Notes in ECEN 5448

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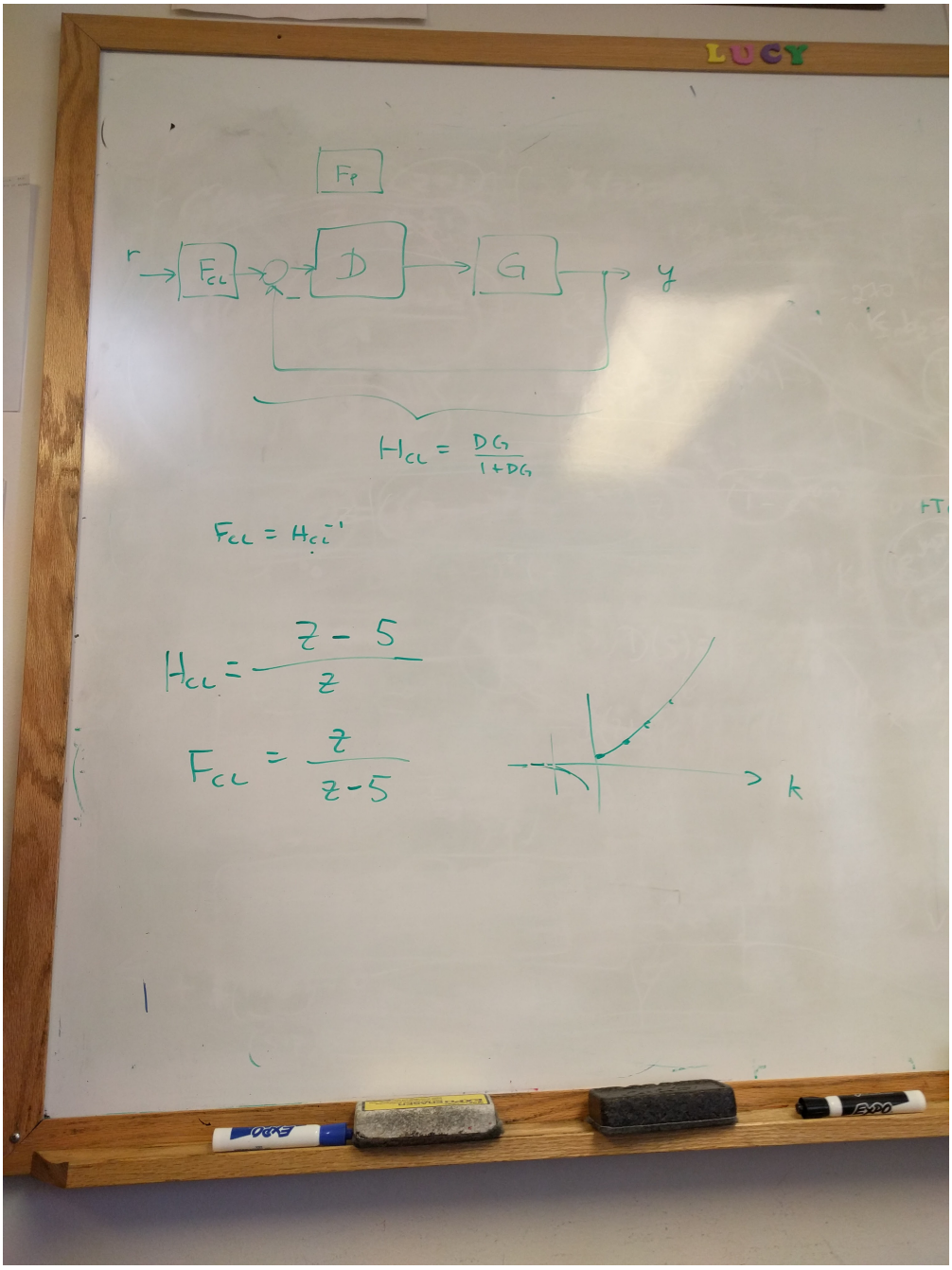
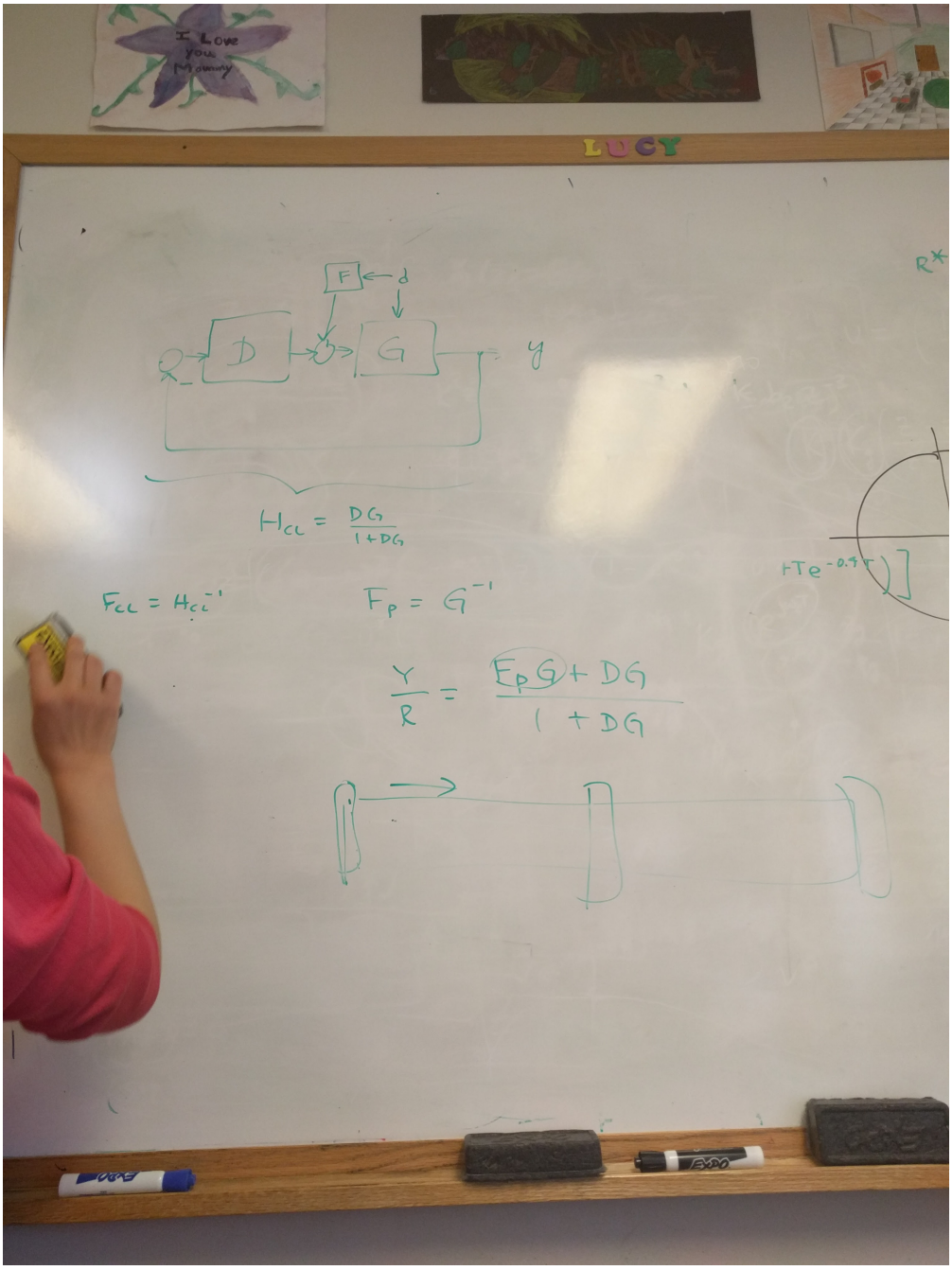
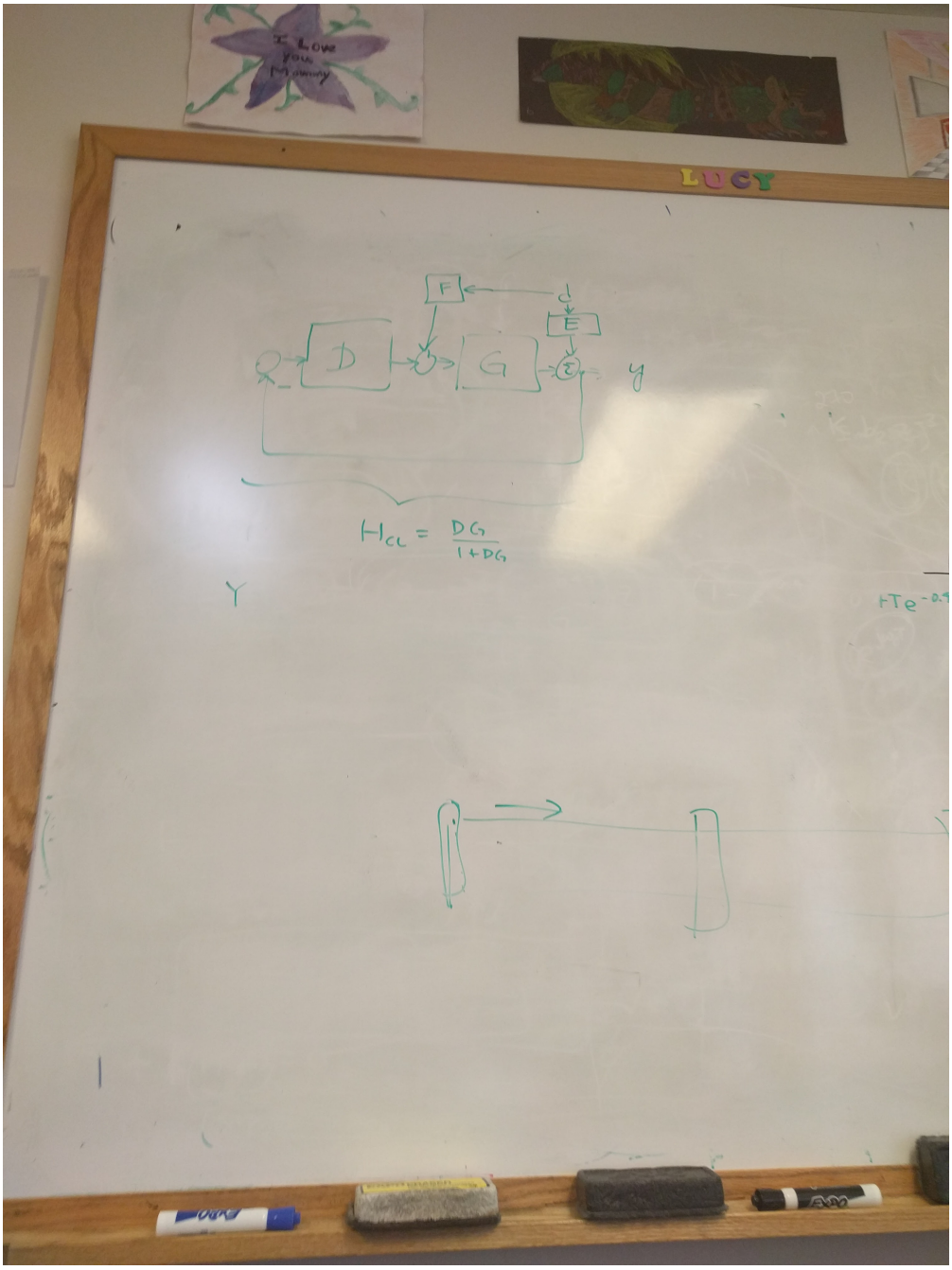
What do we want

- analyze modes to determine rise time, **settle time**
- Analyze how sampling frequency effects performance
- figure out feedword control.
- F_{CL} inverse of closed loop. Can be acausal because you know input.
- this is genrally for reference tracking.
- assume there aren't any dynamics between teh measured and actuation.
- can use matlabs tools, but analyze why matlabs tools work.
- Then figure out how much better we can do with feedforward.


LUCY
F_p
r
F_{cl}
D
G
y
$H_{cl} = \frac{DG}{1+DG}$
$F_{cl} = H_{cl}^{-1}$
$H_{cl} = \frac{z-5}{z}$
$F_{cl} = \frac{z}{z-5}$
k


I Love you Mommy
LUCY
F
d
D
G
y
R*
$H_{cl} = \frac{DG}{1+DG}$
$F_{cl} = H_{cl}^{-1}$
$F_p = G^{-1}$
$\frac{Y}{R} = \frac{F_p G + DG}{1 + DG}$
$Te^{-0.9T}$


I love you Mommy
LUCY
F
E
D
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y
$H_{cl} = \frac{DG}{1+DG}$
Y