

Personal information

Surname(s) / First name(s)

Address(es)

Telephone(s)

Email(s)

Nationality(-ies)

Date of birth

Gender

Zanlungo Francesco

700-0927, Okayama-ken, Okayama-shi, Nishi Furu Matsu, 2-11-6, Japan

(+81) 0774-95-1561, (+81) 080-4018-2731

zanlungo@atr.jp, francesco.zanlungo@gmail.com

Italian, **Holder of Japanese permanent residence permit**

10/03/1976

Male

Research keywords

Complex Systems Modelling, Crowd Behaviour, Simulations, Robotics

Professional experience

April 2021- Present

Lecturer

Osaka Professional University, Osaka, Japan

xxx

April 2021-Present

Researcher

Okayama University, Okayama, Japan

Monden's Kiban-S

April 2017- Present

Collaborative researcher

Intelligent Robotics and Communication Laboratories, ATR, Kyoto, Japan

Studying the behaviour of pedestrians and robot-pedestrian interactions

April 2020-March 2021

Specially appointed lecturer

Okayama University, Okayama, Japan

Kanda's Kiban A

November 2016-March 2017

Researcher

Intelligent Robotics and Communication Laboratories, ATR, Kyoto, Japan

Studying the behaviour of pedestrians and robot-pedestrian interactions

2015-2016

Lecturer in Applied Mathematics

Kingston University, London, UK

Faculty of Science, Engineering and Computing, School of Computer Science and Mathematics

Tenured position, resigned to go back to Japan for family related reasons

2009-2015

Researcher

Intelligent Robotics and Communication Laboratories, ATR, Kyoto, Japan

Studying the behaviour of pedestrians and robot-pedestrian interactions

November 2008 and September 2009

Visiting researcher

CPT (Theoretical Physics Center), Marseilles, France

Collaboration with Prof. Sandro Vaienti

2008

Instructor

	Milan Polytechnic University Teaching Introductory course of Mathematics (“College Algebra”)																																																																																								
2007-2009	Post-doctoral researcher University of Bologna Analysis of the effect of random noise and numerical round-off on discrete maps																																																																																								
June-September 2005	Visiting researcher Artificial Life Laboratory at Nagoya University Collaboration with Prof. Takaya Arita																																																																																								
Journal editing																																																																																									
From August 2018	Area Editor Simulation Modelling Practice and Theory, Elsevier																																																																																								
Professional experience outside research																																																																																									
From 2017	Instructor of conversational Italian language Japan-Italy Society of Okayama																																																																																								
Education and training																																																																																									
2004-2007	Ph.D. course																																																																																								
Major	Theoretical Physics																																																																																								
Institution	Graduate school of Physics, University of Bologna, Italy																																																																																								
Graduation Thesis	Microscopic Dynamics of Artificial Life Systems, supervised by Prof. Giorgio Turchetti																																																																																								
2003	Japanese language education																																																																																								
Institution	Yamasa Language school, Okazaki-shi, Aichi-ken, Japan																																																																																								
2002	Italian Laurea in Physics <i>(The Italian “Laurea” is legally equivalent to a Master degree. To obtain the degree, the candidate was supposed to work on a one year Graduation Thesis project requiring original research.)</i>																																																																																								
Major	Theoretical Physics																																																																																								
Institution	University of Milan, Italy																																																																																								
Graduation Thesis	Studio numerico della cascata ultravioletta nel modello ϕ^4 classico (in Italian), supervised by Prof. Claudio Destri																																																																																								
Languages																																																																																									
Mother tongue(s)	Italian																																																																																								
<i>Self-assessment European level^(*)</i>																																																																																									
English																																																																																									
Japanese(**)																																																																																									
Spanish																																																																																									
Portuguese																																																																																									
French																																																																																									
Turkish																																																																																									
Mandarin Chinese																																																																																									
	<table><tr><th colspan="4">Understanding</th><th colspan="4">Speaking</th><th colspan="2" rowspan="2">Writing</th></tr><tr><th colspan="2">Listening</th><th colspan="2">Reading</th><th colspan="2">Spoken interaction</th><th colspan="2">Spoken production</th></tr><tr><td>C2</td><td>Proficient user</td><td>C2</td><td>Proficient user</td><td>C2</td><td>Proficient user</td><td>C2</td><td>Proficient user</td><td>C2</td><td>Proficient user</td></tr><tr><td>C1</td><td>Proficient user</td><td>C1</td><td>Proficient user</td><td>C1</td><td>Proficient user</td><td>C1</td><td>Proficient user</td><td>C1</td><td>Proficient user</td></tr><tr><td>C2</td><td>Proficient user</td><td>C2</td><td>Proficient user</td><td>C1</td><td>Proficient user</td><td>C1</td><td>Proficient user</td><td>C1</td><td>Proficient user</td></tr><tr><td>C1</td><td>Proficient user</td><td>C1</td><td>Proficient user</td><td>B2</td><td>Independent user</td><td>B2</td><td>Independent user</td><td>B1</td><td>Independent user</td></tr><tr><td>B2</td><td>Independent user</td><td>C1</td><td>Proficient user</td><td>B1</td><td>Independent user</td><td>B1</td><td>Independent user</td><td>A2</td><td>Basic user</td></tr><tr><td>A1</td><td>Basic user</td><td>A1</td><td>Basic user</td><td>A1</td><td>Basic user</td><td>A1</td><td>Basic user</td><td>A1</td><td>Basic user</td></tr><tr><td>A1</td><td>Basic user</td><td>A1</td><td>Basic user</td><td>A1</td><td>Basic user</td><td>A1</td><td>Basic user</td><td>A1</td><td>Basic user</td></tr></table>	Understanding				Speaking				Writing		Listening		Reading		Spoken interaction		Spoken production		C2	Proficient user	C2	Proficient user	C2	Proficient user	C2	Proficient user	C2	Proficient user	C1	Proficient user	C1	Proficient user	C1	Proficient user	C1	Proficient user	C1	Proficient user	C2	Proficient user	C2	Proficient user	C1	Proficient user	C1	Proficient user	C1	Proficient user	C1	Proficient user	C1	Proficient user	B2	Independent user	B2	Independent user	B1	Independent user	B2	Independent user	C1	Proficient user	B1	Independent user	B1	Independent user	A2	Basic user	A1	Basic user	A1	Basic user	A1	Basic user	A1	Basic user	A1	Basic user	A1	Basic user	A1	Basic user	A1	Basic user	A1	Basic user	A1	Basic user
Understanding				Speaking				Writing																																																																																	
Listening		Reading		Spoken interaction		Spoken production																																																																																			
C2	Proficient user	C2	Proficient user	C2	Proficient user	C2	Proficient user	C2	Proficient user																																																																																
C1	Proficient user	C1	Proficient user	C1	Proficient user	C1	Proficient user	C1	Proficient user																																																																																
C2	Proficient user	C2	Proficient user	C1	Proficient user	C1	Proficient user	C1	Proficient user																																																																																
C1	Proficient user	C1	Proficient user	B2	Independent user	B2	Independent user	B1	Independent user																																																																																
B2	Independent user	C1	Proficient user	B1	Independent user	B1	Independent user	A2	Basic user																																																																																
A1	Basic user	A1	Basic user	A1	Basic user	A1	Basic user	A1	Basic user																																																																																
A1	Basic user	A1	Basic user	A1	Basic user	A1	Basic user	A1	Basic user																																																																																
	^(*) Common European Framework of Reference (CEF) level																																																																																								
	^(**) Holder of first (highest) level of Japanese proficiency, approved in 2008																																																																																								

External funding

- 2021 Collaborative researcher at Kanda's Kiban-A project
Granted by the Japan Society for the Promotion of Science
Budget 2M Japanese Yen
- 2016 I was, along with two colleagues, part of the Kingston University team that prepared the proposal for the H2020 EU "Monica" project, to which 26 European universities, research centres, industries and public institutions participated. The project has been approved with a budget of 15 million euros, 1 million of them corresponding to the Kingston University unit.

Awards

- 2016 Awarded a Kingston University Mres studentship (i.e., a fund for a Master student)

Experience in event organisation

- 2006-2009 In-chief of the organising committee
The Italian workshop on Biophysics (Biophys'06-09), held annually in Arcidosso, Grosseto, Italy.

Computer skills

C, C++, Fortran, Matlab, Mathematica
MS Office, HTML
Latex

Additional information

Home page www.irc.atr.jp/~zanlungo/

Driving licence(s) B (cars)

Personal interests Foreign languages, swimming, running, cycling, basketball, traveling, music, digital photography, books in general, my family.

Teaching experience

- 2021-2022 (Ongoing) Linear algebra, Osaka Professional University
- 2021-2022 (Ongoing) Classical mechanics, Okayama University
- 2016-2017 (Appointed, and prepared lecture notes, before resigning) Applications of Calculus, Partial Differential Equations module, School of Computer Science and Mathematics, Kingston University
This undergraduate course introduces the theory of Linear Partial Differential Equations. The course starts with an introduction to the geometrical meaning of vector calculus leading to the expression of the Laplace operator in the principal curvilinear coordinate systems. Then the Heat, Wave, Poisson and Schrödinger equations are introduced, along with separation of variables solutions in Cartesian and spherical coordinates.
- Course notes https://www.dropbox.com/s/ja2arlaweeycn8b/notes_prova.pdf?dl=0
- 2015-2016 Mathematical and Numerical Methods, Numerical Linear Algebra module, School of Computer Science and Mathematics, Kingston University
This undergraduate course revises the main theoretical concepts of linear algebra (linear systems, vector space, linear operators, vector and matrix norm, contraction theorem, eigenvalues and eigenvectors, matrix diagonalisation), and introduces numerical algorithms for the solution of related problems (Gaussian Elimination, LU decomposition, iterative methods, eigenvalue power method).
- Course notes <https://www.dropbox.com/s/z7d28niwldy734m/notes.pdf?dl=0>

2015-2016	<p>Mathematical Models and Computation, Programming module, School of Computer Science and Mathematics, Kingston University</p> <p><i>This undergraduate course introduces the fundamental sorting and search algorithms, along with the theoretical concepts necessary for their analysis (algorithm complexity). Part of the course is directed to practical exercitations aimed at acquiring the abilities for performing scientific programming.</i></p>
2015-2016	<p>Engineering Mathematics and Computing, School of Civil Engineering, Kingston University</p> <p><i>This undergraduate course revises the fundamental concepts of applied calculus (up to ordinary differential equations) and teaches how to solve the related problems by Matlab.</i></p>
2008-2009	<p>Analytical Mechanics, Instructed by Prof. Turchetti and F. Zanlungo, Dep. of Physics, Bologna University</p> <p><i>This course was focused on a throughout analysis of Lagrangian Mechanics (Lagrange equations, symmetries, central field, two body problem, stability, small oscillations, rigid body) and a solid introduction to Hamiltonian dynamics (Hamilton equations, canonical transformations, Noether theorem, integrable systems, Liouville theorem, ergodicity). My task on the course was to give part of the theoretical classes.</i></p>
2008-2009	<p>Teaching assistant of the Institutions of Mathematics course, Instructed by Prof. Bazzani, Milan Polytechnic University</p> <p><i>An introductory calculus course, focused in particular on the concepts of real numbers, functions, limits and derivation, along with some notions of linear algebra. My task on the course was to give some theoretical classes in absence of Prof. Bazzani, hold practice sessions and prepare examination tests.</i></p>
2008	<p>Introductory course of Mathematics ("College Algebra"), Milan Polytechnic University</p> <p><i>A course intended for those students that passed the University entry exam but scored poorly in mathematics, focused mainly on the concept of elementary real functions.</i></p>
2007-2008	<p>Teaching assistant of the Numerical Methods course, Instructed by Profs. Turchetti and Bazzani, Master course in Physics, Bologna University</p> <p><i>This course was focused on an introduction of numerical methods for physical sciences (interpolation, numerical solution of non linear equations, numerical integration, numerical solution of differential equations, stochastic systems). My task on the course was to give a few theoretical classes and to assist students during practice sessions.</i></p>
2007-2008	<p>Teaching assistant of the Complex Systems Laboratory course, Instructed by Dr. Giorgini, Dep. of Physics, Bologna University</p> <p><i>For this course, I prepared lectures on genetic algorithms, population dynamics (evolutionary game theory) and neural networks.</i></p>

Research experience

Crowd dynamics

Mathematical modelling of pedestrian behaviour, crowd dynamics and group behaviour, in collaboration with T. Kanda

In ATR we collected a large amount of data concerning the behaviour of pedestrians in experimental settings and in real world environments, which I used to develop original models of pedestrian and crowd dynamics. More in detail, the major findings regarded:

1. The need to include a velocity dependent potential in a collision avoiding model for pedestrians, and the development of a corresponding mathematical and computational model [6].
2. The tendency of (Japanese) pedestrians to walk on the left side of corridors, and to overtake other pedestrians on the right side, and the development of a method to introduce in a realistic way such a tendency in any pedestrian collision avoidance model [5,19,20].
3. Large pedestrian groups are not stable, and usually break up in more stable 2 or 3 pedestrian sub-units [26].
4. A mathematical model for the behaviour of social pedestrian groups, which was able to correctly predict the shape and velocity of pedestrian groups in low density, large environments [4].
5. Empirical study and mathematical modelling of how crowd density and other environment features affect the behaviour of pedestrian groups [2,3,18].
6. How group composition and social roles affect the behaviour of pedestrian groups, and how this information may be used to automatically recognise groups and their [1,22,24].
7. How gestures affect the behaviour of pedestrian groups [15].
8. How the presence of groups affects crowd dynamics [21]

Human-Robot interaction

Socially acceptable mobile robot navigation, in collaboration with T. Kanda and Z. Yücel

While working at ATR I have been also involved in more engineering oriented works, such as the development of a robot able to smoothly navigate inside a human crowd [16,23,25,30,36,37,40], and the development of algorithms to automatically detect pedestrian walking goals [38] and pedestrian groups [17,31,32,34,35,39].

Discrete chaotic systems

Analysis of the effect of noise on discrete maps, in collaboration with S. Vaienti and G. Turchetti

Development of a method to find a threshold beyond which the numerical results on chaotic maps are not reliable, and analysis of the differences between the effect of random noise and the effect of numerical round-off on the dynamics of the map [7,8,9].

Evolutionary dynamics of agent systems

Microscopic Dynamics of Artificial Life Systems (Ph.D. thesis, sup. G. Turchetti, in collaboration with T. Arita)

Using an approach combining cellular automata or agent models with differential equation (replicator dynamics) models, I studied:

1. The Immune System T cell clonal expansion [12].
2. The relation between the evolution of collision avoidance strategies and the evolution of a *Theory of Mind* [13,27,28].
3. The evolution of “traffic conventions” (such as driving on the left or right side of streets) in a mobility system [10,29].
4. The consequences of the fact that interactions dependent on vision (such as the collision avoidance in crowd dynamics) do not follow the action-reaction law of dynamics [11,33].

Numerical study of statistical
properties of relativistic fields

Numerical study of the ultraviolet cascade in ϕ^4 classical model (Master thesis, sup. C. Destri)

Using a numerical algorithm that treats time and space in a symmetrical way, preserving thus the relativistic structure of the field theory, and conserving energy at machine precision, I studied the energy diffusion to the higher (ultraviolet) modes of a relativistic scalar field with a quartic interaction term. The results were compared with a more traditional numerical treatment of hyperbolic partial differential equations.

Publications

Peer reviewed journal papers (or book chapters) of which I was the corresponding author

- 1 F. Zanlungo, Z. Yücel, D. Bršćić, T. Kanda and N. Hagita
Intrinsic group behaviour: dependence of pedestrian dyad dynamics on principal social and personal features
Plos One 0187253 (2017) (**impact factor 3.54**)
10.1371/journal.pone.0187253
- 2 F. Zanlungo and T. Kanda
A mesoscopic model for the effect of density on pedestrian group dynamics
Europhysics Letters, 111, 38007 (2015) (**impact factor 2.095**)
10.1209/0295-5075/111/38007
- 3 F. Zanlungo, D. Bršćić and T. Kanda
Spatial-size scaling of pedestrian groups under growing density conditions
Physical Review E 91 (6), 062810 (2015) (**impact factor 2.288**)
10.1103/PhysRevE.91.062810
- 4 F. Zanlungo, T. Ikeda and T. Kanda
Potential for the dynamics of pedestrians in a socially interacting group
Physical Review E 89 (1), 012811 (2014) (**impact factor 2.288**)
10.1103/PhysRevE.89.012811
(Paper chosen as “editor suggestion”, i.e. as being of particular clarity and importance)
- 5 F. Zanlungo, T. Ikeda and T. Kanda
A microscopic social norm model to obtain realistic macroscopic velocity and density pedestrian distributions
PLoS ONE 7 (12), e50720 (2012) (**impact factor 3.73**)
10.1371/journal.pone.0050720
- 6 F. Zanlungo, T. Ikeda and T. Kanda
Social force model with explicit collision prediction
Europhysics Letters, 93, 68005 (2011) (**impact factor 2.171**)
10.1209/0295-5075/93/68005
- 7 G. Turchetti, S. Vaienti and F. Zanlungo
Asymptotic distribution of global errors in the numerical computations of dynamical systems
Physica A 389 (2010) pp. 4994-5006 (**impact factor 1.521**)
10.1016/j.physa.2010.06.060
- 8 G. Turchetti, S. Vaienti and F. Zanlungo
Relaxation to the asymptotic distribution of global errors due to round off
Europhysics Letters, 89, 40006 (2010) (**impact factor 2.753**)
10.1209/0295-5075/89/40006
- 9 P. Marie, G. Turchetti, S. Vaienti and F. Zanlungo
Error distribution in randomly perturbed orbits
CHAOS 19, 043118 (2009) (**impact factor 1.795**)
10.1063/1.3267510

- 10 F. Zanlungo, T. Arita, S. Rambaldi
Emergence of a traffic flow convention in a multiagent model
Advances in Complex Systems. Vol.11, Issue 5, pp. 789-802 (2008)
10.1142/S0219525908001921
- 11 G. Turchetti, F. Zanlungo, B. Giorgini
Dynamics and thermodynamics of a gas of automata
Europhysics Letters, Volume 78, Issue 5, 58003 (2007) (**impact factor 2.206**)
10.1209/0295-5075/78/58003

- 12 F. Zanlungo, G. Turchetti, S. Rambaldi
An Automata Based Microscopic Model Inspired by Clonal Expansion
Mathematical Modeling of Biological Systems, Volume II. A. Deutsch et al. (eds.), Birkhäuser, Boston, pp. 133-144 (2007)
10.1007/978-0-8176-4556-4_12
- 13 F. Zanlungo
A collision avoiding mechanism based on a theory of mind
Advances in Complex Systems. Vol. 10 suppl. No. 2, pp. 363-371 (2007)
10.1142/S0219525907001410
- 14 39 authors including F. Zanlungo
A Glossary for Research in Human Crowd Dynamics
Collective Dynamics, 4:1-13 (2019)
10.17815/CD.2019.19
- 15 Z. Yücel, F. Zanlungo and M. Shiomi
Modeling the impact of interaction on pedestrian group motion
Advanced Robotics, 1-11 (2018) (**impact factor 0.92**)
10.1080/01691864.2017.1421481
- 16 M. Shiomi, F. Zanlungo, K. Hayashi and T. Kanda
Towards a Socially Acceptable Collision Avoidance for a Mobile Robot Navigating Among Pedestrians Using a Pedestrian Model
International Journal of Social Robotics, 1-13 (2014) (**impact factor 1.207**)
10.1007/s12369-014-0238-y
- 17 Z. Yücel, F. Zanlungo, T. Ikeda, T. Miyashita, N. Hagita
Deciphering the crowd: Modeling and identification of pedestrian group motion
Sensors, 13(1), 875-897, 2013 (**impact factor 1.953**)
10.3390/s130100875
- 18 F. Zanlungo, D. Bršćić and T. Kanda
Pedestrian group behaviour analysis under different density conditions
Transportation Research Procedia 2, 149-158, Proceedings of PED 2014, Delft TU
10.1016/j.trpro.2014.09.020
- 19 D. Bršćić, F. Zanlungo and T. Kanda
Density and velocity patterns during one year of pedestrian tracking
Transportation Research Procedia 2, 77-86, Proceedings of PED 2014, Delft TU
- 20 F. Zanlungo, Y. Chigodo, T. Ikeda and T. Kanda
Experimental study and modelling of pedestrian space occupation and motion pattern in a real world environment
Pedestrian and Evacuation Dynamics 2012, Zurich ETH, Weidmann et al. (eds.), pp. 289-304, Springer, (published as a book in 2014)

Other peer-reviewed journal papers

Journal papers (or book chapters) of which I was the corresponding author, only abstract subjected to peer reviewing

Peer-reviewed conference
papers of which I was the
corresponding author

- 21 F. Zanlungo, L. Crociani, Z. Yücel, T. Kanda
The effect of social groups on the dynamics of bi-directional pedestrian flow: a numerical study
2019 Traffic and Granular Flow Conference, Pamplona, Spain
- 22 F. Zanlungo, Z. Yücel, T. Kanda
Social group behaviour in triads
2018 Pedestrian and Evacuation Conference, Lund, Sweden
- 23 F. Zanlungo, Z. Yücel, F. Ferreri, J. Even, L.Y. Morales Saiki, T. Kanda
Pedestrian models for robot motion
2018 Pedestrian and Evacuation Conference, Lund, Sweden
- 24 F. Zanlungo, Z. Yücel and T. Kanda
The effect of social roles on group behaviour
2016 Pedestrian and Evacuation Conference, Hefei, China
- 25 F. Zanlungo, Z. Yücel, F. Ferreri, J. Even, L.Y. Morales Saiki, T. Kanda
Social group motion in robots
International Conference on Social Robotics, Tsukuba, 2017
- 26 F. Zanlungo and T. Kanda
Do walking pedestrians stably interact inside a large group? Analysis of group and sub-group spatial structure
The annual meeting of cognitive science society, Humbolt University Berlin, 2013
- 27 F. Zanlungo
Evolution of high level recursive thinking in a collision avoiding model
Artificial Life and Evolutionary Computation, Wivace 2008
- 28 F. Zanlungo, A. Bazzani, B. Giorgini, S. Rambaldi, G. Servizi and G. Turchetti
An evolutionary crowd dynamics model
European Conference on Complex Systems 2007, Dresden TU
- 29 F. Zanlungo and T. Arita
Evolutionary Simulation of an Agent Based Mobility System Using Indirect Communication
International Symposium of Artificial Life and Robotics, pp. 319-322, 2006

Other peer-reviewed conference
papers

- 30 E. Repiso, F. Zanlungo, T. Kanda, A. Garrell, A. Sanfeliu
People's V-Formation and Side-by-Side Model Adapted to Accompany Groups of People by Social Robots
2019 International Conference on Intelligent Robots and Systems, Macau, China
- 31 Z. Yücel, F. Zanlungo, T. Kanda
Gender profiling of pedestrian dyads
2019 Traffic and Granular Flow Conference, Pamplona, Spain

- 32 Z. Yücel, F. Zanlungo, C. Feliciani, T. Kanda
Estimating social relation from trajectories
2018 Pedestrian and Evacuation Conference, Lund, Sweden
 - 33 C. Feliciani, F. Zanlungo, K. Nishinari, T. Kanda
Thermodynamics of a gas of pedestrians: theory and experiment
2018 Pedestrian and Evacuation Conference, Lund, Sweden
 - 34 Z. Yücel, F. Zanlungo and M. Shiomi
Walk the talk: Gestures in mobile interaction
International Conference on Social Robotics, Tsukuba, 2017
 - 35 D. Bršćić, F. Zanlungo and T. Kanda
Modelling of Pedestrian groups and application to group recognition
40th International Convention on Information Information and Communication Technology, Electronics and Microelectronics (MIPRO), Opatija, 2017, pp. 564-569
 - 36 K. Kamei, F. Zanlungo, T. Kanda, Y. Horikawa, T. Miyashita and N. Hagita
Cloud networked robotics for social robotic services extending robotic functional service standards to support autonomous mobility system in social environments
n Ubiquitous Robots and Ambient Intelligence (URAI), 2017 14th International Conference on, pp. 897-902. IEEE, 2017
 - 37 M. Shiomi, F. Zanlungo, K. Hayashi and T. Kanda
A Framework with a Pedestrian Simulator for Deploying Robots into a Real Environment
SIMPAN 2012 (acceptance rate 35%)
 - 38 T. Ikeda, Y. Chigodo, D. Rea, F. Zanlungo, M. Shiomi and T. Kanda
Modeling and Prediction of Pedestrian Behavior based on the Sub-goal Concept
Robotics: Science and Systems, Sidney University, 2012 (acceptance rate 33%)
 - 39 Z. Yücel, F. Zanlungo, T. Ikeda, T. Miyashita, N. Hagita
Modeling Indicators of Coherent Motion
IEEE/RSJ IROS, (acceptance rate 39%) 2012
 - 40 M. D. Cooney, F. Zanlungo, S. Nishio, H. Ishiguro
Designing a Flying Humanoid Robot (FHR): Effects of Flight on Interactive Communication
IEEE RO-MAN, 2012
 - 41 A. Bazzani, B. Giorgini, F. Zanlungo and S. Rambaldi
Cognitive Dynamics in an automata gas
Artificial Life and Evolutionary Computation, Wivace 2008
- Other presentations at conferences
- 42 F. Zanlungo, Z. Yücel, F. Ferreri, J. Even, L.Y. Morales Saiki, T. Kanda
Autonomous vehicles moving as a human group
Poster presentation at IROS 2017
 - 43 F. Zanlungo, G. Turchetti
Dynamics and Thermodynamics of Automata with a visual cone. Comparison with a recursive thinking model
Dynamics and Thermodynamics of Systems with Long Range Interactions: Theory and Experiments, 2007

- 44 F. Zanlungo, G. Turchetti
An evolutionary collision avoiding model based on the theory of mind
 The 9th International Conference on the Simulation of adaptive behavior (SAB'06), La Sapienza University, Rome, 2006
- 45 F. Zanlungo, G. Turchetti
Dynamics and thermodynamics of a gas of automata
 III Italian Workshop in Artificial Life (WIVA3), 2006
- 46 G. Turchetti, F. Zanlungo
Termodinamica di un gas di automi (in Italian)
 II Italian Workshop in Artificial Life, 2005, La Sapienza University, Rome
- 47 G. Turchetti, S. Rambaldi, G. Salustri and F. Zanlungo
Mathematical models of clonal expansion
 WSEAS Transactions on Biology and Biomedicine 1, 373-378, 2004

Invited talks

- 48 *Pedestrian group behaviour*
 Alicante University
 Alicante, Spain, 2019
- 49 *Pedestrian group behaviour*
 Polytechnic University of Catalonia
 Barcelona, Spain, 2019
- 50 *Pedestrian group behaviour*
 Symposium on Physics and Psychology of Human Crowd Dynamics
 Leiden, Netherlands, 2018
- 51 *Pedestrian group behaviour*
 Department of Physics of Bologna University
 Bologna, Italy, 2018
- 52 *Pedestrian group behaviour*
 Linnaeus University
 Växjö, Sweden, 2018
- 53 *Pedestrian group behaviour*
 University of Milano Bicocca
 Milan, Italy, 2017
- 54 *Pedestrian group behaviour*
 Tokyo University, Non-linear seminar, Nishinari Laboratory
 Tokyo, Japan, 2016
- 55 *Potential for the dynamics of pedestrians in a socially interacting group*
 Department of Physics of Bologna University
 Bologna, Italy, 2014

- 56 *Potential for the dynamics of pedestrians in a socially interacting group*
Artificial Life Laboratory of Nagoya University (Arita Lab)
Nagoya, Japan, 2014
- 57 *Experimental study and modelisation of pedestrian space occupation and motion pattern in a real world environment*
Department of Physics of Bologna University
Bologna, Italy, 2012
- 58 *Experimental study and modelisation of pedestrian space occupation and motion pattern in a real world environment*
Artificial Life Laboratory of Nagoya University (Arita Lab)
Nagoya, Japan, 2012
- 59 *Social force model with explicit collision prediction*
Artificial Life Laboratory of Nagoya University (Arita Lab)
Nagoya, Japan, 2011
- 60 *Evolution of Behaviours in Artificial Life*
International Summer School: Interfacing Sciences and Humanities
Rimini, Italy, 2009
- 61 *Chaos and Complexity*
International Summer School: Interfacing Sciences and Humanities
Rimini, Italy, 2009
- 62 *Error statistics in perturbed discrete dynamical systems*
Department of Mathematics of Bologna University
Bologna, Italy, 2009
- 63 *Evolutionary techniques in a traffic model*
Nagatani Laboratory of Shizuoka University
Hamamatsu, Japan, 2008

- 64 林宏太郎、塩見昌裕、Francesco ZANLUNGO、神田崇行
歩行者モデルを用いた話しかけやすい移動行動
日本ロボット学会第32回学術講演会講演論文集RJS2014, 3P2-07, 2014
- 65 池田徹志、児堂義弘、Daniel REA、Francesco ZANLUNGO、塩見昌裕、神田崇行
街角における歩行者のサブゴール遷移モデル
日本ロボット学会第31回学術講演会講演論文集RJS2013, 3I2-03, 2013
- 66 塩見昌裕、Francesco ZANLUNGO、林宏太郎、神田崇行
街角で活動する移動ロボットのための歩行者シミュレータ
日本ロボット学会第30回学術講演会講演論文集RJS2012, 2N1-8, 2012
- 67 塩見昌裕、Francesco ZANLUNGO、林宏太郎、神田崇行
歩行者モデルを用いた街角でのロボットナビゲーション
日本ロボット学会第30回学術講演会講演論文集RJS2012, 2N1-8, 2012

Patents

Registered patents

ecvitem1 T. Ikeda, F. Zanlungo, T.
Miyashita and T. Kanda

System for the prediction of pedestrian motion and robot control

(移動予測装置、ロボット制御装置、移動予測プログラムおよび移動予測方法)
Japanese patent 5763384, registered on 19/6/2015

- 2 M. Shiomi, T. Kanda, F. Zanlungo and T. Ikeda
A robot able to predict pedestrian motion and perform automatic collision avoidance
(歩行者の軌跡を予測して自己の回避行動を決定するロボット)
Japanese patent 5768273, registered on 3/7/2015