Lab3

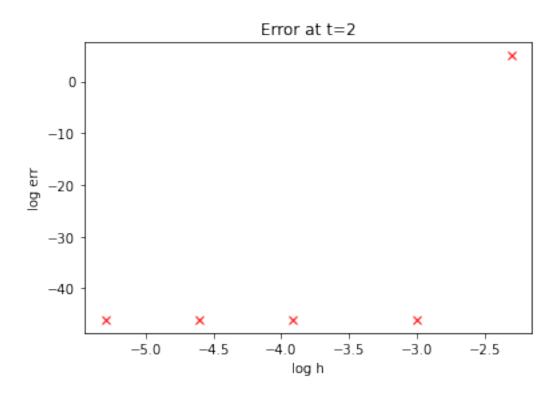
December 6, 2020

```
[330]: #*#*#*#*#*#*#*#*#
      #* Q1 *#
      #*#*#*#*#*#*#*#
      # Cauchy Problem
      # y'(x) = lambda y(x)
      \# y(0) = y0
      def forward_euler(h,y0,lamb):
          y0 = y0 + h*np.dot(lamb, y0)
          return y0
      def backward_euler(h, y0, lamb):
          # Implement Newton's Iteration
          y1 = forward_euler(h, y0, lamb) # Initial value for Newton Iteration
          g = y1-y0-h*lamb*y1
          g_prime = 1-h*lamb**2*y1
          for i in range(0,1000):
              y0 = y1
              y1 = y0 - g/g\_prime
              g = y1-y0-h*lamb*y1
              g_{prime} = 1-h*lamb**2*y1
          return y1
```

```
lamb = -23
h = 0.1
x = np.arange(0,2,h)+h
y = np.ones(x.shape[0]+1)
for i in range(0,x.shape[0]):
    y[i+1] = forward_euler(h, y[i], lamb)
err = np.log(np.abs(y[0:x.shape[0]]-np.exp(lamb*x)))
e1 = err[x.shape[0]-1]
\# 2a) h = 0.05
h = 0.05
x = np.arange(0,2,h)+h
y = np.ones(x.shape[0]+1)
for i in range(0,x.shape[0]):
    y[i+1] = forward_euler(h, y[i], lamb)
err = np.log(np.abs(y[0:x.shape[0]]-np.exp(lamb*x)))
e2 = err[x.shape[0]-1]
\# 2a) h = 0.02
h = 0.02
x = np.arange(0,2,h)+h
y = np.ones(x.shape[0]+1)
for i in range(1,x.shape[0]):
    y[i+1] = forward_euler(h, y[i], lamb)
err = np.log(np.abs(y[0:x.shape[0]]-np.exp(lamb*x)))
e3 = err[x.shape[0]-1]
\# 2a) h = 0.01
h = 0.01
x = np.arange(0,2,h)+h
y = np.ones(x.shape[0]+1)
for i in range(0,x.shape[0]):
    y[i+1] = y[i] + h*lamb*y[i]
```

```
err = np.log(np.abs(y[0:x.shape[0]]-np.exp(lamb*x)))
e4 = err[x.shape[0]-1]
\# 2a) h = 0.005
h = 0.005
x = np.arange(0,2,h)+h
y = np.ones(x.shape[0]+1)
for i in range(0,x.shape[0]):
    y[i+1] = forward_euler(h, y[i], lamb)
err = np.log(np.abs(y[0:x.shape[0]]-np.exp(lamb*x)))
e5 = err[x.shape[0]-1]
plt.plot(np.log([0.1,0.05,0.02,0.01,0.005]),[e1,e2,e3,e4,e5],'rx')
plt.xlabel("log h")
plt.ylabel("log err")
plt.title('Lambda = -23')
plt.title("Error at t=2")
## We can see that the approximations errors are getting small as
## stepsize h becomes small.
```

[331]: Text(0.5, 1.0, 'Error at t=2')



```
[]:
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[]:
[332]: # 2a) lamb = 1; h = 0.1
lamb = 1
h = 0.1
x = np.arange(0,2,h)+h
y = np.ones(x.shape[0]+1)

for i in range(0,x.shape[0]):
    y[i+1] = forward_euler(h, y[i], lamb)
err = np.log(np.abs(y[0:x.shape[0]]-np.exp(lamb*x)))
e1 = err[x.shape[0]-1]

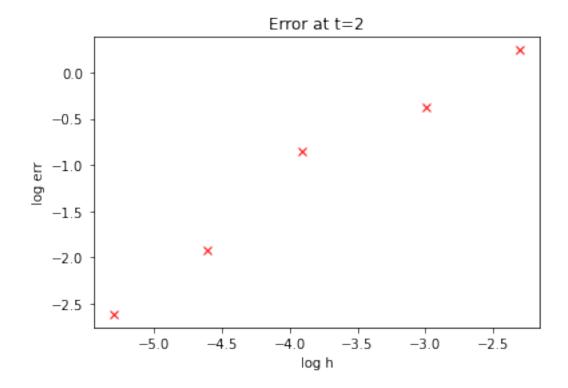
# 2a) lamb = 1; h = 0.05
```

```
h = 0.05
x = np.arange(0,2,h)+h
y = np.ones(x.shape[0]+1)
for i in range(0,x.shape[0]):
    y[i+1] = forward_euler(h, y[i], lamb)
err = np.log(np.abs(y[0:x.shape[0]]-np.exp(lamb*x)))
e2 = err[x.shape[0]-1]
# 2a) lamb = 1; h = 0.02
h = 0.02
x = np.arange(0,2,h)+h
y = np.ones(x.shape[0]+1)
for i in range(1,x.shape[0]):
    y[i+1] = forward_euler(h, y[i], lamb)
err = np.log(np.abs(y[0:x.shape[0]]-np.exp(lamb*x)))
e3 = err[x.shape[0]-1]
# 2a) lamb = 1; h = 0.01
h = 0.01
x = np.arange(0,2,h)+h
y = np.ones(x.shape[0]+1)
for i in range(0,x.shape[0]):
    y[i+1] = y[i] + h*lamb*y[i]
err = np.log(np.abs(y[0:x.shape[0]]-np.exp(lamb*x)))
e4 = err[x.shape[0]-1]
\# 2a) lamb = 1; h = 0.005
h = 0.005
x = np.arange(0,2,h)+h
y = np.ones(x.shape[0]+1)
for i in range(0,x.shape[0]):
    y[i+1] = forward_euler(h, y[i], lamb)
err = np.log(np.abs(y[0:x.shape[0]]-np.exp(lamb*x)))
e5 = err[x.shape[0]-1]
```

```
plt.plot(np.log([0.1,0.05,0.02,0.01,0.005]),[e1,e2,e3,e4,e5],'rx')
plt.xlabel("log h")
plt.ylabel("log err")
plt.title('Lambda = 1')
plt.title("Error at t=2")

## We can see that the approximations errors are getting small as
## stepsize h becomes small.
```

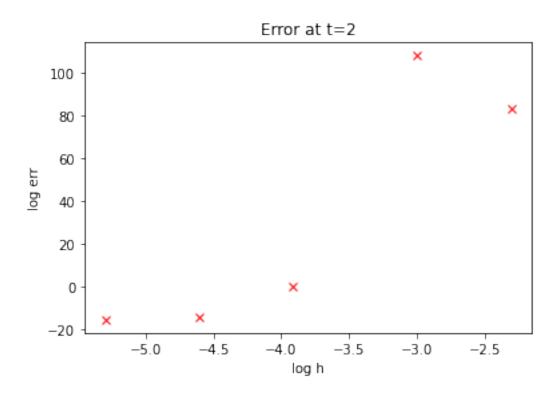
[332]: Text(0.5, 1.0, 'Error at t=2')



```
[333]: \# 2a) lamb = diag(-1, -100); h = 0.1
       lamb = np.diag([+1,-100])
       h = 0.1
       x = np.arange(0,2,h)+h
       y = np.ones([x.shape[0]+1,2])
       for i in range(0,x.shape[0]):
           y[i+1,:] = forward_euler(h, y[i,:], lamb)
       err = np.log(np.abs(np.sum(y[0:x.shape[0],:]**2,axis=1)-(np.exp(-2*x)+np.
        \rightarrowexp(-200*x))))
       e1 = err[x.shape[0]-1]
       \# 2a) lamb = diag(-1,-100); h = 0.05
       lamb = np.diag([-1, -100])
       h = 0.05
       x = np.arange(0,2,h)+h
       y = np.ones([x.shape[0]+1,2])
       for i in range(0,x.shape[0]):
           y[i+1,:] = forward_euler(h, y[i,:], lamb)
       err = np.log(np.abs(np.sum(y[0:x.shape[0],:]**2,axis=1)-(np.exp(-2*x)+np.
        \rightarrow exp(-200*x)))
       e2 = err[x.shape[0]-1]
       \# 2a) lamb = diag(-1, -100); h = 0.02
       lamb = np.diag([-1,-100])
       h = 0.02
       x = np.arange(0,2,h)+h
       y = np.ones([x.shape[0]+1,2])
       for i in range(0,x.shape[0]):
           y[i+1,:] = forward_euler(h, y[i,:], lamb)
       err = np.log(np.abs(np.sum(y[0:x.shape[0],:]**2,axis=1)-(np.exp(-2*x)+np.
        \rightarrowexp(-200*x))))
       e3 = err[x.shape[0]-1]
```

```
\# 2a) lamb = diag(-1, -100); h = 0.01
lamb = np.diag([-1,-100])
h = 0.01
x = np.arange(0,2,h)+h
y = np.ones([x.shape[0]+1,2])
for i in range(0,x.shape[0]):
    y[i+1,:] = forward_euler(h, y[i,:], lamb)
\texttt{err} = \texttt{np.log(np.abs(np.sum(y[0:x.shape[0],:]**2,axis=1)-(np.exp(-2*x)+np.})
\rightarrow \exp(-200*x)))
e4 = err[x.shape[0]-1]
\# 2a) lamb = diag(-1,-100); h = 0.005
lamb = np.diag([-1,-100])
h = 0.005
x = np.arange(0,2,h)+h
y = np.ones([x.shape[0]+1,2])
for i in range(0,x.shape[0]):
    y[i+1,:] = forward_euler(h, y[i,:], lamb)
err = np.log(np.abs(np.sum(y[0:x.shape[0],:]**2,axis=1)-(np.exp(-2*x)+np.
\rightarrow \exp(-200*x)))
e5 = err[x.shape[0]-1]
plt.plot(np.log([0.1,0.05,0.02,0.01,0.005]),[e1,e2,e3,e4,e5],'rx')
plt.xlabel("log h")
plt.ylabel("log err")
plt.title("Error at t=2")
## We can see that the approximations errors are getting small as
## stepsize h becomes small.
```

[333]: Text(0.5, 1.0, 'Error at t=2')

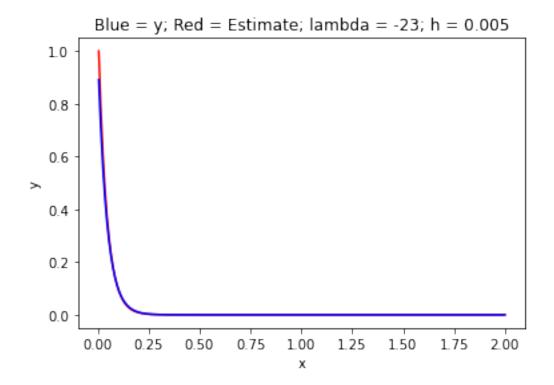


```
## We can see that the approximations are getting very close to the exact⊔

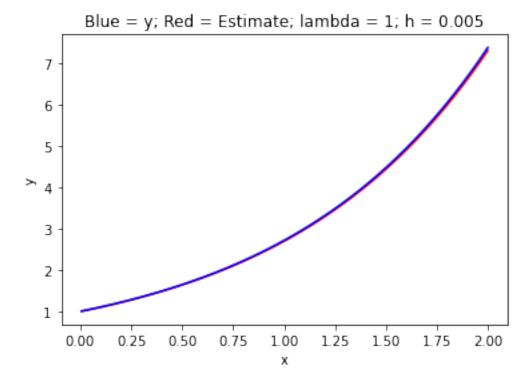
→values as

## stepsize h becomes small.
```

```
[334]: Text(0.5, 1.0, 'Blue = y; Red = Estimate; lambda = -23; h = 0.005')
```



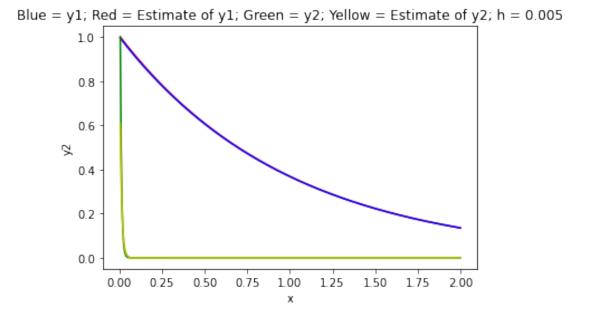
[335]: Text(0.5, 1.0, 'Blue = y; Red = Estimate; lambda = 1; h = 0.005')



```
[336]: # 2c) lamb = diag(-1,-100); h = 0.005
lamb = np.diag([-1,-100])
h = 0.005
x = np.arange(0,2,h)+h
y = np.ones([x.shape[0]+1,2])

for i in range(0,x.shape[0]):
    y[i+1,:] = forward_euler(h, y[i,:], lamb)
```

[336]: Text(0.5, 1.0, 'Blue = y1; Red = Estimate of y1; Green = y2; Yellow = Estimate of y2; h = 0.005')



```
[337]: #*#*#*#*#*#*#*#*#*#

#* Q3 *#

#*#*#*#*#*#*#*#*#*#*

# Runge-Kutta
```

```
def RK(h,y0,lamb):
   b1 = 0
    c2 = 0.5
    b2 = 1
   K1 = np.dot(lamb,y0)
   K2 = np.dot(lamb,(y0+h*c2*K1))
   y1 = y0+h*(b1*K1+b2*K2)
    return y1
def RK4(h,y0,lamb):
   c1 = 0
    c2 = 0.5
    c3 = 0.5
    c4 = 1
    b1 = 1/6
   b2 = 1/3
    b3 = 1/3
    b4 = 1/6
   K1 = np.dot(lamb,y0)
    K2 = np.dot(lamb,(y0+h*c2*K1))
   K3 = np.dot(lamb,(y0+h*c3*K2))
    K4 = np.dot(lamb,(y0+h*c4*K3))
    y1 = y0+h*(b1*K1+b2*K2+b3*K3+b4*K4)
    return y1
```

```
[338]: # 2-Stage Runge Kutta for Lambda = -23 with varying step size

lamb = -23

# 3a) h = 0.1
h = 0.1
x = np.arange(0,2,h)+h
y = np.ones(x.shape[0]+1)

for i in range(0,x.shape[0]):
    y[i+1] = RK(h, y[i], lamb)

err = np.log(np.abs(y[0:x.shape[0]]-np.exp(lamb*x)))
e1 = err[x.shape[0]-1]
```

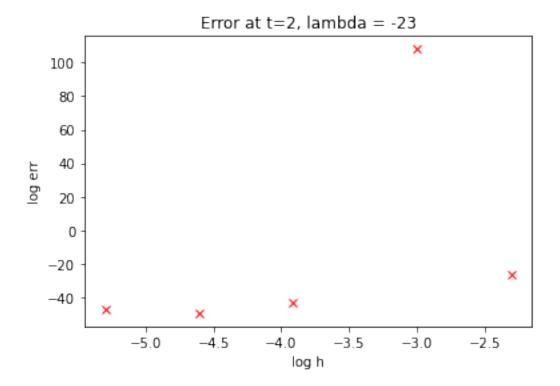
```
# 3a) h = 0.05
h = 0.05
x = np.arange(0,2,h)+h
y = np.ones(x.shape[0]+1)
for i in range(0,x.shape[0]):
    y[i+1] = RK(h, y[i], lamb)
err = np.log(np.abs(y[0:x.shape[0]]-np.exp(lamb*x)))
e1 = err[x.shape[0]-1]
# 3a) h = 0.02
h = 0.02
x = np.arange(0,2,h)+h
y = np.ones(x.shape[0]+1)
for i in range(0,x.shape[0]):
    y[i+1] = RK(h, y[i], lamb)
err = np.log(np.abs(y[0:x.shape[0]]-np.exp(lamb*x)))
e3 = err[x.shape[0]-1]
# 3a) h = 0.01
h = 0.001
x = np.arange(0,2,h)+h
y = np.ones(x.shape[0]+1)
for i in range(0,x.shape[0]):
    y[i+1] = RK(h, y[i], lamb)
err = np.log(np.abs(y[0:x.shape[0]]-np.exp(lamb*x)))
e4 = err[x.shape[0]-1]
# 3a) h = 0.005
h = 0.005
x = np.arange(0,2,h)+h
y = np.ones(x.shape[0]+1)
for i in range(0,x.shape[0]):
    y[i+1] = RK(h, y[i], lamb)
```

```
err = np.log(np.abs(y[0:x.shape[0]]-np.exp(lamb*x)))
e5 = err[x.shape[0]-1]

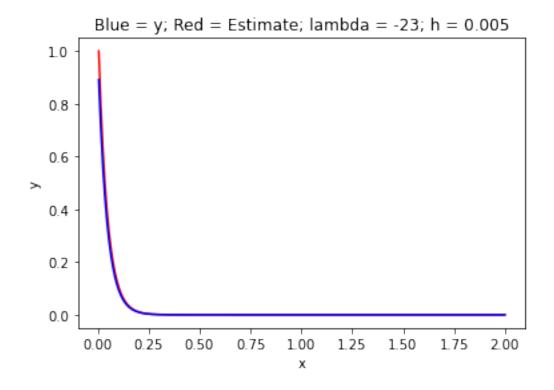
plt.plot(np.log([0.1,0.05,0.02,0.01,0.005]),[e1,e2,e3,e4,e5],'rx')
plt.xlabel("log h")
plt.ylabel("log err")
plt.title("Error at t=2, lambda = -23")

## We can see that the approximations errors are getting small as
## stepsize h becomes small.
```

[338]: Text(0.5, 1.0, 'Error at t=2, lambda = -23')



```
[339]: Text(0.5, 1.0, 'Blue = y; Red = Estimate; lambda = -23; h = 0.005')
```



```
[]:

[340]: # 2-Stage Runge Kutta for Lambda = 1 with varying step size

lamb = 1

# 3a) h = 0.1
h = 0.1
x = np.arange(0,2,h)+h
y = np.ones(x.shape[0]+1)

for i in range(0,x.shape[0]):
    y[i+1] = RK(h, y[i], lamb)

err = np.log(np.abs(y[0:x.shape[0]]-np.exp(lamb*x)))
e1 = err[x.shape[0]-1]
```

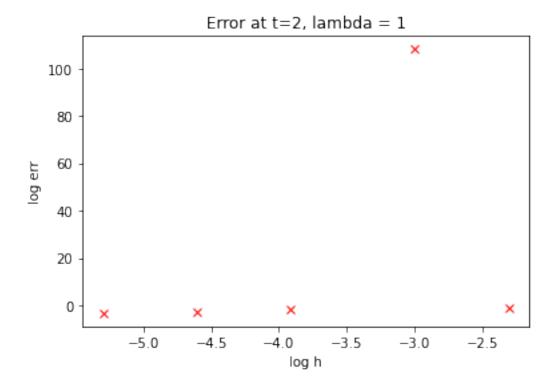
```
# 3a) h = 0.05
h = 0.05
x = np.arange(0,2,h)+h
y = np.ones(x.shape[0]+1)
for i in range(0,x.shape[0]):
    y[i+1] = RK(h, y[i], lamb)
err = np.log(np.abs(y[0:x.shape[0]]-np.exp(lamb*x)))
e1 = err[x.shape[0]-1]
# 3a) h = 0.02
h = 0.02
x = np.arange(0,2,h)+h
y = np.ones(x.shape[0]+1)
for i in range(0,x.shape[0]):
    y[i+1] = RK(h, y[i], lamb)
err = np.log(np.abs(y[0:x.shape[0]]-np.exp(lamb*x)))
e3 = err[x.shape[0]-1]
# 3a) h = 0.01
h = 0.01
x = np.arange(0,2,h)+h
y = np.ones(x.shape[0]+1)
for i in range(0,x.shape[0]):
    y[i+1] = RK(h, y[i], lamb)
err = np.log(np.abs(y[0:x.shape[0]]-np.exp(lamb*x)))
e4 = err[x.shape[0]-1]
# 3a) h = 0.005
h = 0.005
x = np.arange(0,2,h)+h
y = np.ones(x.shape[0]+1)
for i in range(0,x.shape[0]):
    y[i+1] = RK(h, y[i], lamb)
```

```
err = np.log(np.abs(y[0:x.shape[0]]-np.exp(lamb*x)))
e5 = err[x.shape[0]-1]

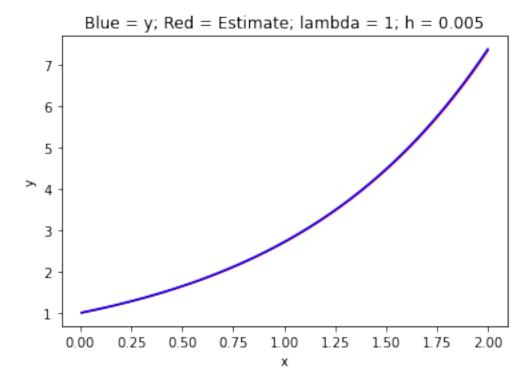
plt.plot(np.log([0.1,0.05,0.02,0.01,0.005]),[e1,e2,e3,e4,e5],'rx')
plt.xlabel("log h")
plt.ylabel("log err")
plt.title("Error at t=2, lambda = 1")

## We can see that the approximations errors are getting small as
## stepsize h becomes small.
```

[340]: Text(0.5, 1.0, 'Error at t=2, lambda = 1')



```
[341]: Text(0.5, 1.0, 'Blue = y; Red = Estimate; lambda = 1; h = 0.005')
```



```
y = np.ones([x.shape[0]+1,2])
for i in range(0,x.shape[0]):
    y[i+1,:] = RK(h, y[i,:], lamb)
err = np.log(np.abs(np.sum(y[0:x.shape[0],:]**2,axis=1)-(np.exp(-2*x)+np.
\rightarrow \exp(-200*x)))
e2 = err[x.shape[0]-1]
# 3a) h = 0.02
lamb = np.diag([-1,-100])
h = 0.02
x = np.arange(0,2,h)+h
y = np.ones([x.shape[0]+1,2])
for i in range(0,x.shape[0]):
    y[i+1,:] = RK(h, y[i,:], lamb)
err = np.log(np.abs(np.sum(y[0:x.shape[0],:]**2,axis=1)-(np.exp(-2*x)+np.
\rightarrow \exp(-200*x)))
e3 = err[x.shape[0]-1]
# 3a) h = 0.01
lamb = np.diag([-1,-100])
h = 0.01
x = np.arange(0,2,h)+h
y = np.ones([x.shape[0]+1,2])
for i in range(0,x.shape[0]):
    y[i+1,:] = RK(h, y[i,:], lamb)
err = np.log(np.abs(np.sum(y[0:x.shape[0],:]**2,axis=1)-(np.exp(-2*x)+np.
\rightarrow exp(-200*x)))
e4 = err[x.shape[0]-1]
# 3a) h = 0.005
lamb = np.diag([-1,-100])
h = 0.005
```

```
x = np.arange(0,2,h)+h
y = np.ones([x.shape[0]+1,2])

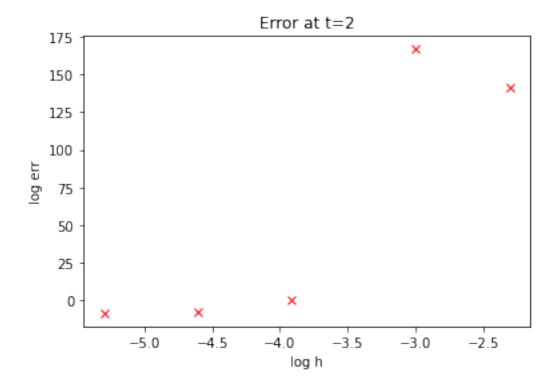
for i in range(0,x.shape[0]):
    y[i+1,:] = RK(h, y[i,:], lamb)

err = np.log(np.abs(np.sum(y[0:x.shape[0],:]**2,axis=1)-(np.exp(-2*x)+np.
    →exp(-200*x))))
e5 = err[x.shape[0]-1]

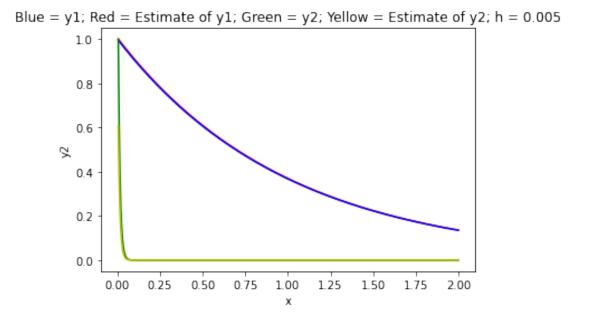
plt.plot(np.log([0.1,0.05,0.02,0.01,0.005]),[e1,e2,e3,e4,e5],'rx')
plt.xlabel("log h")
plt.ylabel("log err")
plt.title("Error at t=2")

## We can see that the approximations errors are getting small as
## stepsize h becomes small.
```

[342]: Text(0.5, 1.0, 'Error at t=2')



[343]: Text(0.5, 1.0, 'Blue = y1; Red = Estimate of y1; Green = y2; Yellow = Estimate of y2; h = 0.005')

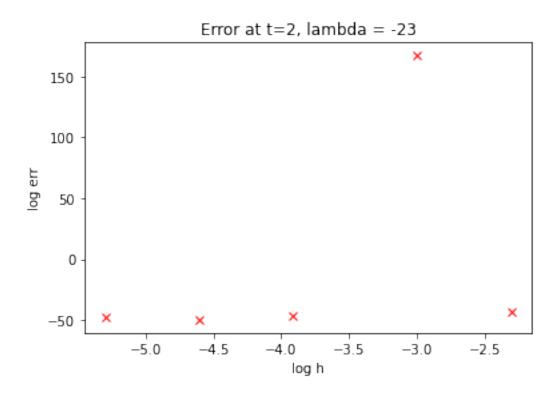


```
[]:
[344]: # 4-Stage Runge Kutta for Lambda = -23 with varying step size
```

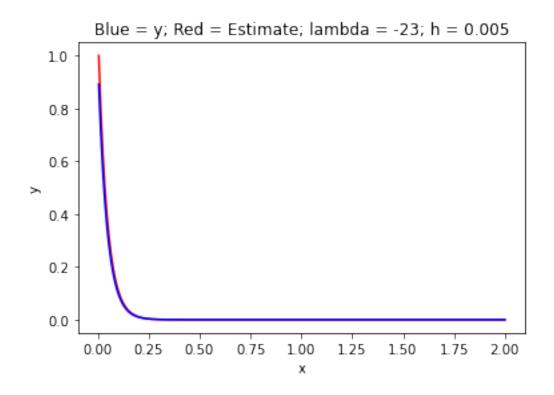
```
lamb = -23
# 3a) h = 0.1
h = 0.1
x = np.arange(0,2,h)+h
y = np.ones(x.shape[0]+1)
for i in range(0,x.shape[0]):
    y[i+1] = RK4(h, y[i], lamb)
err = np.log(np.abs(y[0:x.shape[0]]-np.exp(lamb*x)))
e1 = err[x.shape[0]-1]
# 3a) h = 0.05
h = 0.05
x = np.arange(0,2,h)+h
y = np.ones(x.shape[0]+1)
for i in range(0,x.shape[0]):
    y[i+1] = RK4(h, y[i], lamb)
err = np.log(np.abs(y[0:x.shape[0]]-np.exp(lamb*x)))
e1 = err[x.shape[0]-1]
# 3a) h = 0.02
h = 0.02
x = np.arange(0,2,h)+h
y = np.ones(x.shape[0]+1)
for i in range(0,x.shape[0]):
    y[i+1] = RK4(h, y[i], lamb)
err = np.log(np.abs(y[0:x.shape[0]]-np.exp(lamb*x)))
e3 = err[x.shape[0]-1]
# 3a) h = 0.01
h = 0.001
x = np.arange(0,2,h)+h
y = np.ones(x.shape[0]+1)
for i in range(0,x.shape[0]):
    y[i+1] = RK4(h, y[i], lamb)
```

```
err = np.log(np.abs(y[0:x.shape[0]]-np.exp(lamb*x)))
e4 = err[x.shape[0]-1]
# 3a) h = 0.005
h = 0.005
x = np.arange(0,2,h)+h
y = np.ones(x.shape[0]+1)
for i in range(0,x.shape[0]):
    y[i+1] = RK4(h, y[i], lamb)
err = np.log(np.abs(y[0:x.shape[0]]-np.exp(lamb*x)))
e5 = err[x.shape[0]-1]
plt.plot(np.log([0.1,0.05,0.02,0.01,0.005]),[e1,e2,e3,e4,e5],'rx')
plt.xlabel("log h")
plt.ylabel("log err")
plt.title("Error at t=2, lambda = -23")
## We can see that the approximations errors are getting small as
## stepsize h becomes small.
```

[344]: Text(0.5, 1.0, 'Error at t=2, lambda = -23')



[345]: Text(0.5, 1.0, 'Blue = y; Red = Estimate; lambda = -23; h = 0.005')



```
[]:
[350]: # 4-Stage Runge Kutta for Lambda = 1 with varying step size

lamb = 1

# 3a) h = 0.1

h = 0.1

x = np.arange(0,2,h)+h

y = np.ones(x.shape[0]+1)

for i in range(0,x.shape[0]):
 y[i+1] = RK4(h, y[i], lamb)

err = np.log(np.abs(y[0:x.shape[0]]-np.exp(lamb*x)))
e1 = err[x.shape[0]-1]

# 3a) h = 0.05

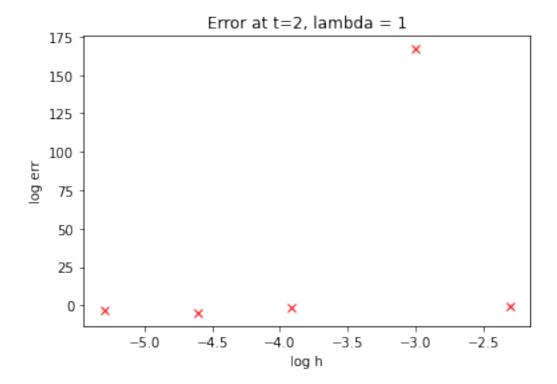
h = 0.05
```

```
x = np.arange(0,2,h)+h
y = np.ones(x.shape[0]+1)
for i in range(0,x.shape[0]):
    y[i+1] = RK4(h, y[i], lamb)
err = np.log(np.abs(y[0:x.shape[0]]-np.exp(lamb*x)))
e1 = err[x.shape[0]-1]
# 3a) h = 0.02
h = 0.02
x = np.arange(0,2,h)+h
y = np.ones(x.shape[0]+1)
for i in range(0,x.shape[0]):
    y[i+1] = RK4(h, y[i], lamb)
err = np.log(np.abs(y[0:x.shape[0]]-np.exp(lamb*x)))
e3 = err[x.shape[0]-1]
# 3a) h = 0.01
h = 0.001
x = np.arange(0,2,h)+h
y = np.ones(x.shape[0]+1)
for i in range(0,x.shape[0]):
    y[i+1] = RK4(h, y[i], lamb)
err = np.log(np.abs(y[0:x.shape[0]]-np.exp(lamb*x)))
e4 = err[x.shape[0]-1]
# 3a) h = 0.005
h = 0.005
x = np.arange(0,2,h)+h
y = np.ones(x.shape[0]+1)
for i in range(0,x.shape[0]):
    y[i+1] = RK4(h, y[i], lamb)
err = np.log(np.abs(y[0:x.shape[0]]-np.exp(lamb*x)))
e5 = err[x.shape[0]-1]
```

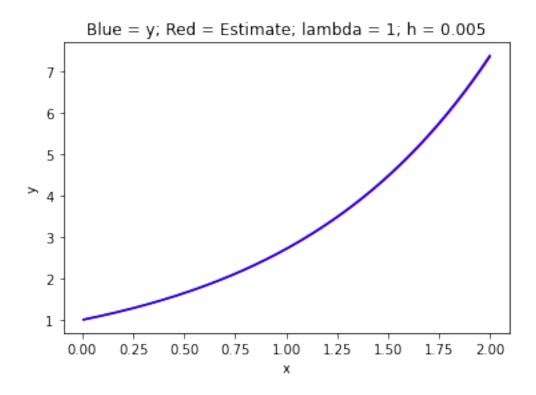
```
plt.plot(np.log([0.1,0.05,0.02,0.01,0.005]),[e1,e2,e3,e4,e5],'rx')
plt.xlabel("log h")
plt.ylabel("log err")
plt.title("Error at t=2, lambda = 1")

## We can see that the approximations errors are getting small as
## stepsize h becomes small.
```

[350]: Text(0.5, 1.0, 'Error at t=2, lambda = 1')



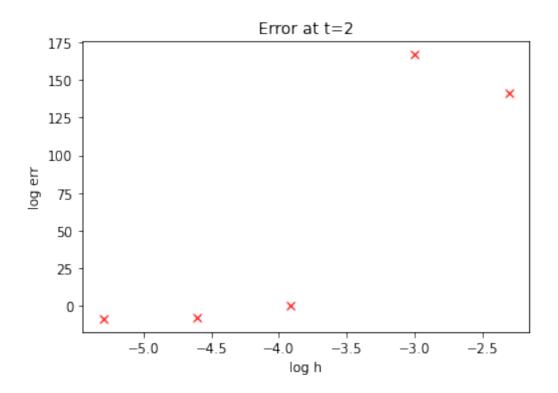
[351]: Text(0.5, 1.0, 'Blue = y; Red = Estimate; lambda = 1; h = 0.005')



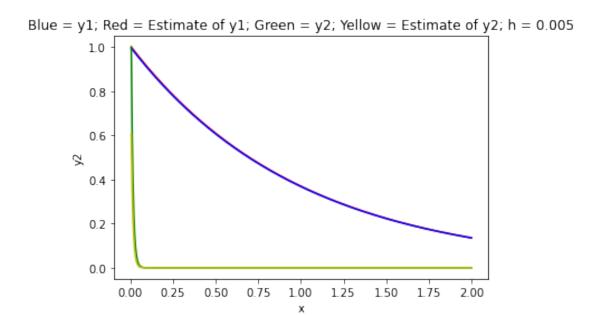
```
# 3a) h = 0.05
lamb = np.diag([-1,-100])
h = 0.05
x = np.arange(0,2,h)+h
y = np.ones([x.shape[0]+1,2])
for i in range(0,x.shape[0]):
    y[i+1,:] = RK(h, y[i,:], lamb)
err = np.log(np.abs(np.sum(y[0:x.shape[0],:]**2,axis=1)-(np.exp(-2*x)+np.
\rightarrow \exp(-200*x)))
e2 = err[x.shape[0]-1]
# 3a) h = 0.02
lamb = np.diag([-1,-100])
h = 0.02
x = np.arange(0,2,h)+h
y = np.ones([x.shape[0]+1,2])
for i in range(0,x.shape[0]):
    y[i+1,:] = RK(h, y[i,:], lamb)
err = np.log(np.abs(np.sum(y[0:x.shape[0],:]**2,axis=1)-(np.exp(-2*x)+np.
\rightarrow \exp(-200*x)))
e3 = err[x.shape[0]-1]
# 3a) h = 0.01
lamb = np.diag([-1,-100])
h = 0.01
x = np.arange(0,2,h)+h
y = np.ones([x.shape[0]+1,2])
for i in range(0,x.shape[0]):
    y[i+1,:] = RK(h, y[i,:], lamb)
err = np.log(np.abs(np.sum(y[0:x.shape[0],:]**2,axis=1)-(np.exp(-2*x)+np.
\rightarrowexp(-200*x))))
e4 = err[x.shape[0]-1]
```

```
# 3a) h = 0.005
lamb = np.diag([-1,-100])
h = 0.005
x = np.arange(0,2,h)+h
y = np.ones([x.shape[0]+1,2])
for i in range(0,x.shape[0]):
    y[i+1,:] = RK(h, y[i,:], lamb)
\texttt{err} = \texttt{np.log(np.abs(np.sum(y[0:x.shape[0],:]**2,axis=1)-(np.exp(-2*x)+np.})
\rightarrowexp(-200*x))))
e5 = err[x.shape[0]-1]
plt.plot(np.log([0.1,0.05,0.02,0.01,0.005]),[e1,e2,e3,e4,e5],'rx')
plt.xlabel("log h")
plt.ylabel("log err")
plt.title("Error at t=2")
## We can see that the approximations errors are getting small as
## stepsize h becomes small.
```

[352]: Text(0.5, 1.0, 'Error at t=2')



[353]: Text(0.5, 1.0, 'Blue = y1; Red = Estimate of y1; Green = y2; Yellow = Estimate of y2; h = 0.005')



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