

Topics covered: • Vect

- Subspaces of a Vector space
 - Column space $C(A)$

Vector spaces

let's recall the set of real numbers \mathbb{R} .

Common numbers in \mathbb{R} include

$$2, -30, \frac{1}{2}, -\frac{3}{4}, \sqrt{2}, \pi.$$

1
natural
numbers

whole numbers

↑ integers

1

(fractions)

(fractions)

is 12 13 14

Irrational numbers
(numbers which cannot
be expressed as a
fraction)

We already know about vector addition and scalar multiplication. These two operations are key to a vector space: they define what operations can be done within the space itself.

The vector addition is denoted by a ' $+$ ' sign, and scalar multiplication a ' \cdot ' (sometimes the dot is omitted).

With the vector addition and scalar multiplication defined, there are

* eight core properties of a vector space V :

For $\underline{x}, \underline{y}, \underline{z} \in V$ and c_1, c_2 constants:

$$\textcircled{1} \quad \underline{x} + \underline{y} = \underline{y} + \underline{x}$$

$$\textcircled{2} \quad \underline{x} + (\underline{y} + \underline{z}) = (\underline{x} + \underline{y}) + \underline{z}$$

* $\textcircled{3}$ There is a unique zero vector $\underline{0}$ such that
 $\underline{0} + \underline{x} = \underline{x}$ for every $\underline{x} \in V$.

* $\textcircled{4}$ For every $\underline{x} \in V$, there is a $-\underline{x}$ such that

$$\underline{x} + (-\underline{x}) = \underline{0}$$

$$\textcircled{5} \quad 1 \cdot \underline{x} = \underline{x} \text{ for all } \underline{x} \in V$$

$$\textcircled{6} \quad (c_1 c_2) \cdot \underline{x} = c_1 (c_2 \underline{x})$$

$$\textcircled{7} \quad c_1 (\underline{x} + \underline{y}) = c_1 \underline{x} + c_1 \underline{y}$$

$$\textcircled{8} \quad (c_1 + c_2) \underline{x} = c_1 \underline{x} + c_2 \underline{x}$$

★ Another two properties of a vector space V are:
(These are the key properties of a subspace too)

① If you add any two vectors $\underline{x}, \underline{y}$ in V
the resulting $\underline{x} + \underline{y}$ is also in V .

② If you multiply a vector \underline{x} in V by
any scalar c , the resulting $c\underline{x}$ is also in V .

Examples of vector spaces

① \mathbb{R}^k , where $k = 1, 2, 3, \dots$

Note that \mathbb{R} is
also a vector space:
numbers can be
viewed as vectors
with one component.

they represent the usual vectors

$$(\underline{x}_1, \underline{x}_2, \dots, \underline{x}_k)$$

Each of these
components are real
numbers.

that we deal with.

Vector addition is defined as

$$\begin{aligned} & (\underline{x}_1, \underline{x}_2, \dots, \underline{x}_k) + (\underline{x}'_1, \underline{x}'_2, \dots, \underline{x}'_k) \\ &= (\underline{x}_1 + \underline{x}'_1, \underline{x}_2 + \underline{x}'_2, \dots, \underline{x}_k + \underline{x}'_k) \end{aligned}$$

Scalar multiplication is defined as

$$c(\underline{x}_1, \dots, \underline{x}_k) = (c\underline{x}_1, c\underline{x}_2, \dots, c\underline{x}_k).$$

② $M_2(\mathbb{R})$ the space containing the 2×2 matrices with real entries

$$\begin{bmatrix} a & b \\ c & d \end{bmatrix} \quad a, b, c, d \in \mathbb{R}$$

Vector addition

$$\begin{bmatrix} a_1 & b_1 \\ c_1 & d_1 \end{bmatrix} + \begin{bmatrix} a_2 & b_2 \\ c_2 & d_2 \end{bmatrix} = \begin{bmatrix} a_1 + a_2 & b_1 + b_2 \\ c_1 + c_2 & d_1 + d_2 \end{bmatrix}$$

Scalar multiplication

$$\alpha \begin{bmatrix} a & b \\ c & d \end{bmatrix} = \begin{bmatrix} \alpha a & \alpha b \\ \alpha c & \alpha d \end{bmatrix}$$

③ The space containing only the zero vector, i.e.

$$\underbrace{\{(0, 0, \dots, 0)\}}_{k \text{ zeroes}}$$

Vector addition and scalar multiplication defined in the same way as the first example.

* This is the smallest vector space.

* Subspaces

Let's say we work within the confines of a vector space V , where vector addition and scalar multiplication have already been defined, and the 8 core properties (pg 2) hold, and most importantly, the vectors resulting from adding two vectors or scaling a vector stays within V .

Qn Since a vector space is large, is it possible that these properties hold for a 'smaller part' of the vector space?

subset of V

The answer is yes. For any subset of a vector space V , vector addition and scalar multiplication are the same. However, when we add two vectors within the subset or scale a vector in the subset, the resulting vector may not be in that subset!

Example

Let $V = \mathbb{R}^2$, and let S be the subset of V such that the 2 vector components are non negative, i.e.

S consists of (x_1, x_2) where $x_1, x_2 \geq 0$.

Then for example, $(1, 1) \in S$ but scaling it by a negative number, e.g. $-\frac{1}{2}$

$$-\frac{1}{2}(1, 1) = \left(-\frac{1}{2}, -\frac{1}{2}\right) \notin S$$

results in a vector that is not in S !

Thus, vector space operations cannot be performed 'within' S , unless we are okay with objects ending up outside of the vector space we are working with, which is unheard of.

* We seek to look for subsets of V with such properties. These are what we call subspaces of V . It is like a 'localized' vector space.

★ A subset S of V is called a subspace of V if these three conditions are satisfied:

- ① The zero vector $\underline{0} \in S$.
- ② For any $\underline{v}, \underline{w} \in S$, $\underline{v} + \underline{w} \in S$.
- ③ For any scalar c , and any $\underline{v} \in S$, $c\underline{v} \in S$.

E.g.

(a) For $V = \mathbb{R}^2$, let S be the subset where (x_1, x_2) satisfies $x_2 = 2x_1$.

① $(0,0) \in S$ because $0 = 2 \cdot 0$

② Let (x'_1, x'_2) and $(x''_1, x''_2) \in S$, then

$$x'_2 = 2x'_1 \text{ and } x''_2 = 2x''_1$$

$$\begin{aligned}\Rightarrow x'_2 + x''_2 &= 2x'_1 + 2x''_1 \\ &= 2(x'_1 + x''_1)\end{aligned}$$

$$\Rightarrow (x'_1 + x''_1, x'_2 + x''_2) \in S$$

③ Let c be a scalar, and $(x_1, x_2) \in S$.

Then $c(x_1, x_2) = (cx_1, cx_2)$.

Note that $c \underbrace{x_2}_{\substack{= c \cdot \underbrace{2x_1}_{\uparrow} = 2(cx_1)}} = 2(cx_1)$
because $(x_1, x_2) \in S$

So $(cx_1, cx_2) \in S$.

Thus S is a subspace of $V = \mathbb{R}^2$.

(b) For $V = M_2(\mathbb{R})$, let S be the subset

where

$\begin{bmatrix} a & b \\ c & d \end{bmatrix}$ satisfies $b = c = 0$.

(i.e. S is the subset of diagonal matrices)

(a) $\begin{bmatrix} 0 & 0 \\ 0 & 0 \end{bmatrix} \in S$ (obvious) ✓

(b) $\begin{bmatrix} a' & 0 \\ 0 & d' \end{bmatrix} + \begin{bmatrix} a'' & 0 \\ 0 & d'' \end{bmatrix}$

$$= \begin{bmatrix} a' + a'' & 0 \\ 0 & d' + d'' \end{bmatrix} \quad \checkmark$$

$$(C) \quad c \begin{bmatrix} a & 0 \\ 0 & d \end{bmatrix} = \begin{bmatrix} ca & 0 \\ 0 & cd \end{bmatrix} \quad \checkmark$$

Therefore S is a subspace of $V = M_2(\mathbb{R})$.

Exercises

① Let $V = \mathbb{R}^3$. Let S be the subset of V where (x_1, x_2, x_3) satisfies $x_1 + 2x_2 - 5x_3 = 0$.

Show that S is a subspace of V .

② Let $V = M_2(\mathbb{R})$. Let S be the subset of V where $\begin{bmatrix} a & b \\ c & d \end{bmatrix}$ satisfies $c = 0$.

Show that S is a subspace of V .

③ Let S be a subspace of a vector space V . Show that for any $\underline{v}, \underline{w} \in S$, and a, b scalars, $a\underline{v} + b\underline{w} \in S$.

T

linear combination of \underline{v} and \underline{w} .

④ For the following subsets of \mathbb{R}^3 , determine if they are subspaces of \mathbb{R}^3 or not. Give an example like in page 6 if it is not a subspace of \mathbb{R}^3 .

1. The set of (x_1, x_2, x_3) where $x_2 = 2$.

2. The set of (x_1, x_2, x_3) where $x_1 x_2 x_3 = 0$.

*3. The set of (x_1, x_2, x_3) where $x_1 \geq x_2 \geq x_3$.

*4. The set of (x_1, x_2, x_3) where $5x_1^2 - 3x_2^2 + 6x_3^2 = 0$.

⑤ Replicate the same exercises as in ④

for these subsets of $M_2(\mathbb{R})$.

1. The set of $\begin{bmatrix} a & b \\ c & d \end{bmatrix}$ where $ad - bc \neq 0$.

2. The set of $\begin{bmatrix} a & b \\ c & d \end{bmatrix}$ where $b = c$.

3. The set of 2 by 2 elimination matrices.

Column space of a $m \times n$ matrix A , $C(A)$

let A be a $m \times n$ matrix. Recall the matrix equation

$$A \underline{x} = \underline{b}.$$

* We say that this equation/system is solvable if there is a solution to this equation/system.

If A is invertible (this also means $m=n$), then this system is solvable for every \underline{b} .

Otherwise, there are some \underline{b} for which this system is not solvable.

$$A \underline{x} = \underline{b} \text{ solvable}$$

Qn How to find out which \underline{b} works?

The answer lies in the column form of $A \underline{x}$.

let $\underline{a}_1, \underline{a}_2, \dots, \underline{a}_n$ be the columns of A ,

then

$$A \underline{x} = x_1 \underline{a}_1 + x_2 \underline{a}_2 + \dots + x_n \underline{a}_n.$$

Here, $\underline{x} = \begin{bmatrix} x_1 \\ x_2 \\ \vdots \\ x_n \end{bmatrix}$ is a $n \times 1$ matrix,
* $x_1, x_2, \dots, x_n \in \mathbb{R}$.

Each of the columns of A are $m \times 1$ matrices.
We can also treat them as m -dimensional
vectors, i.e.

$$\underline{a}_1, \underline{a}_2, \dots, \underline{a}_n \in \mathbb{R}^m \quad \begin{matrix} \text{very easy} \\ \text{to confuse} \\ \text{with } n! \end{matrix}$$

as each \underline{a}_i has m entries!

* A linear combination of vectors $\underline{v}_1, \underline{v}_2, \dots, \underline{v}_n$
is the form

$$c_1 \underline{v}_1 + c_2 \underline{v}_2 + \dots + c_n \underline{v}_n$$

where c_1, c_2, \dots, c_n are arbitrary constants
in \mathbb{R} .

Therefore, $A \underline{x} = \underline{b}$ is solvable if \underline{b} is
a linear combination of the columns of A :

$$\underline{b} = x_1 \underline{a}_1 + \dots + x_n \underline{a}_n.$$

From here, we define the column space of A ,
based on these linear combinations.

* The column space of a $m \times n$ matrix A is the subspace of \mathbb{R}^m which contains all linear combinations of the columns of A , i.e.

$$x_1 \underline{a}_1 + x_2 \underline{a}_2 + \dots + x_n \underline{a}_n$$

where x_1, x_2, \dots, x_n are any real numbers.

The column space is denoted as $C(A)$.

Here, we say that the subspace $C(A)$ is spanned by the columns of A .

Eg.

$$(a) A = \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix}$$

$$\underline{a}_1 = \begin{bmatrix} 1 \\ 0 \end{bmatrix} \text{ and } \underline{a}_2 = \begin{bmatrix} 0 \\ 1 \end{bmatrix} \quad m=2$$

take all linear combinations of,

Note A is invertible

$C(A)$ contains

$$x_1 \begin{bmatrix} 1 \\ 0 \end{bmatrix} + x_2 \begin{bmatrix} 0 \\ 1 \end{bmatrix} \text{ for every } x_1 \text{ and } x_2.$$

$$= \begin{bmatrix} x_1 \\ x_2 \end{bmatrix} \text{ for every } x_1, x_2$$

$$\Rightarrow C(A) = \mathbb{R}^2. \quad \text{whole space } \mathbb{R}^m$$

$$(b) A = \begin{bmatrix} 1 & 2 \\ 2 & 4 \end{bmatrix}$$

$C(A)$ contains

$$x_1 \begin{bmatrix} 1 \\ 2 \end{bmatrix} + x_2 \begin{bmatrix} 2 \\ 4 \end{bmatrix} \text{ for all } x_1, x_2 \in \mathbb{R}$$

$$= x_1 \begin{bmatrix} 1 \\ 2 \end{bmatrix} + 2x_2 \begin{bmatrix} 1 \\ 2 \end{bmatrix}$$

$$= x_1 + 2x_2 \begin{bmatrix} 1 \\ 2 \end{bmatrix}$$

$$= c \begin{bmatrix} 1 \\ 2 \end{bmatrix} \quad \text{since } x_1 \text{ and } x_2 \text{ are arbitrary numbers, replace } x_1 + 2x_2 \text{ as another arbitrary number } c.$$

kind of like
in integration
Constants

$\Rightarrow C(A)$ consists of vectors that obey

$$\begin{bmatrix} x \\ y \end{bmatrix} = \begin{bmatrix} c \\ 2c \end{bmatrix} \Rightarrow \begin{array}{l} x=c \\ y=2c \end{array} \Rightarrow y=2x$$

$\Rightarrow C(A)$ consists of all points on the line $y=2x$.

\downarrow Note $C(A)$ is not the whole space \mathbb{R}^2 .

$$(C) \quad A = \begin{bmatrix} 1 & 0 \\ 0 & 0 \\ 0 & 3 \end{bmatrix} \quad m=3 \quad n=2$$

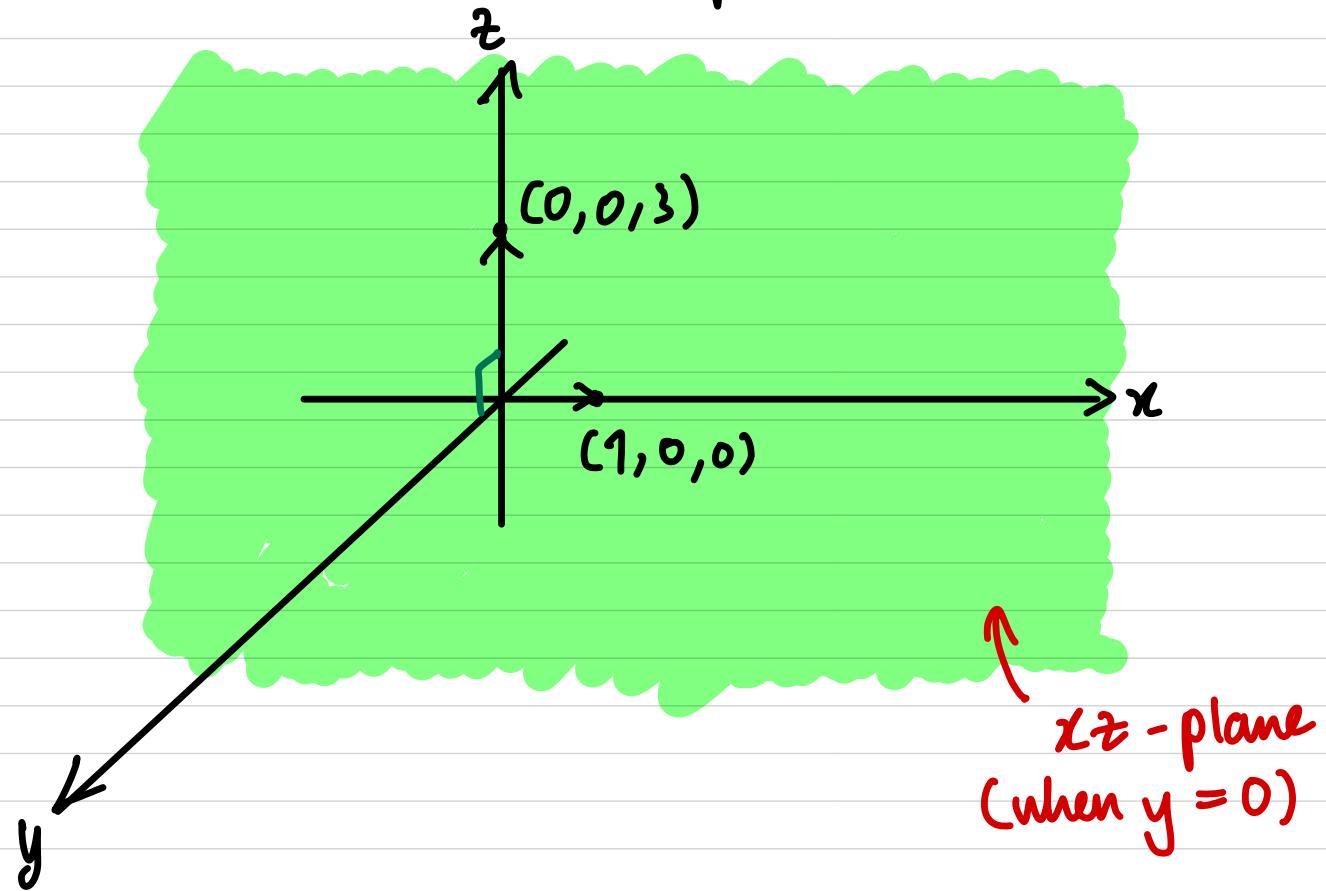
$C(A)$ contains

$$x_1 \begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix} + x_2 \begin{bmatrix} 0 \\ 0 \\ 3 \end{bmatrix} = \begin{bmatrix} x_1 \\ 0 \\ 3x_2 \end{bmatrix} = \begin{bmatrix} x_1 \\ 0 \\ x'_2 \end{bmatrix}$$

$$x'_2 = 3x_2$$

since x_2 is arbitrary

$\Rightarrow C(A)$ is the xz -plane



Note that $m > n$, so $C(A)$ can never be \mathbb{R}^3 !

You need at least three columns for $C(A)$ to be \mathbb{R}^3 .

(↳ we will see later in bases and linear independence.)

Exercises

① Describe $C(A)$ where

$$(a) A = \begin{bmatrix} 1 & 0 \\ 2 & 0 \\ 0 & 0 \end{bmatrix}. \quad (b) A = \begin{bmatrix} 1 & 0 \\ 0 & 3 \\ 1 & 0 \end{bmatrix}.$$

② What is the column space of a 7×7 invertible matrix A ?

③ Find 5 different vectors in $C(A)$ for

① (b).