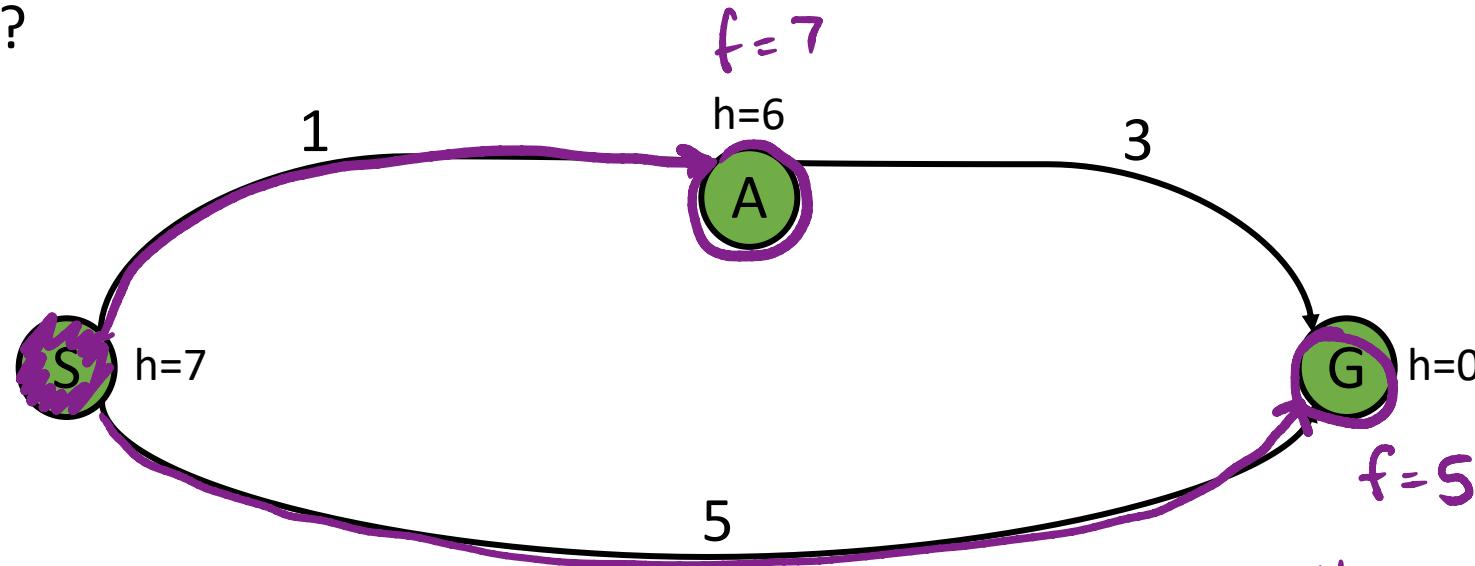
Example: When should A\* search terminate?

When you "dequeue" the goal.



# A\* Search

Is A\* optimal?



Here we would expand G.

- We would terminate.
- solution path  $S \rightarrow G$

\* Why did A\* fail?

poorly chosen heuristic at node A.

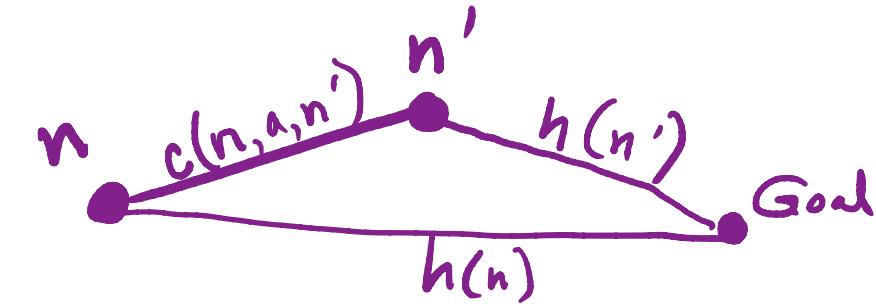
Heuristics must **admissible**.

# A\* Search

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**Consistent:** for every node  $n$  and successor  $n'$  of  $n$ , generated by some action  $a$ , the estimated cost of reaching the goal from  $n$  is no greater than the step cost from  $n$  to  $n'$ , plus the estimated cost of reaching the goal from  $n'$

- That is:  $h(n) \leq c(n, a, n') + h(n')$
- General **triangle inequality** between  $n$ ,  $n'$ , and the goal



- \* A heuristic  $h$  is **admissible** (optimistic) if  $0 \leq h(n) \leq h^*(n)$ , where  $h^*(n)$  is the true cost to the nearest goal.

# A\* Search

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Search only works when:

- domain is fully observable
- domain must be known
- domain must be deterministic
- domain must be static

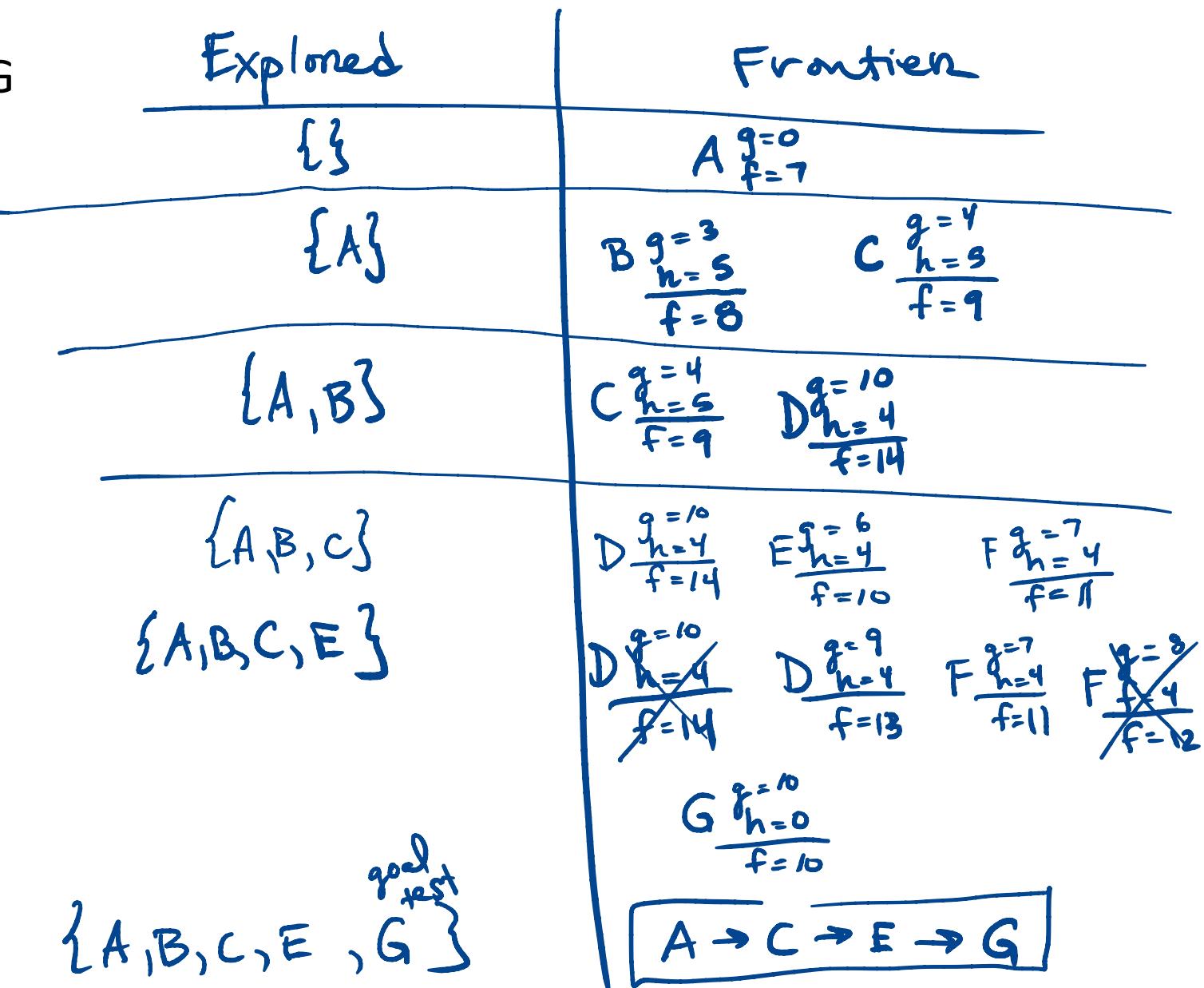
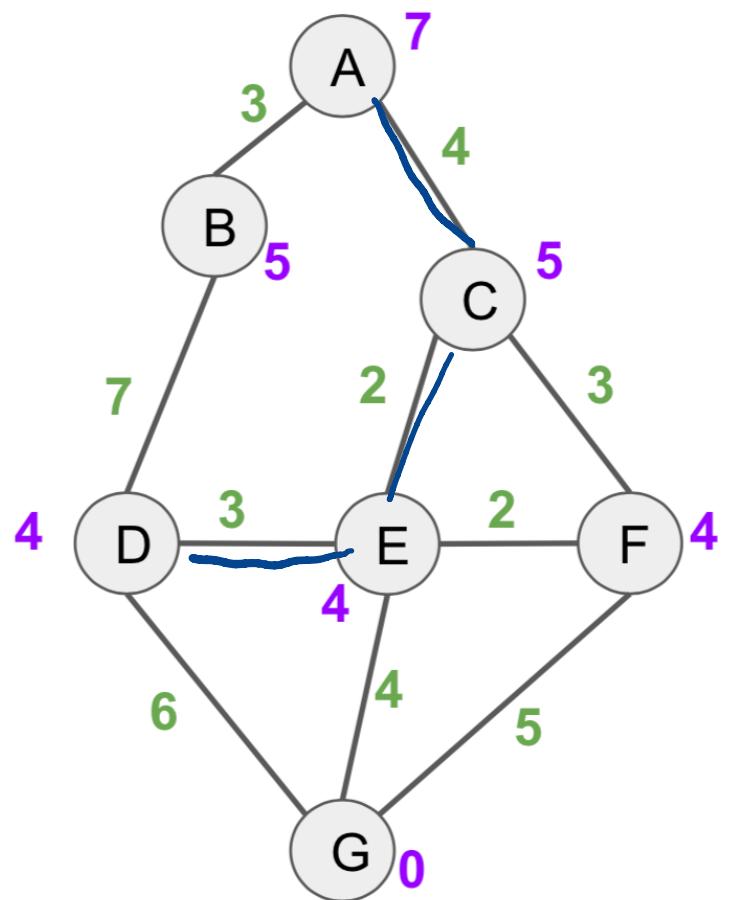
implementation: use a **node**

- state - indicates state at end of path
- action - action taken to get here
- cost - total cost
- parent - pointer to another node

# A\* Search

## A\* Search:

- Find the cheapest path from A to G
- $h(n)$  values are given in purple
- Step costs are given in green

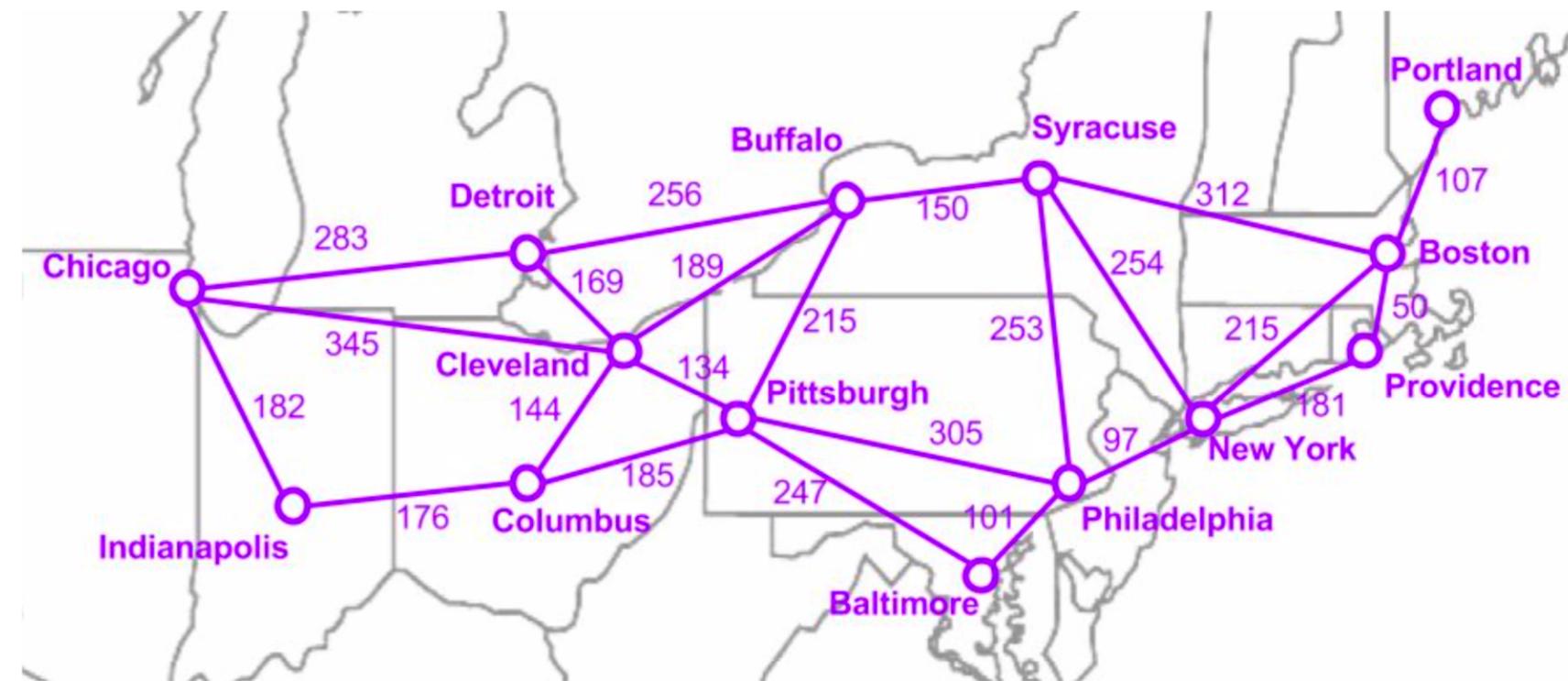


# A\* Search

Example: Use A\* search to find a route from Chicago to Providence.

practice at home

$h(n)$  = straight-line distance to Providence  
 $g(n)$  = Path cost so far



## A\* Search

$$\begin{array}{l} \text{consistent: } h(n) \leq c(n,a,n') + h(n') \\ \text{admissible: } h(n) \leq h^*(n) \end{array}$$

Any consistent heuristic is also admissible (but not the other way around).

Example: Prove the above statement by induction.

Proof: Base Case: Assume that a heuristic  $h(n)$  is consistent for  $K=1$  nodes along the shortest path to the goal node.

$$h(n) \leq c(n,a,n') + h(n') \quad \text{by consistent property.}$$

Let  $n'$  be the goal node.

$$\Rightarrow h(n') = 0$$

$$\begin{aligned} \Rightarrow h(n) &\leq c(n,a,n') + 0 \\ &= h^*(n) \end{aligned}$$

Thus  $h(n) \leq h^*(n)$  and  $h(n)$  is admissible.

# A\* Search

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**Any consistent heuristic is also admissible (but not the other way around).**

**Example:** Prove the above statement by induction.

## Next Time

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Optimality and Variants of A\*