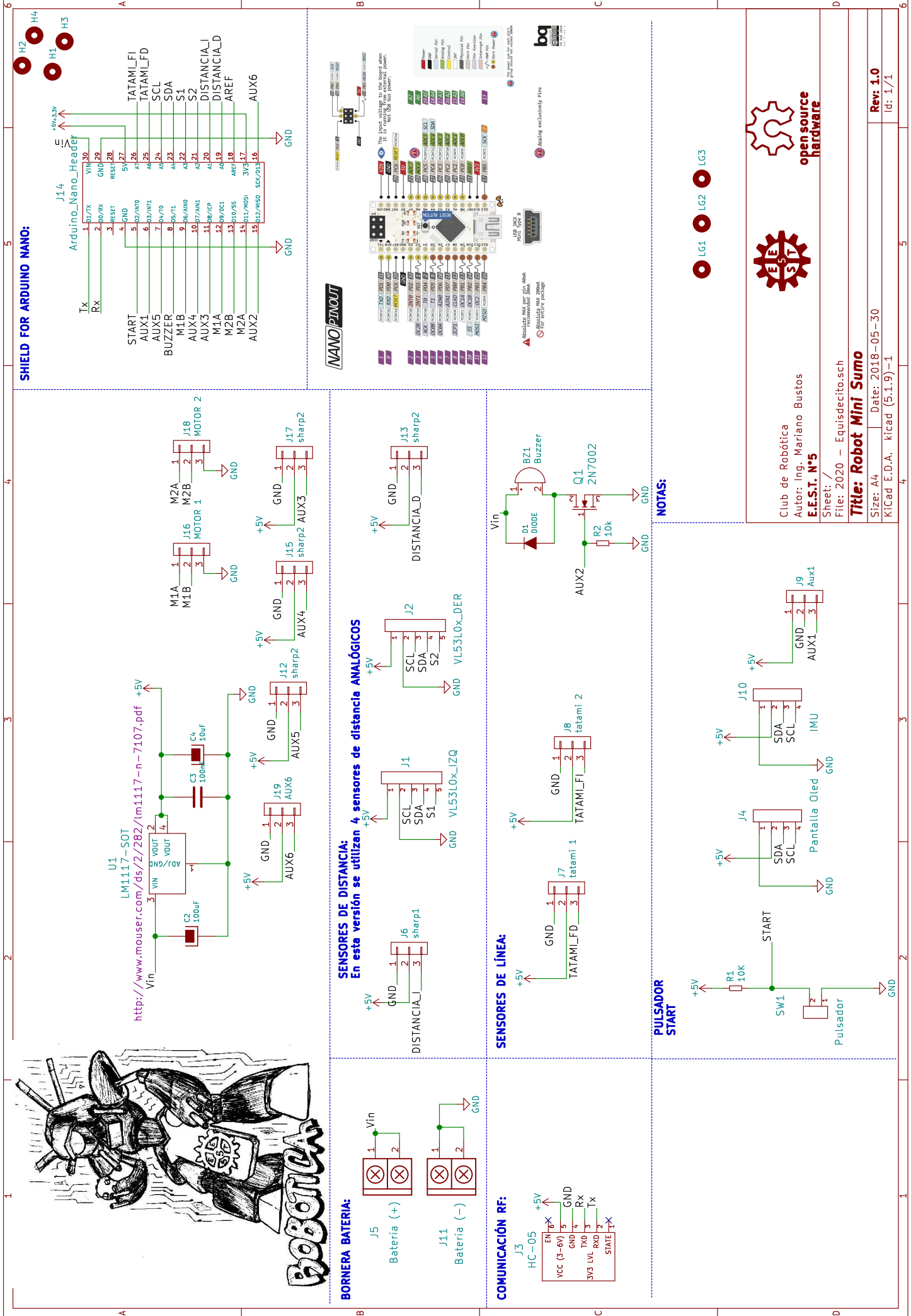


# SHIELD FOR ARDUINO NANO:



### SHIELD FOR ARDUINO NANO:

### Arduino Nano Pinout

### SENSORES DE DISTANCIA:

En esta versión se utilizan 4 sensores de distancia ANALÓGICOS

### SENSORES DE LÍNEA:

### COMUNICACIÓN RF:

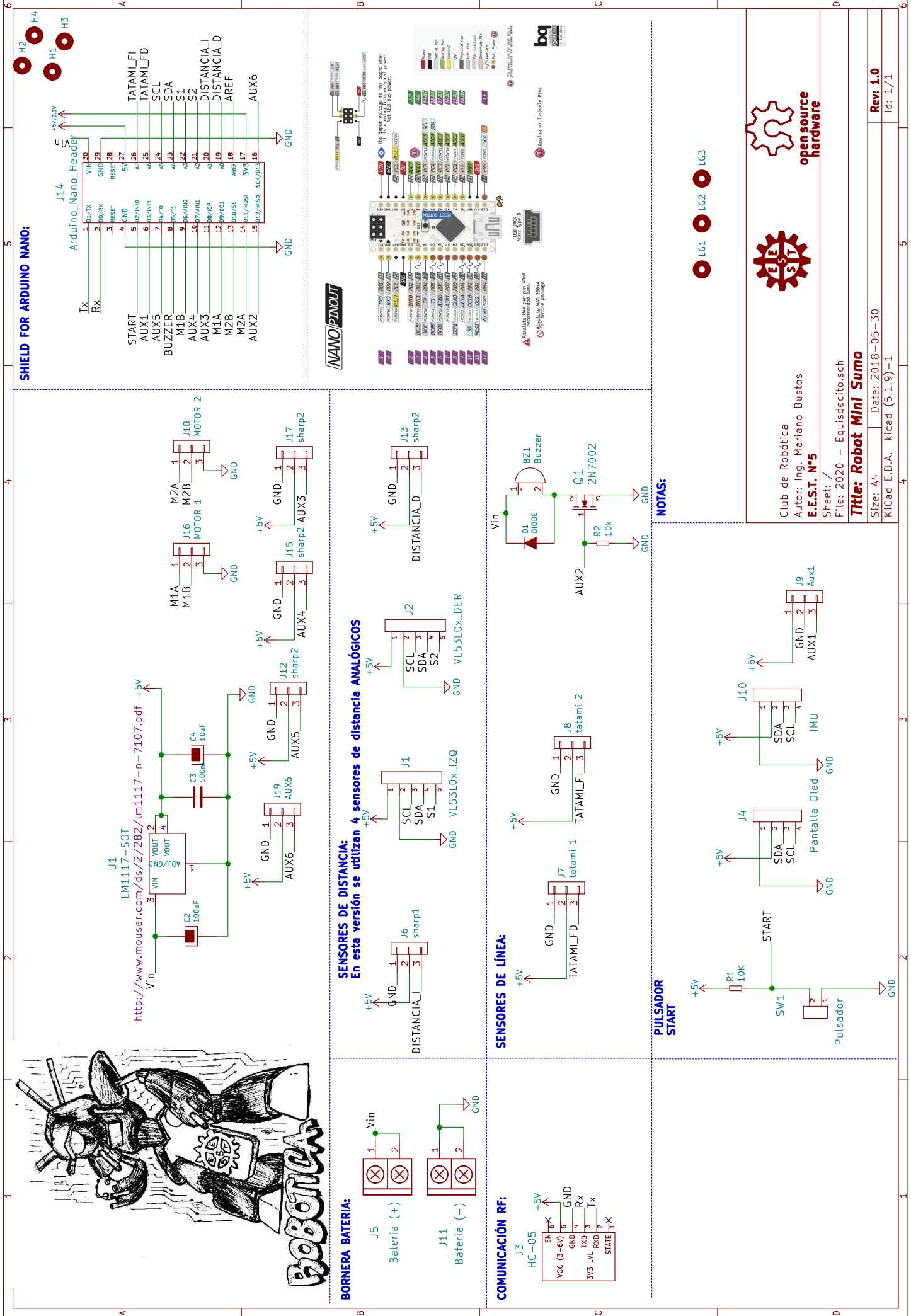
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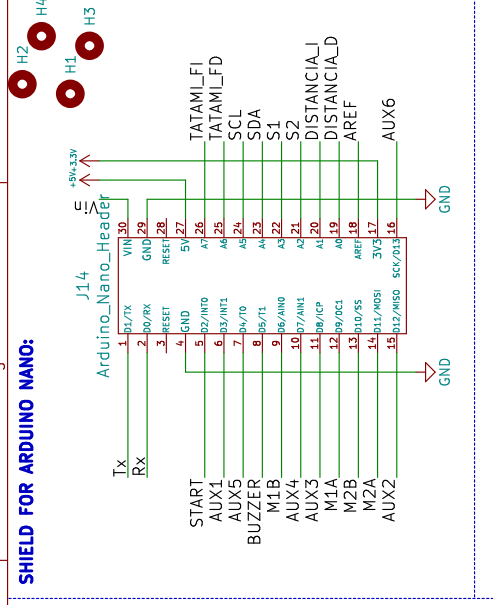
### PULSADOR START:

### NOTAS:

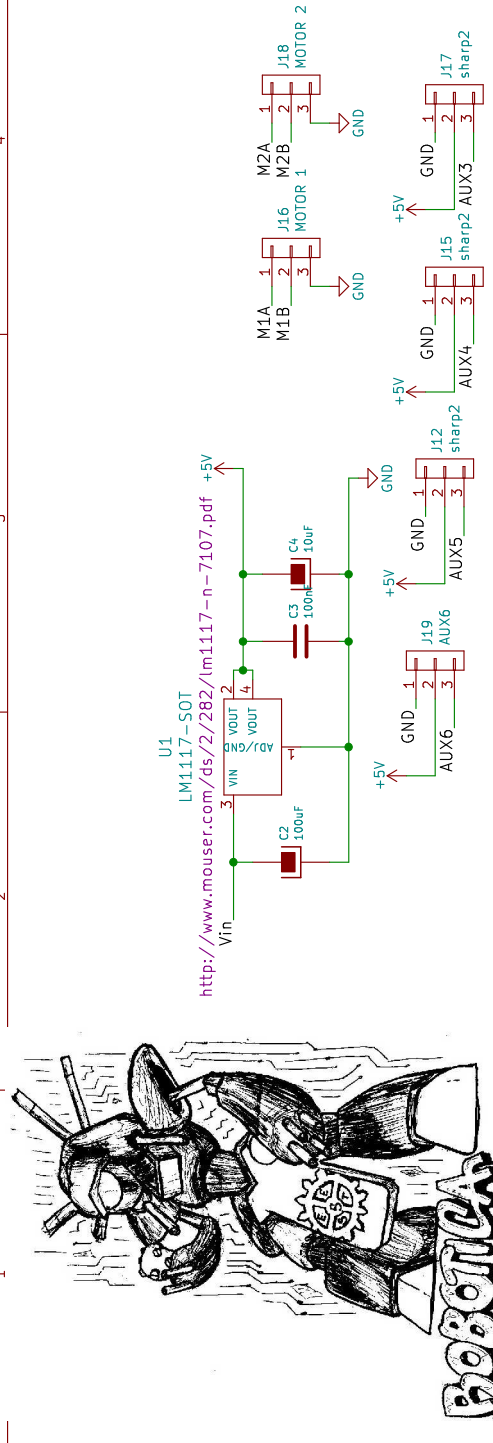
Club de Robótica  
 Autor: Ing. Mariano Bustos  
**E.E.S.T. N°5**  
 Sheet: /  
 File: 2020 - Equisdecito.sch  
**Title: Robot Mini Sumo**  
 Size: A4 Date: 2018-05-30  
 KiCad E.D.A. kicad (5.1.9)-1

Rev: 1.0  
 Id: 1/1

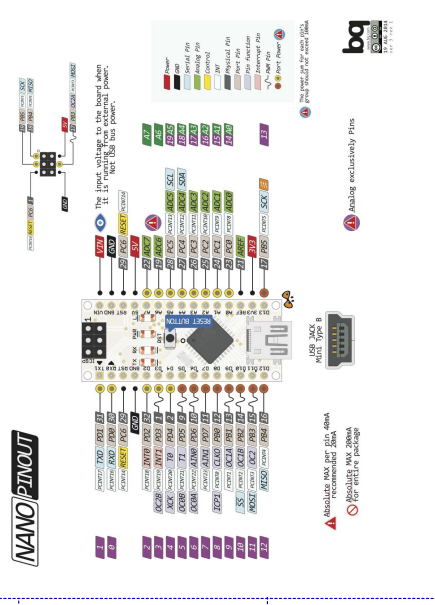




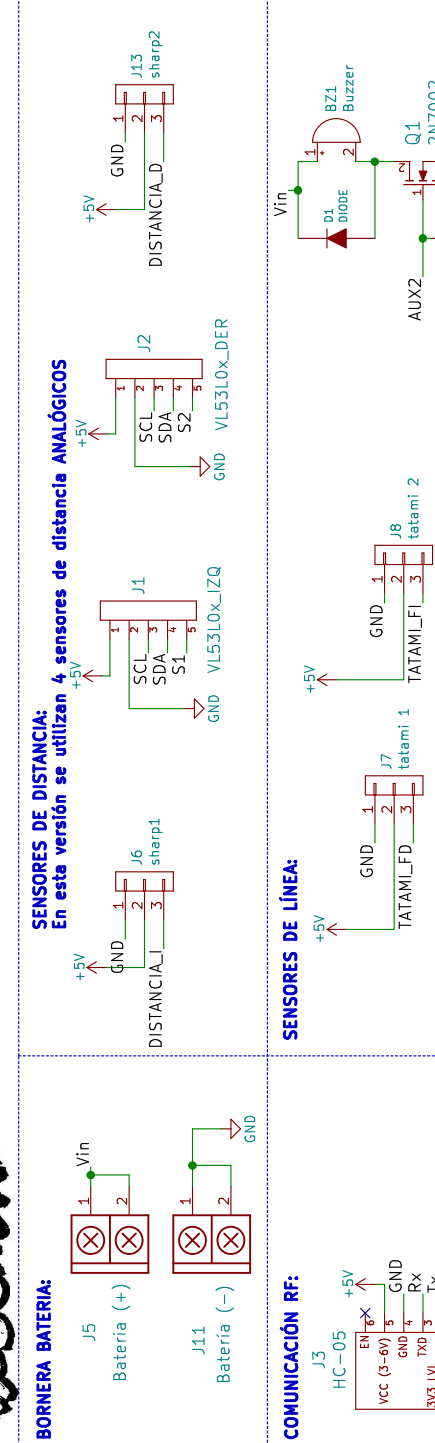
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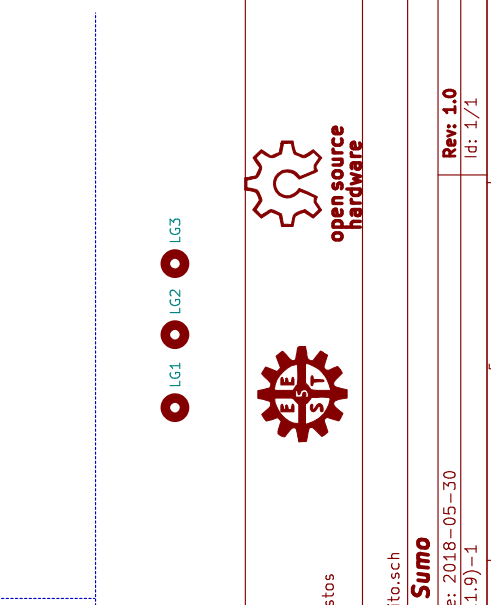


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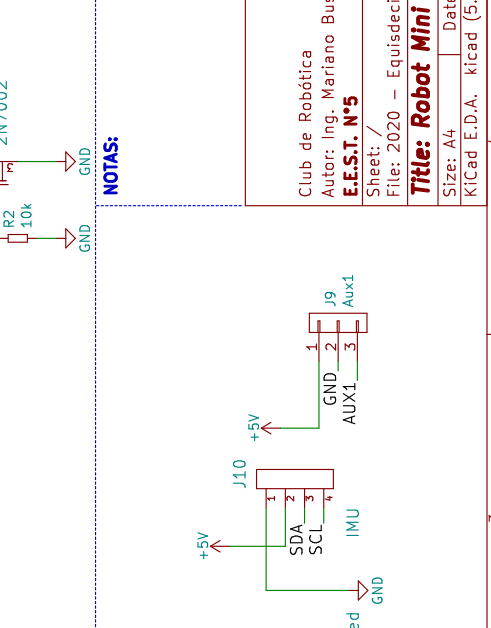


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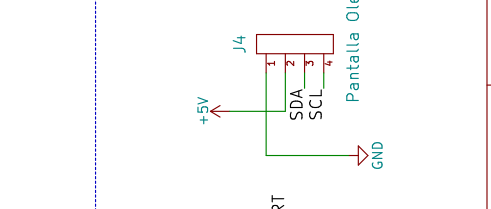
En esta versión se utilizan 4 sensores de distancia ANALÓGICOS



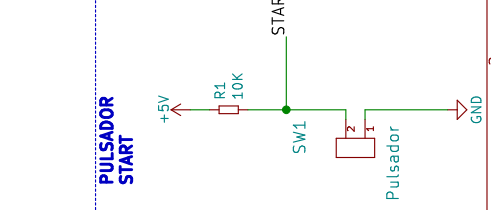
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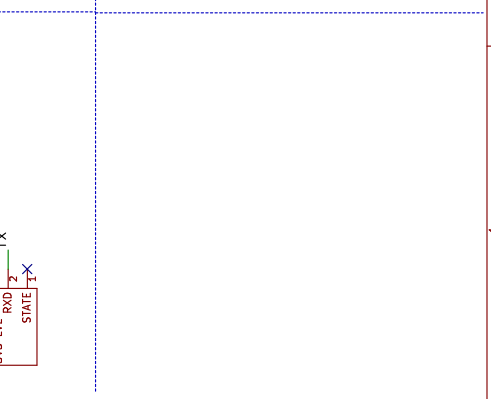
### PULSADOR START



### NOTAS:



### SENSORES DE LÍNEA:



### Club de Robótica

Autor: Ing. Mariano Bustos

**E.E.S.T. N°5**

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**Title: Robot Mini Sumo**

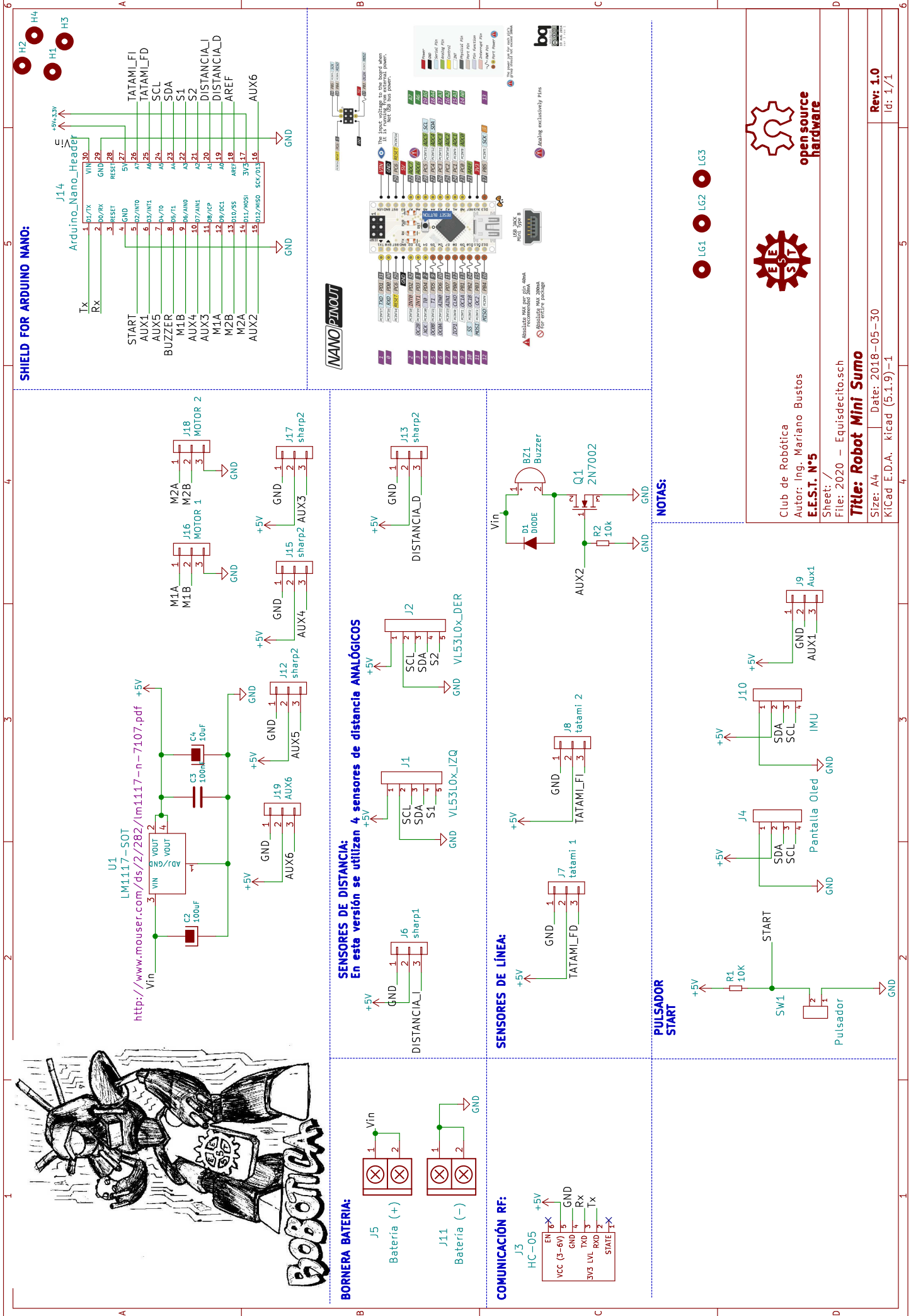
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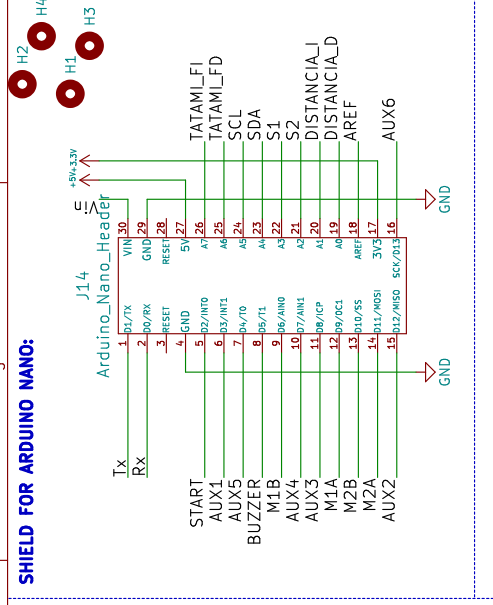
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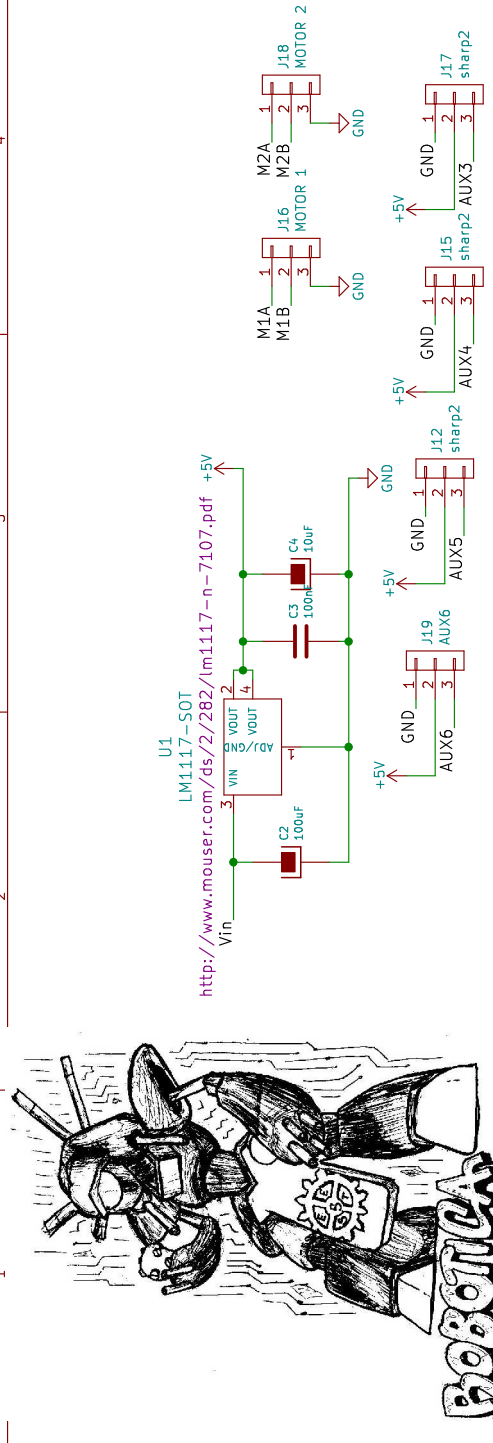
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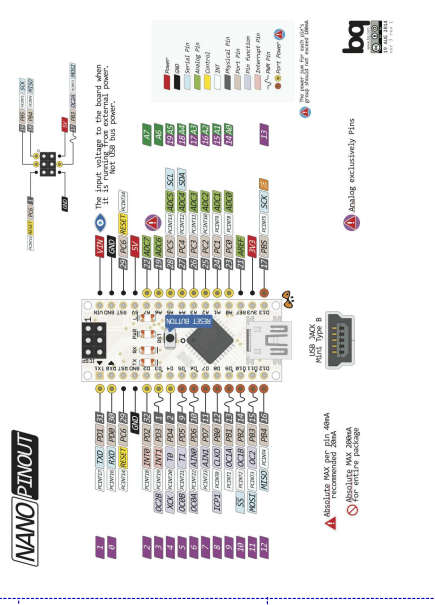




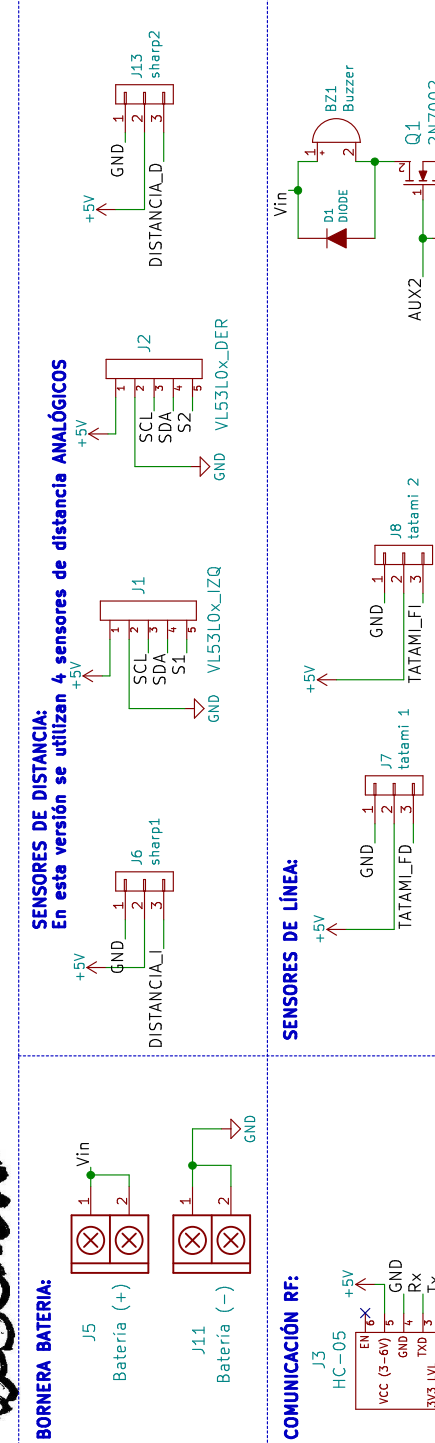
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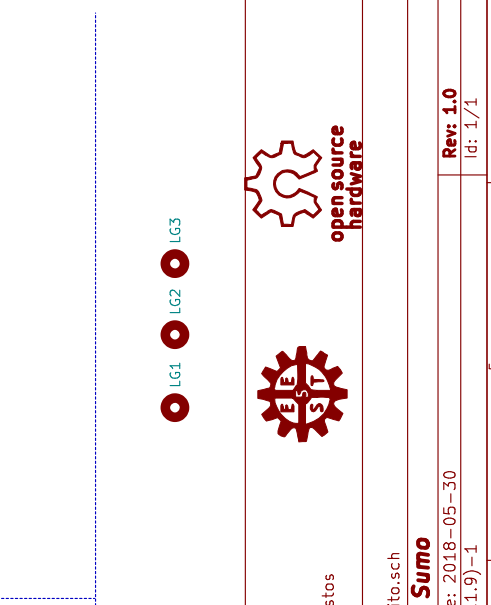


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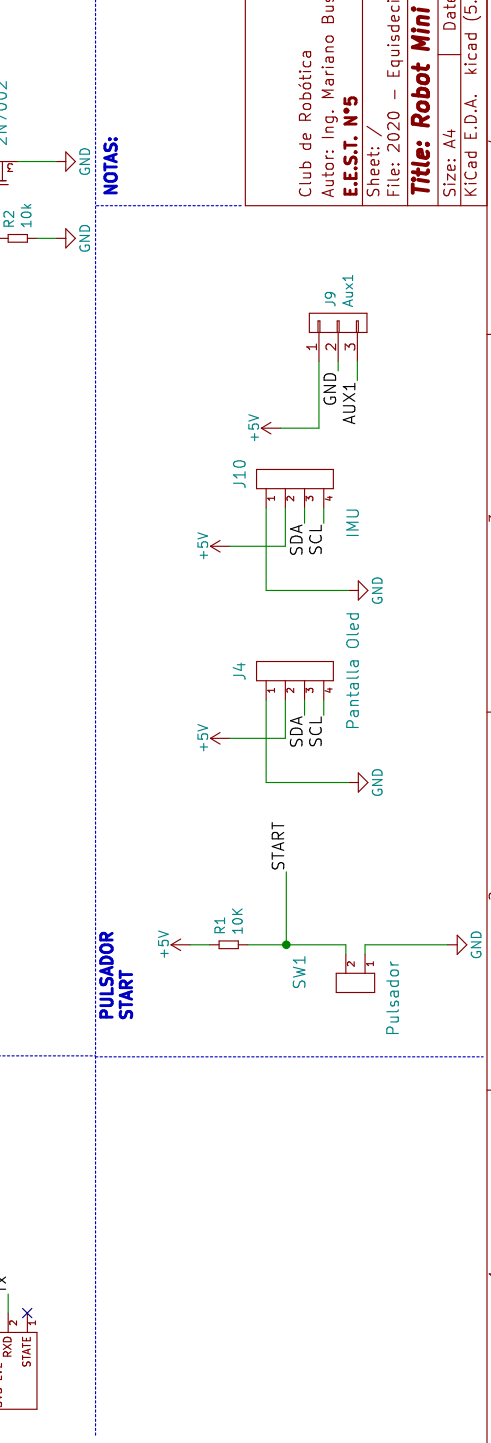


### SENSORES DE DISTANCIA:

En esta versión se utilizan 4 sensores de distancia ANALÓGICOS

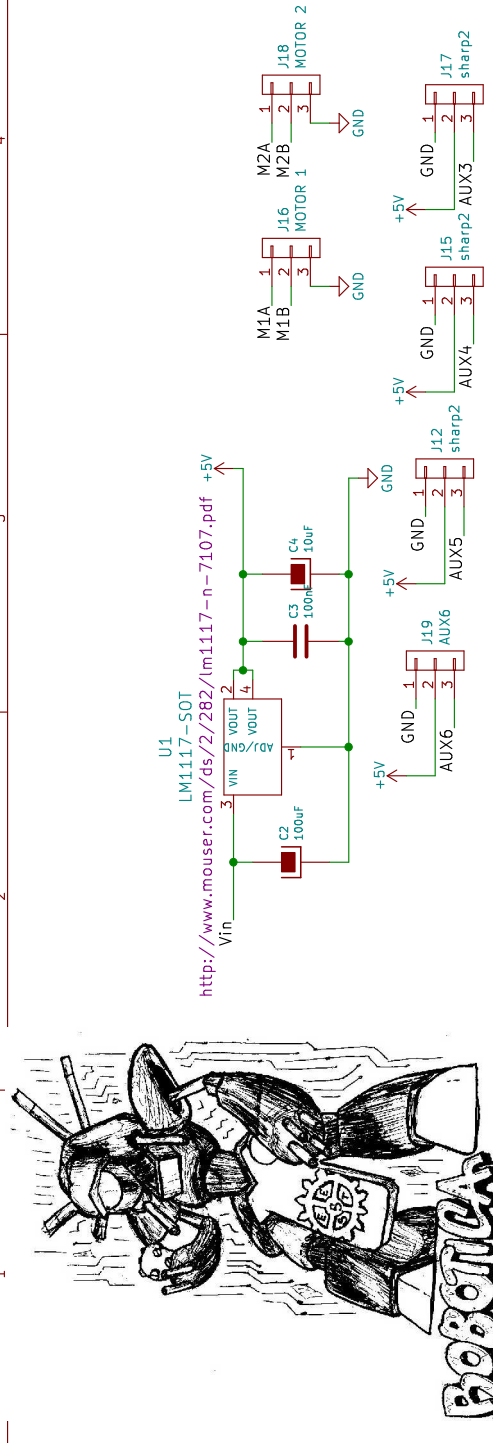


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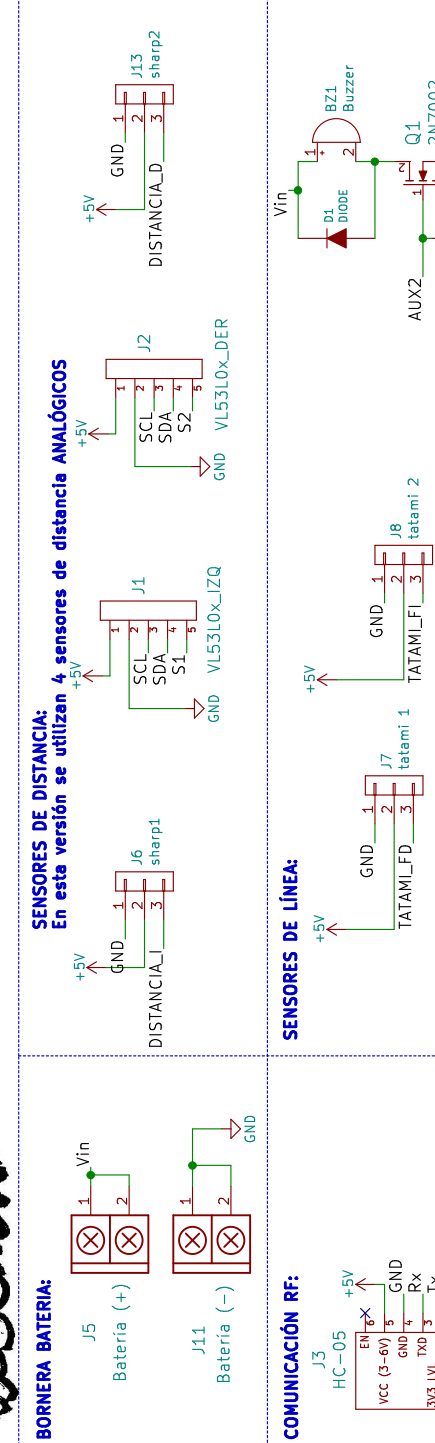


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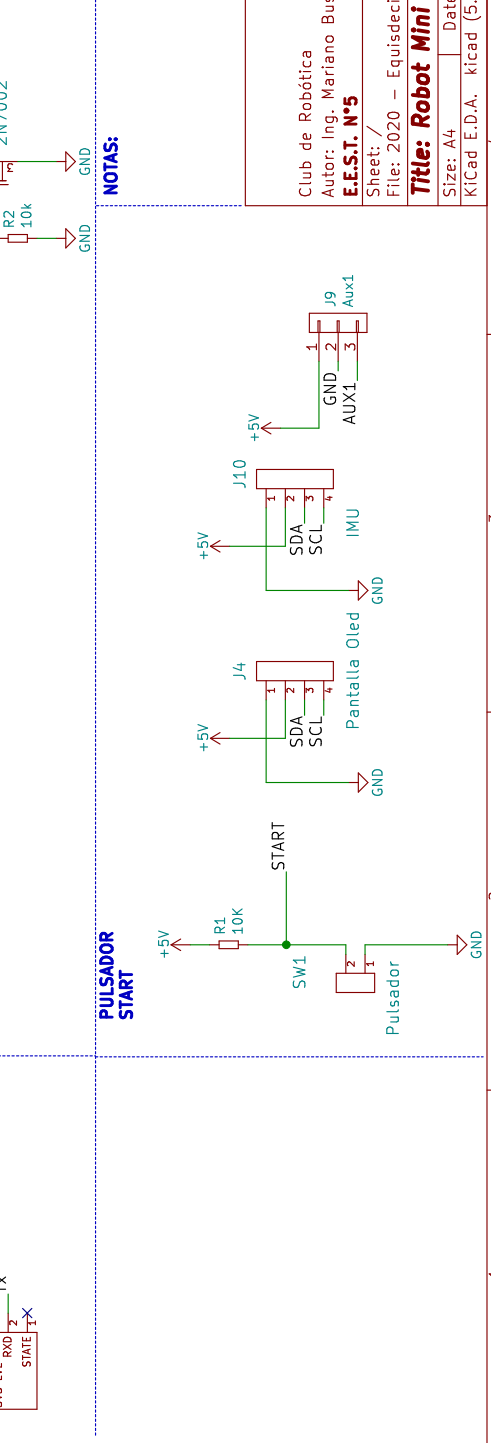
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### PULSADOR START



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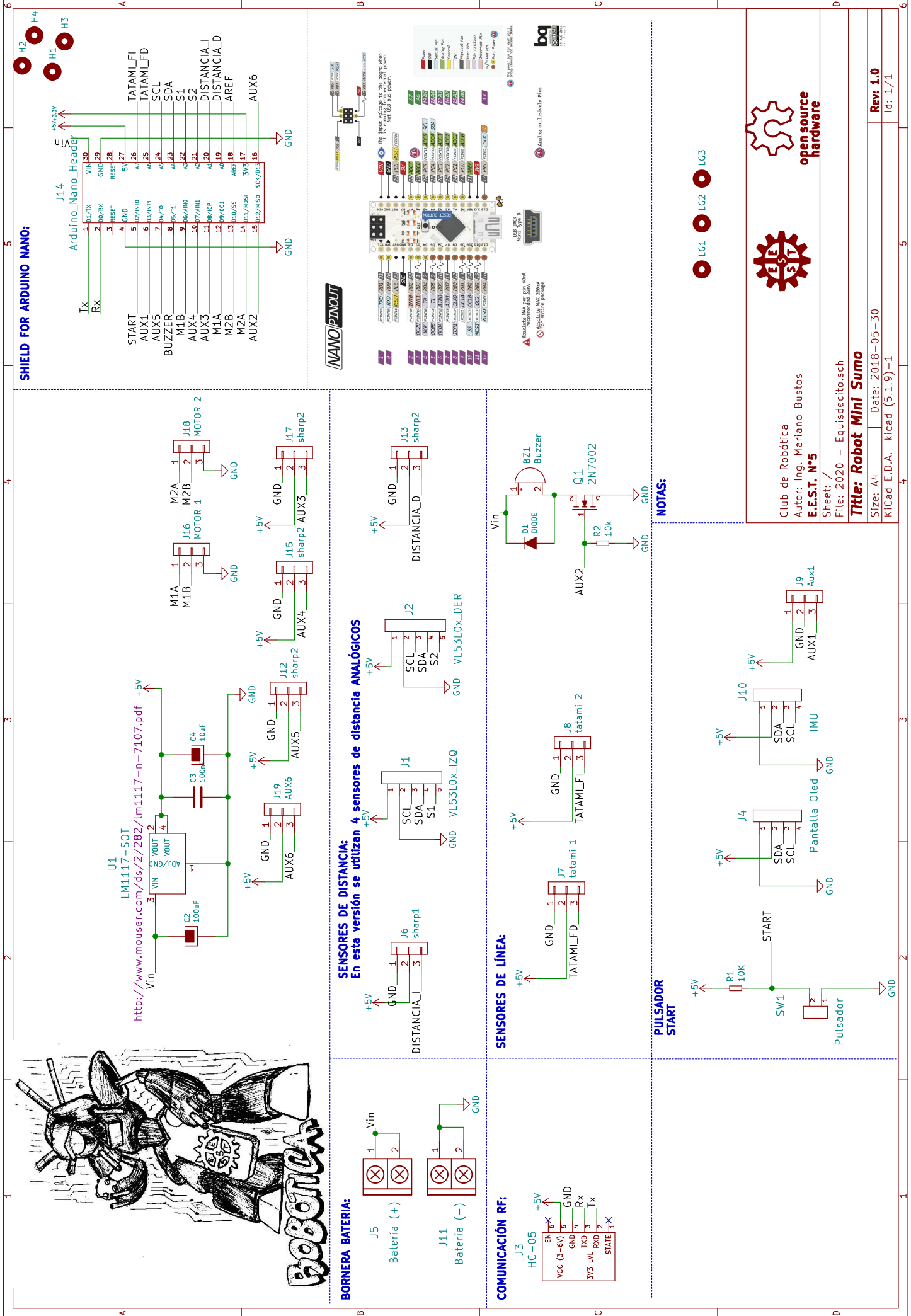
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### Arduino Nano Pinout

### SENSORES DE DISTANCIA:

En esta versión se utilizan 4 sensores de distancia ANALÓGICOS

### SENSORES DE LÍNEA:

### COMUNICACIÓN RF:

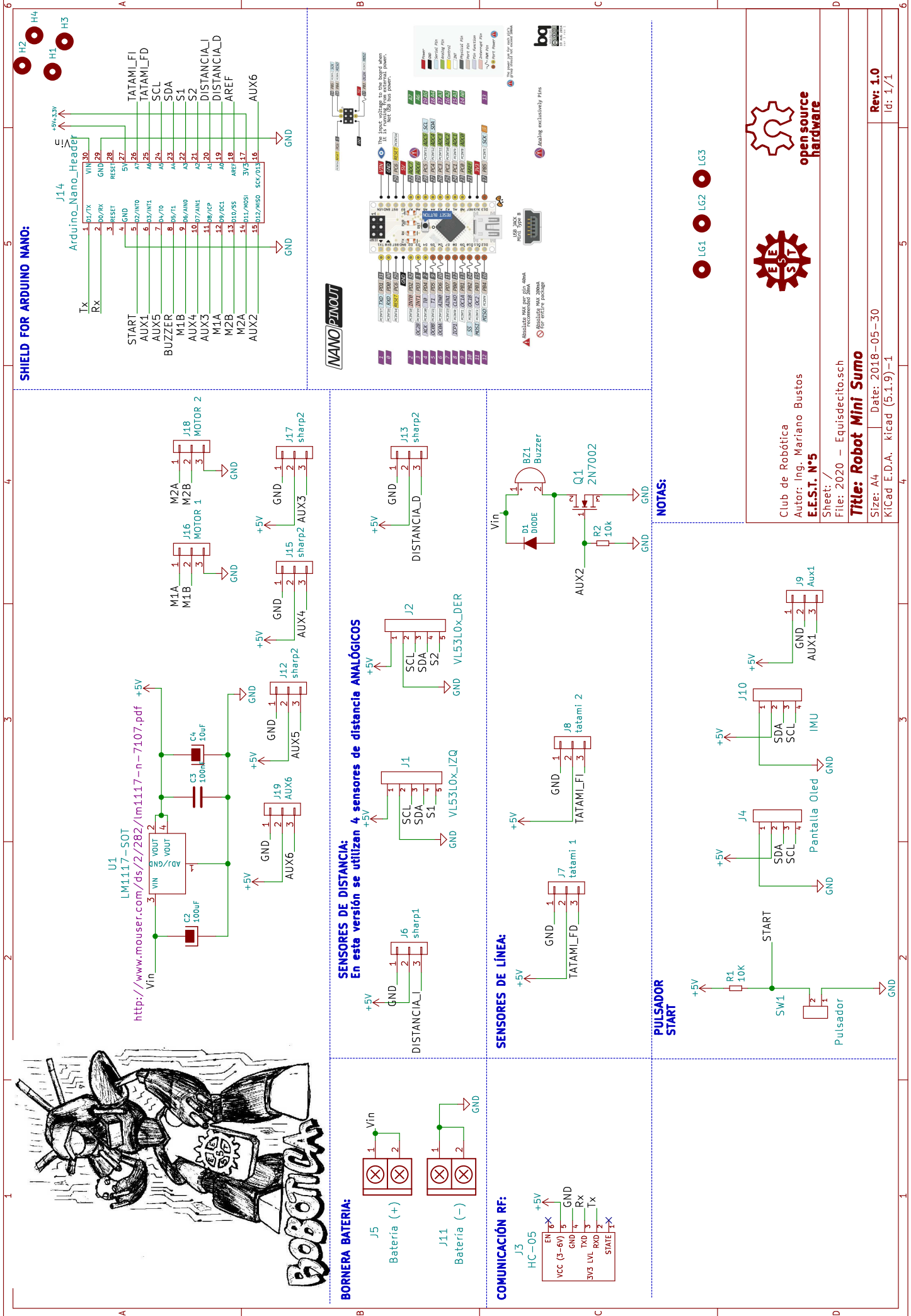
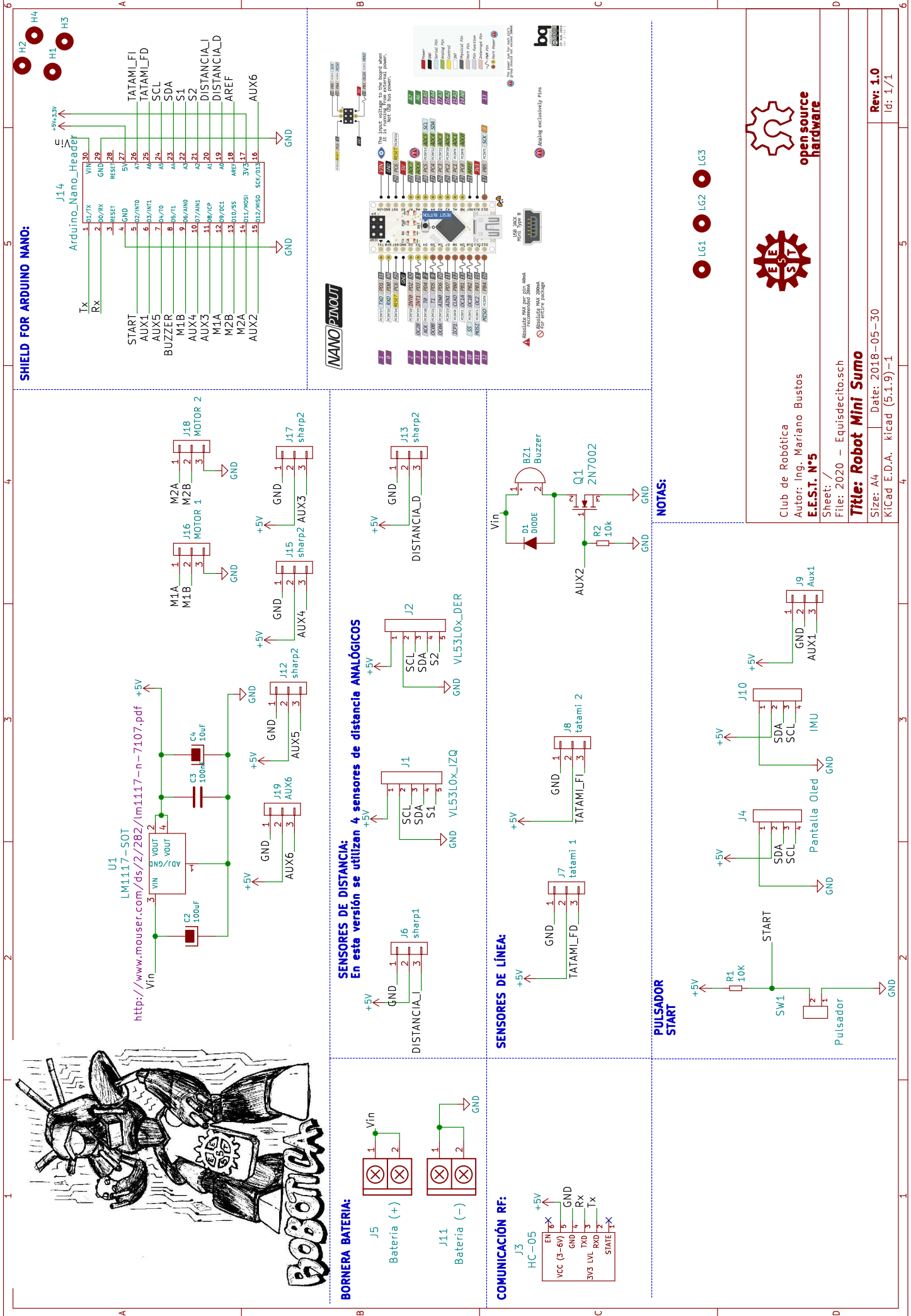
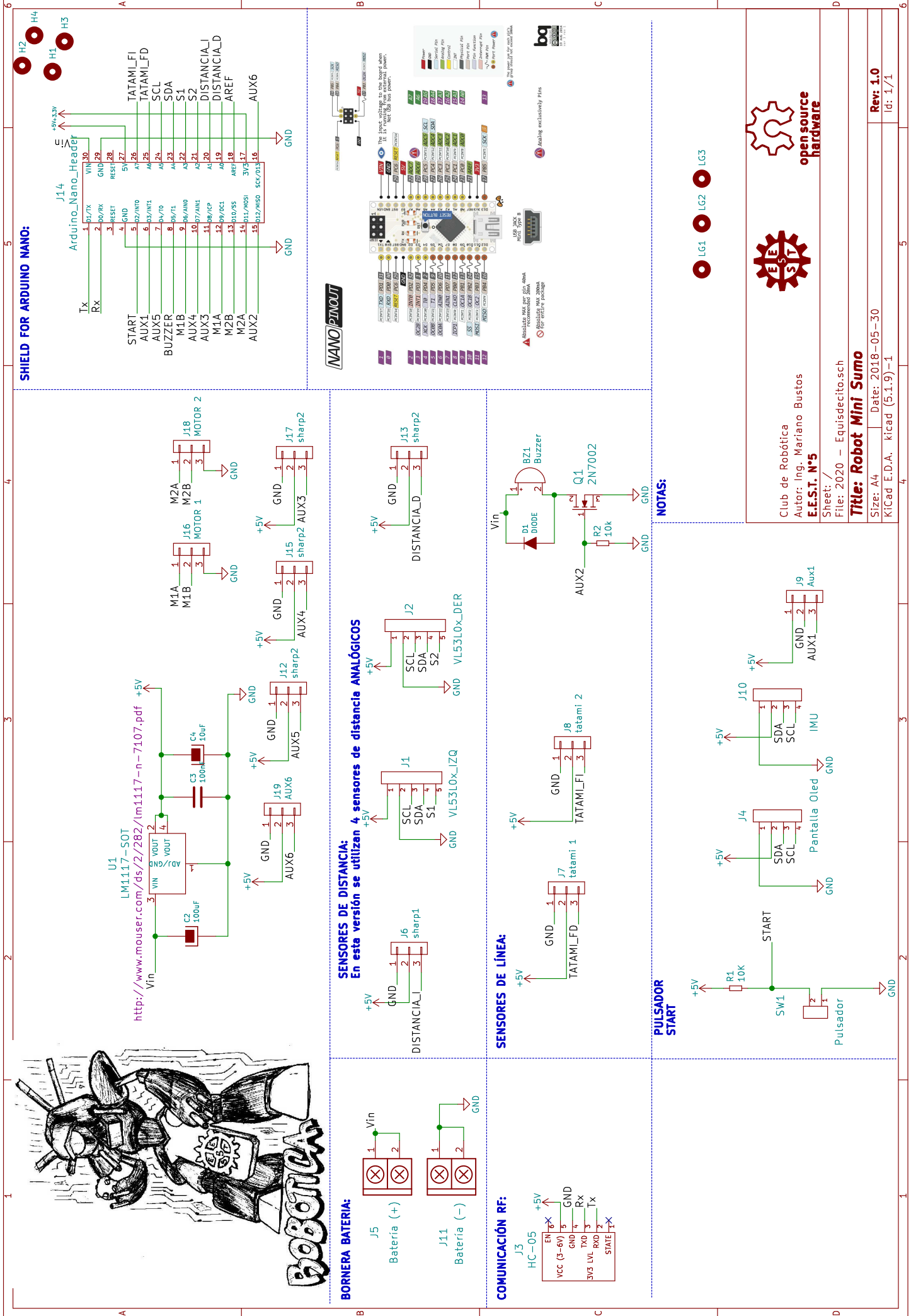
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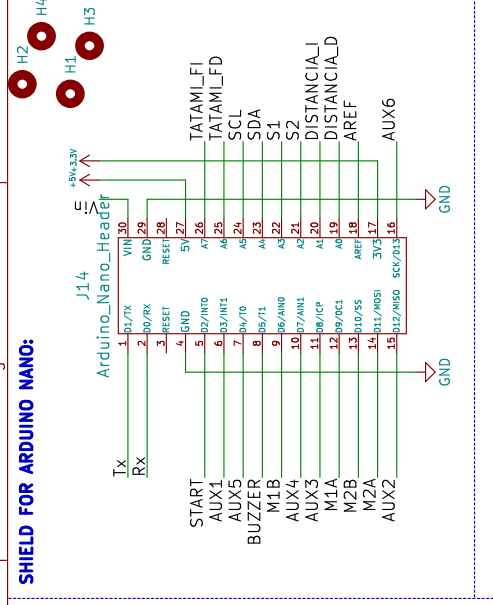
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### NOTAS:

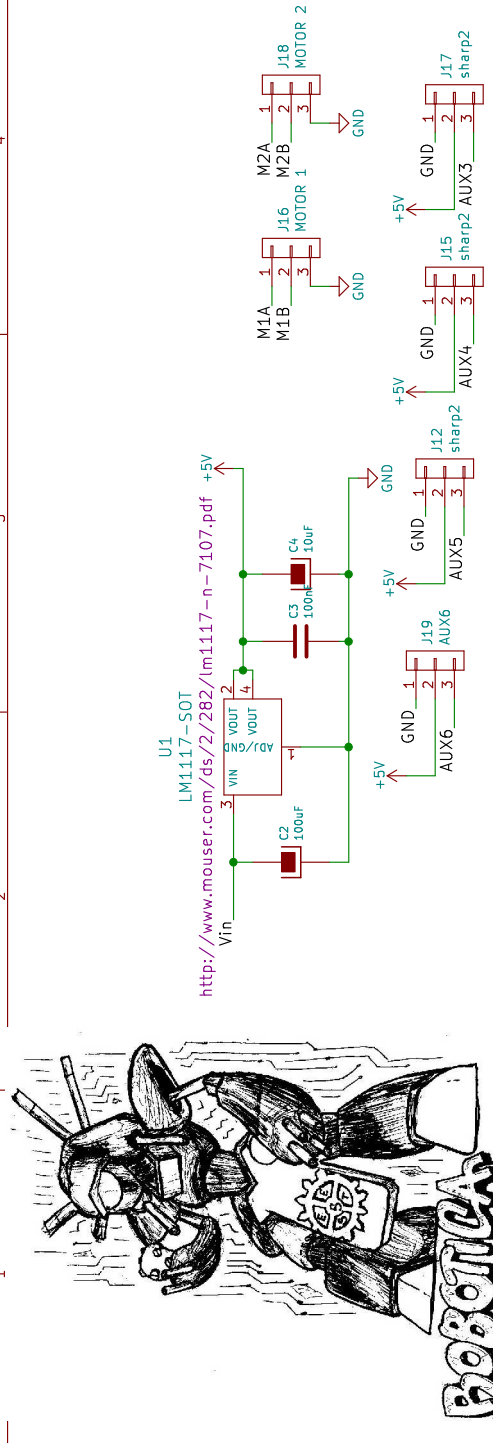
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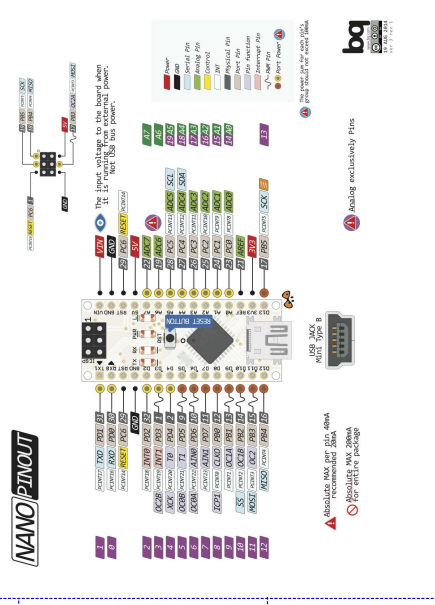
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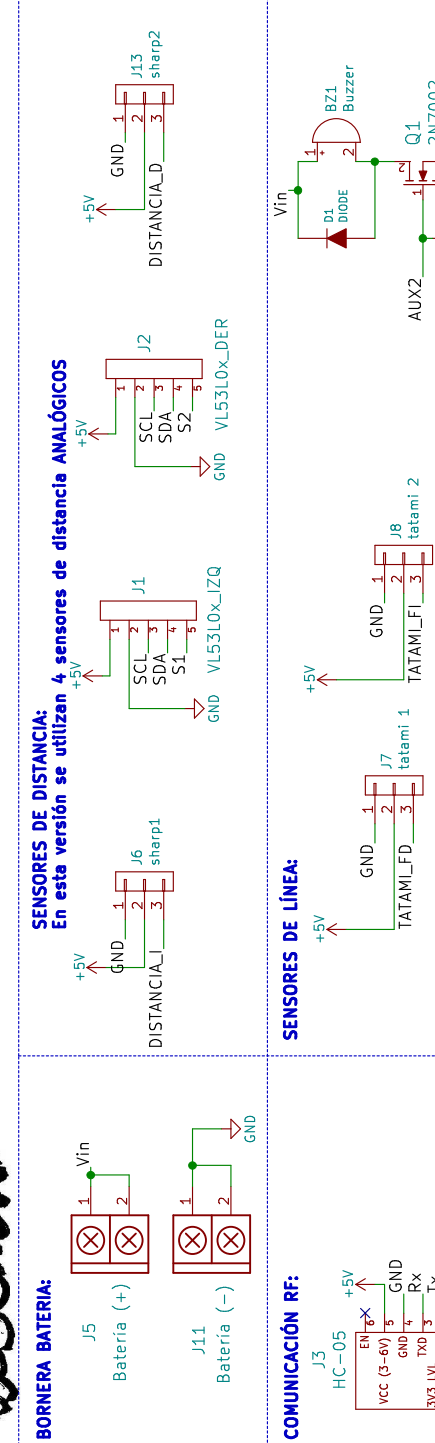
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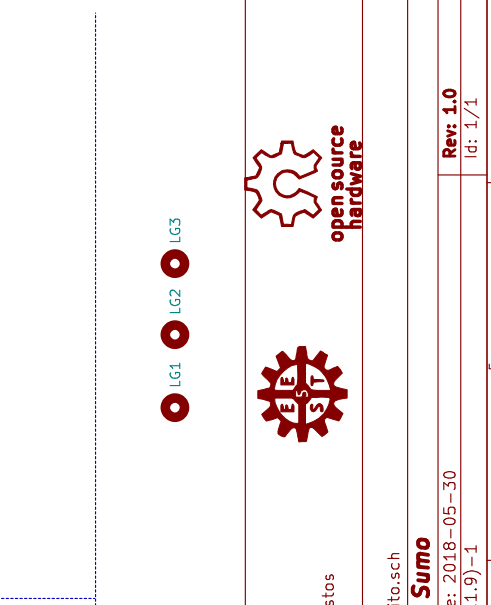


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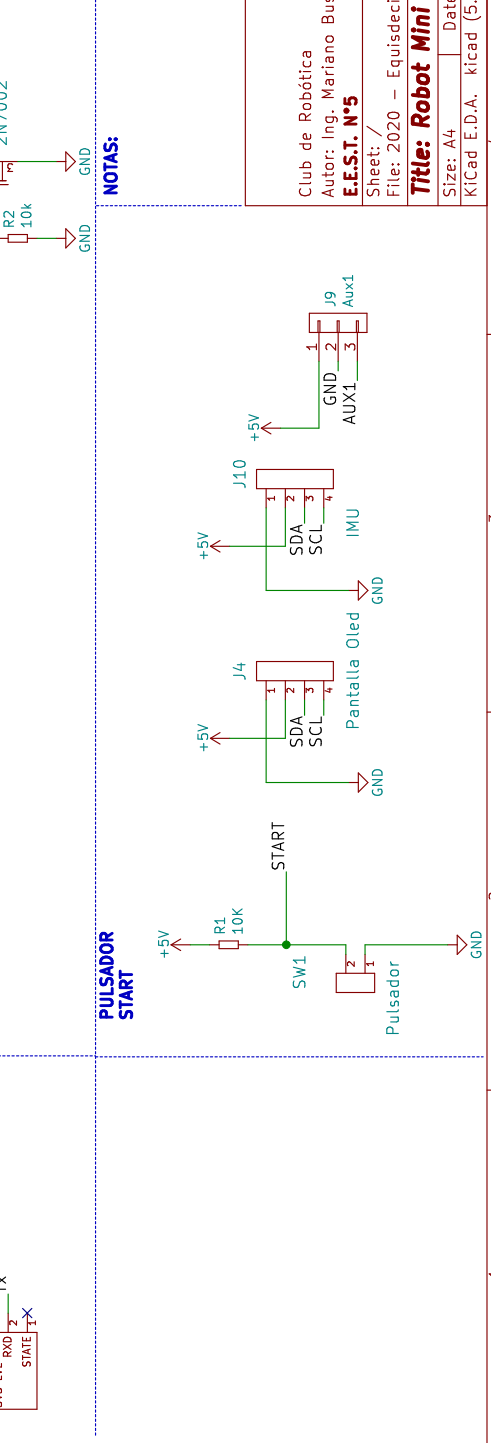


### SENSORES DE DISTANCIA:

En esta versión se utilizan 4 sensores de distancia ANALÓGICOS

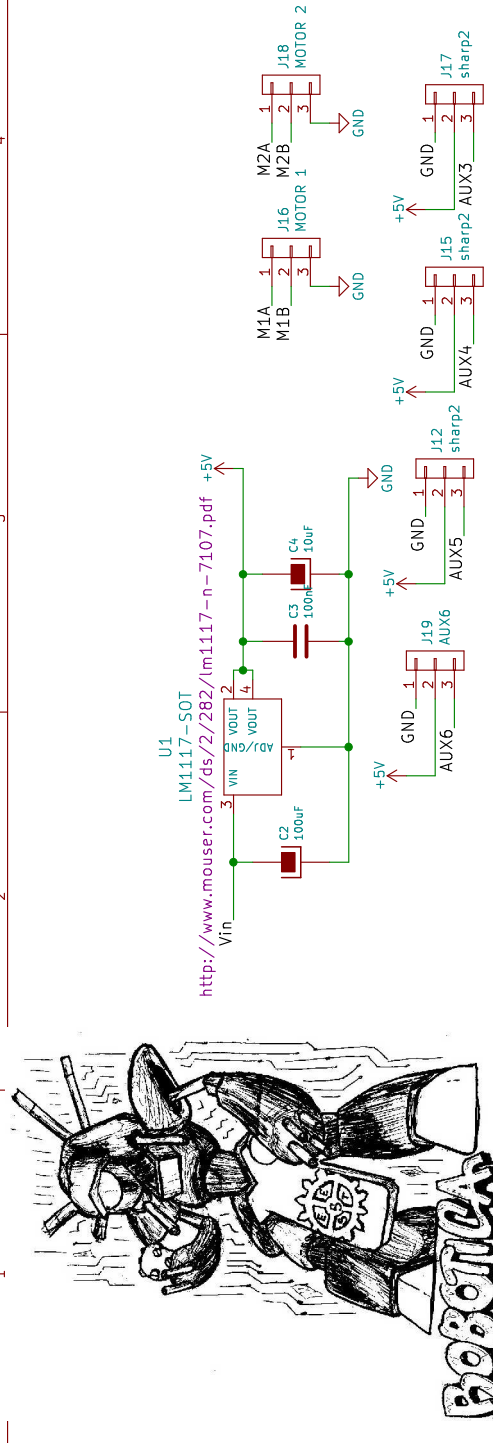


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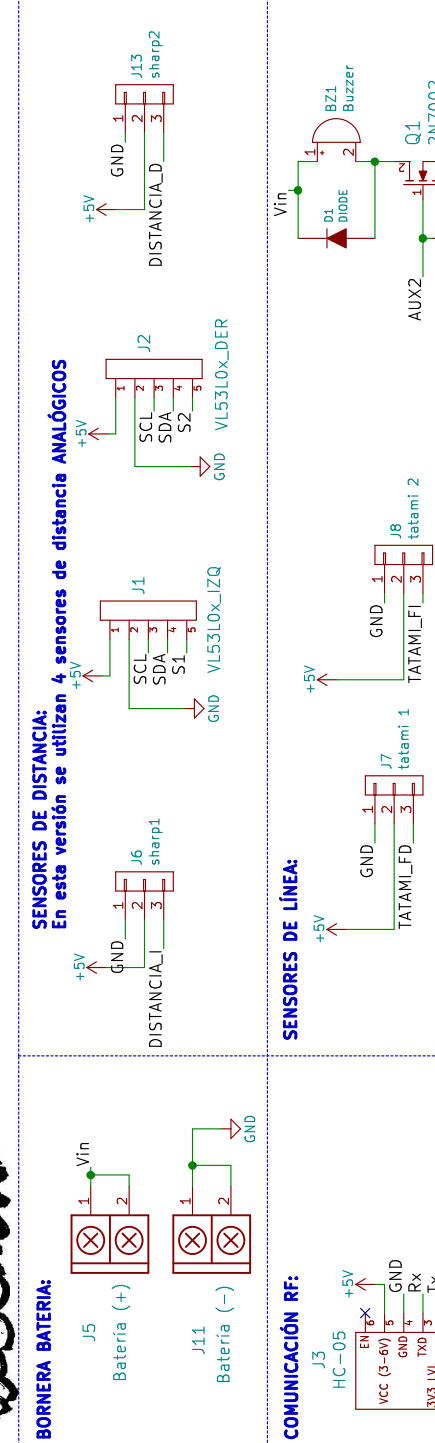


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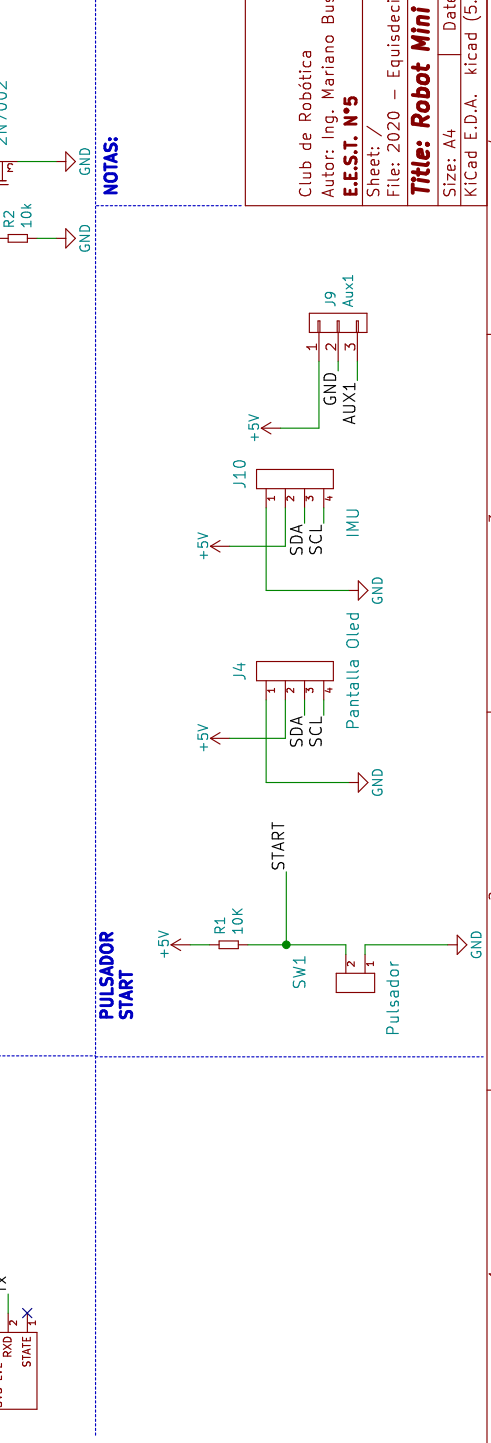
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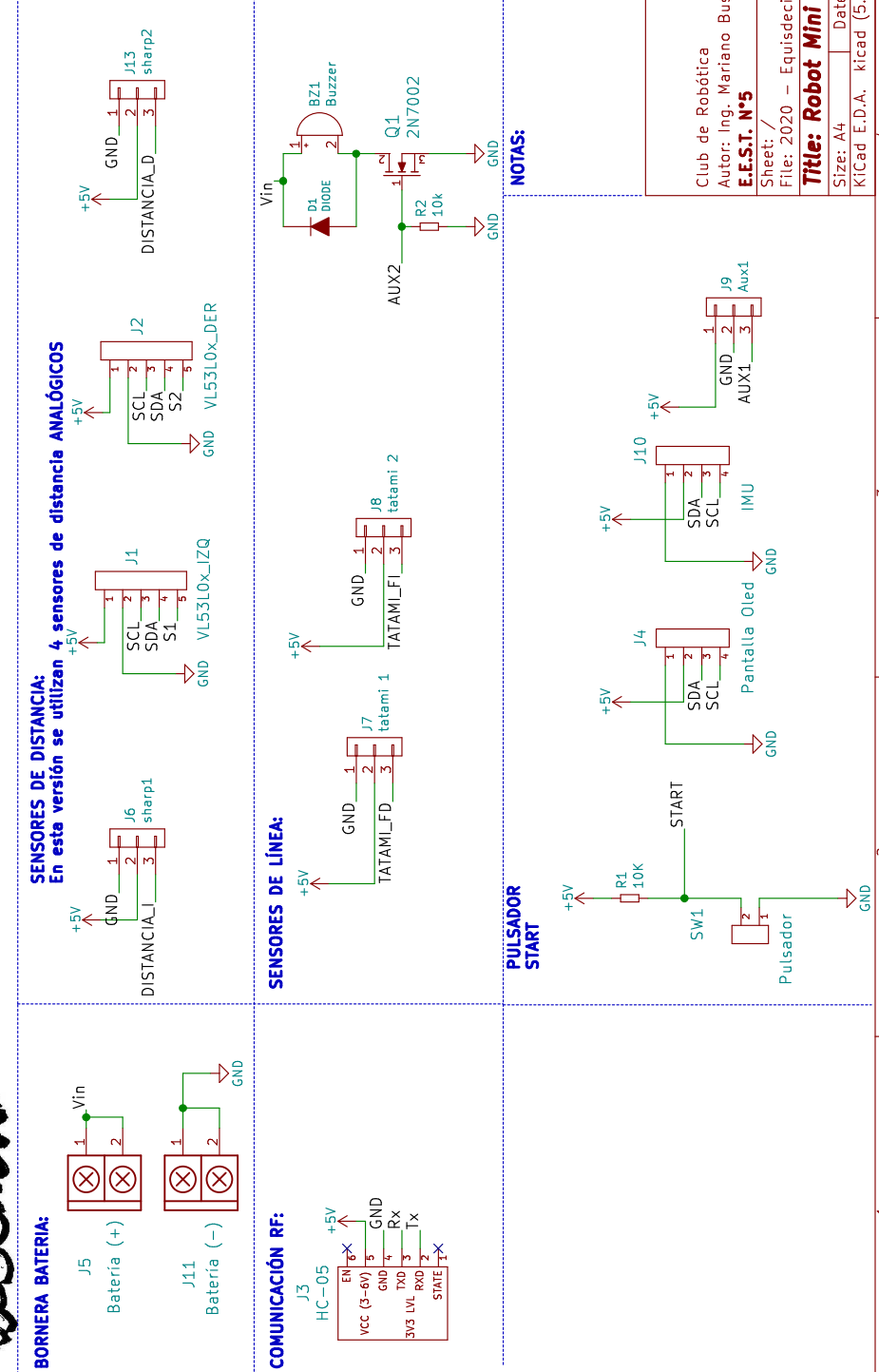
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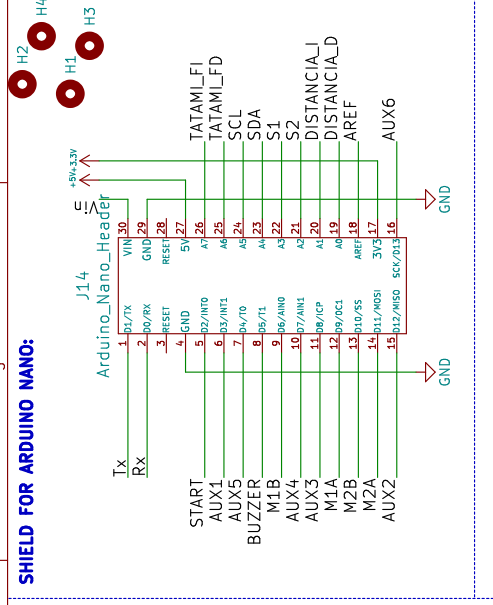


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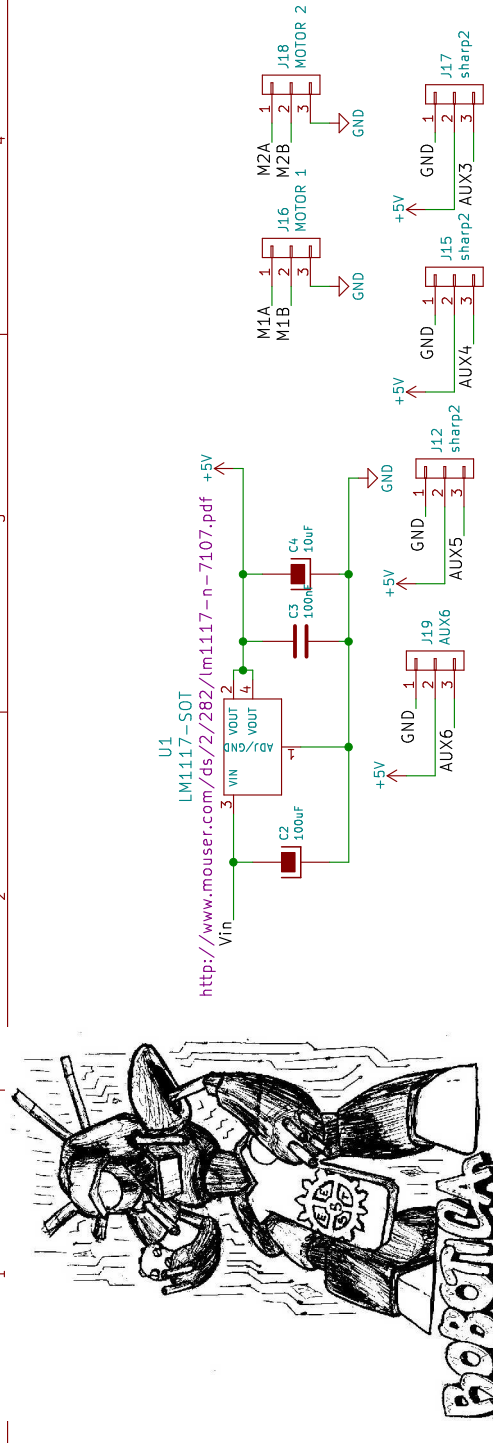
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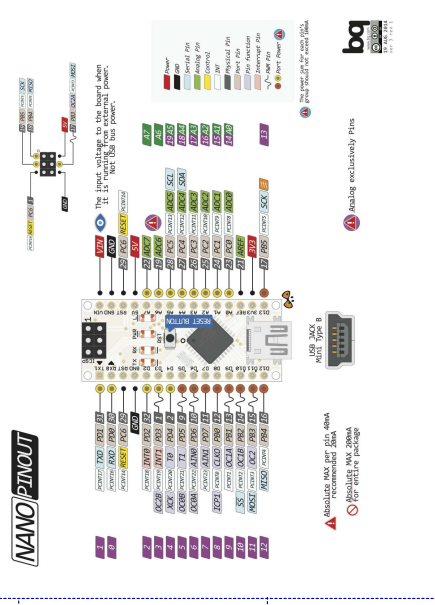




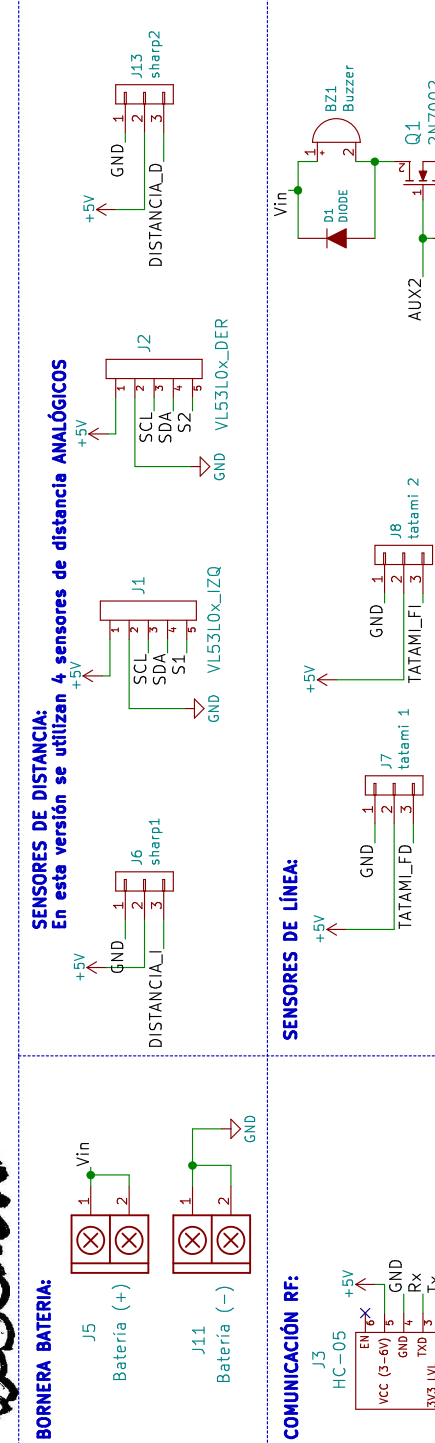
### SHIELD FOR ARDUINO NANO:



### BORNERA BATERIA:

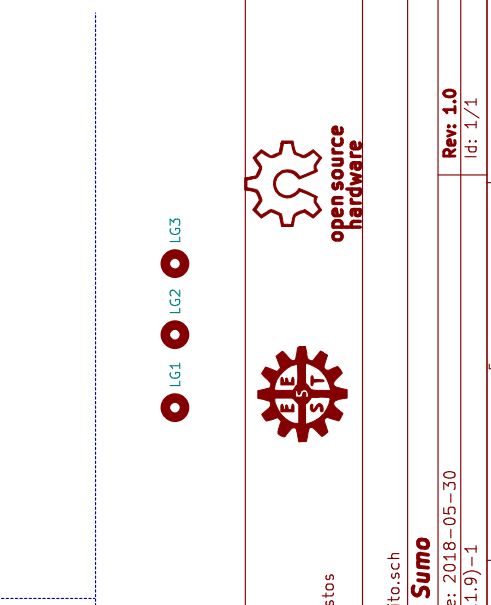


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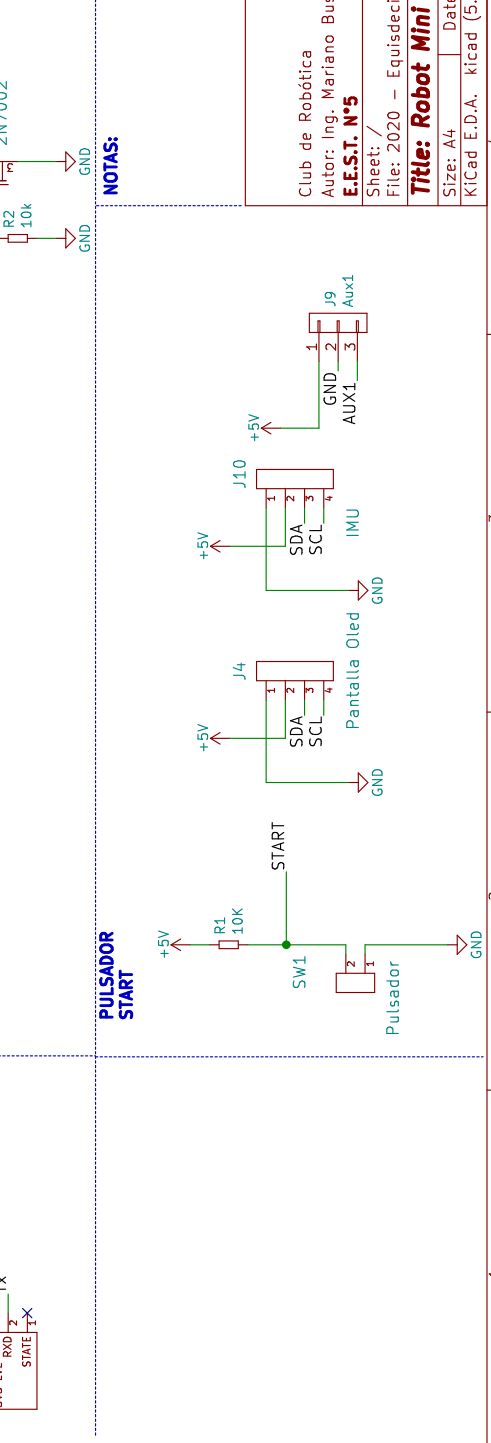


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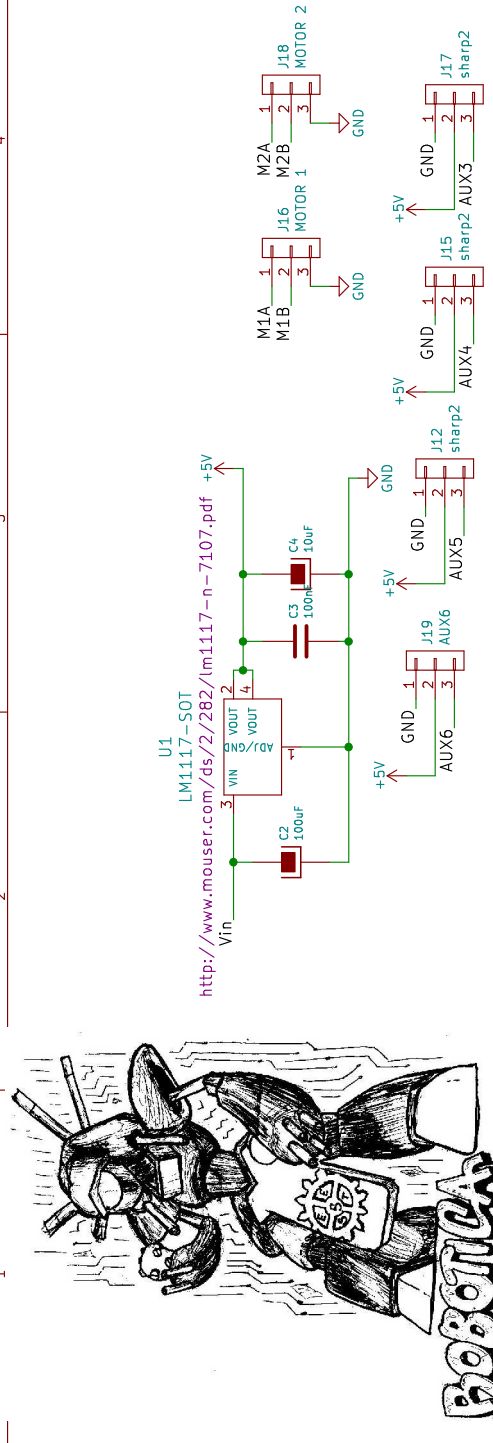
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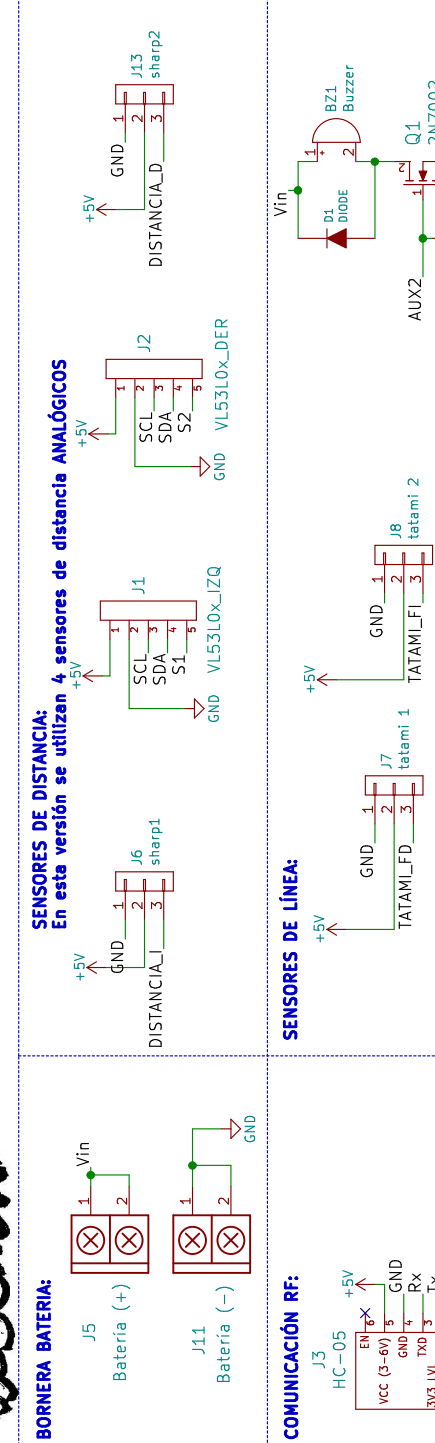
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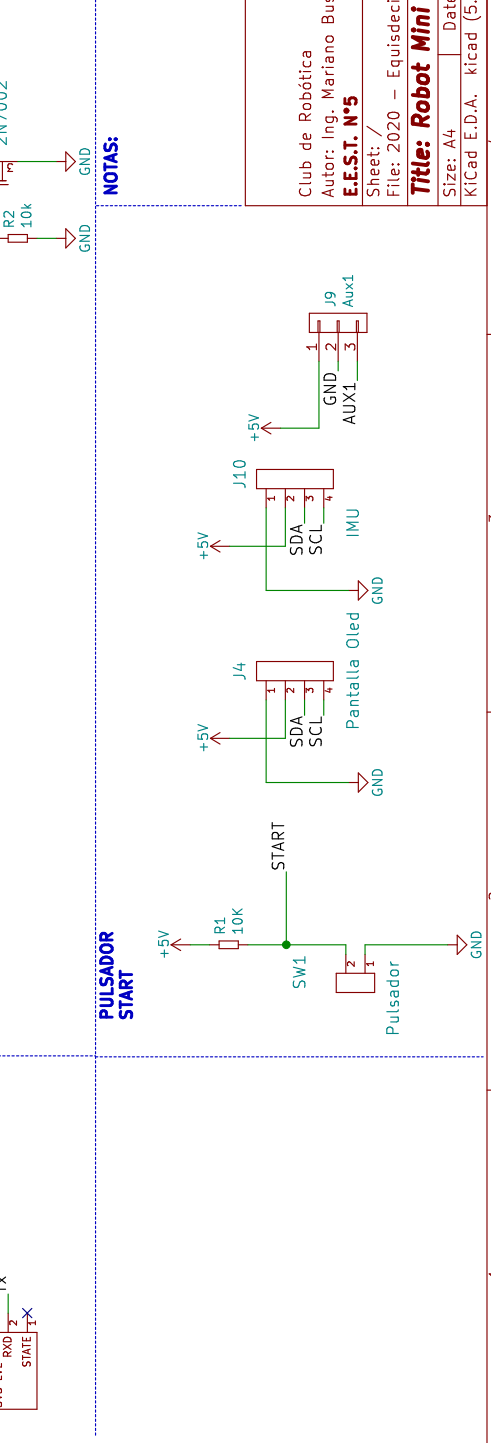
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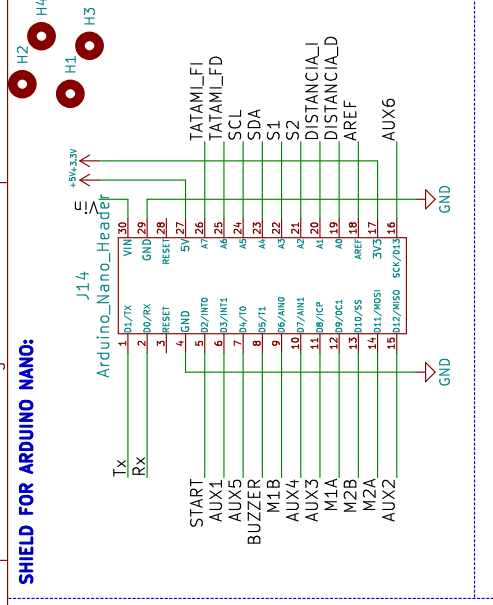
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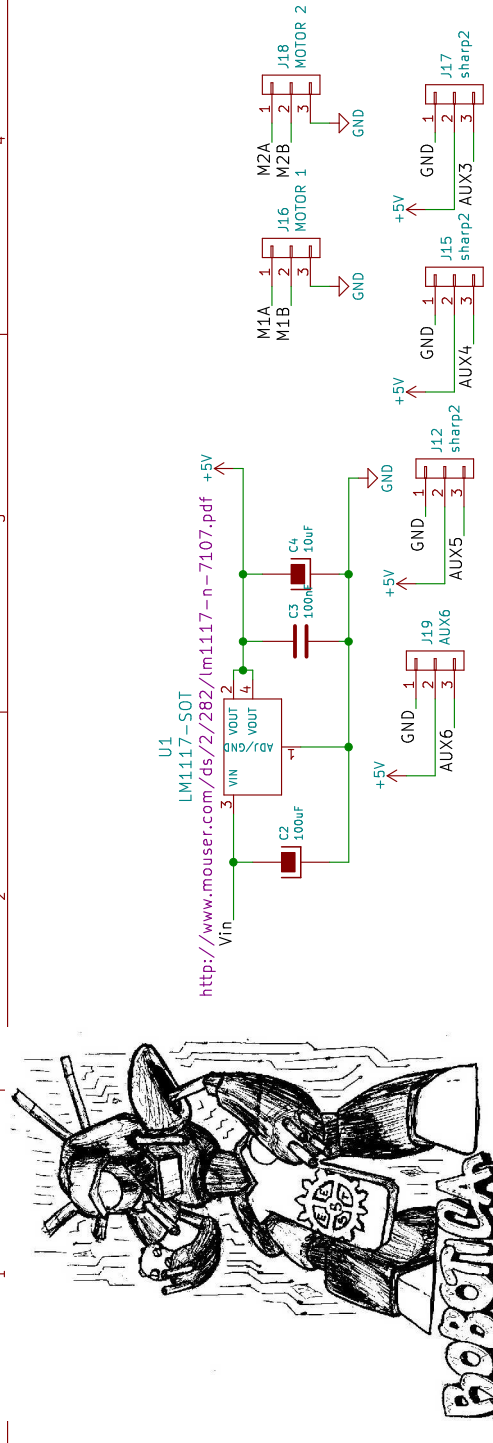
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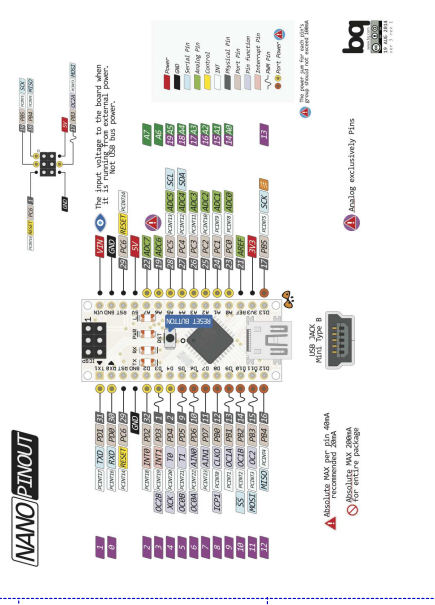
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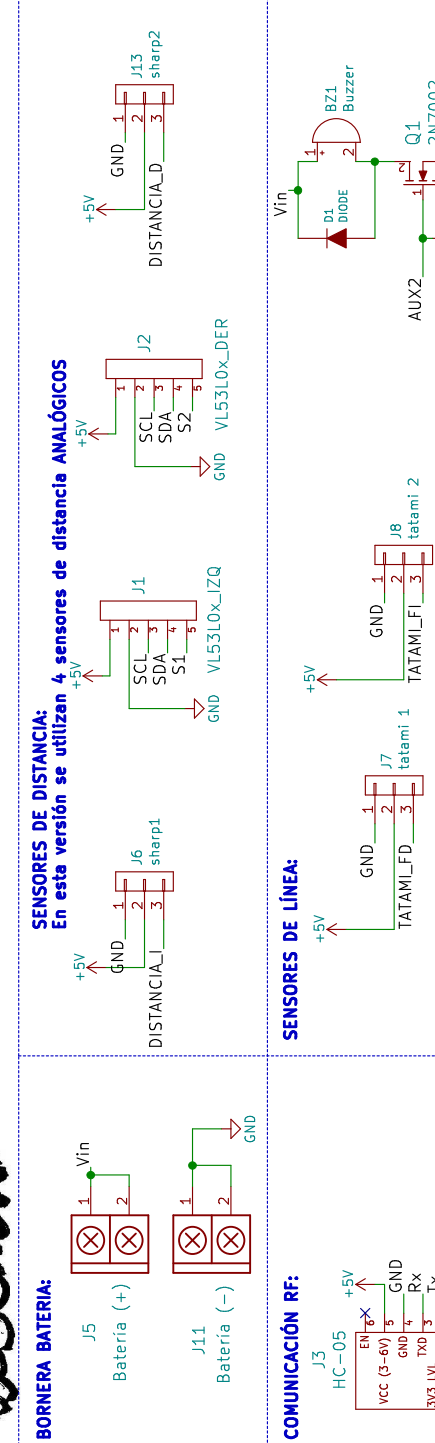
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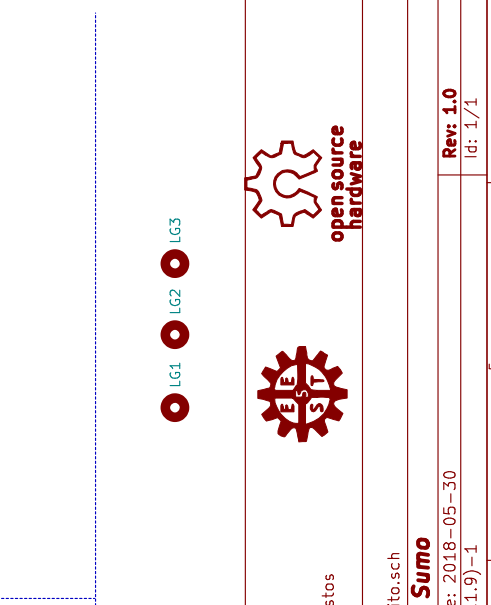


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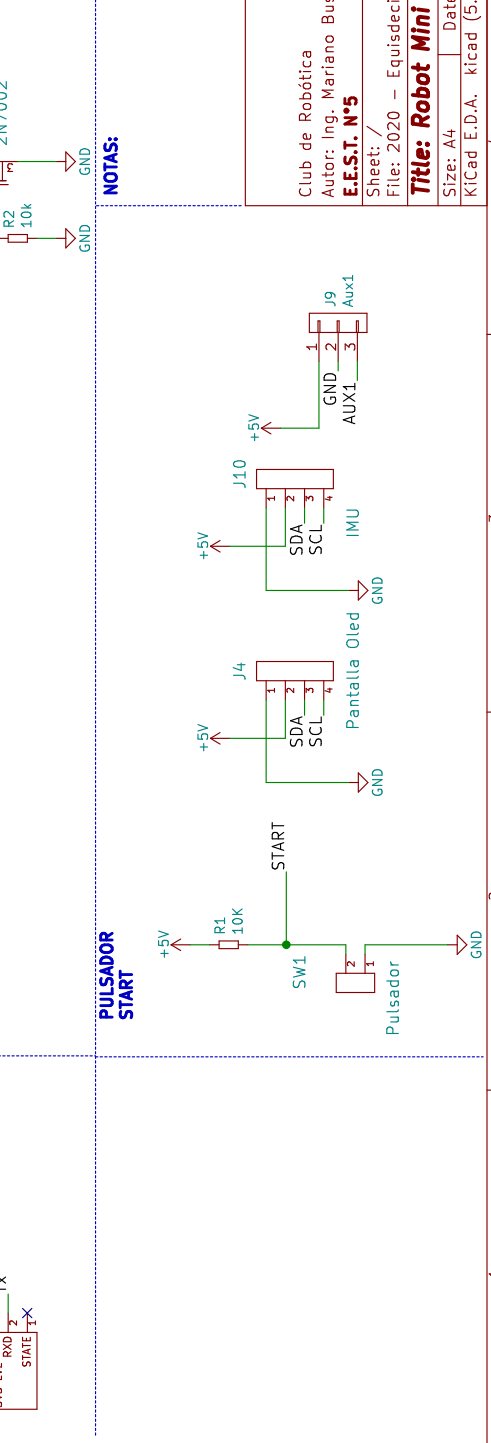


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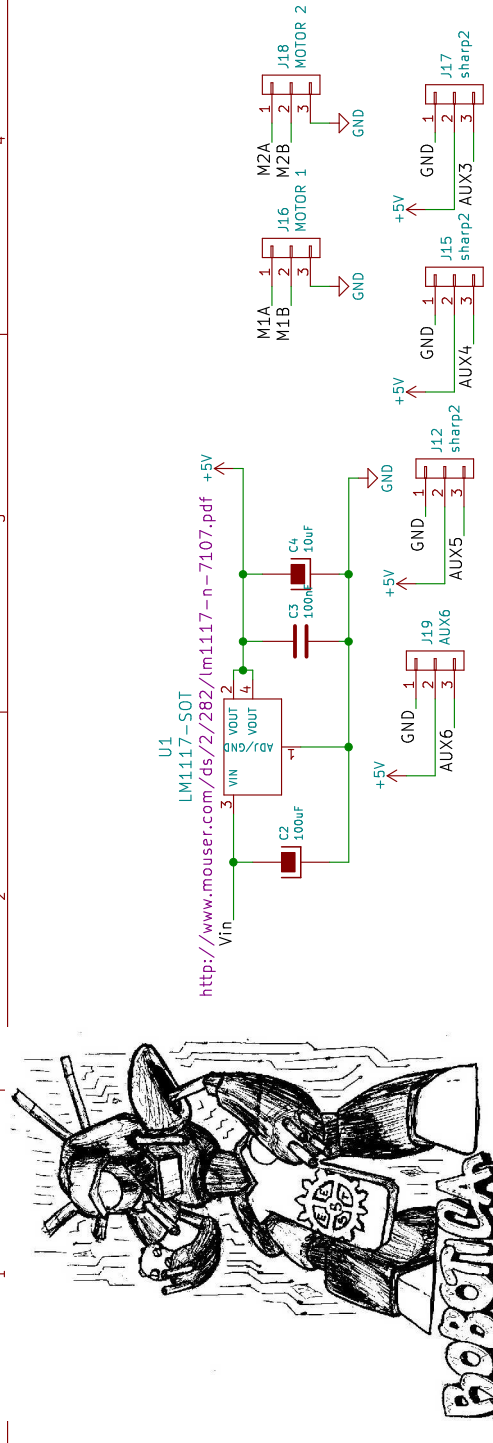
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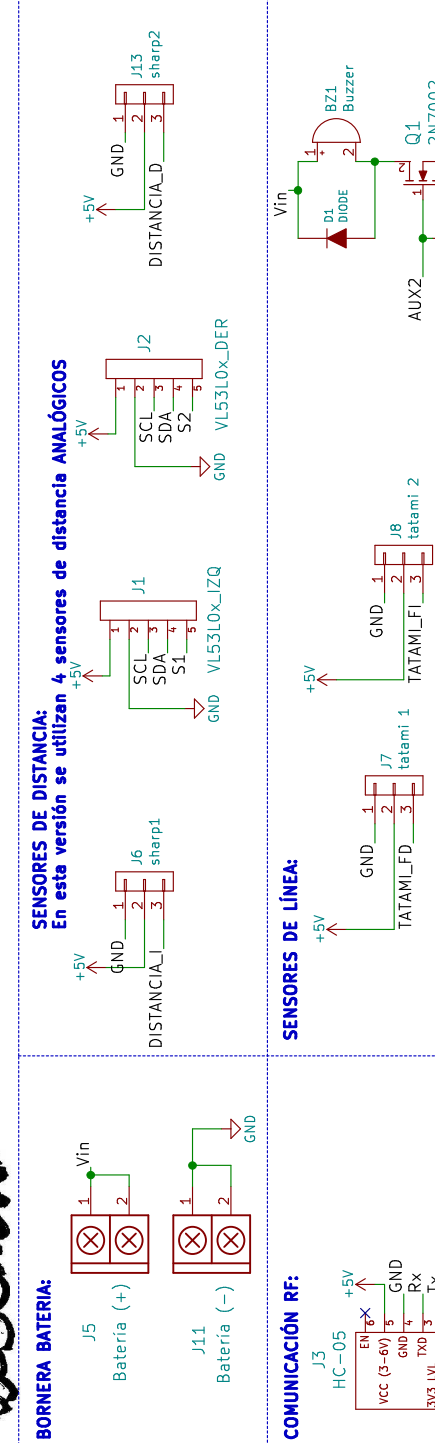
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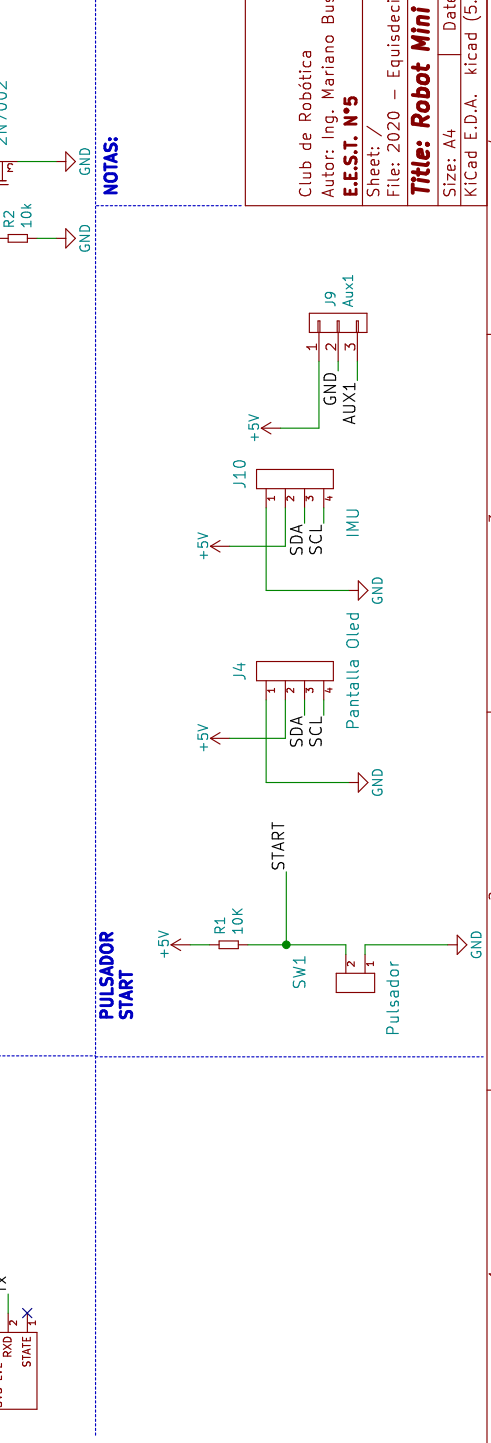
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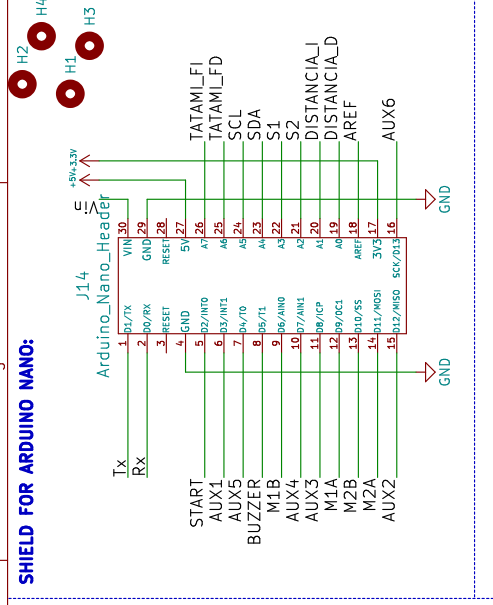
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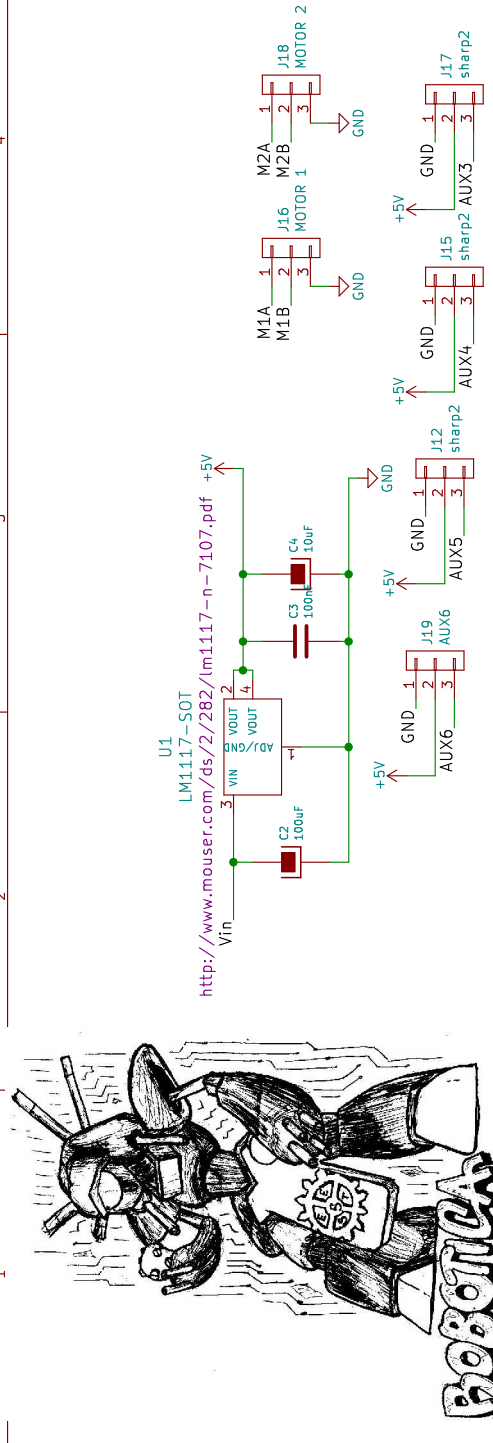
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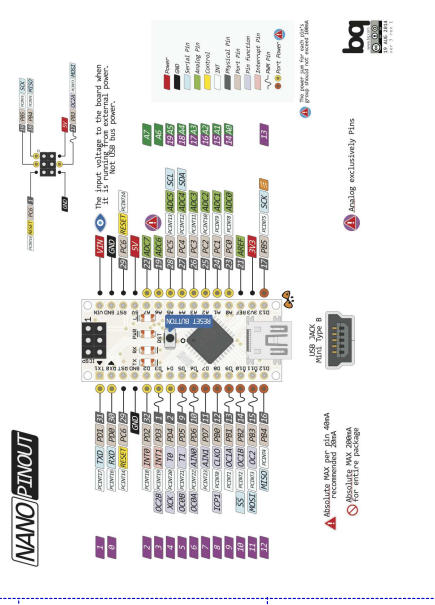
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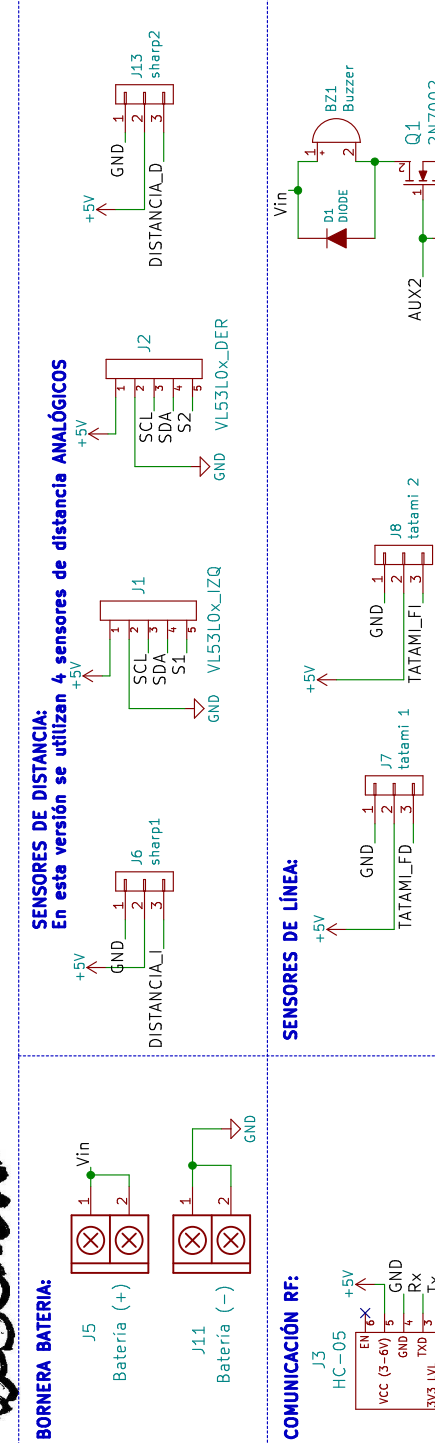
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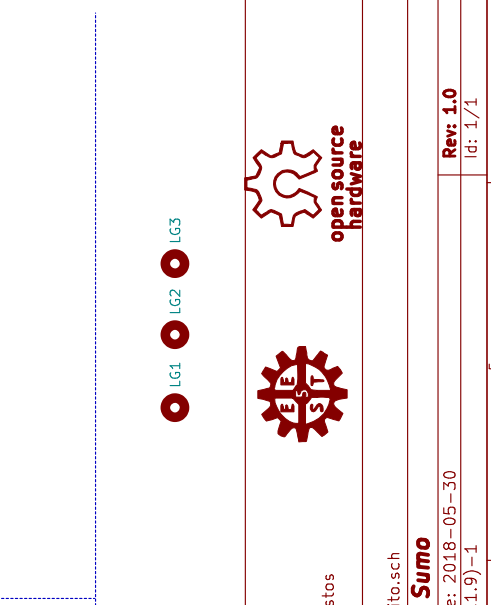


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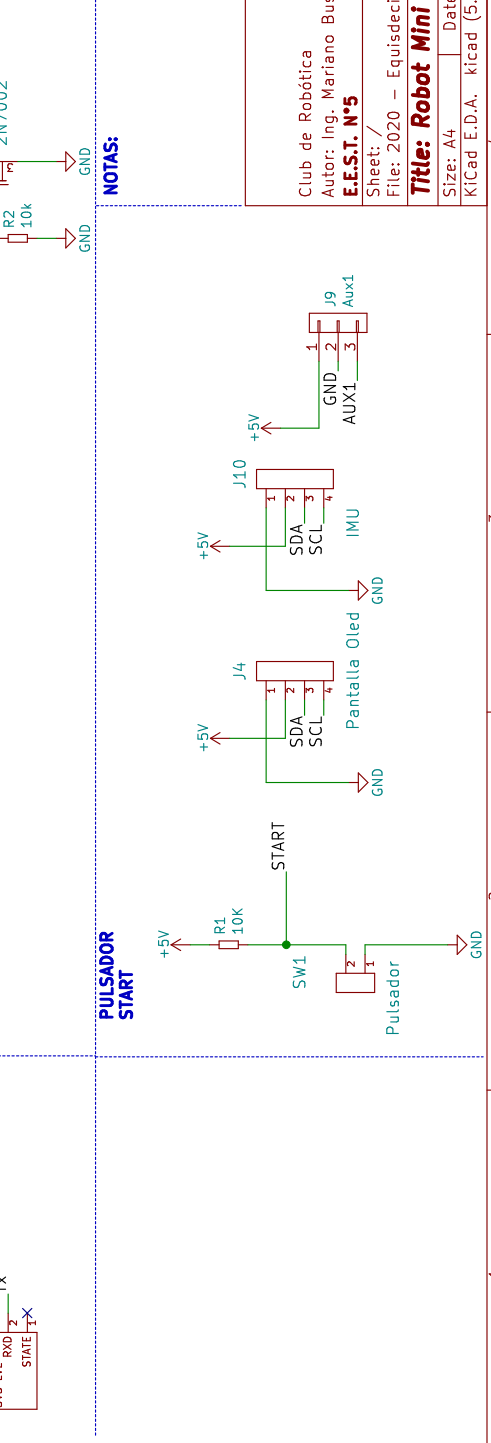


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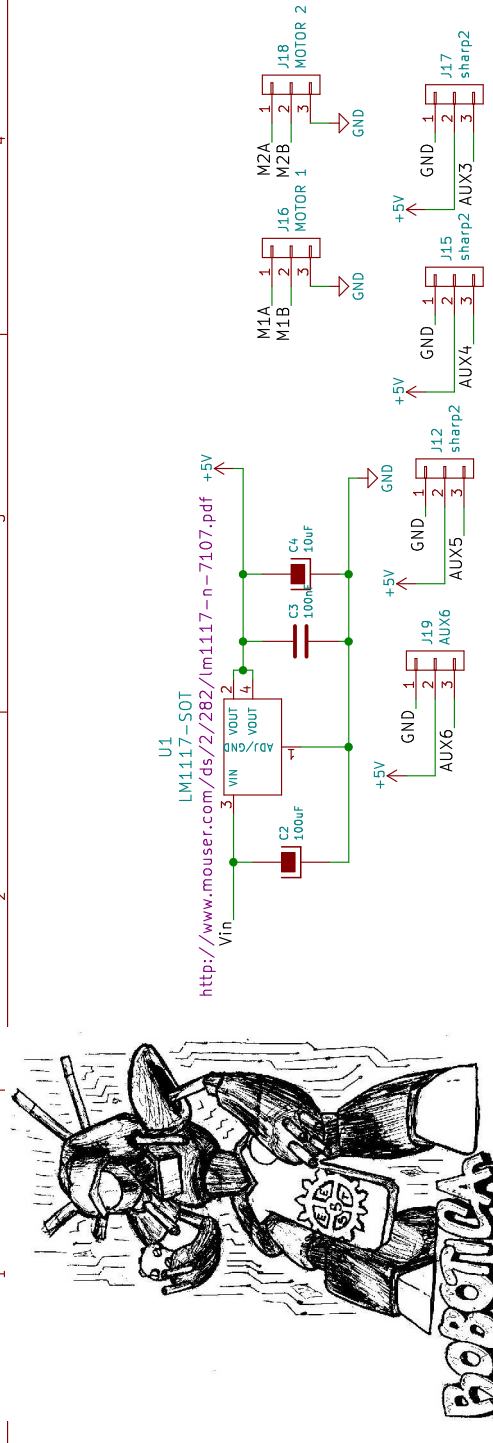
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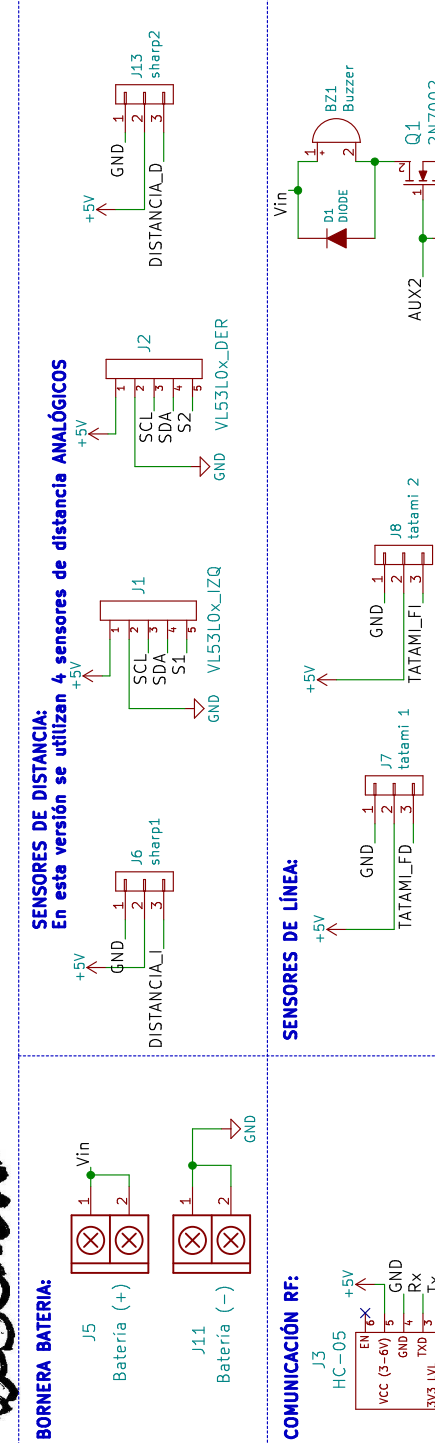
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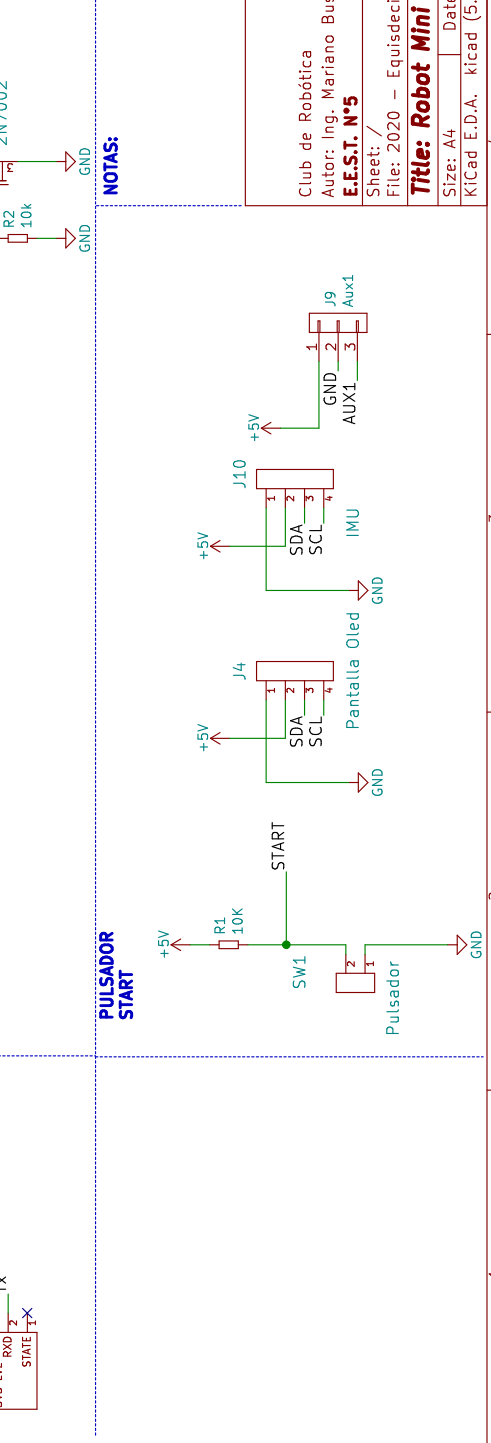
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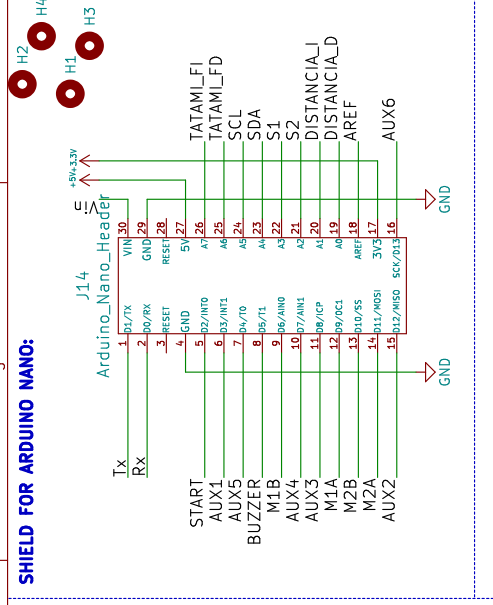
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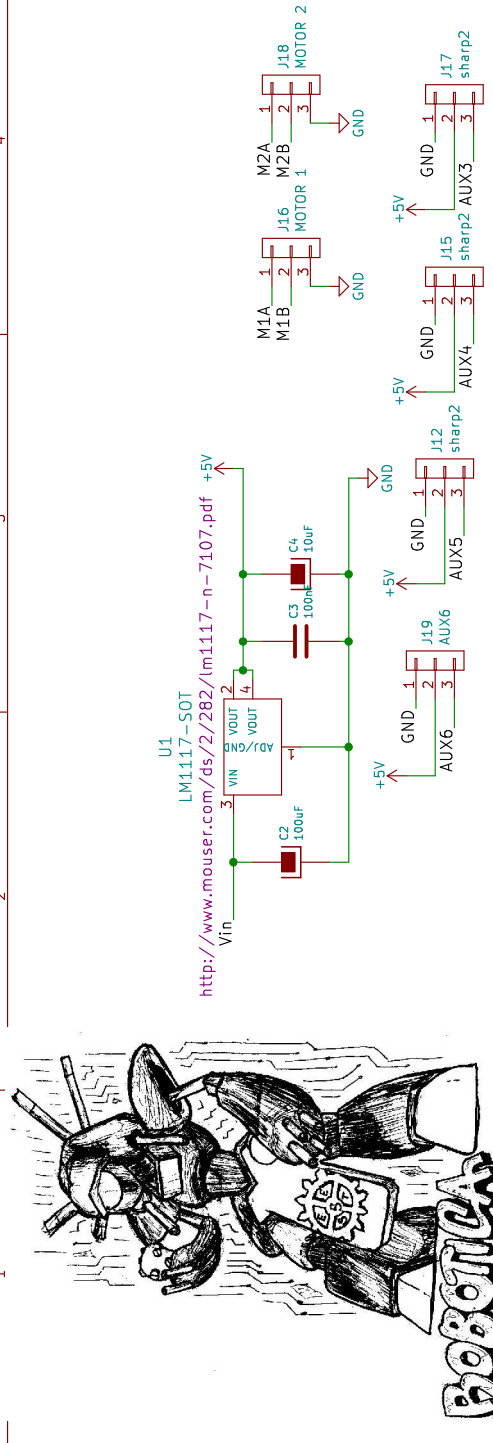
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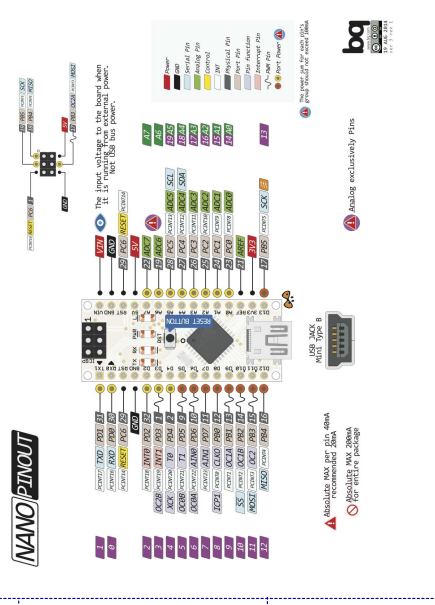
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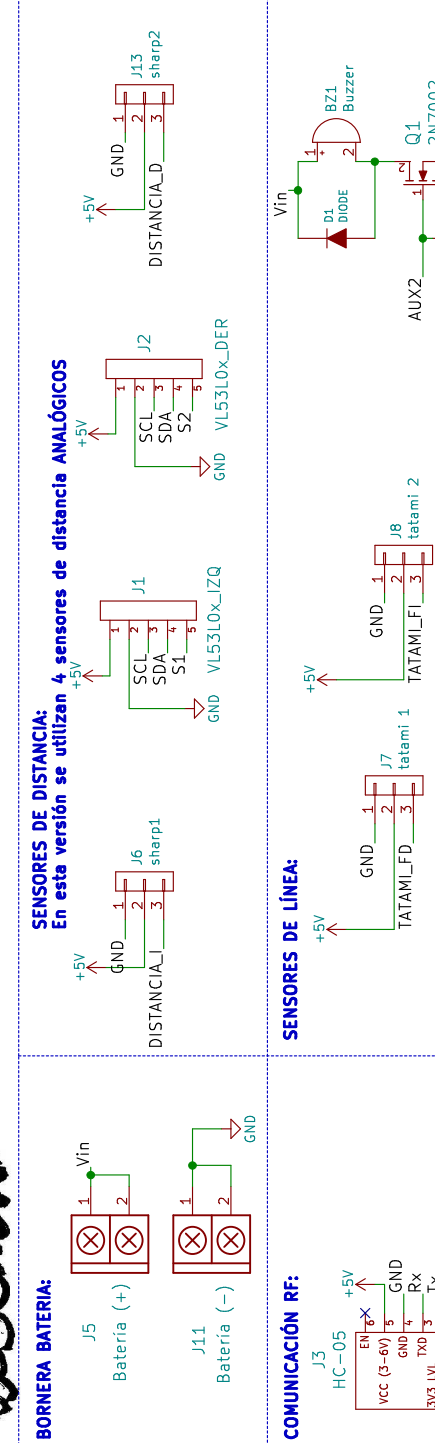
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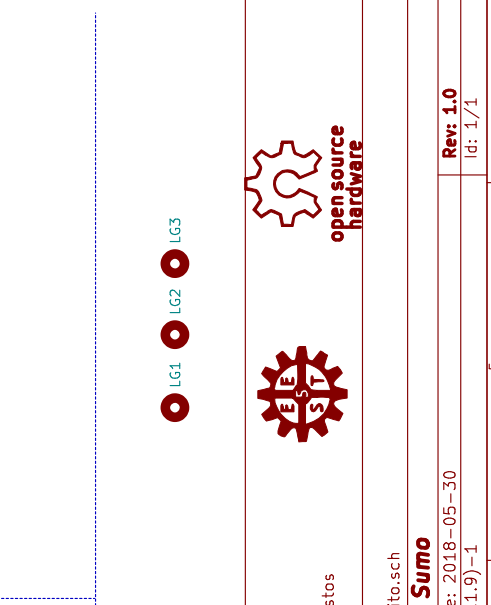


### COMUNICACIÓN RF:

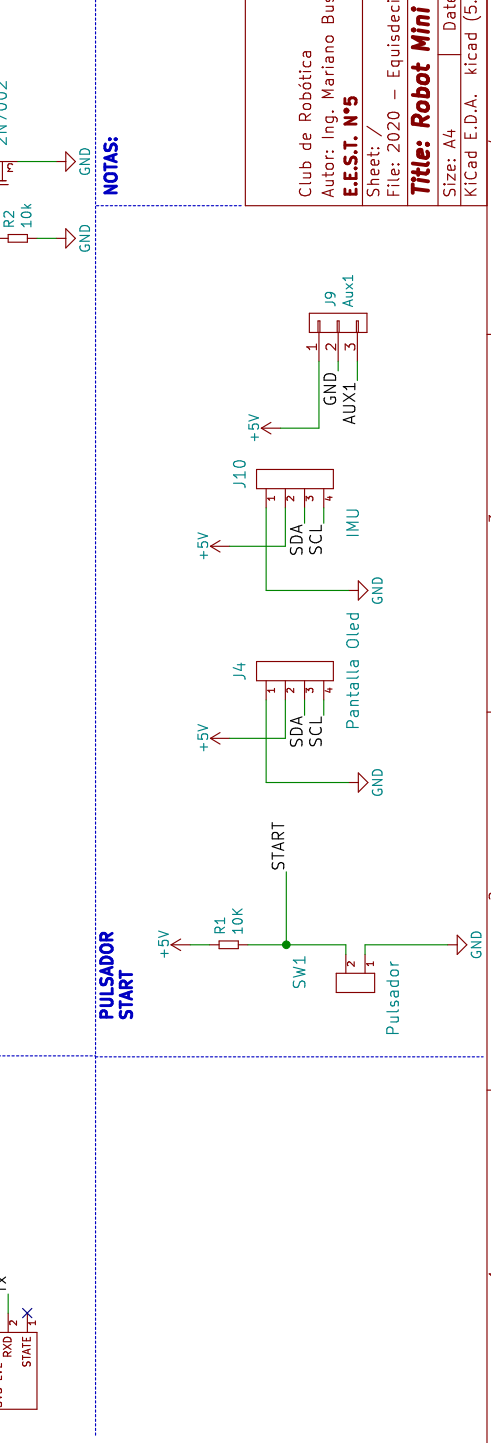


### SENSORES DE DISTANCIA:

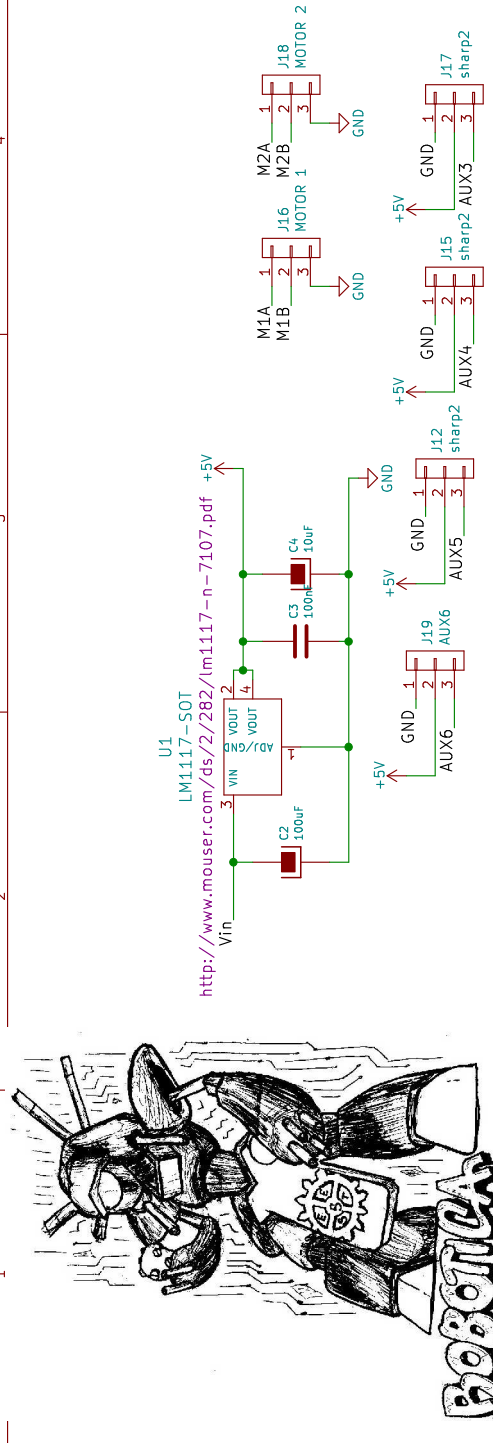
En esta versión se utilizan 4 sensores de distancia ANALÓGICOS



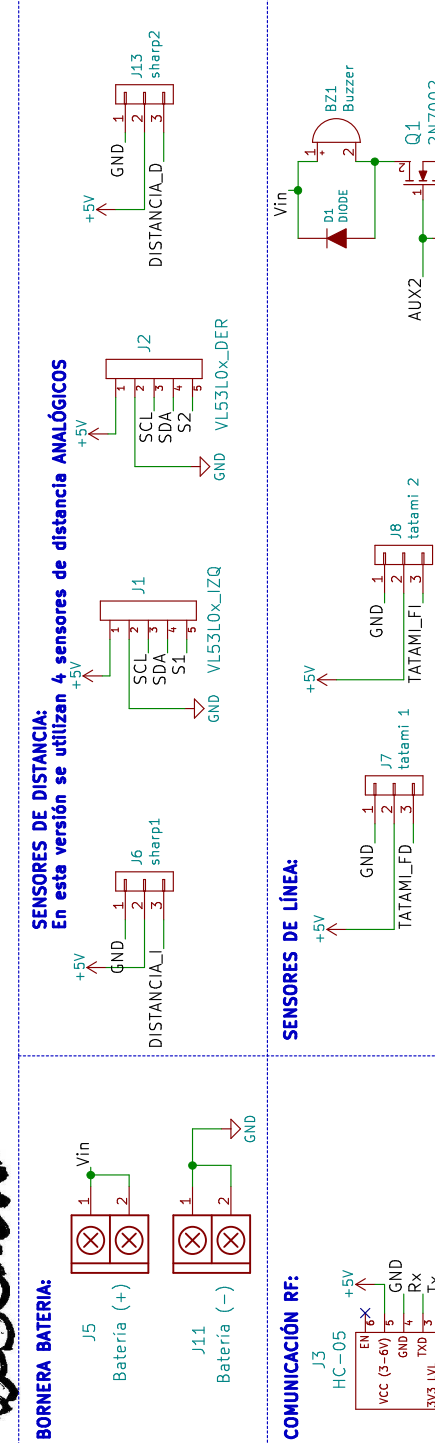
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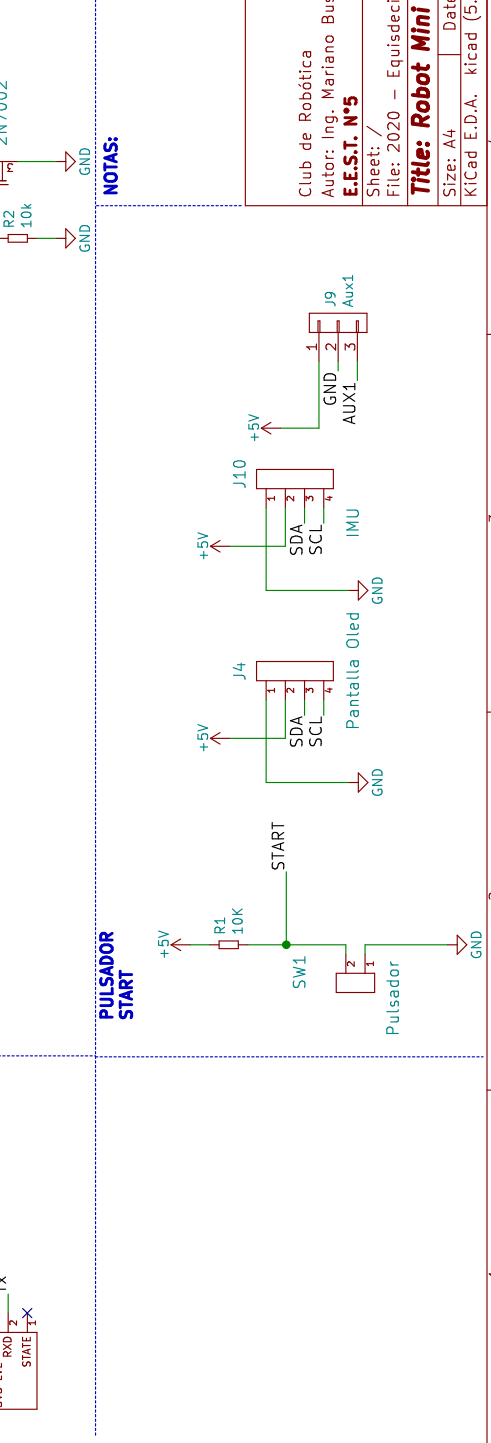
### PULSADOR START:



### NOTAS:



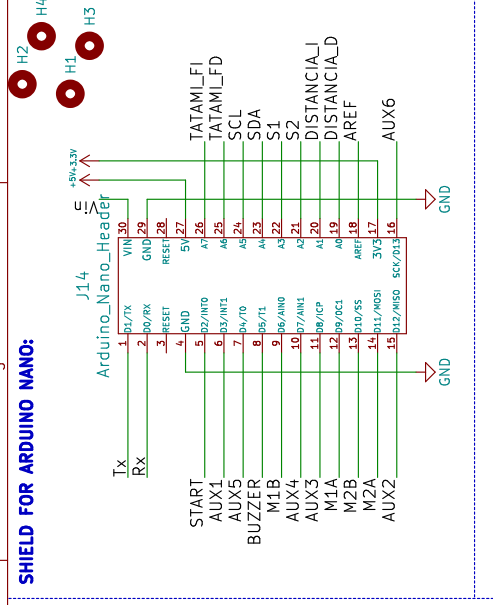
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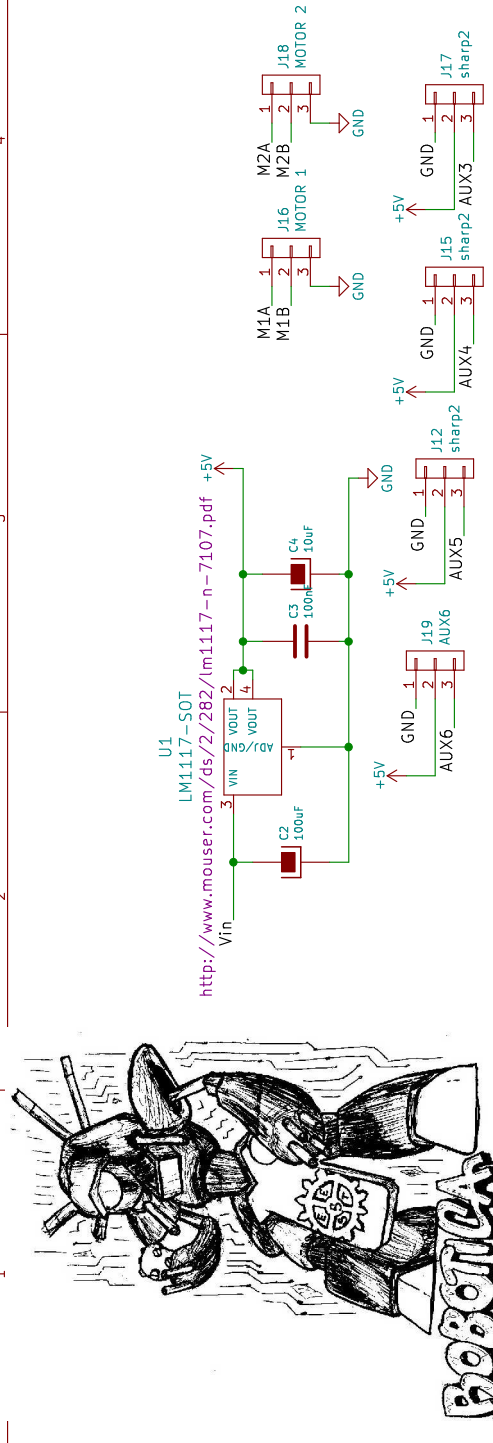
Club de Robótica  
Autor: Ing. Mariano Bustos  
**E.E.S.T. N°5**  
Sheet: /  
File: 2020 - Equisdecito.sch  
**Title: Robot Mini Sumo**  
Size: A4 Date: 2018-05-30  
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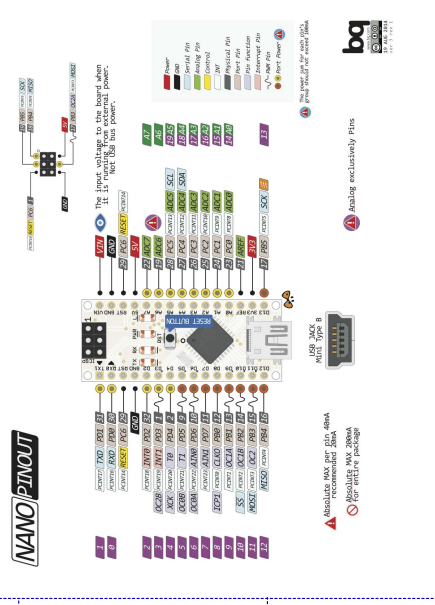
Rev: 1.0  
Id: 1/1



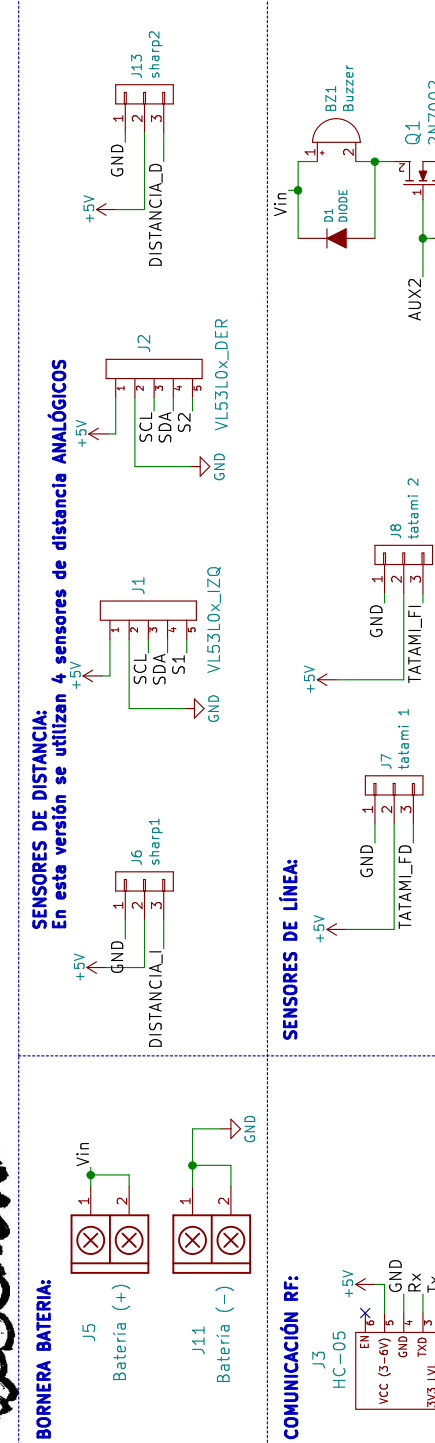
### SHIELD FOR ARDUINO NANO:



### BORNERA BATERIA:

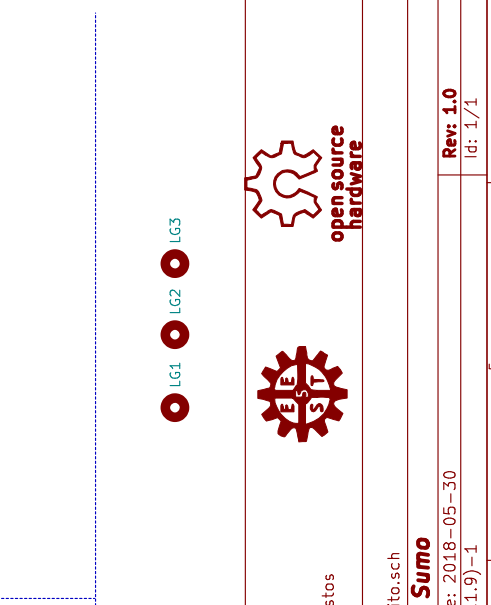


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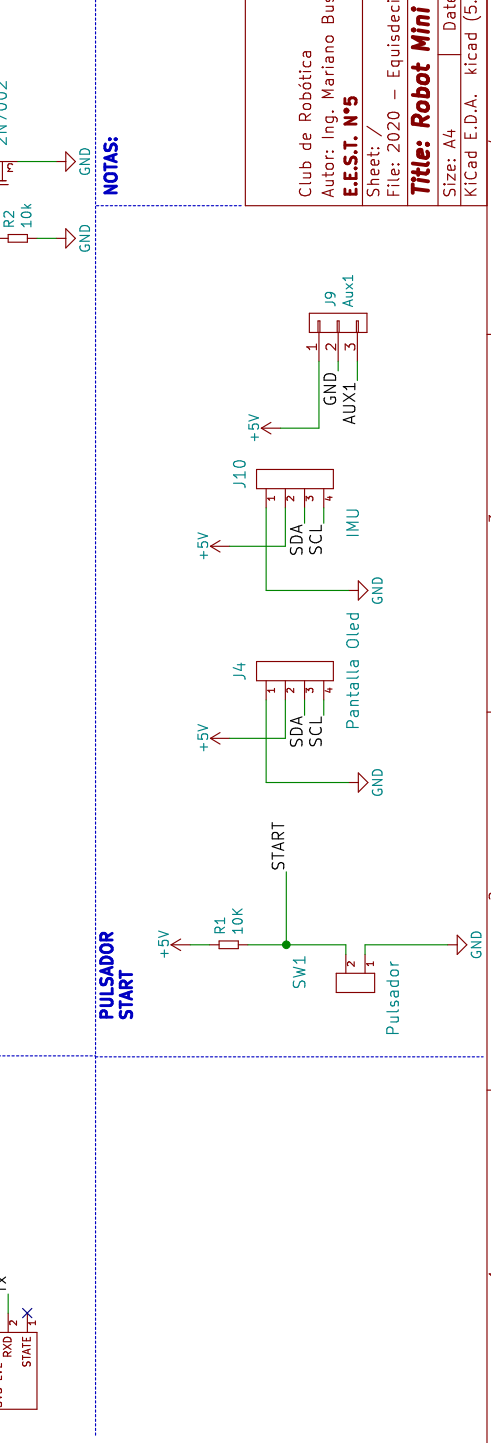


### SENSORES DE DISTANCIA:

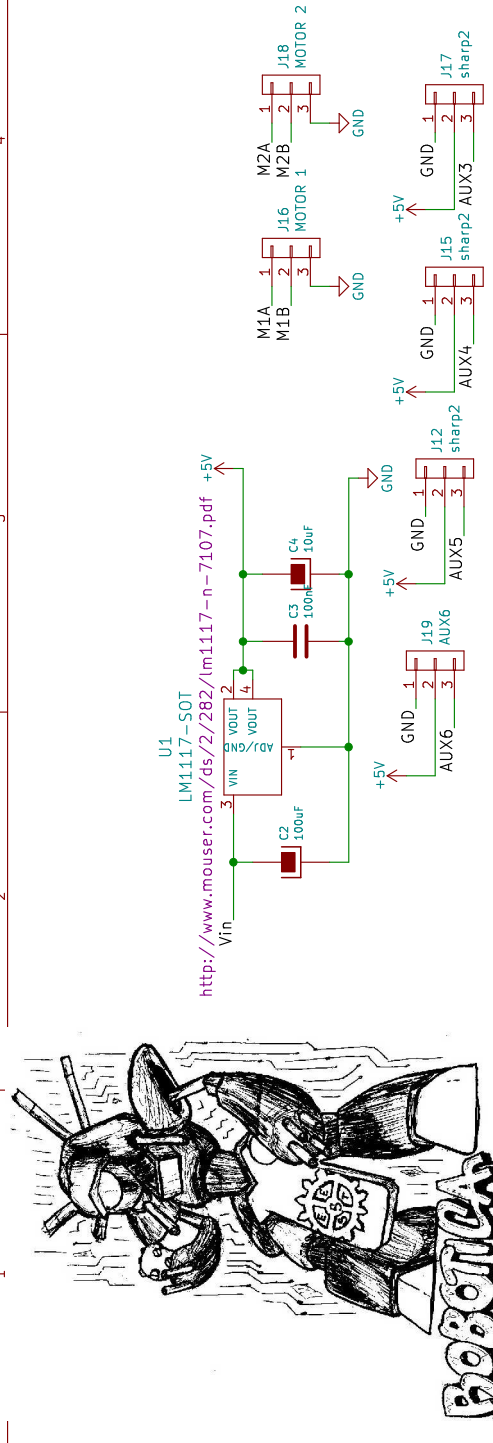
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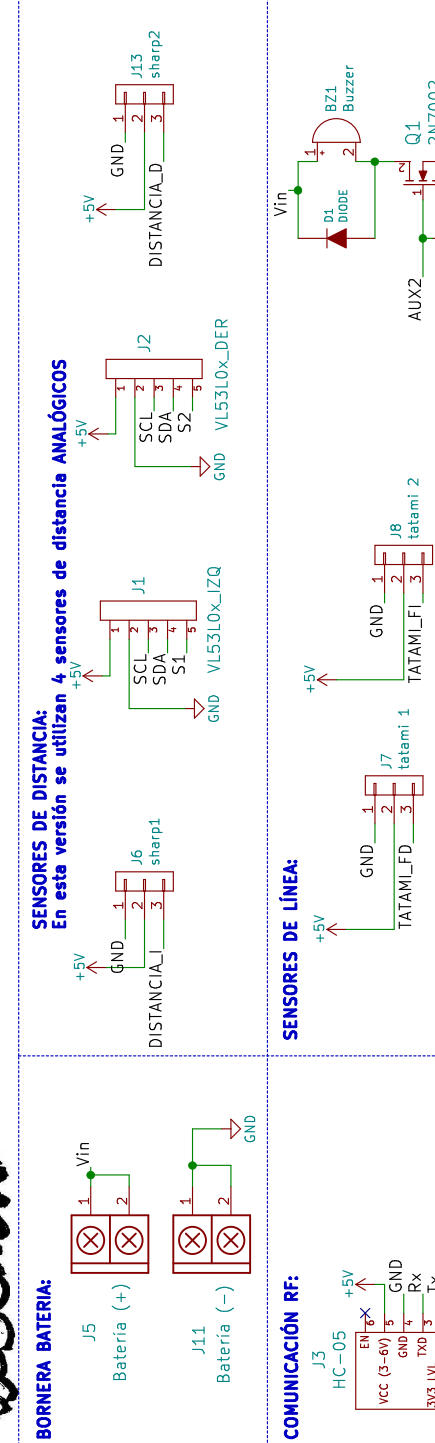
### SENSORES DE LÍNEA:



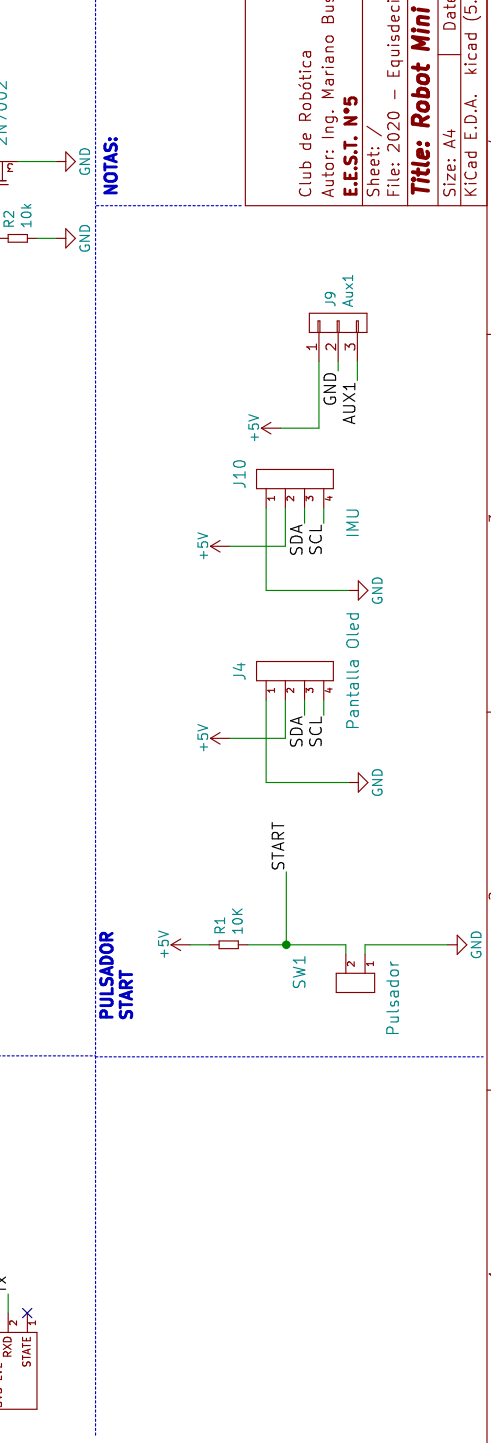
### PULSADOR START:



### NOTAS:



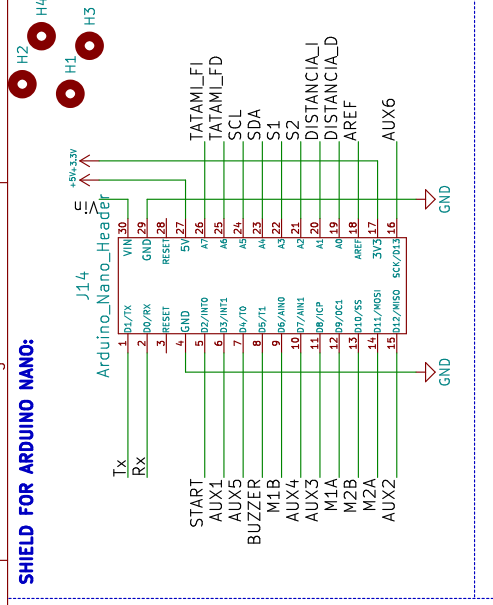
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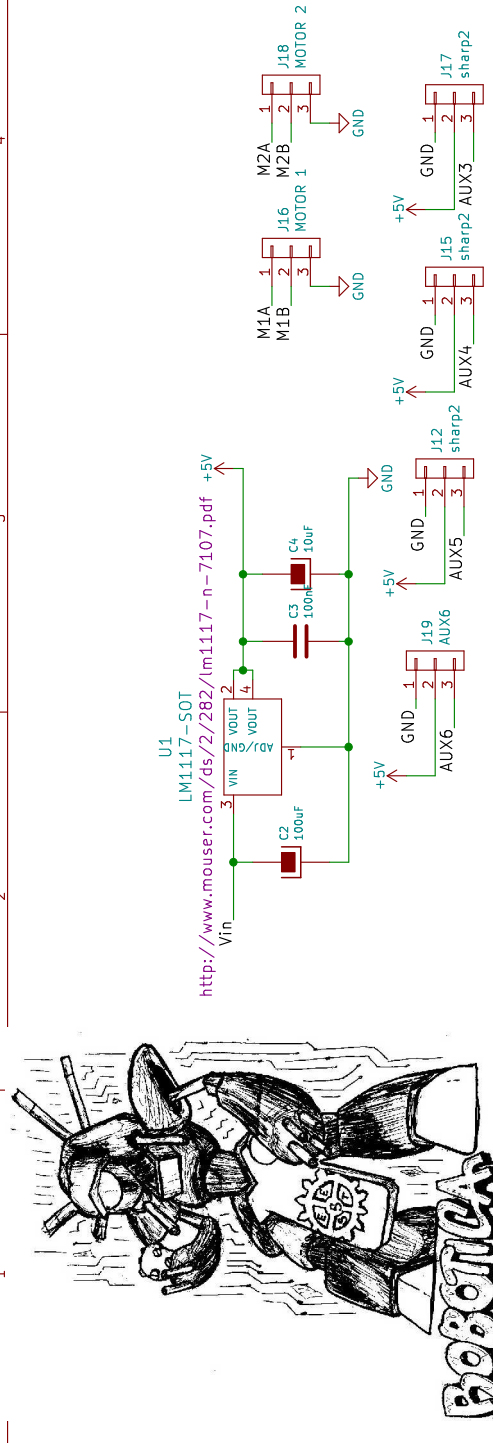
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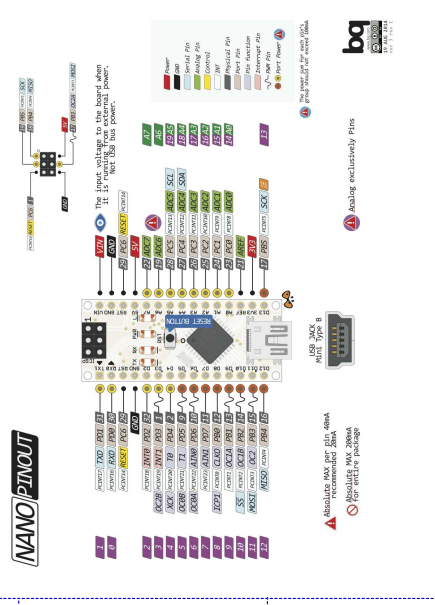
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Id: 1/1



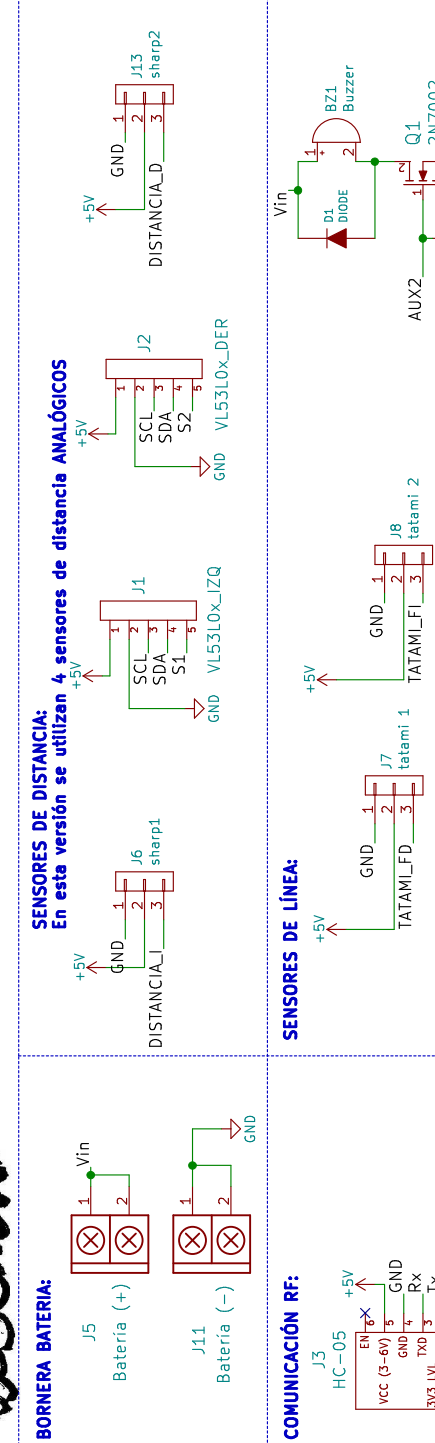
### SHIELD FOR ARDUINO NANO:



### BORNERA BATERIA:

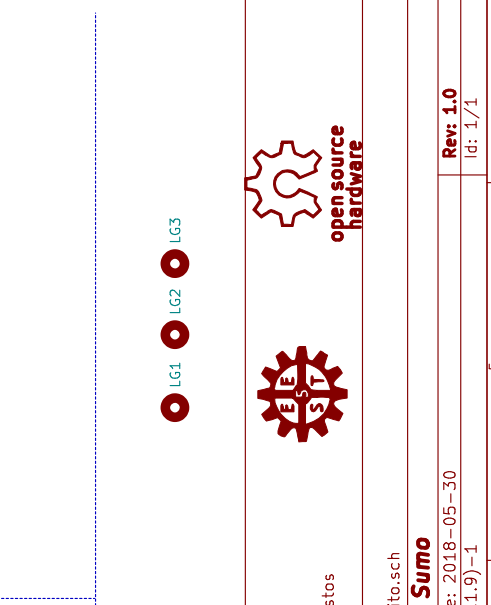


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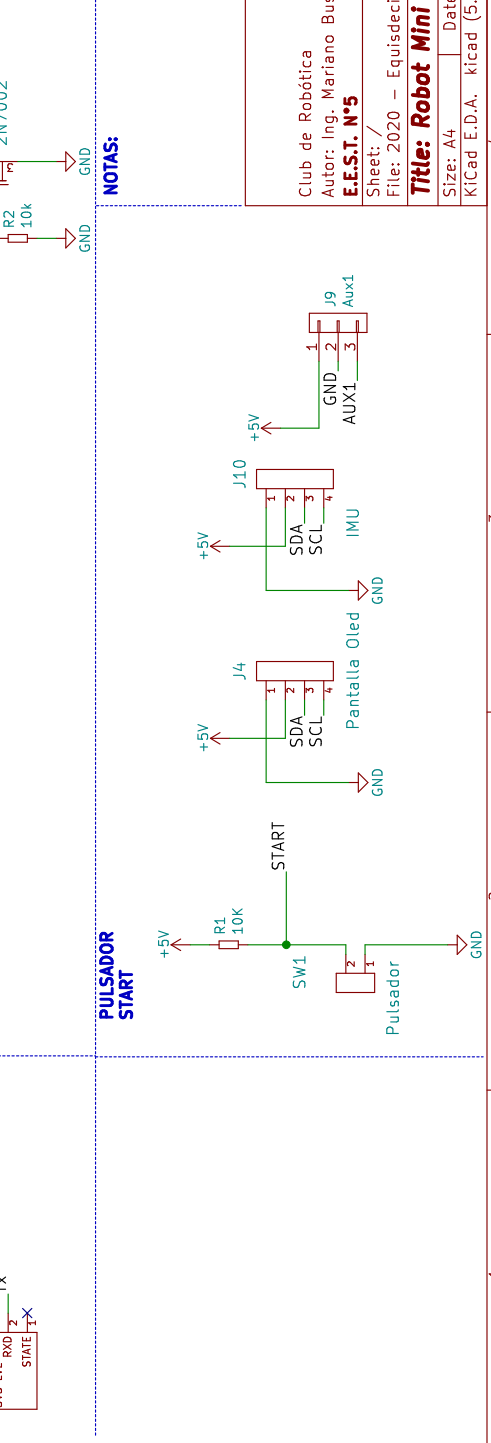


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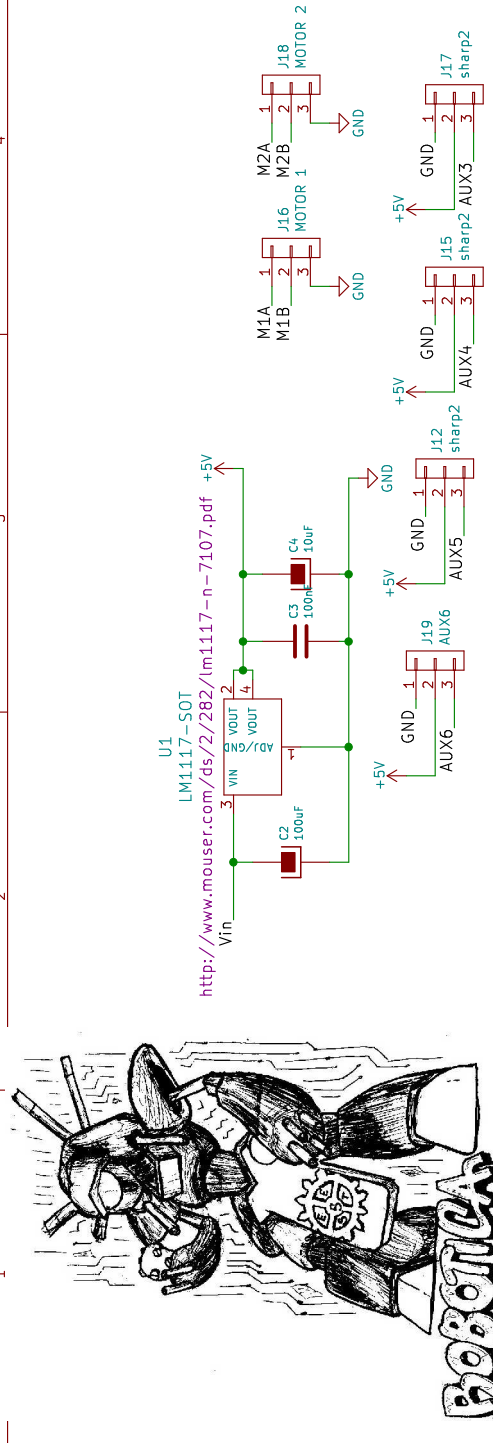
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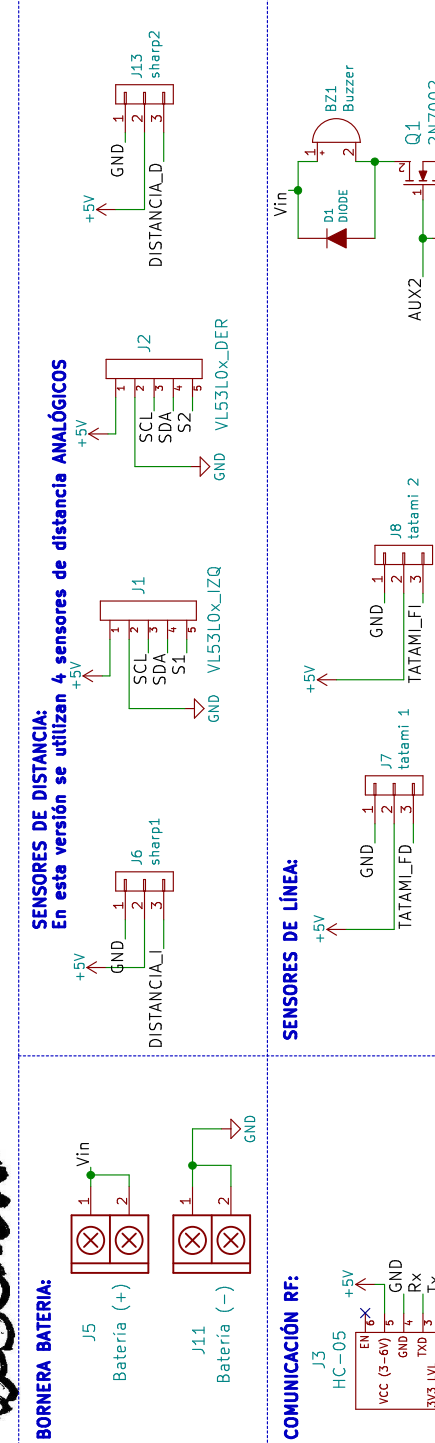
### SENSORES DE LÍNEA:



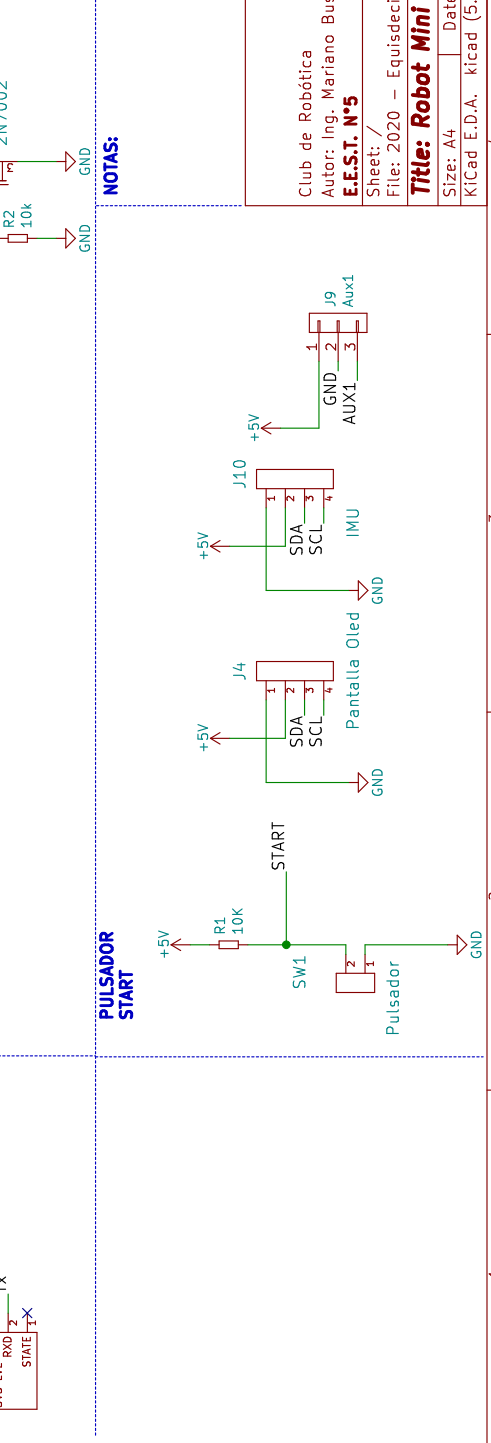
### PULSADOR START:



### NOTAS:



### NOTAS:



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