

# Assignment 1

## COMP3670

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**Exercise 1 Solving Linear Systems (5+5 credits)**

Find the set  $S$  of all solutions  $x$  of the following inhomogenous linear systems  $Ax = b$ , where  $A$  and  $b$  are defined as follows. Write the solution space  $S$  in parametric form.

(a)

The image shows handwritten work for solving two linear systems. The left system is  $Ax = b$  with  $A = \begin{bmatrix} 2 & -2 & -5 \\ 1 & -1 & 3 \\ 3 & -3 & -2 \end{bmatrix}$  and  $b = \begin{bmatrix} -4 \\ 9 \\ -5 \end{bmatrix}$ . The right system is  $Ax = 0$  with the same  $A$  and  $b = \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix}$ . Both systems are solved using row operations to reach row echelon form. The left system's solution is  $\begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} = \begin{bmatrix} 3 \\ 0 \\ 2 \end{bmatrix}$ . The right system's solution is  $\begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} = \lambda \begin{bmatrix} 1 \\ 1 \\ 0 \end{bmatrix}$  for  $\lambda \in \mathbb{R}$ . The final part combines these into the general solution:  $\begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} = \begin{bmatrix} 3 \\ 0 \\ 2 \end{bmatrix} + \lambda \begin{bmatrix} 1 \\ 1 \\ 0 \end{bmatrix}, \lambda \in \mathbb{R}$ .

**Solve for  $Ax = b$**

$$\begin{bmatrix} 2 & -2 & -5 & -4 \\ 1 & -1 & 3 & 9 \\ 3 & -3 & -2 & -5 \end{bmatrix}$$

swap  $r_1$  with  $r_2$

$$\begin{bmatrix} 1 & -1 & 3 & 9 \\ 2 & -2 & -5 & -4 \\ 3 & -3 & -2 & -5 \end{bmatrix}$$

$r_2 = r_2 - 2r_1$   
 $r_3 = r_3 - 3r_1$

$$\begin{bmatrix} 1 & -1 & 3 & 9 \\ 0 & 0 & -11 & -22 \\ 0 & 0 & -11 & -22 \end{bmatrix}$$

$r_3 = r_3 - r_2$   
 $r_2 = r_2 / (-11)$

$$\begin{bmatrix} 1 & -1 & 3 & 9 \\ 0 & 0 & 1 & 2 \\ 0 & 0 & 0 & 0 \end{bmatrix}$$

$r_1 = r_1 + r_2$

$$\begin{bmatrix} 1 & -1 & 0 & 5 \\ 0 & 0 & 1 & 2 \\ 0 & 0 & 0 & 0 \end{bmatrix}$$
$$\begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} = \begin{bmatrix} 3 \\ 0 \\ 2 \end{bmatrix}$$

**Solve for  $Ax = 0$**

$$\begin{bmatrix} 2 & -2 & -5 & 0 \\ 1 & -1 & 3 & 0 \\ 3 & -3 & -2 & 0 \end{bmatrix}$$

swap  $r_1$  with  $r_2$

$$\begin{bmatrix} 1 & -1 & 3 & 0 \\ 2 & -2 & -5 & 0 \\ 3 & -3 & -2 & 0 \end{bmatrix}$$

$r_2 = r_2 - 2r_1$   
 $r_3 = r_3 - 3r_1$

$$\begin{bmatrix} 1 & -1 & 3 & 0 \\ 0 & 0 & -11 & 0 \\ 0 & 0 & -11 & 0 \end{bmatrix}$$

$r_3 = r_3 - r_2$   
 $r_2 = r_2 / (-11)$

$$\begin{bmatrix} 1 & -1 & 3 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 0 \end{bmatrix}$$

$r_1 = r_1 + r_2$

$$\begin{bmatrix} 1 & -1 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 0 \end{bmatrix}$$
$$\begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} = \lambda \begin{bmatrix} 1 \\ 1 \\ 0 \end{bmatrix} \quad \lambda \in \mathbb{R}$$

$\therefore$  combine these two solutions:

the general solution is:

$$\begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} = \begin{bmatrix} 3 \\ 0 \\ 2 \end{bmatrix} + \lambda \begin{bmatrix} 1 \\ 1 \\ 0 \end{bmatrix}, \lambda \in \mathbb{R}$$

The solution Space  $S = \left\{ \begin{pmatrix} 3 \\ 0 \\ 2 \end{pmatrix} + \lambda \begin{pmatrix} 1 \\ 1 \\ 0 \end{pmatrix}, \lambda \in \mathbb{R} \right\}$

(b)

$$\begin{aligned} & \left[ \begin{array}{ccc|c} -2 & -3 & -10 & 4 \\ -4 & 2 & 3 & 0 \\ 10 & -3 & 1 & 1 \end{array} \right] \\ & \rightarrow \left[ \begin{array}{ccc|c} -2 & -3 & -10 & 4 \\ 0 & -4 & -17 & 8 \\ 0 & 12 & 51 & 6-4 \end{array} \right] \begin{array}{l} r_2 = r_2 + 2r_1 \\ r_3 = r_3 - 5r_1 \end{array} \\ & \left[ \begin{array}{ccc|c} -2 & -3 & -10 & 4 \\ 0 & -4 & -17 & 8 \\ 0 & 0 & 0 & 5 \end{array} \right] r_3 = r_3 + 3r_2 \\ & \left[ \begin{array}{ccc|c} -2 & -3 & -10 & 4 \\ 0 & -4 & -17 & 8 \\ 0 & 0 & 0 & 1 \end{array} \right] r_3 = r_3 / 5 \\ & \left[ \begin{array}{ccc|c} -2 & -3 & -10 & 0 \\ 0 & -4 & -17 & 0 \\ 0 & 0 & 0 & 1 \end{array} \right] \begin{array}{l} r_1 = r_1 - 4r_3 \\ r_2 = r_2 - 8r_3 \end{array} \\ & \left[ \begin{array}{ccc|c} -2 & -3 & -10 & 0 \\ 0 & 1 & \frac{17}{4} & 0 \\ 0 & 0 & 0 & 1 \end{array} \right] r_2 = r_2 / -4 \\ & \left[ \begin{array}{ccc|c} -2 & 0 & \frac{11}{4} & 0 \\ 0 & 1 & \frac{17}{4} & 0 \\ 0 & 0 & 0 & 1 \end{array} \right] r_1 = r_1 + 3r_2 \\ & \left[ \begin{array}{ccc|c} 1 & 0 & \frac{11}{8} & 0 \\ 0 & 1 & \frac{17}{4} & 0 \\ 0 & 0 & 0 & 1 \end{array} \right] r_1 = r_1 / 2. \end{aligned}$$

The system has no solutions and the Space  $S = \emptyset$

**Exercise 2** For what values of  $\lambda$  does the inverse of the following matrix exist?

When the inverse of matrix exists, the determinant of matrix cannot be 0.

$$\det = \begin{vmatrix} \lambda & 1 & 2 \\ 0 & 3 & 1 \\ 1 & 1 & 1 \end{vmatrix} = 3\lambda + 1 - 6 - \lambda = 2\lambda - 5 = 0$$

If  $\lambda \neq \frac{5}{2}$ , the inverse of matrix exists.

**Exercise 3** Which of the following sets are subspaces of  $\mathbb{R}^3$ . Prove your answer. (That is, if it is a subspace, you must demonstrate the subspace axioms are satisfied, and if it is not a subspace, you must show which axiom fails.)

- (a)  $A = (x, y, 1) : x, y, \in \mathbb{R}$
- (b)  $B = (x, y, z) : x + 4y - 3z = t$ , where  $t$  is some real number. (Your answer may depend on the value of  $t$ .)
- (c)  $C = (x, y, z) : x \geq 0, y \geq 0, z \geq 0$
- (d)  $D = (x, y, z) : x, y \in \mathbb{R}, z \in \mathbb{Q}$ .

(a) It is not subspace of  $\mathbb{R}^3$ . Since 0 is not in A, A is not the subspace of  $\mathbb{R}^3$

(b) If  $t \neq 0$ , then  $0 \notin B$  and it implies that B is not a subspace of  $\mathbb{R}^3$ .

if  $t = 0$ , then  $0 \in B$  and  $B \subseteq \mathbb{R}^3$ .

Also, assume  $B_1(x_1, y_1, z_1) \in B$ ,  $B_2(x_2, y_2, z_2) \in B$ , We get  $x_1 + 4y_1 - 3z_1 + x_2 + 4y_2 - 3z_2 = (x_1 + x_2) + 4(y_1 + y_2) - 3(z_1 + z_2) \in B$ , i.e.  $B_1 + B_2 \in B$

Assume  $\lambda \in \mathbb{R}$ ,  $(X, Y, Z) \in B$  and we can obtain that  $X + 4Y - 3Z = 0$ .  $\lambda X + 4\lambda Y - 3\lambda Z = \lambda(X + 4Y - 3Z)$ . i.e.  $\lambda(X, Y, Z) \in B$ .

Therefore, we can conclude that when  $t \neq 0$ , B is not a subspace of  $\mathbb{R}^3$  and when  $t = 0$ , B is a subspace of  $\mathbb{R}^3$ .

(c) It is not subspace of  $\mathbb{R}^3$ . We assume that  $C_1(x_c, y_c, z_c) \in C$ ,  $C_2 \lambda(x_c, y_c, z_c)$  ( $\lambda = -1$ ).  $-x_c \leq 0$ ;  $-y_c \leq 0$ ;  $-z_c \leq 0$ ;  $C_2 \notin C$ . Therefore, C is not subspace of  $\mathbb{R}^3$ .

(d) It is not subspace of  $\mathbb{R}^3$ . Here is a counterexample,  $D_1(2, 3, 4)$ ,  $\lambda = \sqrt{3}$ ,  $D_2 = \lambda D_1 = (2\sqrt{3}, 3\sqrt{3}, 4\sqrt{3})$ , as  $4\sqrt{3} \notin \mathbb{Q}$ . Therefore, D is not a subspace of  $\mathbb{R}^3$ .

**Exercise 4** Let  $v_1, v_2, v_3$  be vectors in  $\mathbb{R}^2$ . Prove that the set  $v_1, v_2, v_3$  is linearly dependant.

Assume  $v_1, v_2, v_3$  is linearly independent. From the definition of the basis of a vector space,  $v_1, v_2$  can form a basis in  $\mathbb{R}^2$  which means  $v_3$  can be written in terms of  $v_1$  and  $v_2$ . It implies that  $v_1, v_2, v_3$  set is linearly dependent which draws the contradiction. Therefore,  $v_1, v_2, v_3$  is linearly dependent.

**Exercise 5**

(a) Is the following function  $\langle \cdot, \cdot \rangle$  defined for all  $x = [x_1, x_2]^T \in \mathbb{R}^2$  and  $y = [y_1, y_2]^T \in \mathbb{R}^2$  as  $\langle x, y \rangle = y_1(x_1 - x_2) + y_2(x_2 - x_1)$

**It is not an inner mapping.**

For bilinear mapping:

$$\Omega(\lambda x + \phi y, z) = z_1(\lambda x_1 + \phi y_1 - \lambda x_2 - \phi y_2) + z_2(\lambda x_2 + \phi y_2 - \lambda x_1 - \phi y_1) \quad (1)$$

$$= \lambda(z_1 x_1 - z_1 x_2 + z_2 x_2 - z_2 x_1) + \phi(y_1 z_1 - y_2 z_1 + y_2 z_2 - y_1 z_2) \quad (2)$$

$$= \lambda\Omega(x, z) + \phi\Omega(y, z) \quad (3)$$

$$\lambda\Omega(x, y) + \phi\Omega(x, z) = \lambda[y_1(x_1 - x_2) + y_2(x_2 - x_1)] + \phi[z_1(x_1 - x_2) + z_2(x_2 - x_1)] \quad (4)$$

$$= (x_1 - x_2)(\lambda y_1 + \phi z_1) + (x_2 - x_1)(\lambda y_2 + \phi z_2) \quad (5)$$

$$= (\lambda y_1 + \phi z_1)(x_1 - x_2) + (\lambda y_2 + \phi z_2)(x_2 - x_1) \quad (6)$$

$$= \lambda(x, \lambda y + \phi z) \quad (7)$$

**It is satisfied with bilinear mapping.**

For symmetric axiom:

$$\langle x, y \rangle = y_1(x_1 - x_2) + y_2(x_2 - x_1) = x_1 y_1 - x_2 y_1 + x_2 y_2 - x_1 y_2$$

$$\langle y, x \rangle = x_1(y_1 - y_2) + x_2(y_2 - y_1) = x_1 y_1 - x_1 y_2 + x_2 y_2 - x_2 y_1$$

Therefore  $\langle x, y \rangle = \langle y, x \rangle$  is symmetric

**It is satisfied with symmetric axiom.**

For positive definite axiom:

$$\langle x, x \rangle = x_1(x_1 - x_2) + x_2(x_2 - x_1) = x_1^2 - 2x_1 x_2 + x_2^2 = (x_1 - x_2)^2$$

if  $x_1 = x_2$  then the formula equal to 0 instead of larger than 0.

Therefore, it is not positive definite matrix.

(b) Prove that  $\langle \cdot, \cdot \rangle$  defined for all  $x = [x_1, x_2]^T \in R^2$  and  $y = [y_1, y_2]^T \in R^2$  as  $\langle x, y \rangle = x_1 y_1 - x_2 y_2$  is not an inner product.

An inner product must satisfy positive definite axiom.

$$\forall X \in R^2 / 0, \langle x, x \rangle = x_1 y_1 - x_2 y_2 = x_1^2 - x_2^2$$

if  $x_1 < x_2$  then  $x_1^2 - x_2^2 < 0$ . Therefore, it is not satisfied with positive definite axiom. i.e. it is not an inner product.

### Exercise 6

(a) Prove that if  $x$  and  $y$  are linearly dependant vectors, then  $|\langle x, y \rangle| = \|x\| \|y\|$

As  $x$  and  $y$  are linearly dependent vectors, then  $c_1 x + c_2 y = 0$ , ( $c_1, c_2$  not all equal to 0). And we can derive that  $y = kx$ .

$$|\langle x, y \rangle| = |\langle x, kx \rangle| = |k| |\langle x, x \rangle| = |k| \|x\|^2$$

$$\|x\| \|y\| = \|x\| \|kx\| = |k| \|x\|^2$$

Therefore  $|\langle x, y \rangle| = \|x\| \|y\|$

(b) Show that we can retrieve the inner product from the norm via the following expression:

$$\langle x, y \rangle = \frac{1}{2}(\|x + y\|^2 - \|x\|^2 - \|y\|^2)$$

$$\begin{aligned} & \frac{1}{2}(\langle x + y, x + y \rangle - \langle x, x \rangle - \langle y, y \rangle) \\ &= \frac{1}{2}(\langle x, x + y \rangle + \langle y, x + y \rangle - \langle x, x \rangle - \langle y, y \rangle) \\ &= \frac{1}{2}(\langle x, x \rangle + \langle x, y \rangle + \langle y, x \rangle + \langle y, y \rangle - \langle x, x \rangle - \langle y, y \rangle) \\ &= \frac{1}{2} * 2 \langle x, y \rangle = \langle x, y \rangle \end{aligned}$$

Therefore the expression is proved.

(c) Show that norm equivalence is an equivalence relation, that is, that norm equivalence is reflexive, symmetric and transitive

reflexive:  $\|v\|_a$  is equivalent to  $\|v\|_a$ .

We can get  $M_1\|v\|_a \leq \|v\|_a \leq M_2\|v\|_a$  when  $M_1 = M_2 = 1$ .

symmetric: Assume " $\|v\|_a$  and  $\|v\|_b$  are equivalent if  $M_1\|v\|_a \leq \|v\|_b \leq M_2\|v\|_a$  when  $M_1 > 0, M_2 > 0$  such that for any  $v \in V$ " is true.

We can derive that  $\|v\|_a \leq \frac{\|v\|_b}{M_1}$ ,  $\|v\|_a \geq \frac{\|v\|_b}{M_2}$ , i.e.  $\frac{\|v\|_b}{M_2} \leq \|v\|_a \leq \frac{\|v\|_b}{M_1}$   
Set  $M_3 = \frac{1}{M_2}$ ,  $M_4 = \frac{1}{M_1}$ , we can conclude that " **$\|v\|_b$  and  $\|v\|_a$  are equivalent if  $M_3\|v\|_b \leq \|v\|_a \leq M_4\|v\|_b$  when  $M_3 > 0, M_4 > 0$  such that for any  $v \in V$** " is also established

transitive: Assume " $\|v\|_a$  and  $\|v\|_b$  are equivalent if  $M_1\|v\|_a \leq \|v\|_b \leq M_2\|v\|_a$  when  $M_1 > 0, M_2 > 0$  such that for any  $v \in V$ " and " $\|v\|_b$  and  $\|v\|_c$  are equivalent if  $M_3\|v\|_b \leq \|v\|_c \leq M_4\|v\|_b$  when  $M_3 > 0, M_4 > 0$  such that for any  $v \in V$ " is true.

We can derive that  $\|v\|_a \leq \frac{\|v\|_b}{M_1}$ ,  $\|v\|_a \geq \frac{\|v\|_b}{M_2}$ ,  $\|v\|_b \leq \frac{\|v\|_c}{M_3}$ ,  $\|v\|_b \geq \frac{\|v\|_c}{M_4}$

$\implies \|v\|_a \leq \frac{\|v\|_b}{M_1} \leq \frac{\|v\|_c}{M_1 M_3}$ ,  $\|v\|_a \geq \frac{\|v\|_b}{M_2} \geq \frac{\|v\|_c}{M_2 M_4}$   
Set  $M'_1 = \frac{1}{M_1 M_3}$  and  $M'_2 = \frac{1}{M_2 M_4}$ , we can get that  $M'_1\|v\|_c \leq \|v\|_a \leq M'_2\|v\|_c$ .  
We can conclude that  $\|v\|_a$  and  $\|v\|_c$  are equivalent when  $M'_1 > 0, M'_2 > 0$ .

Therefore, it satisfied with reflective, symmetric and transitive properties.

(d) Assuming that  $V = \mathbb{R}$ , show that  $\|\cdot\|_1$  and  $\|\cdot\|_2$  are equivalent norms.  
Assume that  $v = [x_1, x_2]^T \in \mathbb{R}^2$

$$\|v\|_1 = |x_1| + |x_2|, \|v\|_2 = \sqrt{x_1^2 + x_2^2} \quad (8)$$

Assume that  $x_2 = kx_1$  ( $k \in \mathbb{R}$ )

$$\|v\|_1 = |x_1| + |k||x_1| = (1 + |k|)|x_1| \quad (9)$$

$$\|v\|_2 = \sqrt{x_1^2 + (kx_1)^2} = \sqrt{k^2 + 1}|x_1| \quad (10)$$

Divide  $\|v\|_2$  by  $\|v\|_1$ :

$$\frac{\|v\|_2}{\|v\|_1} = \frac{\sqrt{k^2 + 1}}{1 + |k|} \quad (11)$$

Let  $f(k) = \frac{\sqrt{k^2 + 1}}{1 + |k|}$ ,  $f(x)$  is an even function and  $f(x) > 0$  ( $\forall x \in \mathbb{R}$ )  
When  $k = 0$ ,

$$f(0) = 1 \quad (12)$$

When  $k > 0$ ,

$$f(k)^2 = \frac{k^2 + 1}{k^2 + 2k + 1} = \frac{k + \frac{1}{k}}{k + \frac{1}{k} + 2} \quad (13)$$

As  $k + \frac{1}{k} \geq 2$  (if  $k > 0$ )

We can get that:

$$\frac{2}{2 + 2} = \frac{1}{2} \leq f(k)^2 = \frac{k + \frac{1}{k}}{k + \frac{1}{k} + 2} < 1 \quad (14)$$

$$\frac{\sqrt{2}}{2} \leq f(k) < 1 \quad (15)$$

When  $k < 0$ , it has the same condition with  $k > 0$  which is  $\frac{\sqrt{2}}{2} \leq f(k) < 1$   
Now, we can say that the range of the function  $f(x)$  is  $[\frac{\sqrt{2}}{2}, 1]$

Which is to say,  $\frac{\sqrt{2}}{2} \leq \frac{\|v\|_2}{\|v\|_1} \leq 1$

i.e.,  $\frac{\sqrt{2}}{2}\|v\|_1 \leq \|v\|_2 \leq \|v\|_1$  which  $M_1 = \frac{\sqrt{2}}{2}, M_2 = 1$

**Exercise 7** Consider the Euclidean vector space  $\mathbb{R}^3$  with the dot product. A subspace  $U$  subset  $\mathbb{R}^3$  and vector  $x \in \mathbb{R}^3$  are given by

$$U = \text{span} \left\{ \begin{bmatrix} 1 \\ 1 \\ 1 \end{bmatrix}, \begin{bmatrix} 2 \\ 2 \\ 3 \end{bmatrix} \right\}, \mathbf{x} = \begin{bmatrix} 1 \\ 0 \\ 3 \end{bmatrix}$$

a) Show that  $\mathbf{x} \notin U$

Solve  $a \begin{bmatrix} 1 \\ 1 \\ 1 \end{bmatrix} + b \begin{bmatrix} 2 \\ 2 \\ 3 \end{bmatrix} = \begin{bmatrix} 1 \\ 0 \\ 3 \end{bmatrix}$

$$\begin{bmatrix} 1 & 2 & | & 1 \\ 1 & 2 & | & 0 \\ 1 & 3 & | & 3 \end{bmatrix}$$

$r_2 = r_2 - r_1$   
 $r_3 = r_3 - r_1 \rightarrow$

$$\begin{bmatrix} 1 & 2 & | & 1 \\ 0 & 0 & | & -1 \\ 0 & 1 & | & 2 \end{bmatrix}$$

$r_1 = r_1 + r_2$   
 $r_3 = r_3 + 2r_2 \rightarrow$

$$\begin{bmatrix} 1 & 2 & | & 0 \\ 0 & 0 & | & -1 \\ 0 & 1 & | & 0 \end{bmatrix}$$

$\hookrightarrow$

$$\begin{bmatrix} 1 & 0 & | & 0 \\ 0 & 1 & | & 0 \\ 0 & 0 & | & 1 \end{bmatrix}$$

In the last row is  $0 \cdot a + 0 \cdot b = 1$ , which has no solutions. Therefore  $\mathbf{x} \notin U$ .

b) Determine the orthogonal projection  $\pi_U(\mathbf{x})$  of  $\mathbf{x}$  onto  $U$ . Show that  $\pi_U(\mathbf{x})$  can be written as a linear combination of  $[1, 1, 1]^T$  and  $[2, 2, 3]^T$



As  $U = \text{span}[1, 1, 1]^T, [2, 2, 3]^T$ ,  $x = [1, 0, 3]^T$

The basis of Vector is:

$$\begin{pmatrix} 1 & 2 \\ 1 & 2 \\ 1 & 3 \end{pmatrix}$$

Compute the  $B^T B$  and the vector  $B^T x$ :

$$B^T B = \begin{pmatrix} 1 & 1 & 1 \\ 2 & 2 & 3 \end{pmatrix} \cdot \begin{pmatrix} 1 & 2 \\ 1 & 2 \\ 1 & 3 \end{pmatrix} = \begin{pmatrix} 3 & 7 \\ 7 & 17 \end{pmatrix} \quad (16)$$

$$B^T x = \begin{pmatrix} 1 & 1 & 1 \\ 2 & 2 & 3 \end{pmatrix} \cdot \begin{pmatrix} 1 \\ 0 \\ 3 \end{pmatrix} = \begin{pmatrix} 4 \\ 11 \end{pmatrix} \quad (17)$$

Solve the normal equation  $B^T B \lambda = B^T x$  to get the value of  $\lambda$ :

$$\lambda = \begin{pmatrix} -9/2 \\ 5/2 \end{pmatrix} \quad (18)$$

$$\pi_U(x) = B \lambda = \begin{pmatrix} 1/2 \\ 1/2 \\ 3 \end{pmatrix} \quad (19)$$

$$\begin{pmatrix} 1 & 2 & 1/2 \\ 1 & 2 & 1/2 \\ 1 & 3 & 3 \end{pmatrix} \quad (20)$$

Minus the second row with the first row; minus the second row with the first row.

$$\begin{pmatrix} 1 & 2 & 1/2 \\ 0 & 0 & 0 \\ 0 & 1 & 5/2 \end{pmatrix} \quad (21)$$

Minus the first row with two times of third row.

$$\begin{pmatrix} 1 & 0 & -9/2 \\ 0 & 1 & 5/2 \\ 0 & 0 & 0 \end{pmatrix} \quad (22)$$

$$\pi_U(x) = -\frac{9}{2} \cdot [1, 1, 1]^T + \frac{5}{2} \cdot [2, 2, 3]^T$$

Therefore,  $\pi_U(x)$  can be written as a linear combination of  $[1, 1, 1]^T$  and  $[2, 2, 3]^T$

(c) Determine the distance  $d(x, U)$

$d(x, U)$  is the distance between the original vector and its projection onto  $U$ .

$$\|x - \pi_U(x)\| = \|[-1/2, 1/2, 0]^T\| = \frac{\sqrt{2}}{2} \quad (23)$$