

- 1 a. Show that the sum of any two orthogonal spacelike vectors is spacelike

"Spacelike" $\Rightarrow \vec{A} \cdot \vec{A} > 0, \vec{B} \cdot \vec{B} > 0$

"Orthogonal" $\Rightarrow \vec{A} \cdot \vec{B} = 0$

$$\vec{A} + \vec{B} \equiv \vec{C}$$

$$\Rightarrow \vec{C} \cdot \vec{C} = \underbrace{\vec{A} \cdot \vec{A}}_{>0} + \underbrace{\vec{B} \cdot \vec{B}}_{>0} + \underbrace{2\vec{A} \cdot \vec{B}}_0$$

$$\Rightarrow \boxed{\vec{C} \cdot \vec{C} > 0 \text{ and } \vec{A} + \vec{B} \text{ is also spacelike}}$$

- b. Show that a timelike vector and a null vector cannot be orthogonal

• If \vec{A} timelike, then $\vec{A} \cdot \vec{A} < 0$ $\vec{B} \neq 0$

• If \vec{B} null, then $\vec{B} \cdot \vec{B} = 0$ and ~~scribble~~

• Assume $\vec{A} \cdot \vec{B}$ is orthogonal i.e. $\vec{A} \cdot \vec{B} = 0$

$$-(B^0)^2 + |\vec{B}|^2 = 0$$

$$\Rightarrow (B^0)^2 = |\vec{B}|^2$$

$$-A^0 B^0 + A^1 B^1 + A^2 B^2 + A^3 B^3 = 0$$

• Choose a frame where \vec{A} is completely temporal: $\vec{A} = (A^0, 0, 0, 0)$ ← $\vec{A} \cdot \vec{B}$ is

$$\Rightarrow A^0 B^0 = 0, \text{ Also } (A^0)^2 < 0$$

$$\Rightarrow B^0 = 0$$

$$\Rightarrow (B^0)^2 = |\vec{B}|^2 = 0$$

$$\Rightarrow (B^1)^2 + (B^2)^2 + (B^3)^2 = 0$$

$$\Rightarrow B^1 = B^2 = B^3 = 0$$

$$\Rightarrow \vec{B} = (0, \vec{0})$$

• Which contradicts our definition of a null or "light like" vector \vec{B} and implies

$$\boxed{\vec{A} \cdot \vec{B} \text{ cannot } = 0 \quad \times}$$

[2] • In some reference frame \vec{U} and \vec{D} have the components:

$$U^\mu \doteq (1+t^2, t^2, \sqrt{2}t, 0)$$

$$D^\mu \doteq (x, stx, \sqrt{2}t, 0)$$

Lorentz invariant
so we are free
to work in
this frame
W.L.O.G.

and the scalar $\rho = x^2 + t^2 - y^2$

[a] • Show that \vec{U} is suitable as a 4-Velocity.
Is \vec{D} also?

• a 4-velocity requires that $\vec{U} \cdot \vec{U} = -1$

$$\begin{aligned}\vec{U} \cdot \vec{U} &= -(1+t^2)^2 + t^4 + 2t^2 \\ &= -1 - t^4 - 2t^2 + t^4 + 2t^2 \\ &= \boxed{-1} \quad \checkmark\end{aligned}$$

• What about \vec{D} ?

$$\begin{aligned}\vec{D} \cdot \vec{D} &= -x^2 + 5^2 t^2 x^2 + 2t^2 \\ &\neq -1 \quad \boxed{\text{So NO} \times}\end{aligned}$$

[b] • Find the spatial velocity \vec{V} of a particle whose 4-velocity is \vec{U} , for arbitrary t :

$$\vec{U} \cdot \vec{U} = -(U^0)^2 + |\vec{V}|^2$$

$$\Rightarrow |\vec{V}|^2 = (U^0)^2 - 1 = 1 + 2t^2 + t^4 - 1$$

$$\Rightarrow |\vec{V}| = \sqrt{2t^2 + t^4} = \boxed{t \sqrt{2+t^2}} = |\vec{V}|$$

$$\lim_{t \rightarrow 0} |\vec{V}| = 0, \quad \lim_{t \rightarrow \infty} |\vec{V}| \rightarrow \infty \approx t^2$$

[c] Find $\partial_\beta U^\alpha$ for all α, β . Show that

$$U_\alpha \partial_\beta U^\alpha = 0 \text{ via brute force}$$

α	β	$\partial_\beta U^\alpha$
t	t	2t
t	x	0
t	y	0
t	z	0
x	t	2t
x	x	0
x	y	0
x	z	0
y	t	$\sqrt{2}$
y	x	0
y	y	0
y	z	0
z	t	0
z	x	0
z	y	0
z	z	0

• one could cleverly show that:

$$\begin{aligned} U_\alpha \partial_\beta U^\alpha &= \partial_\beta U_\alpha U^\alpha \\ &= \partial_\beta (\vec{U} \cdot \vec{U}) \\ &= \partial_\beta (-1) = 0 \quad \checkmark \end{aligned}$$

• But we will use Brute force:

$$\begin{aligned} U_\alpha \partial_\beta U^\alpha &= -U_t \partial_t U^t \\ &\quad + U_x \partial_t U^x \\ &\quad + U_y \partial_t U^y \\ &\quad + U_z \partial_t U^z \end{aligned}$$

$$\begin{aligned} &= -(1+t^2)(2t) \\ &\quad + (t^2)(2t) \\ &\quad + (\sqrt{2}t)(\sqrt{2}) \end{aligned}$$

$$= 0$$

$$\Rightarrow U_\alpha \partial_\beta U^\alpha = 0 \quad \checkmark$$

d. Find $\partial_\alpha D^\alpha \rightarrow$ represents a set of 4 numbers that we sum together?

$$\begin{aligned}\partial_\alpha D^\alpha &= \partial_t D^t + \partial_x D^x + \partial_y D^y + \partial_z D^z \\ &= 0 + 5t + 0 + 0\end{aligned}$$

$$\Rightarrow \boxed{\partial_\alpha D^\alpha = 5t}$$

e. Find $\partial_\beta (U^\alpha D^\beta)$ for all α

$$= U^\alpha \partial_\beta D^\beta = \boxed{5t U^\alpha \text{ -or equivalently-}}$$

$$= \boxed{(5t + 5t^3, 5t^4, 5\sqrt{2}t^2, 0)}$$

f. Find $U_\alpha \partial_\beta (U^\alpha D^\beta)$

$$= 5t U_\alpha U^\alpha = 5t (\vec{U} \cdot \vec{U}) = \boxed{-5t}$$

• This is similar to d since the expressions are actually equivalent up to a minus sign $\forall \ddot{\smile}$

g. calculate $\partial_\alpha \mathcal{P}$ for all α . Calculate $\partial^\alpha \mathcal{P}$:

$$\partial_\alpha \mathcal{P} \rightarrow \{ \partial_t \mathcal{P}, \partial_x \mathcal{P}, \partial_y \mathcal{P}, \partial_z \mathcal{P} \}$$

$$\partial_\alpha \mathcal{P} = \{ zt, zx, -zy, 0 \}$$

$\partial^\alpha \mathcal{P}$ is shorthand for:

$$\partial^\alpha \mathcal{P} = g^{\alpha\beta} \partial_\beta \mathcal{P} \quad \text{where } g^{\alpha\beta} \text{ is the metric tensor} = \text{diag}(-1, 1, 1, 1)$$

• therefore,

$$\partial^\alpha \mathcal{P} = \begin{bmatrix} -1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} zt \\ zx \\ -zy \\ 0 \end{bmatrix} = \begin{bmatrix} -zt \\ zx \\ -zy \\ 0 \end{bmatrix} = \partial^\alpha \mathcal{P}$$

[h] • Find $\nabla_{\vec{U}} \mathcal{P}$ and $\nabla_{\vec{D}} \mathcal{P}$:

$$\parallel \quad U^\alpha \partial_\alpha \mathcal{P}$$

$$\parallel \quad D^\alpha \partial_\alpha \mathcal{P}$$

$$zt + 2t^4 + 2xt^2 - 2\sqrt{2}yt$$

$$2tx + 10x^2t - 2\sqrt{2}yt$$

group like terms

3. Consider a timelike unit 4-vector \vec{U} and the tensor:

$$P_{\alpha\beta} = \eta_{\alpha\beta} + U_{\alpha}U_{\beta}$$

a. show that $V_{\perp}^{\alpha} = P^{\alpha}_{\beta} V^{\beta}$ is orthogonal to \vec{U} :

• We know $\vec{U} \cdot \vec{U} < 0$ "timelike" and unit vector

$$\text{so } \Rightarrow \vec{U} \cdot \vec{U} = -1$$

$$\text{• Let } P^{\alpha}_{\beta} = \eta^{\alpha}_{\beta} + U^{\alpha}U_{\beta}$$

$$\Rightarrow P^{\alpha}_{\beta} V^{\beta} = \eta^{\alpha}_{\beta} V^{\beta} + U^{\alpha}U_{\beta} V^{\beta} \equiv V_{\perp}^{\alpha}$$

$$\Rightarrow U_{\alpha} V_{\perp}^{\alpha} = \underbrace{U_{\alpha} \eta^{\alpha}_{\beta} V^{\beta}}_{\vec{U} \cdot \vec{V}} + \underbrace{U_{\alpha} U^{\alpha}}_{-1} \underbrace{U_{\beta} V^{\beta}}_{\vec{U} \cdot \vec{V}}$$

$$\Rightarrow U_{\alpha} V_{\perp}^{\alpha} = \vec{U} \cdot \vec{V}_{\perp} = \vec{U} \cdot \vec{V} - \vec{U} \cdot \vec{V} = 0$$

$$\Rightarrow \boxed{\vec{U} \cdot \vec{V}_{\perp} = 0} \quad \checkmark$$

[b] • show that $V_{\perp}^{\alpha} = P_{\perp}^{\alpha} V^{\beta}$ is unaffected by further projections:

• i.e. show that $V_{\perp\perp}^{\alpha} \equiv P_{\perp}^{\alpha} V_{\perp}^{\beta} = V_{\perp}^{\alpha}$

$$P_{\perp}^{\alpha} V_{\perp}^{\beta} = \eta_{\perp}^{\alpha} V_{\perp}^{\beta} + U^{\alpha} \underbrace{U_{\beta} V_{\perp}^{\beta}}_{\vec{U} \cdot \vec{V}_{\perp} = 0} \equiv V_{\perp\perp}^{\alpha}$$

$$= \eta_{\perp}^{\alpha} V_{\perp}^{\beta} = V_{\perp}^{\alpha}$$

$$\Rightarrow \boxed{V_{\perp\perp}^{\alpha} = V_{\perp}^{\alpha} \quad \checkmark}$$

[c] • show that $P_{\perp}^{\alpha} V_{\perp}^{\beta} W_{\perp}^{\gamma} = \vec{V}_{\perp} \cdot \vec{W}_{\perp}$

$$\text{RHS} = \vec{V}_{\perp} \cdot \vec{W}_{\perp} = V_{\perp}^{\alpha} W_{\perp\alpha}$$

$$= P_{\perp}^{\alpha} V^{\beta} P_{\perp}^{\gamma} W_{\gamma} = V^{\beta} W_{\gamma} (\eta_{\perp}^{\alpha} + U^{\alpha} U_{\beta}) (\eta_{\perp}^{\gamma} + U^{\gamma} U_{\alpha})$$

$$= V^{\beta} W_{\gamma} \delta_{\beta}^{\gamma} + V^{\beta} W_{\gamma} U^{\alpha} U_{\alpha} U_{\beta} U^{\gamma} + V^{\beta} W_{\gamma} U^{\alpha} U_{\beta} \eta_{\perp}^{\gamma} + V^{\beta} W_{\gamma} \eta_{\perp}^{\alpha} U^{\gamma} U_{\alpha}$$

$$= V^{\beta} W_{\beta} - (\vec{U} \cdot \vec{V})(\vec{U} \cdot \vec{W}) + 2(\vec{U} \cdot \vec{V})(\vec{U} \cdot \vec{W})$$

$$= (\vec{V} \cdot \vec{W}) + (\vec{U} \cdot \vec{V})(\vec{U} \cdot \vec{W}) \quad \checkmark \quad \rightsquigarrow$$

$$\begin{aligned}
 \text{LHS} &= P_{\alpha\beta} V_{\perp}^{\alpha} W_{\perp}^{\beta} \\
 &= (n_{\alpha\beta} + v_{\alpha} v_{\beta}) (P_{\gamma}^{\alpha} V^{\gamma}) (P_{\chi}^{\beta} W^{\chi}) \\
 &= (n_{\alpha\beta} + v_{\alpha} v_{\beta}) (n_{\gamma}^{\alpha} + v^{\alpha} v_{\gamma}) (n_{\chi}^{\beta} + v^{\beta} v_{\chi}) V^{\gamma} W^{\chi} \\
 &= (n_{\alpha\beta} n_{\gamma}^{\alpha} + v_{\alpha} v_{\beta} n_{\gamma}^{\alpha} + n_{\alpha\beta} v^{\alpha} v_{\gamma} + v_{\alpha} v_{\beta} v^{\alpha} v_{\gamma}) \\
 &\quad \cdot (n_{\chi}^{\beta} + v^{\beta} v_{\chi}) V^{\gamma} W^{\chi}
 \end{aligned}$$

$$\begin{aligned}
 &= n_{\alpha\beta} n_{\gamma}^{\alpha} n_{\chi}^{\beta} V^{\gamma} W^{\chi} + v_{\alpha} v_{\beta} n_{\gamma}^{\alpha} n_{\chi}^{\beta} V^{\gamma} W^{\chi} \\
 &+ n_{\alpha\beta} n_{\chi}^{\beta} v^{\alpha} v_{\gamma} V^{\gamma} W^{\chi} + v_{\alpha} v_{\beta} v^{\alpha} v_{\gamma} n_{\chi}^{\beta} V^{\gamma} W^{\chi} \\
 &+ n_{\alpha\beta} n_{\gamma}^{\alpha} v^{\beta} v_{\chi} V^{\gamma} W^{\chi} + v_{\alpha} v_{\beta} v^{\beta} v_{\chi} n_{\gamma}^{\alpha} V^{\gamma} W^{\chi} \\
 &+ n_{\alpha\beta} v^{\alpha} v_{\gamma} v^{\beta} v_{\chi} V^{\gamma} W^{\chi} + v_{\alpha} v_{\beta} v^{\alpha} v_{\gamma} v^{\beta} v_{\chi} V^{\gamma} W^{\chi}
 \end{aligned}$$

$$\begin{aligned}
 &= (\vec{v} \cdot \vec{w}) + (\vec{v} \cdot \vec{v})(\vec{v} \cdot \vec{w}) + \text{[scribbled out]} \\
 &\quad \text{[scribbled out]} (\vec{v} \cdot \vec{v})(\vec{v} \cdot \vec{w}) - (\vec{v} \cdot \vec{v})(\vec{v} \cdot \vec{w}) \\
 &+ (\vec{v} \cdot \vec{v})(\vec{v} \cdot \vec{w}) - (\vec{v} \cdot \vec{v})(\vec{v} \cdot \vec{w}) - (\vec{v} \cdot \vec{v})(\vec{v} \cdot \vec{w}) \\
 &+ (\vec{v} \cdot \vec{v})(\vec{v} \cdot \vec{w}) = (\vec{v} \cdot \vec{w}) + (\vec{v} \cdot \vec{v})(\vec{v} \cdot \vec{w}) \quad \text{W}
 \end{aligned}$$

$$\Rightarrow \text{LHS} = \text{RHS} \Rightarrow \boxed{P_{\alpha\beta} V_{\perp}^{\alpha} W_{\perp}^{\beta} = \vec{V}_{\perp} \cdot \vec{W}_{\perp}} \quad \checkmark$$

[d] • Show that for an arbitrary non-null vector \vec{q} , the projection tensor is given by:

$$P_{\alpha\beta}(q^{\alpha}) = \eta_{\alpha\beta} - \frac{q_{\alpha} q_{\beta}}{q^{\gamma} q_{\gamma}}$$

• If this is the case, then $q_{\perp} \equiv \eta_{\alpha\beta} - \frac{q_{\alpha} q_{\beta}}{q^{\gamma} q_{\gamma}}$ and q^{α} should be orthogonal:

$$q_{\perp\alpha} q^{\alpha} = \eta_{\alpha\beta} q^{\alpha} - \frac{q_{\alpha} q^{\alpha} q^{\beta}}{q^{\gamma} q_{\gamma}}$$

$$= q_{\beta} - q_{\beta} = 0 \quad \checkmark$$

• It doesn't make sense to have a projection tensor for null vectors since every vector is orthogonal to a null vector... \checkmark

[4] Let $\Lambda_B(\bar{v})$ be a Lorentz boost associated with velocity \bar{v} . Consider

$$\Lambda_{tot} \equiv \Lambda_B(\bar{v}_1) \Lambda_B(\bar{v}_2) \Lambda_B(-\bar{v}_1) \Lambda_B(-\bar{v}_2)$$

where $\bar{v}_1 \cdot \bar{v}_2 = 0$ and $v_1, v_2 \ll 1$. Show that Λ_{tot} is a rotation. What is the axis + angle.

• Intuitively it makes sense that the composition of these 4 boosts should generally get you back to the same frame, but since they don't commute, there is some mixing going on that causes these rotations.

• Take the case:

$$\Lambda_{tot} = \Lambda_B(v_x) \Lambda_B(v_y) \Lambda_B(-v_x) \Lambda_B(-v_y)$$

where $v_x \perp v_y$

$$\Lambda_B(v_x) = \begin{bmatrix} \gamma_1 & -\gamma_1 \beta_1 & 0 & 0 \\ -\gamma_1 \beta_1 & \gamma_1 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \end{bmatrix}$$

and \rightsquigarrow

$$\Lambda_B(v_y) = \begin{bmatrix} \gamma_2 & 0 & -\gamma_2 \beta_2 & 0 \\ 0 & 1 & 0 & 0 \\ -\gamma_2 \beta_2 & 0 & \gamma_2 & 0 \\ 0 & 0 & 0 & 1 \end{bmatrix}$$

and for $\Lambda_B(-v_x)$ and $\Lambda_B(-v_y)$ they are similar but all the entries are positive

$$\Rightarrow \Lambda_B(-v_x) \Lambda_B(-v_y) = \begin{bmatrix} +\gamma_1 & +\gamma_1 \beta_1 & 0 & 0 \\ +\gamma_1 \beta_1 & +\gamma_1 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} \gamma_2 & 0 & \gamma_2 \beta_2 & 0 \\ 0 & 1 & 0 & 0 \\ \gamma_2 \beta_2 & 0 & \gamma_2 & 0 \\ 0 & 0 & 0 & 1 \end{bmatrix}$$

$$= \begin{bmatrix} \gamma_1 \gamma_2 & \gamma_1 \beta_1 & \gamma_1 \gamma_2 \beta_2 & 0 \\ \gamma_1 \gamma_2 \beta_1 & \gamma_1 & \gamma_1 \gamma_2 \beta_1 \beta_2 & 0 \\ \gamma_2 \beta_2 & 0 & \gamma_2 & 0 \\ 0 & 0 & 0 & 1 \end{bmatrix}$$

• Also

$$\Lambda_B(v_x) \Lambda_B(v_y) = \begin{bmatrix} \gamma_1 & -\gamma_1 \beta_1 & 0 & 0 \\ -\gamma_1 \beta_1 & \gamma_1 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} \gamma_2 & 0 & -\gamma_2 \beta_2 & 0 \\ 0 & 1 & 0 & 0 \\ -\gamma_2 \beta_2 & 0 & \gamma_2 & 0 \\ 0 & 0 & 0 & 1 \end{bmatrix}$$

$$= \begin{bmatrix} \gamma_1 \gamma_2 & -\gamma_1 \beta_1 & -\gamma_1 \gamma_2 \beta_2 & 0 \\ -\gamma_1 \gamma_2 \beta_1 & \gamma_1 & \gamma_1 \gamma_2 \beta_1 \beta_2 & 0 \\ -\gamma_2 \beta_2 & 0 & \gamma_2 & 0 \\ 0 & 0 & 0 & 1 \end{bmatrix}$$



$$\Lambda_{\text{tot}} = \Lambda(V_x) \Lambda(V_y) \Lambda(-V_x) \Lambda(-V_y)$$

$$= \begin{bmatrix} x_1 x_2 & -x_1 \beta_1 & -x_1 x_2 \beta_2 & 0 \\ -x_1 x_2 \beta_1 & x_1 & x_1 x_2 \beta_1 \beta_2 & 0 \\ -x_2 \beta_2 & 0 & x_2 & 0 \\ 0 & 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} x_1 x_2 & x_1 \beta_1 & x_1 x_2 \beta_2 & 0 \\ x_1 x_2 \beta_1 & x_1 & x_1 x_2 \beta_1 \beta_2 & 0 \\ x_2 \beta_2 & 0 & x_2 & 0 \\ 0 & 0 & 0 & 1 \end{bmatrix}$$

$$= \begin{bmatrix} x_1^2 x_2^2 - x_1^2 x_2 \beta_1^2 - x_1 x_2^2 \beta_2^2 & x_1^2 x_2 \beta_1 - x_1^2 \beta_1 & x_1^2 x_2^2 \beta_2 - x_1 x_2 \beta_1 \beta_2 - x_1 x_2^2 \beta_2 & 0 \\ -x_1^2 x_2^2 \beta_1 + x_1^2 x_2 \beta_1 + x_1 x_2^2 \beta_1 \beta_2 & -x_1^2 x_2 \beta_1^2 + x_1^2 & -x_1^2 x_2^2 \beta_2 \beta_1 + x_1^2 x_2 \beta_1 \beta_2 + x_1 x_2^2 \beta_1 \beta_2 & 0 \\ -x_1 x_2^2 \beta_2 + x_2^2 \beta_2 & -x_1 x_2 \beta_1 \beta_2 & x_2^2 & 0 \\ 0 & 0 & 0 & 1 \end{bmatrix}$$

• This huge annoying 4x4 matrix should in theory represent a rotation around z . Therefore, we compare the circled 3x3 matrix to a Rotation matrix.

$$\begin{bmatrix} -x_1^2 x_2 \beta_1^2 + x_1^2 & -x_1^2 x_2^2 \beta_1 \beta_2 + x_1^2 x_2 \beta_1 \beta_2 + x_1 x_2^2 \beta_1 \beta_2 & 0 \\ -x_1 x_2 \beta_1 \beta_2 & x_2^2 & 0 \\ 0 & 0 & 1 \end{bmatrix}$$

$$\stackrel{?}{=} \begin{bmatrix} \cos \theta & -\sin \theta & 0 \\ \sin \theta & \cos \theta & 0 \\ 0 & 0 & 1 \end{bmatrix}$$



• That would imply:

$$\sin \theta = -\gamma_1 \gamma_2 \beta_1 \beta_2$$

\S

θ

$=$

$$\frac{-V_1 V_2}{\sqrt{(1-V_1^2)(1-V_2^2)}}$$

units with $c=1$

denominator ≈ 1 since
 $V_1 \ll 1$ and $V_2 \ll 1$

$\Rightarrow |\theta| \approx V_1 V_2$ about the z axis.

Back in units with $c=c$, we get

$$|\theta| \approx \frac{V_1 V_2}{c^2}$$

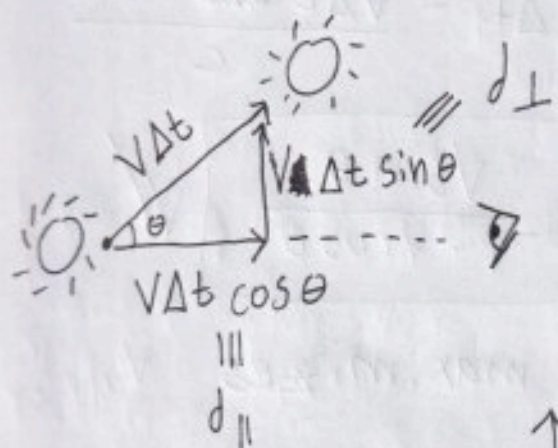
about z -axis

✓✓

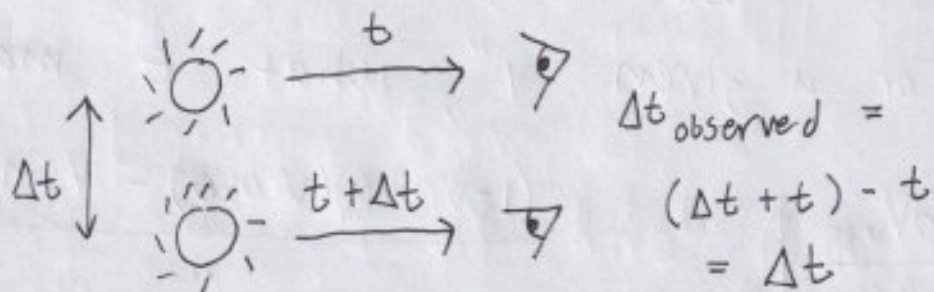
[5]. A quasar is moving towards you and up at an angle θ . The apparent upwards velocity is v_{app} :

[a]. Find the expression for v_{app} in terms of θ and the true velocity " v ":

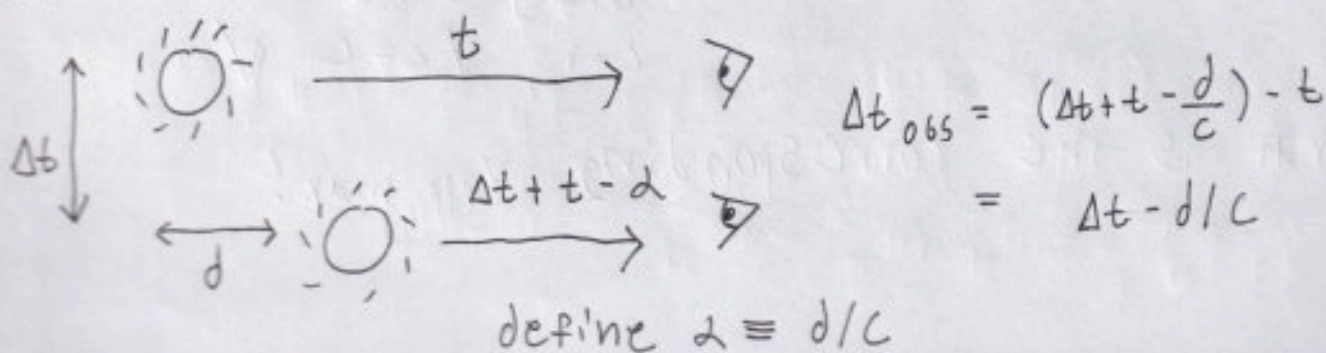
• Let's draw a diagram:



• Also take an aside & start to think about light discretely. Imagine a light bulb releasing photons at intervals of Δt :



• If the light bulb is stationary, then you also perceive the time between flashes as Δt as above. However, if the bulb is moving towards you:



• Then $\Delta t_{\text{obs}} = \Delta t - d/c \neq \Delta t$
 i.e. you see a different time between emission of photons compared to the proper time of the bulb.

• we can say that the perceived upwards velocity of the quasar is:

$$V_{\text{app}} = \frac{d_{\perp}}{\Delta t_{\text{obs}}} ; \quad \Delta t_{\text{obs}} = \Delta t - d_{\parallel}/c$$

$$= \Delta t - \frac{V \Delta t \cos \theta}{c}$$

$$\Rightarrow V_{\text{app}} = \frac{V \Delta t \sin \theta}{\Delta t - V \Delta t \cos \theta} \Rightarrow \boxed{V_{\text{app}} = \frac{V \sin \theta}{1 - V \cos \theta}} \quad \checkmark$$

[b]. For a given "V", what θ maximizes V_{app} ?

$$0 = \left. \frac{\partial V_{\text{app}}}{\partial \theta} \right|_{\theta_{\text{max}}} = \frac{(1 - V \cos \theta_m)(V \sin \theta_m) - V \sin \theta_m (V \sin \theta_m)}{\dots}$$

$$\Rightarrow V \cos \theta_{\text{max}} - V^2 (\sin^2 \theta_{\text{max}} + \cos^2 \theta_{\text{max}}) = 0$$

$$\Rightarrow \cos \theta_{\text{max}} = V \Rightarrow \boxed{\theta_{\text{max}} = \cos^{-1}(V)}$$

↑ okay since in units with $c=1$, $V <= c$ ✓

• What is the corresponding $V_{\text{app, max}}$?

$$V_{am} = \frac{V \sin(\cos^{-1}(V))}{1 - V^2}, \quad V < 1$$

bounded to ≤ 1

really small if $V \ll 1$

⇒ possible for $V_{am} > 1$ (in units with $c=1$)

- Special Relativity is not violated in this case because this is just the apparent motion / information is not actually being transmitted at $> c$ values... 😊

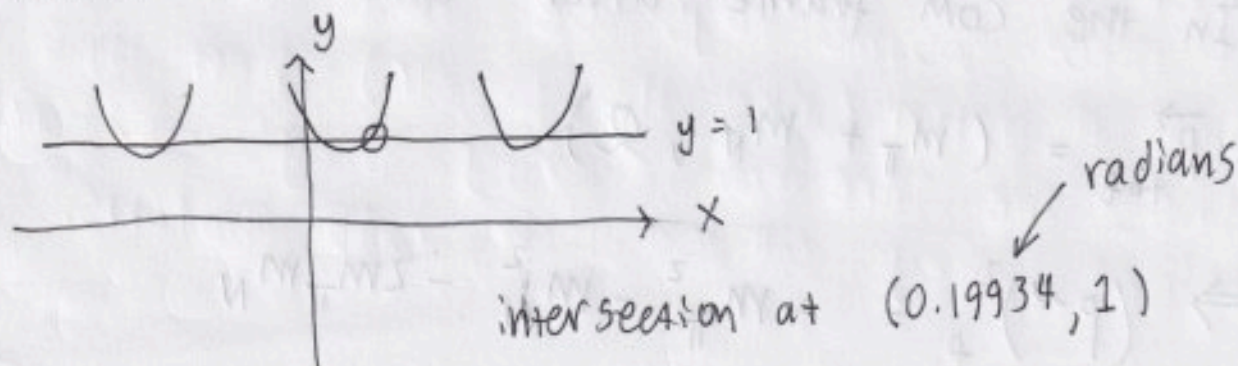
[C] • For $V_{app} \approx 10c$, what is the largest possible value of θ ?

i.e. $10 = \frac{V \sin \theta}{1 - V \cos \theta}$

• plot this as $\theta \rightarrow x$
and $V \rightarrow y$ and
ensure $y < 1$:

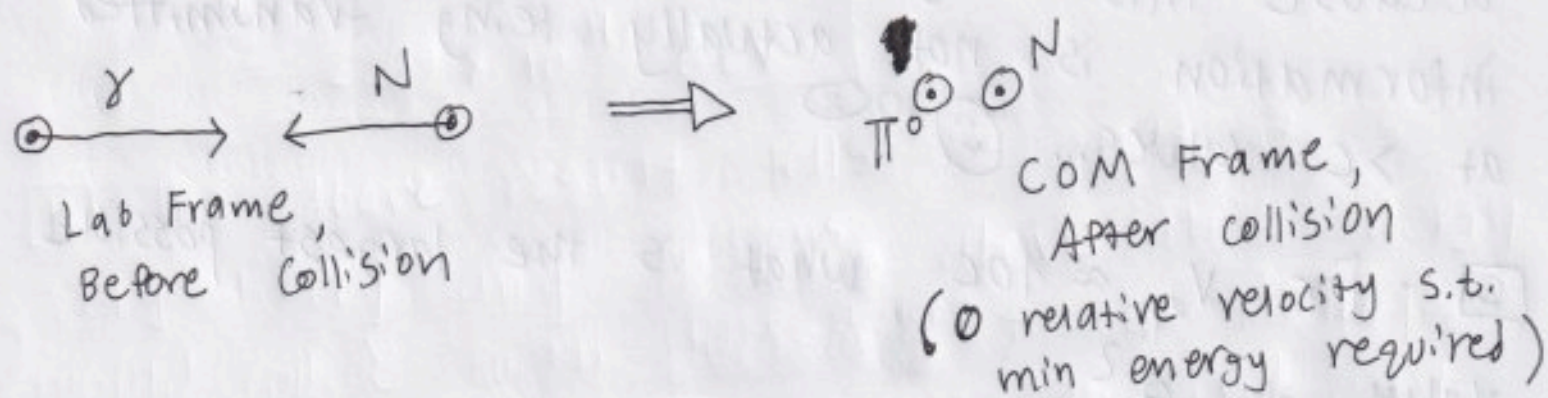
⇒ $10 - 10y \cos x = y \sin x$

⇒ $\frac{10}{\sin x + 10 \cos x} = y ; y \leq 1$



$$\Rightarrow 0.199 \times \frac{180^\circ}{\pi} \approx 11.4^\circ \text{ is max possible } \theta \text{ for this configuration}$$

6a. Calculate the threshold energy of a nucleon N for it to undergo the reaction $\gamma + N \rightarrow N + \pi^0$ where γ is a CMB photon w/ energy kT where $T = 2.73$ kelvin. Assume the collision is head on + take $M_N = 938$ MeV and $M_\pi = 135$ MeV:



\vec{p}^μ is a conserved quantity (the momentum 4-vector) and $(p^\mu)^2$ {the square of 4-mom is a Lorentz invariant between frames}.

Therefore, to solve relativistic kinematics problems like this we will compare $(p^\mu)^2_{\text{initial}} = (p^\mu)^2_{\text{final}}$

• In the COM frame after collision:

$$\vec{p}_{\text{tot}} = (m_\pi + m_N, 0)$$

$$\Rightarrow (p^\mu)^2_f = -m_\pi^2 - m_N^2 - 2m_\pi m_N$$

• In the lab frame before the collision,

$$\vec{P}_{\text{tot}} = \vec{P}_\gamma + \vec{P}_N$$

$$\Rightarrow (P^\mu)^2 = P_\gamma^2 + P_N^2 + 2\vec{P}_\gamma \cdot \vec{P}_N$$

Lorentz Invariants

• In lab frame; $\vec{P}_\gamma = (\epsilon, -\vec{\epsilon})$

$\epsilon = kT$

• Since $E^2 = p^2 + m^2$ zero rest mass for photon

$$\Rightarrow |\vec{P}|_{\text{Spatial Photon}} = \epsilon$$

$$\Rightarrow P_\gamma^2 = -\epsilon^2 + \epsilon^2 = 0$$

• Also in lab frame; $\vec{P}_N \approx (E_N, \vec{E}_N)$

Since we assume $|\vec{P}_{N, \text{spatial}}| \gg m_N$

$$\Rightarrow 2\vec{P}_\gamma \cdot \vec{P}_N \approx 2(-\epsilon E_N - \epsilon E_N) = -4kTE_N$$

• In rest frame of Nucleon; $\vec{P}_N = (m_N, 0)$

$$\Rightarrow P_N^2 = -m_N^2$$

• Putting this all together yields:

$$-\cancel{m_N^2} - m_\pi^2 - 2m_\pi m_N = -\cancel{m_N^2} - 4kT E_N$$

$$\Rightarrow E_N = \frac{m_\pi^2 + 2m_\pi m_N}{4kT}$$

$$\Rightarrow E_N \approx 2.89 \times 10^{20} \text{ eV} \\ = 2.89 \times 10^{11} \text{ GeV}$$

[b] The above result tells us that it is very likely any ~~nucleons~~ above this energy would collide with ~~CMB photons~~ & be "destroyed". It would then seem unlikely to find any ~~nucleons~~ above this energy. Freely traveling ~~nucleons~~ above this energy. This is called the Griesen-Zatsepin-Kuzmin GZK cutoff.

[c] Many examples of cosmic rays above the GZK cutoff have been found. These are puzzling, but if these cosmic rays are made of nucleons heavier than a proton (like He, Li, etc) then this would raise the threshold energy they could achieve before they collide with CMB photons.