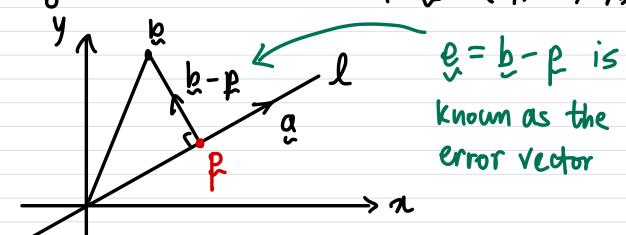
## CSD2250/MAT250 Lecture 10 (Fri 1016)

Topics covered: Projections onto lines and subspaces

In our course, the main motivation for projections is the least squares approximation. Which will be gone through after the recess week.

1) Projection of a vector & onto a line.

Suppose  $b_{i} = (b_{i}, ..., b_{m})$  is a fixed point in  $R^{m}$  and L is a line passing through the origin in the direction of  $a = (a_{i}, ..., a_{m})$ .



We are interested in finding the point p on the line p that is <u>closest</u> to p. To find this point p, we note that the line connecting p and p must be <u>orthogonal</u> to the line p!

The main observation that is key to finding the point p is that if must be parallel to a!

Thus, 
$$p = \frac{1}{2}$$

where  $\hat{\pi}$  is a constant we want to find.

\* Here, we note that the vector &-p is orthogonal to a, hence

$$\alpha^{T}(b-p)=0$$

$$\Rightarrow \alpha^{\mathsf{T}} \left( \dot{b} - \hat{\chi} \alpha \right) = \alpha^{\mathsf{T}} \dot{b} - \hat{\chi} \alpha^{\mathsf{T}} \alpha = 0$$

$$\Rightarrow \chi = \frac{\alpha^{\mathsf{T}} b}{\alpha^{\mathsf{T}} a}.$$

Thus, the point p on the line I that is closest to the point b is

$$b = \frac{a_{\perp} \dot{a}}{\ddot{a}_{\perp} \dot{p}} \ddot{a} .$$

R is called the projection of b outo the line & through a.

Eg. Find the projection of b onto the line through a, where

$$b = \begin{bmatrix} 1 \\ 2 \\ 2 \end{bmatrix} \quad \text{and} \quad a = \begin{bmatrix} 1 \\ 1 \\ 1 \end{bmatrix}.$$

Also check that the error vector  $\mathcal{L} = \mathcal{L} - \mathcal{R}$  is orthogonal to  $\mathcal{Q}$ .

Solution
Solve for 
$$\hat{\lambda} = \frac{\vec{a}^T \vec{b}}{\vec{a}^T \vec{a}} = \frac{1+2+2}{3} = \frac{5}{3}$$

The projection of & on to the line through a is the point

$$\rho = \frac{5}{3} \stackrel{?}{a} = \frac{5}{3} \left[ \begin{array}{c} 1 \\ 1 \\ 1 \end{array} \right].$$

The error yector e is

$$Q = Q - R = \begin{bmatrix} 1 \\ 2 \\ 2 \end{bmatrix} - \frac{S}{3} \begin{bmatrix} 1 \\ 1 \\ 1 \end{bmatrix}$$

$$= \begin{bmatrix} -\frac{2}{3} \\ \frac{4}{3} \\ \frac{1}{3} \end{bmatrix} = \begin{bmatrix} -\frac{2}{3} \\ 1 \\ 1 \end{bmatrix}.$$

Check that 
$$\underline{e}$$
 is orthogonal to  $\underline{a}$ :
$$\underbrace{e^{T}}_{x} \underline{a} = \begin{bmatrix} -\frac{2}{3} & \frac{1}{3} & \frac{1}{3} \end{bmatrix} \begin{bmatrix} 1\\1\\1 \end{bmatrix}$$

$$= -\frac{2}{3} + \frac{1}{3} + \frac{1}{3} = 0.$$

Projection of a vector b onto a subspace let a subspace S be spanned by these vectors  $a_1, \dots, a_n \in \mathbb{R}^m$ .

The assume that these vectors are linearly independent. We want to find a point on'the subspace S where it is closest to a fixed point be ER. Note that when n=1, then it is the projection of b onto the line through an, thus we consider n>1.

Eq. 2

error e=b-p

sis the xy
plane, spanned

by [1] and [1].

We want to find the point p on the subspace S that is closest to p. Since p is on S, then p can be written as a linear combination of  $a_1, \ldots, a_n$ :

$$p = \hat{\lambda}_1 \hat{a}_1 + \dots + \hat{\lambda}_n \hat{a}_n$$

Where  $\hat{\lambda}_1, \dots, \hat{\lambda}_n$  are to be determined.

Now,  $\beta - \beta$  must be orthogonal to the subspace S, and hence must be orthogonal to all of  $\alpha_1, \dots, \alpha_n$ . Hence

$$\widetilde{\alpha}_{1}^{T}(\widetilde{p}-p)=0$$

$$a_n^{\tau}(b-p)=0.$$

If we let A be the matrix whose columns one  $g_1, \dots, g_n$  and  $\hat{\chi} = (\hat{\chi}_1, \dots, \hat{\chi}_n)$ , then the equations above can be written as

$$A^{T}(b-A\lambda)=0$$

$$\Leftrightarrow$$
  $A^TA\hat{\chi} = A^Tb$ .

* ATA is invertible if and only if A	has
linearly independent columns.	
Proof We show that N(ATA) = N(A)	•
To show this, we show two things:	
TIF ZENCATA), then ZEN(A).	
2) If $x \in N(A)$ , then $x \in N(A^TA)$ .	
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(1) Let 
$$\chi \in N(A^TA)$$
. Then  $A^TA\chi = 0$ .

Multiplying this equation by  $\chi^T$  gives

 $\chi^TA^TA\chi = 0$ 

$$\Rightarrow (Ax)^{T}(Ax) = 0 \Rightarrow ||Ax||^{2} = 0$$

$$\Rightarrow ||Ax||^{2} = 0$$

Since the length of  $A\chi$  is 0, then  $A\chi$  must be the zero vector, and hence  $A\chi = 0 \Rightarrow \chi \in N(A)$ .

② Let  $x \in N(A)$ , then Ax = Q. Multiplying this equation by  $A^{T}$  gives  $A^{T}Ax = A^{T}Q = Q$ . Hence  $A^{T}Ax = Q \Rightarrow x \in N(A^{T}A)$ . Therefore, the nullspace of A is the same as the nullspace of  $A^TA$ . Hence, if the columns of A are linearly independent, then the only Solution to Ax = 0 is x = 0 and by the statement above, the only solution to  $A^TAx = 0$  is x = 0. Since  $A^TA$  is square, it must mean that  $A^TA$  is invertible!

\*Previously, we assumed that

 $\alpha_1, \ldots, \alpha_n$ 

are linearly independent. Hence the columns of A are linearly independent, and thus, ATA is invertible. We can then solve for  $\hat{x}$ :

$$\lambda = (A^T A)^T A^T b,$$

and the point p on the subspace S that is closest to b is

 $P = A (A^T A)^{-1} A^T b.$ 

\*Note that  $(A^TA)^{-1} \neq A^{-1}(A^T)^{-1}$  because A is not necessarily a square matrix!

E.g Let S be the subspace spanned by the vectors

$$a_1 = \begin{bmatrix} 1 \\ 1 \end{bmatrix}$$
 and  $a_2 = \begin{bmatrix} 0 \\ 1 \end{bmatrix}$ .

Find the shortest distance from the point  $b = \begin{bmatrix} 6 \\ 0 \end{bmatrix}$  to S.

## Solution

(1) Check that the columns of A are linearly independent, where

$$A = \begin{bmatrix} 1 & 1 & 0 \\ a_1 & a_2 \\ \vdots & \ddots & 1 \end{bmatrix} = \begin{bmatrix} 1 & 0 \\ 1 & 1 \\ 1 & 2 \end{bmatrix}.$$

- = 2 = no. of columns, hence the columns of A are linearly independent.
- (2) Find the projection p of p onto S. We can find  $\hat{x}$  by either computing  $(A^TA)^{-1}$  or Solving  $A^TA\hat{x} = A^Tb$ . We do the latter.

$$A^{T}A = \begin{bmatrix} 3 & 3 \\ 3 & 5 \end{bmatrix}$$

$$\begin{bmatrix} 3 & 3 \\ 3 & 5 \end{bmatrix} \begin{bmatrix} \hat{\chi_1} \\ \hat{\chi_1} \end{bmatrix} = \begin{bmatrix} 1 & 1 & 1 \\ 0 & 1 & 2 \end{bmatrix} \begin{bmatrix} 6 \\ 0 \\ 0 \end{bmatrix}$$

$$A^T A$$

$$\Rightarrow \begin{bmatrix} 3 & 3 \\ 3 & 5 \end{bmatrix} \begin{bmatrix} \hat{\chi}_1 \\ \hat{\chi}_2 \end{bmatrix} = \begin{bmatrix} 6 \\ 0 \end{bmatrix}$$

$$\begin{array}{c} R_{2} \cdot R_{1} \\ \Rightarrow \\ 0 \quad 2 \end{array} \begin{bmatrix} \hat{\chi}_{1} \\ \hat{\chi}_{2} \end{bmatrix} = \begin{bmatrix} 6 \\ -6 \end{bmatrix}$$

$$\Rightarrow \hat{\chi}_2 = -3, \hat{\chi}_1 = 5$$

$$\dot{x} = \begin{bmatrix} 5 \\ -3 \end{bmatrix}$$

The projection 
$$p = A\hat{x} = 5\begin{bmatrix} 1\\1 \end{bmatrix} - 3\begin{bmatrix} 0\\2 \end{bmatrix}$$

$$= \begin{bmatrix} 5 \\ 2 \\ -1 \end{bmatrix}.$$

(3) The shortest distance from & to the subspace S is the distance betw & and &.

$$\|g\| = \|g - g\| = \sqrt{1^2 + (-1)^2 + 1^2} = \sqrt{6}$$

## Exercises

$$\alpha = \begin{bmatrix} -1 \\ -3 \end{bmatrix}$$
. Check that  $\alpha$  is orthogonal to  $\alpha$ .

(2) Project b onto the columns pace of A by Solving 
$$A^T A \hat{x} = A^T b$$
 and  $p = A \hat{x}$ :

(a) 
$$A = \begin{bmatrix} 1 & 1 \\ 0 & 1 \\ 0 & 0 \end{bmatrix}$$
,  $b = \begin{bmatrix} 2 \\ 3 \\ 4 \end{bmatrix}$ ,

(b) 
$$A = \begin{bmatrix} 1 & 1 & 1 \\ 1 & 1 & 1 \\ 0 & 1 \end{bmatrix}, b = \begin{bmatrix} 4 \\ 4 \\ 6 \end{bmatrix}$$

Check that e=b-p is orthogonal to a.