

CSD2250/MAT250 Lecture 3 (Wed 18/5)

Topics covered:

- Matrix operations and rules
- Inverse of a matrix
- Transpose of a matrix

Matrix operations and rules

Let A be a $m \times n$ matrix.

rows columns

Recall: A can be added to another $m \times n$ matrix B by adding their entries "component-wise":

$$\text{Eg. } \begin{bmatrix} 1 & 2 & 3 \\ 4 & 5 & 6 \end{bmatrix} + \begin{bmatrix} 7 & 8 & 9 \\ 10 & 11 & 12 \end{bmatrix} = \begin{bmatrix} 8 & 10 & 12 \\ 14 & 16 & 18 \end{bmatrix}.$$

A can also be multiplied by a constant c by multiplying each entry by c :

$$\text{Eg. } 7 \begin{bmatrix} 1 & 2 & 3 \\ 4 & 5 & 6 \end{bmatrix} = \begin{bmatrix} 7 & 14 & 21 \\ 28 & 35 & 42 \end{bmatrix}.$$

What about matrix multiplication?

Let A be an $m \times n$ matrix, and B be a $p \times q$ matrix.

* Important test:

- $A \cdot B$ is valid if A has the same number of columns as the number of rows of B , i.e. $n = p$.
- Similarly, $B \cdot A$ is valid if B has the same number of columns as the number of rows of A , i.e. $q = m$.

$$(m \times n)(\overbrace{n \times q}^{\uparrow \text{if } p=n}) = (m \times q)$$

if $p = n$

\leftarrow AB is an $m \times q$ matrix.
Likewise, BA is a $p \times n$ matrix (if $q = m$)

Observation: We can see that AB may have a different size from BA .

* How to multiply two matrices A and B?

① First, check if the sizes of A and B match (see previous page).

② Every entry of AB , which can be described as $(AB)_{ij}$, can be computed in the following fashion:

↑
row i , column j entry
of the matrix AB

fashion:

$$(AB)_{ij} = (\text{row } i \text{ of } A) \cdot (\text{column } j \text{ of } B)$$

dot product

↑
has the same no.
of entries corresponding
to the no. of
columns of A

↑
has the same no.
of entries corresponding
to the no. of
rows of B.

↓
must be the same for dot
product to work!

Exercise

1. Let

$$A = \begin{bmatrix} 2 & 4 & 5 \\ -1 & 2 & -3 \end{bmatrix} \text{ and } B = \begin{bmatrix} 5 & -3 & 6 \\ 6 & 1 & -2 \\ 2 & 4 & -5 \end{bmatrix}$$

(a) Express $(AB)_{23}$ in terms of the dot product of a row of A and a column of B .

(b) Calculate AB and BA . If either of these multiplications are not possible, explain why.

Laws for matrix multiplication

In this part, and in each case, we assume that the matrices A , B and C are of suitable sizes for either addition or multiplication.

Also, let α be a constant.

Addition laws

$$(1) A + B = B + A \text{ (commutative law)}$$

$$(2) \alpha(A + B) = \alpha A + \alpha B \text{ (distributive law)}$$

$$(3) A + (B + C) = (A + B) + C \text{ (associative law)}$$

Multiplication laws

$$(1) C(A + B) = CA + CB \text{ (left distributive law)}$$

$$(2) (A + B)C = AC + BC \text{ (right distributive law)}$$

$$(3) (AB)C = A(BC) \text{ (associative law)}$$

***NOTE:** AB is usually NOT equal to BA , i.e. the commutative law for multiplication is broken.

Inverse matrix

Let A be a $n \times n$ matrix (we refer to this matrix as a square matrix of size n). We search for a matrix A^{-1} of the same size as A so that A^{-1} multiplied by A (either way AA^{-1} or $A^{-1}A$) equals I_n .

If such a matrix exists (it doesn't always exist), then solving $A\underline{x} = \underline{b}$ becomes trivial:

⇒ Multiply A^{-1} to both sides of $A\underline{x} = \underline{b}$ gives

$$A^{-1}A\underline{x} = A^{-1}\underline{b} \Rightarrow \underline{x} = A^{-1}\underline{b},$$

i.e. we have essentially solved the system $A\underline{x} = \underline{b}$.

We introduce some important notes on the inverse A^{-1} , before delving into the method of finding A^{-1} (if such a matrix exists).

~~✖~~ A square matrix A is invertible if there exists a matrix A^{-1} such that

$$A^{-1}A = I_n \quad \text{and} \quad AA^{-1} = I_n$$

Notes on A^{-1}

① A^{-1} exists if and only if elimination produces n pivots (note that pivots must be nonzero).

↑ equal to the size of A .

② If A^{-1} exists, then it must be unique.

* ③ The system $A\underline{x} = \underline{0}$ has at least one solution: $\underline{x} = \underline{0}$ is a solution. If $\underline{x} = \underline{0}$ is not the only solution to $A\underline{x} = \underline{0}$, then A is not invertible.

Why? Suppose $\underline{x}' \neq \underline{0}$ is a solution to $A\underline{x} = \underline{0}$, then $A\underline{x}' = \underline{0}$. If A^{-1} exists then multiply to this equation:

$$A^{-1} A \underline{x}' = A^{-1} \underline{0} = \underline{0} \Rightarrow \underline{x}' = \underline{0}.$$

any matrix multiplied by $\underline{0}$ must be $\underline{0}$

But this contradicts $\underline{x}' \neq \underline{0}$, so A^{-1} cannot exist.

We will see this later in the nullspace of A .

* ④ The inverse of a 2×2 matrix

$$\begin{bmatrix} a & b \\ c & d \end{bmatrix}$$

is $\frac{1}{ad-bc} \begin{bmatrix} d & -b \\ -c & a \end{bmatrix}$ provided $ad-bc \neq 0$.

Here, $ad-bc$ is the determinant of the matrix $\begin{bmatrix} a & b \\ c & d \end{bmatrix}$.

Important: Since A^{-1} is rather tedious to find, it is often enough to show that A^{-1} exists through ①, ③ and ④. In ④, as we will see later, A^{-1} exists if and only if the determinant of A is non zero.

*Product of invertible matrices

Let A and B be invertible matrices of size n . Then AB is also invertible.

The inverse of AB is

$$(AB)^{-1} = B^{-1}A^{-1}.$$

✓ The shoe-and-sock principle.

We recall that matrices perform actions on other matrices/vectors. As a way to remember this, we can think of

A = "putting on shoes" and

B = "putting on socks"

then logically

A^{-1} = "taking off shoes" and

B^{-1} = "taking off socks".

AB here means that we put on socks first, followed by our shoes. (Matrices are "read" from right to left), so naturally to reverse this, we perform $B^{-1}A^{-1}$, taking off our shoes, then our socks.

Exercises

What is the inverse of

(a) $\begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & -5 & 1 \end{bmatrix}?$

(b) $\begin{bmatrix} 0 & 1 & 0 \\ 1 & 0 & 0 \\ 0 & 0 & 1 \end{bmatrix}?$

(c) $\begin{bmatrix} 0 & 0 & 1 \\ 1 & 0 & 0 \\ 0 & 1 & 0 \end{bmatrix}?$

(Slightly harder)

Hint: What actions do these matrices perform?

*Calculating A^{-1} using Gauss-Jordan

Gauss-Jordan algorithm is technically the elimination + back-substitution algorithm we have learnt last week. We now show how it can be used to compute A^{-1} , using an example we are familiar with:

$$\text{Let } A = \begin{bmatrix} 2 & 4 & -2 \\ 4 & 9 & -3 \\ -2 & -3 & 7 \end{bmatrix}$$

Place A and I_3 into a matrix, side by side:

$$\begin{array}{c} A \\ \left[\begin{array}{ccc|ccc} 2 & 4 & -2 & 1 & 0 & 0 \\ 4 & 9 & -3 & 0 & 1 & 0 \\ -2 & -3 & 7 & 0 & 0 & 1 \end{array} \right] \\ I_3 \end{array}$$

Perform Gauss-Jordan on this matrix until I_3 appears on the left side of this matrix. Then the matrix of the right side becomes A^{-1} .

Demonstration to find A^{-1} using Gauss-Jordan

$$\begin{bmatrix} 2 & 4 & -2 & 1 & 0 & 0 \\ 4 & 9 & -3 & 0 & 1 & 0 \\ -2 & -3 & 7 & 0 & 0 & 1 \end{bmatrix}$$

↓ Eqn 2 - 2 x Eqn 1

$$\begin{bmatrix} 2 & 4 & -2 & 1 & 0 & 0 \\ 0 & 1 & 1 & -2 & 1 & 0 \\ -2 & -3 & 7 & 0 & 0 & 1 \end{bmatrix}$$

↓ Eqn 3 + Eqn 1

$$\begin{bmatrix} 2 & 4 & -2 & 1 & 0 & 0 \\ 0 & 1 & 1 & -2 & 1 & 0 \\ 0 & 1 & 5 & 1 & 0 & 1 \end{bmatrix}$$

↓ Eqn 3 - Eqn 2

$$\begin{bmatrix} 2 & 4 & -2 & 1 & 0 & 0 \\ 0 & 1 & 1 & -2 & 1 & 0 \\ 0 & 0 & 4 & 3 & -1 & 1 \end{bmatrix}$$

↓ $\frac{1}{4}$ x Eqn 3

$$\begin{bmatrix} 2 & 4 & -2 & 1 & 0 & 0 \\ 0 & 1 & 1 & -2 & 1 & 0 \\ 0 & 0 & 1 & \frac{3}{4} & -\frac{1}{4} & \frac{1}{4} \end{bmatrix}$$

↓ Eqn 2 - Eqn 1

$$\begin{bmatrix} 2 & 4 & -2 & 1 & 0 & 0 \\ 0 & 1 & 0 & -\frac{11}{4} & \frac{5}{4} & -\frac{1}{4} \\ 0 & 0 & 1 & \frac{3}{4} & -\frac{1}{4} & \frac{1}{4} \end{bmatrix}$$

↓ $\frac{1}{2} \times \text{Eqn 1}$

$$\begin{bmatrix} 1 & 2 & -1 & \frac{1}{2} & 0 & 0 \\ 0 & 1 & 0 & -\frac{11}{4} & \frac{5}{4} & -\frac{1}{4} \\ 0 & 0 & 1 & \frac{3}{4} & -\frac{1}{4} & \frac{1}{4} \end{bmatrix}$$

↓ Eqn 1 + Eqn 3

$$\begin{bmatrix} 1 & 2 & 0 & \frac{5}{4} & -\frac{1}{4} & \frac{1}{4} \\ 0 & 1 & 0 & -\frac{11}{4} & \frac{5}{4} & -\frac{1}{4} \\ 0 & 0 & 1 & \frac{3}{4} & -\frac{1}{4} & \frac{1}{4} \end{bmatrix}$$

↓ Eqn 1 - 2 × Eqn 2

$$\begin{bmatrix} 1 & 0 & 0 & \frac{27}{4} & -\frac{11}{4} & \frac{3}{4} \\ 0 & 1 & 0 & -\frac{11}{4} & \frac{5}{4} & -\frac{1}{4} \\ 0 & 0 & 1 & \frac{3}{4} & -\frac{1}{4} & \frac{1}{4} \end{bmatrix}$$

I_3 , so algorithm stops

this is A^{-1} !

Exercises

Use the Gauss-Jordan algorithm to find the inverses of the following matrices:

$$(a) \begin{bmatrix} 2 & -1 & 0 \\ -1 & 2 & -1 \\ 0 & -1 & 2 \end{bmatrix}$$

$$(b) \begin{bmatrix} 1 & 0 & 0 \\ 2 & 1 & 3 \\ 0 & 0 & 1 \end{bmatrix}$$

Transpose of a matrix

We cover another useful matrix, the transpose of another matrix A , which is denoted by A^T . \leftarrow stands for transpose

Simply put, the rows and columns of A are the columns and rows of A^T respectively.

E.g. $A = \begin{bmatrix} 1 & 2 & 3 \\ 0 & 0 & 4 \end{bmatrix} \Rightarrow A^T = \begin{bmatrix} 1 & 0 \\ 2 & 0 \\ 3 & 4 \end{bmatrix}$

Important rules for transpose

① $(A+B)^T = A^T + B^T$

② $(A \cdot B)^T = B^T A^T$ (swapped, like inverse)

③ $(A^{-1})^T = (A^T)^{-1}$

\uparrow The transpose of the inverse of A is exactly the inverse of the transpose of A .

Exercises

① Let

$$\underline{x} = \begin{bmatrix} 1 \\ 2 \\ 3 \end{bmatrix} \quad \text{and} \quad y = \begin{bmatrix} 4 \\ 5 \\ 6 \end{bmatrix}.$$

Compute

(a) $\underline{x}^T y$, and

(b) $\underline{x} y^T$.

For (a), what does this remind you of?

② Let A be an $m \times n$ matrix of your choosing. Compute

(a) $A^T A$, and

(b) AA^T .

What are the sizes of $A^T A$ and AA^T ?

What other characteristics of $A^T A$ and AA^T do you observe?