Decoupled Neural Interfaces for PyTorch

This tiny library is an implementation of Decoupled Neural Interfaces using Synthetic Gradients https://arxiv.org/abs/1608.05343 for PyTorch http://pytorch.org/ .. It's very simple to use as it was designed to enable researchers to integrate DNI into existing models with minimal amounts of code.

To install, run::

\$ python setup.py install

Description of the library and how to use it in some typical cases is provided below. For more information, please read the code.

Terminology

This library uses a message passing abstraction introduced in the paper. Some terms used in the API (matching those used in the paper wherever possible):

- Interface A Decoupled Neural Interface that decouples two parts (let's call them part A and part B) of the network and lets them communicate via message passing. It may be Forward, Backward or Bidirectional.
- BackwardInterface A type of Interface that the paper focuses on. It can be used to prevent update locking by predicting gradient for part A of the decoupled network based on the activation of its last layer.
- ForwardInterface A type of Interface that can be used to prevent forward locking by predicting input for part B of the network based on some information known to both parts in the paper it's the input of the whole network.
- BidirectionalInterface A combination of ForwardInterface and BackwardInterface, that can be used to achieve a complete unlock.
- message Information that is passed through an Interface activation of the last layer for ForwardInterface or
 gradient w.r.t. that activation for BackwardInterface. Note that no original information passes through. A
 message is consumed by one end of the Interface and used to update a Synthesizer. Then the Synthesizer
 can be used produce a synthetic message at the other end of the Interface.
- trigger Information based on which message is synthesized. It needs to be accessible by both parts of the network. For BackwardInterface, it's activation of the layer w.r.t. which gradient is to be synthesized. For ForwardInterface it can be anything in the paper it's the input of the whole network.
- context Additional information normally not shown to the network at the forward pass, that can condition an
 Interface to provide a better estimate of the message. The paper uses labels for this purpose and calls DNI with
 context cDNI.
- send A method of an Interface, that takes as input message and trigger, based on which that message should be generated, and updates Synthesizer to improve the estimate.
- receive A method of an Interface, that takes as input trigger and returns a message generated by a Synthesizer.
- Synthesizer A regression model that estimates message based on trigger and context.

Typical use cases

Synthetic Gradient for Feed-Forward Networks ^^^^^^^^^^^^^^^^^^^^^^^^^^^^^^

In this case we want to decouple two parts A and B of a neural network to achieve an update unlock, so that there is a normal forward pass from part A to B, but part A learns using synthetic gradient generated by the DNI.

.. image:: images/feedforward-update-unlock.png

Following the paper's convention, solid black arrows are update-locked forward connections, dashed black arrows are update-unlocked forward connections, green arrows are real error gradients and blue arrows are synthetic error gradients. Full circles denote synthetic gradient loss computation and Synthesizer update.

We can use a BackwardInterface to do that:

```
.. code-block:: python
  class Network(torch.nn.Module):
      def __init__(self):
          # ...
          # 1. create a BackwardInterface, assuming that dimensionality of
               the activation for which we want to synthesize gradients is
               activation_dim
          self.backward_interface = dni.BackwardInterface(
              dni.BasicSynthesizer(output_dim=activation_dim, n_hidden=1)
          # ...
      def forward(self, x):
          # ...
          # 2. call the BackwardInterface at the point where we want to
          # decouple the network
          x = self.backward_interface(x)
          # ...
```

That's it! During the forward pass, BackwardInterface will use a Synthesizer to generate synthetic gradient w.r.t. activation, backpropagate it and add to the computation graph a node that will intercept the real gradient during the backward pass and use it to update the Synthesizer 's estimate.

The Synthesizer used here is BasicSynthesizer - a multi-layer perceptron with ReLU activation function. Writing a custom Synthesizer is described at Writing custom Synthesizers _.

You can specify a context by passing context_dim (dimensionality of the context vector) to the BasicSynthesizer constructor and wrapping all DNI calls in the dni.synthesizer_context context manager:

.. code-block:: python

return x

```
# assuming that context is labels given in variable y
with dni.synthesizer_context(y):
   x = self.backward_interface(x)
# ...
return x
```

Example code for digit classification on MNIST is at examples/mnist-mlp <examples/mnist-mlp>_.

Complete Unlock for Feed-Forward Networks ^^^^^^^^^^^^^^^^^^^^^^^^^

In this case we want to decouple two parts A and B of a neural network to achieve forward and update unlock, so that part B receives synthetic input and part A learns using synthetic gradient generated by the DNI.

.. image:: images/feedforward-complete-unlock.png

```
Red arrows are synthetic inputs.
We can use a BidirectionalInterface to do that:
.. code-block:: python
  class Network(torch.nn.Module):
      def __init__(self):
          # ...
          # 1. create a BidirectionalInterface, assuming that dimensionality of
               the activation for which we want to synthesize gradients is
               activation_dim and dimensionality of the input of the whole
              network is input_dim
          self.bidirectional_interface = dni.BidirectionalInterface(
              # Synthesizer generating synthetic inputs for part B, trigger
              # here is the input of the network
              dni.BasicSynthesizer(
                  output_dim=activation_dim, n_hidden=1,
                  trigger_dim=input_dim
              ),
              # Synthesizer generating synthetic gradients for part A,
              # trigger here is the last activation of part A (no need to
              # specify dimensionality)
              dni.BasicSynthesizer(
                  output_dim=activation_dim, n_hidden=1
          )
          # ...
      def forward(self, input):
          x = input
          # 2. call the BidirectionalInterface at the point where we want to
               decouple the network, need to pass both the last activation
               and the trigger, which in this case is the input of the whole
               network
          x = self.backward_interface(x, input)
          # ...
          return x
```

During the forward pass, BidirectionalInterface will receive real activation, use it to update the input Synthesizer, generate synthetic gradient w.r.t. that activation using the gradient Synthesizer, backpropagate it, generate synthetic input using the input Synthesizer and attach to it a computation graph node that will intercept the real gradient w.r.t. the synthetic input and use it to update the gradient Synthesizer.

Example code for digit classification on MNIST is at examples/mnist-full-unlock <examples/mnist-full-unlock> _.

Writing custom Synthesizers ^^^^^^^^^^^^^^^^^^^^^^^^^^^

This library includes only BasicSynthesizer - a very simple Synthesizer based on a multi-layer perceptron with ReLU activation function. It may not be sufficient for all cases, for example for classifying MNIST digits using a CNN the paper uses a Synthesizer that is also a CNN.

You can easily write a custom Synthesizer by subclassing torch.nn.Module with method forward taking trigger and context as arguments and returning a synthetic message:

.. code-block:: python

```
class CustomSynthesizer(torch.nn.Module):
    def forward(self, trigger, context):
        # synthesize the message
        return message
```

trigger will be a torch.autograd.Variable and context will be whatever is passed to the dni.synthesizer_context context manager, or None if dni.synthesizer_context is not used.

Example code for digit classification on MNIST using a CNN is at examples/mnist-cnn <examples/mnist-cnn> _.

Synthetic Gradient for Recurrent Networks ^^^^^^^^^^^^^^^^^^^^^^^^^^^^^^

In this case we want to use DNI to approximate gradient from an infinitely-unrolled recurrent neural network and feed it to the last step of the RNN unrolled by truncated BPTT.

.. image:: images/rnn-update-unlock.png

We can use methods make_trigger and backward of BackwardInterface to do that:

.. code-block:: python

```
class Network(torch.nn.module):
   def __init__(self):
        # ...
        # 1. create a BackwardInterface, assuming that dimensionality of
           the RNN hidden state is hidden_dim
        self.backward_interface = dni.BackwardInterface(
            dni.BasicSynthesizer(output_dim=hidden_dim, n_hidden=1)
        )
        # ...
   def forward(self, input, hidden):
        # ...
        # 2. call make_trigger on the first state of the unrolled RNN
        hidden = self.backward_interface.make_trigger(hidden)
        # run the RNN
        (output, hidden) = self.rnn(input, hidden)
        # 3. call backward on the last state of the unrolled RNN
        self.backward_interface.backward(hidden)
```

```
# in the training loop:
with dni.defer_backward():
    (output, hidden) = model(input, hidden)
    loss = criterion(output, target)
```

...

dni.backward(loss)

BackwardInterface.make_trigger marks the first hidden state as a trigger used to update the gradient estimate. During the backward pass, gradient passing through the trigger will be compared to synthetic gradient generated based on the same trigger and the Synthesizer will be updated. BackwardInterface.backward computes synthetic gradient based on the last hidden state and backpropagates it.

Because we are passing both real and synthetic gradients through the same nodes in the computation graph, we need to use <code>dni.defer_backward</code> and <code>dni.backward</code>. <code>dni.defer_backward</code> is a context manager that accumulates all gradients passed to <code>dni.backward</code> (including those generated by <code>Interfaces</code>) and <code>backpropagates</code> them all at once in the end. If we don't do that, PyTorch will complain about backpropagating twice through the same computation graph.

Example code for word-level language modeling on Penn Treebank is at examples/rnn <examples/rnn> _.

Distributed training with a Complete Unlock ^^^^^^^^^^^^^^^^^^^^^^^^^^^^^

The paper describes distributed training of complex neural architectures as one of the potential uses of DNI. In this case we have a network split into parts A and B trained independently, perhaps on different machines, communicating via DNI. We can use methods send and receive of BidirectionalInterface to do that:

.. code-block:: python

```
class PartA(torch.nn.Module):
    def forward(self, input):
        x = input

    # ...

    # send the intermediate results computed by part A via DNI
    self.bidirectional_interface.send(x, input)

class PartB(torch.nn.Module):

    def forward(self, input):
        # receive the intermediate results computed by part A via DNI
        x = self.bidirectional_interface.receive(input)

    # ...
    return x
```

PartA and PartB have their own copies of the BidirectionalInterface. BidirectionalInterface.send will compute synthetic gradient w.r.t. x (intermediate results computed by PartA) based on x and input (input of the whole network), backpropagate it and update the estimate of x. BidirectionalInterface.receive will compute synthetic x based on input and in the backward pass, update the estimate of the gradient w.r.t. x. This should work as long as BidirectionalInterface parameters are synchronized between PartA and PartB once in a while.

There is no example code for this use case yet. Contributions welcome!