



- Classification can be approached from the perspective of building a decision boundary that separates class labels,  $y$ , in the input space.

Classification boundary problem



$$y \in \{1, \dots, K\}$$

$$\hat{y} = g(f(\mathbf{x}; \theta))$$

decision boundary is a hyperplane,  $H$ :

in this lecture we'll discuss a label:



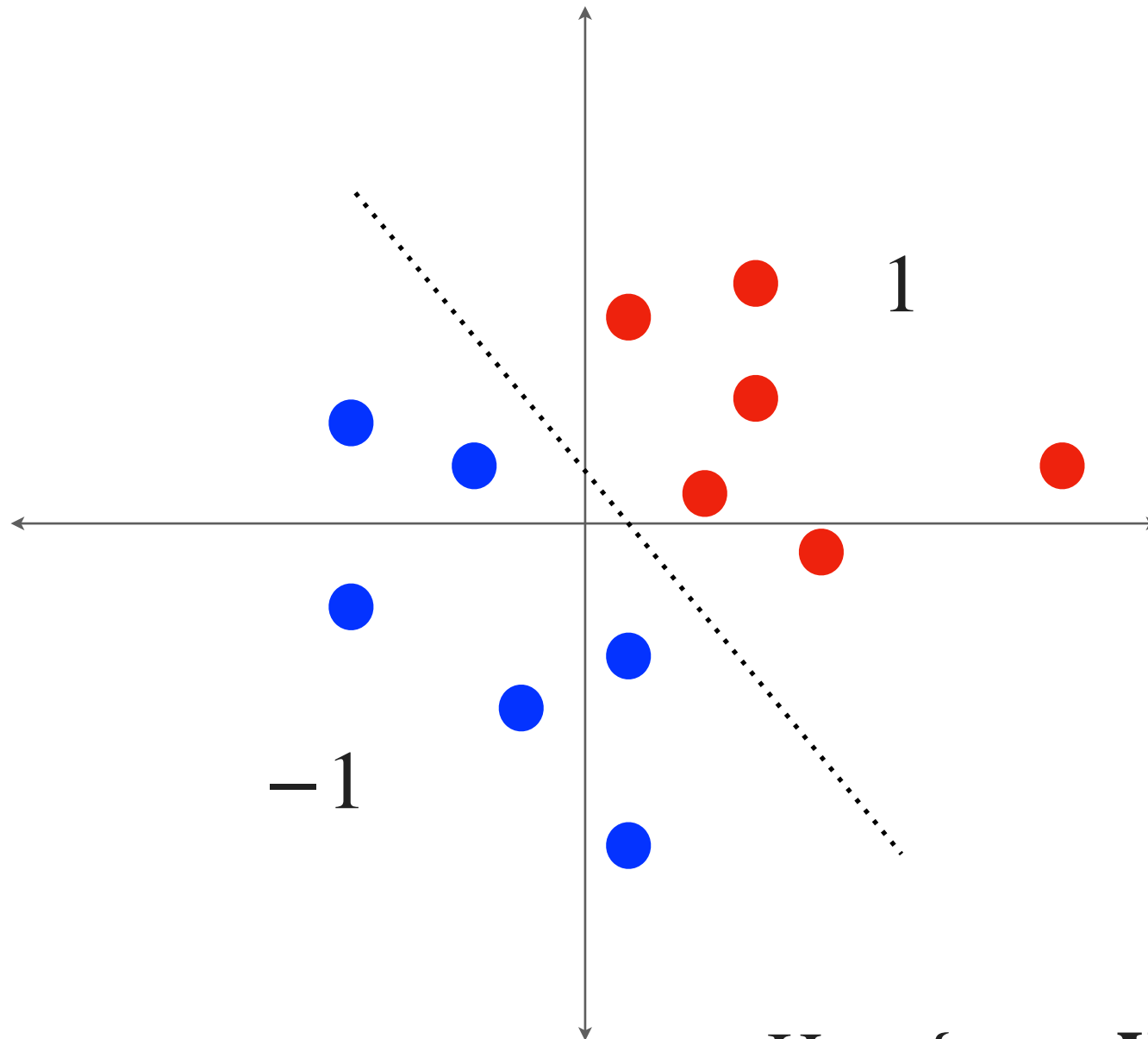
$$H \equiv \{ \mathbf{x} : f(\mathbf{x}; \theta) = 0 \}$$

$$f: \mathbb{R}^N \rightarrow \mathbb{R}^N$$

decision boundary is represented by  $f(\cdot)$ :

then our predictor is  $g: f(\mathbf{x}; \theta) \rightarrow y:$

binary classification, linear decision boundary



$$H = \{ \mathbf{x} : \mathbf{W}\mathbf{x} + \mathbf{b} = \mathbf{0} \}$$

$$y \in \{ \text{blue circle}, \text{red circle} \}$$

# Classification as a decision boundary problem

- Classification can be approached from the perspective of building a decision boundary that separates class labels,  $y$ , in the input space.

In this lecture we'll assume a scalar label:

$$y \in \{1, \dots, K\}$$

decision boundary is a hyperplane,  $H$ :

$$H = \{ \mathbf{x} : f(\mathbf{x}; \boldsymbol{\theta}) = \mathbf{0} \}$$

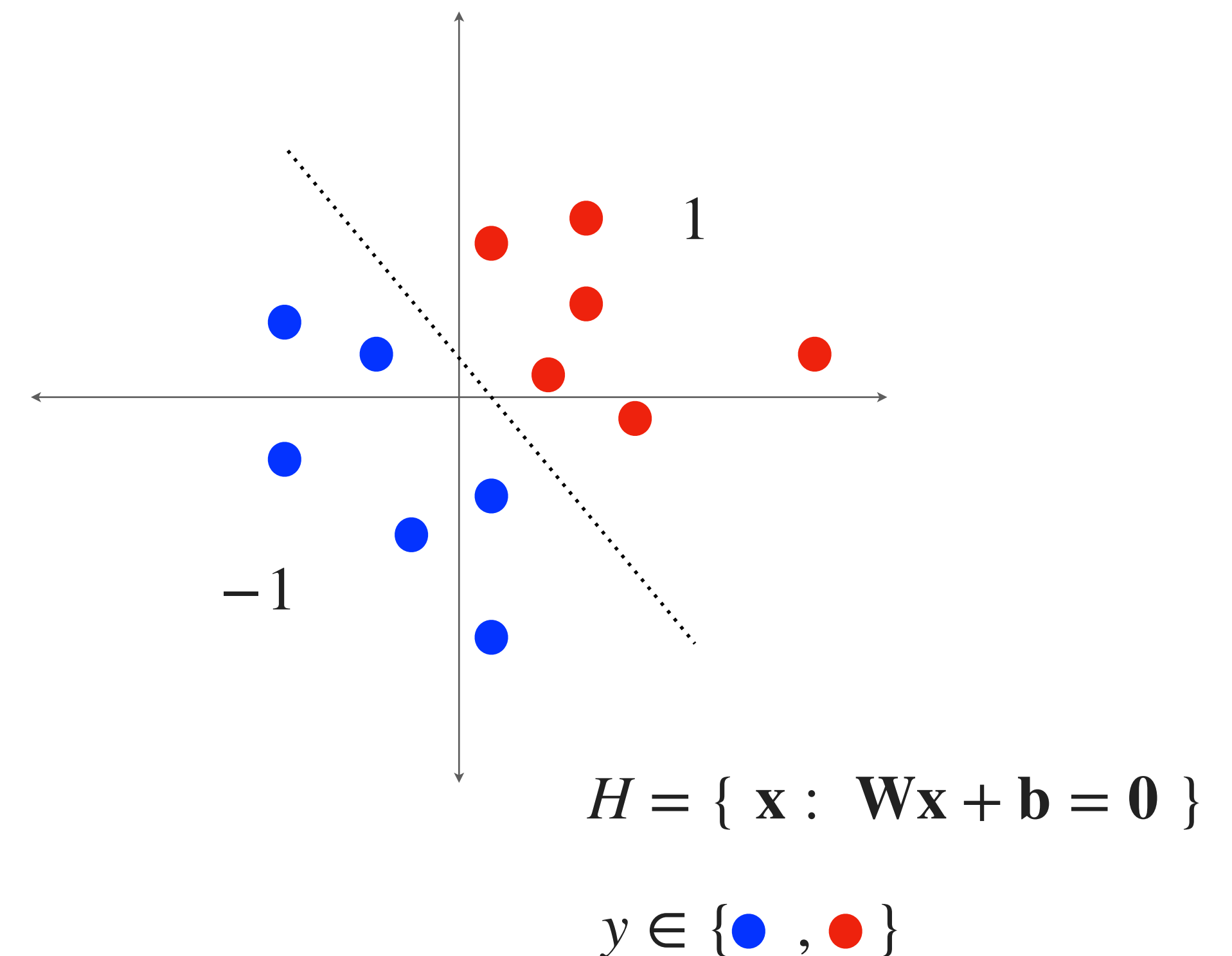
decision boundary is represented by  $f(\cdot)$ :

$$f : \mathbb{R}^N \rightarrow \mathbb{R}$$

then our predictor is  $g : f(\mathbf{x}; \boldsymbol{\theta}) \rightarrow y$ :

$$\hat{y} = g(f(\mathbf{x}; \boldsymbol{\theta}))$$

binary classification, linear decision boundary



# Curse of dimensionality

- Somewhat counter intuitively, in high dimensional space, volume gets concentrated at the boundaries. In the world of decision boundaries, this means that presence of a linearly separating hyperplane increases with the number of dimensions, and in fact is guaranteed to exist at  $N \rightarrow \infty$  ... great news!?!?!?