

BeRGeR

Using Braids for Byzantine-Resistant Geometric Routing on
Polyhedral Networks

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Contents

Problem Definition

Online routing	Nodes are myopic (only see immediate neighbors)
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Robust routing on low-resource devices

- IoT
- Sensor networks
- Vehicular networks

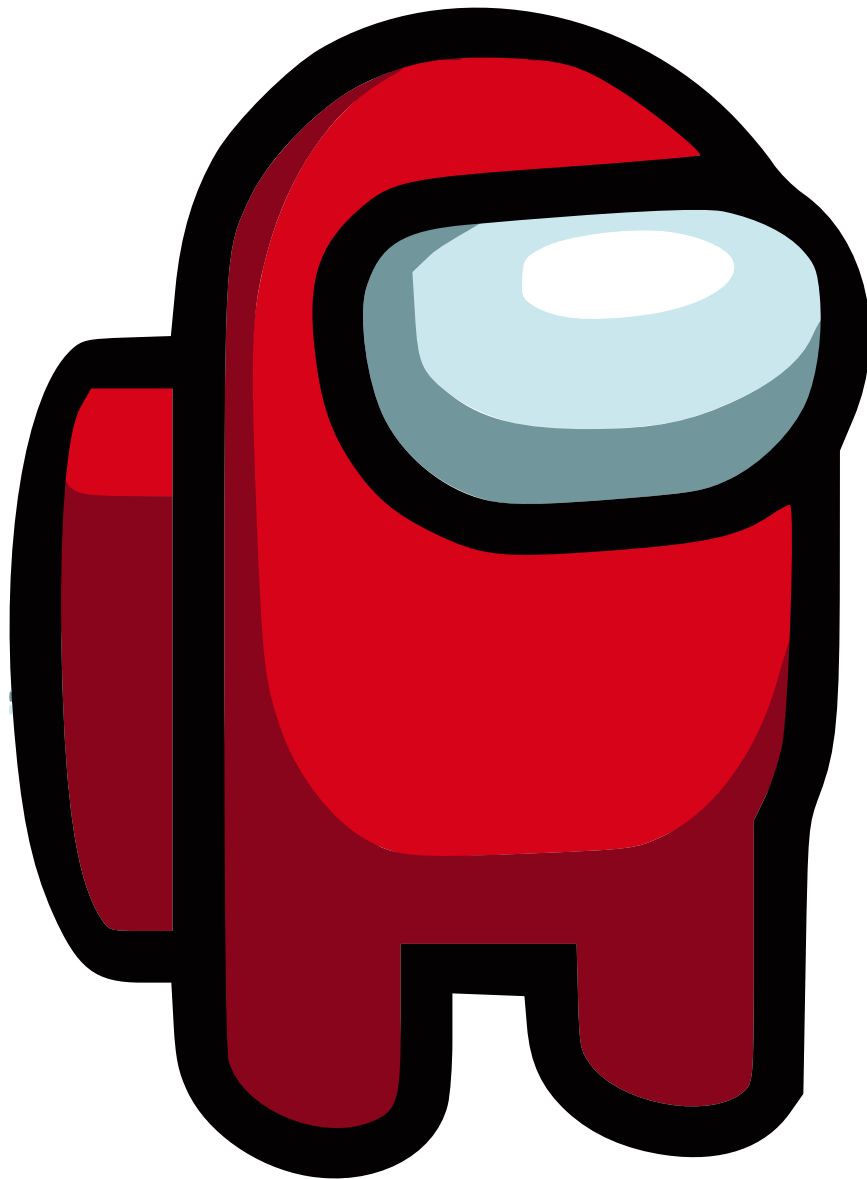
1 faulty “Byzantine” node

Using Braids for Byzantine-Resistant Geometric Routing on Polyhedral Networks

Offline routing	Routing tables (nodes store directions)
Geometric routing	
Greedy routing	Go to node closest to destination
Face routing	Always turn right (or left)

Using Braids for Byzantine-Resistant Geometric Routing on Polyhedral Networks

Byzantine node Node that behaves arbitrarily



Using Braids for Byzantine-Resistant Geometric Routing on Polyhedral Networks

Network	Graph
Polyhedral	
Planar	No edges intersect
3-Connected	To disconnect the network, you need to remove 3 nodes
3-Connected	\exists 3 disjoint paths between each pair of nodes

Planar \because \exists algorithms to planarize; simplicity **3-connected** \because it is necessary **Menger's theorem**: 3-connected equivalence

Using Braids for Byzantine-Resistant Geometric Routing on Polyhedral Networks

Exactly what they sound like.

Naïve approach

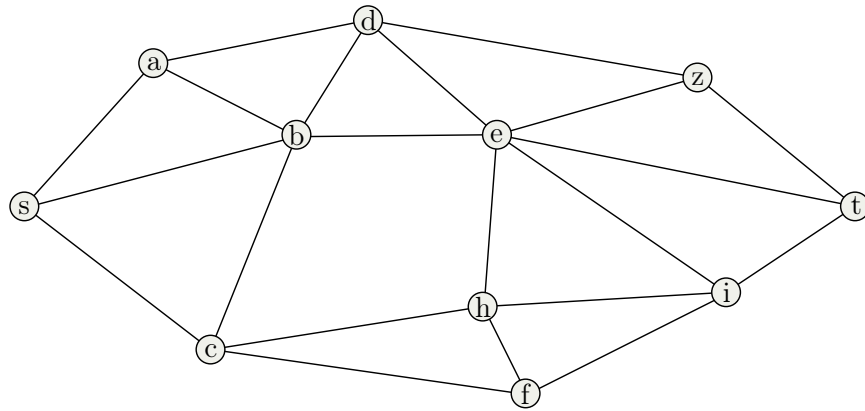
Route along 3 disjoint paths

$$\begin{aligned} \exists i, j : m_i &= m_j, \\ p_i \cap p_j &= \emptyset \end{aligned}$$

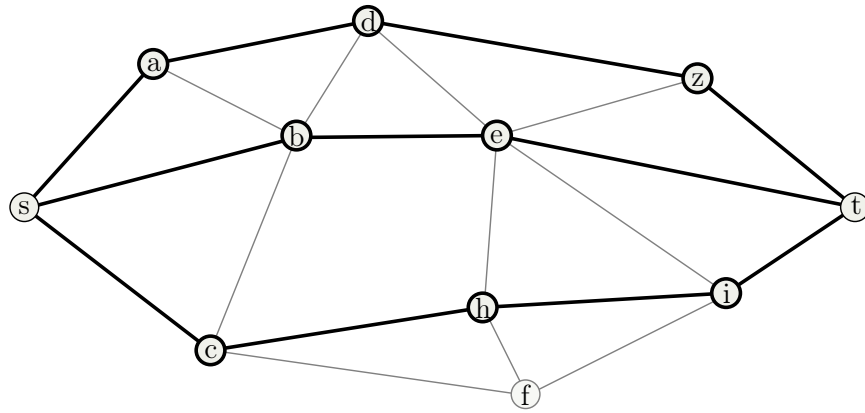
For each node, find 2 disjoint paths that skip it.

We **need** to use 3-connectivity.

Naïve approach



Naïve approach



Hard to do online.

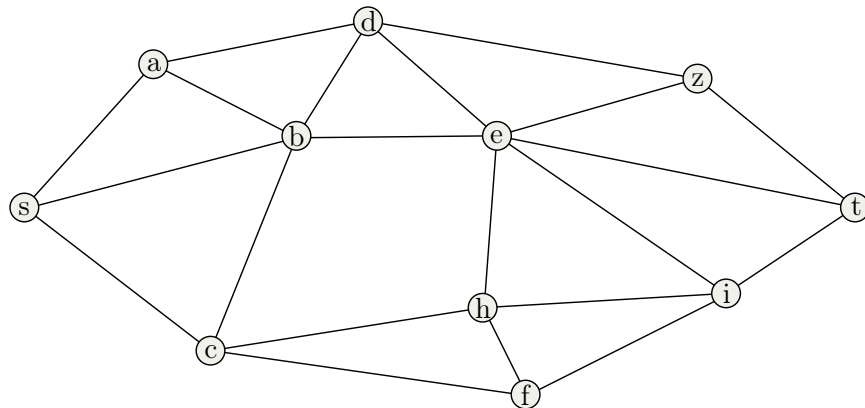
Generalized approach

Route along *collectively* disjoint paths

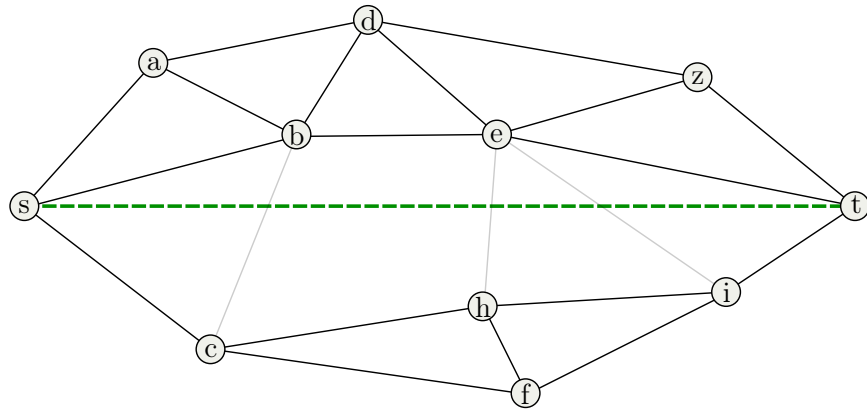
$$\begin{aligned} \exists i, j, k, \dots : m_i = m_j = m_k = \dots, \\ p_i \cap p_j \cap p_k \cap \dots = \emptyset \end{aligned}$$

For each node, find a set of collectively disjoint paths that skip it.

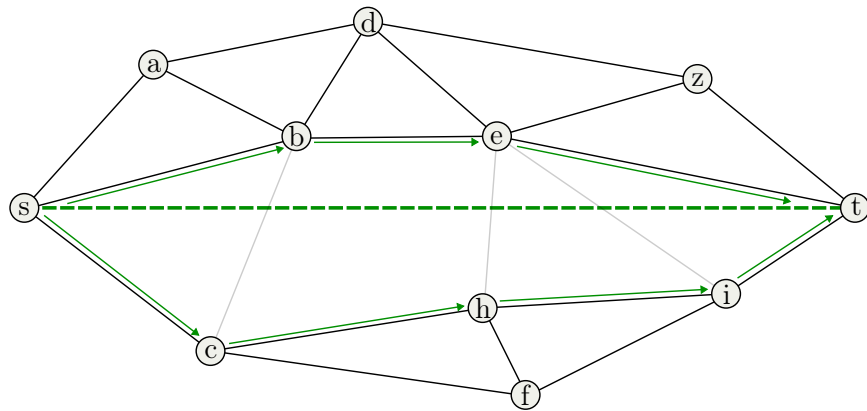
Remove edges that intersect st-line



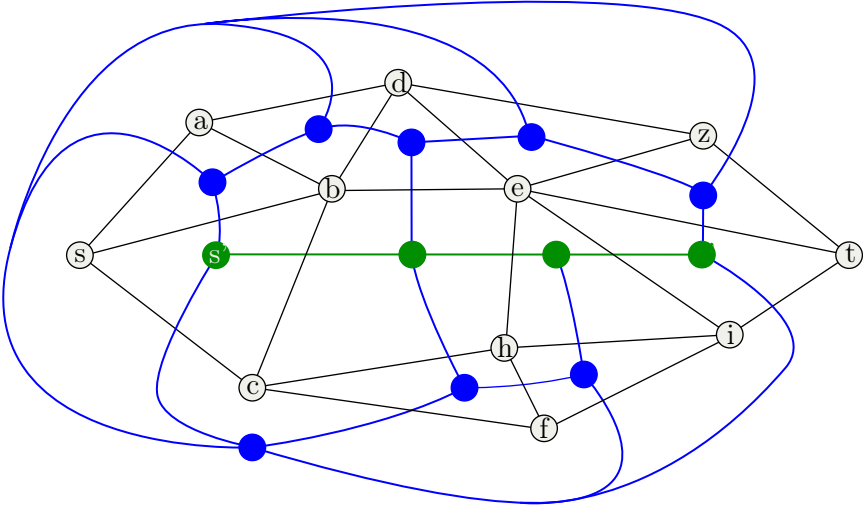
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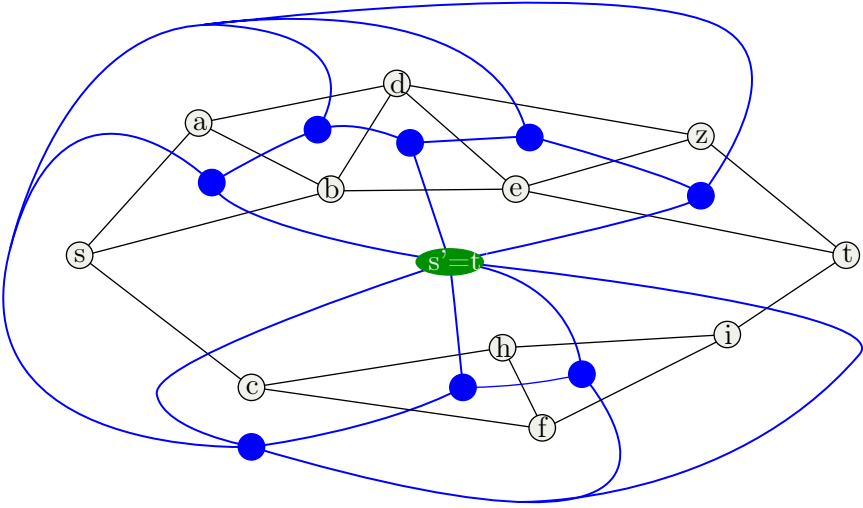
Route along both sides



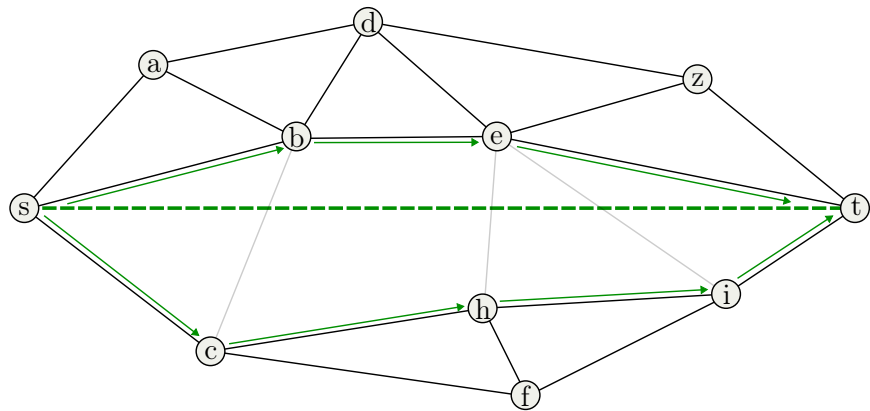
Proof



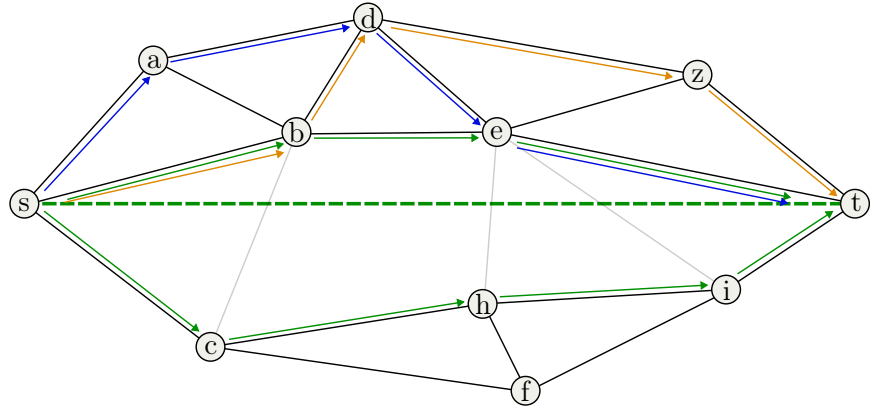
Proof



Route along both sides



Braids



Paper

Reliable Geometric Routing

1 Introduction

We have a network (graph), G , of nodes that know only the current packet, their position, and the set of their neighbors' positions. They do not have space for routing tables, nor space to store information about packets that pass through them. The goal is to route a message from s to t such that t will decode the correct message even in the presence of 1 node that behaves arbitrarily (i.e. is Byzantine).

The simplest solution without a Byzantine node would be to greedily route; at each step going to the node geometrically closest to t . However, local minima result in this naive algorithm not reaching t . A guaranteed solution is to include draw a line through s and t (encoded in the packet), and then route along all edges of any face that intersects the $s-t$ line. This was done in Concurrent Face Routing (CFR) [1] and is adapted here in Piths / Half-Face Routing as "Half-Face Routing" (HFR) to generate 2 disjoint paths "piths" that form the core of our braided routing algorithm.

The state of the art in geographic routing is GOAFR+ [2] where they route packets within an ellipse, increasing the size of the ellipse if progress is not made. They demonstrate practical efficiency and prove their algorithm is asymptotically optimal in the worst-case: $O(p^2)$, where p is the shortest path length from s to t , and we assume a unit-disk graph (UDG). We attempted something similar, but were stymied by networks that had multiple external faces on the $s-t$ line: we may attempt this again assuming no such intersections.

Finally, [3] proves a correspondence between interactive consensus conditions (ICCs) and error-correcting codes (ECCs). But I believe the ICCs apply to broadcast networks (complete graphs), so are not directly applicable here.

2 Mathematical Formalism

Formally, each node, except for 1, uses the same routing algorithm, f , that takes a message, $m \in M$, the proximal source of the packet, \mathbf{v}_{-1} , the current node's position \mathbf{v}_0 , and the set of the current node's neighbors' positions \mathbf{V} and returns a set of (possibly modified) packets along with the node to pass each packet to:

$$f : m, \mathbf{v}_{-1}, \mathbf{v}_0, \mathbf{V} \mapsto \{(m \in M, \mathbf{v}) : \forall m, \mathbf{v} \in \mathbf{V}\}$$

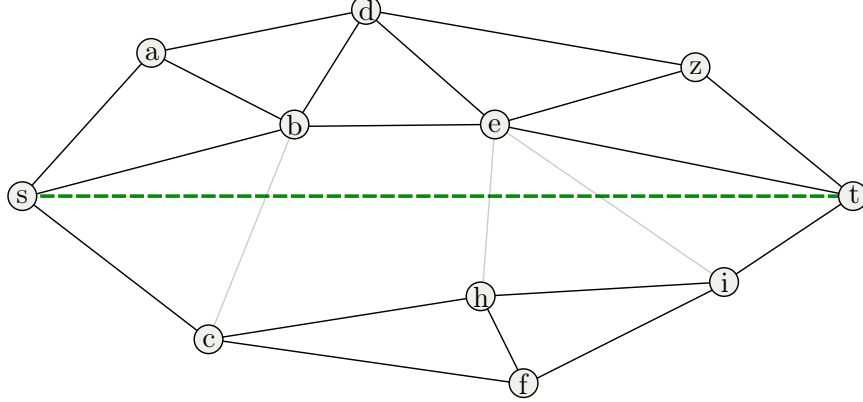
Algorithm 1: BeRGer: Byzantine Resistant Geographic Routing

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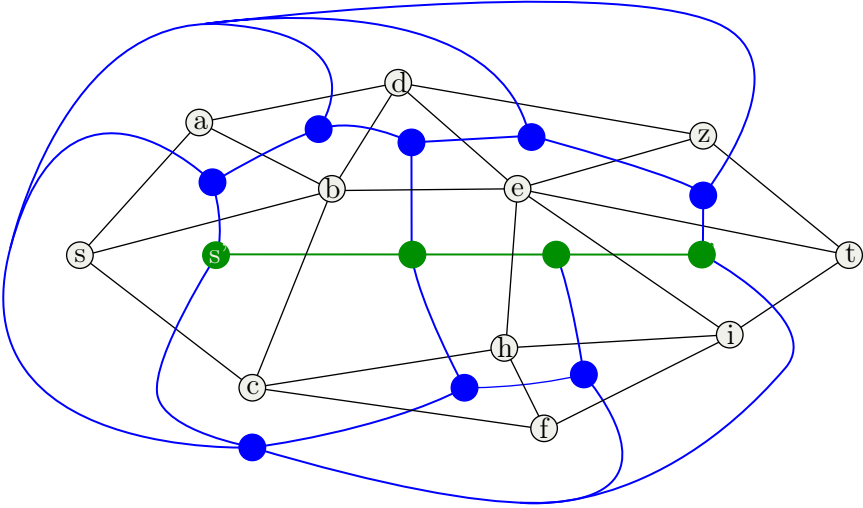
1 constants
2  $\mathbf{n}$  // node coordinates
3  $\mathbf{N}$  // circular list of neighbor coordinates sorted clockwise
4 variables
5  $\mathbf{S}$  // set of packets sent by source
6  $\mathbf{T}$  // set of packets received by target
7 source node
8 input:
9  $m$  // message
10  $t$  // target
11 initial action:
12  $\mathbf{S} \leftarrow \text{append}(m)$  // record the packet at  $s$ 
13  $\text{send}(m, s, t, \text{CCW} \perp)$  to  $\text{nextnode}(N, t, s, t, \text{CCW} \perp)$  // send CW core
14  $\text{send}(m, s, t, \text{CCW} \perp)$  to  $\text{nextnode}(N, t, s, t, \text{CCW} \perp)$  // send CCW core
15  $k \leftarrow \text{nextnode}(N, t, s, t, \text{CCW} \perp)$ 
16  $\text{send}(m, s, t, \text{CCW}, k)$  to  $\text{nextnode}(N, t, s, t, \text{CCW}, k)$  // send CW braid
17  $k \leftarrow \text{nextnode}(N, t, s, t, \text{CCW} \perp)$ 
18  $\text{send}(m, s, t, \text{CCW}, k)$  to  $\text{nextnode}(N, t, s, t, \text{CCW}, k)$  // send CCW braid
19 all nodes
20 receive  $(m, s, t, c, k, f)$  from  $p \rightarrow$  // if this is a core
21 if  $k = \perp$  then
22  $f \leftarrow \text{append}(p)$  // append previous node to list of visited nodes
23 if  $s \neq t$  then
24 if  $k \neq p$  // if packet is not at target
25 and  $s \neq p$  or  $(t, m) \in \mathbf{S}$  then // if sender is not trying to skip itself
26  $\text{send}(m, s, t, c, k, f)$  to  $\text{nextnode}(N, p, s, t, c, k)$  // forward packet
27 if  $k = \perp$  then // if received packet is core
28  $k \leftarrow \text{nextnode}(N, p, s, t, c, \perp)$  // next grown node
29 if  $k \neq \perp$  and  $k \neq f$  then // if  $k$  is unvisited
30  $\text{send}(m, s, t, c, k, f)$  to  $\text{nextnode}(N, p, s, t, c, k)$  // generate braid
31 else // packet reached target
32 // core nodes neighboring  $t$ 
33  $\text{coreCW} \leftarrow \text{nextnode}(N, s, s, t, \text{CCW} \perp)$ 
34  $\text{coreCCW} \leftarrow \text{nextnode}(N, s, s, t, \text{CCW} \perp)$ 
35 // nodes neighboring  $t$  next to core nodes (may be the same)
36  $\text{braidCW} \leftarrow \text{nextnode}(N, s, s, t, \text{CCW}, \text{coreCW})$ 
37  $\text{braidCCW} \leftarrow \text{nextnode}(N, s, s, t, \text{CCW}, \text{coreCCW})$ 
38 if  $p = \text{coreCW}$  and  $k = \perp$  and  $c = \text{CW}$  then // record CW core
39  $\mathbf{T} \leftarrow \text{append}(m, s, \text{CCW}, \perp, f)$  // record CW core
40 else if  $p = \{\text{coreCW}, \text{braidCW}\}$  and  $c = \text{CW}$  then // record CW braid
41  $\mathbf{T} \leftarrow \text{append}(m, s, \text{CCW}, k, \perp)$  // record CW braid
42 else if  $p = \{\text{coreCCW}, \text{braidCCW}\}$  and  $c = \text{CCW}$  then // record CCW braid
43  $\mathbf{T} \leftarrow \text{append}(m, s, \text{CCW}, k, \perp)$  // record CCW braid
44 if  $\exists m, s, f_1, f_2 : \{(m, s, \text{CCW}, \perp, f_1), (m, s, \text{CCW}, \perp, f_2)\} \subset \mathbf{T}$  then
45  $\text{deliver } m$  // received matching cores
46 else if  $\exists (m, s, c, \perp, f) \in \mathbf{T} : \forall f_1 \in f, (m, s, c, f_1) \in \mathbf{T}$  then
47  $\text{deliver } m$  // received braids that skip each visited node of a core

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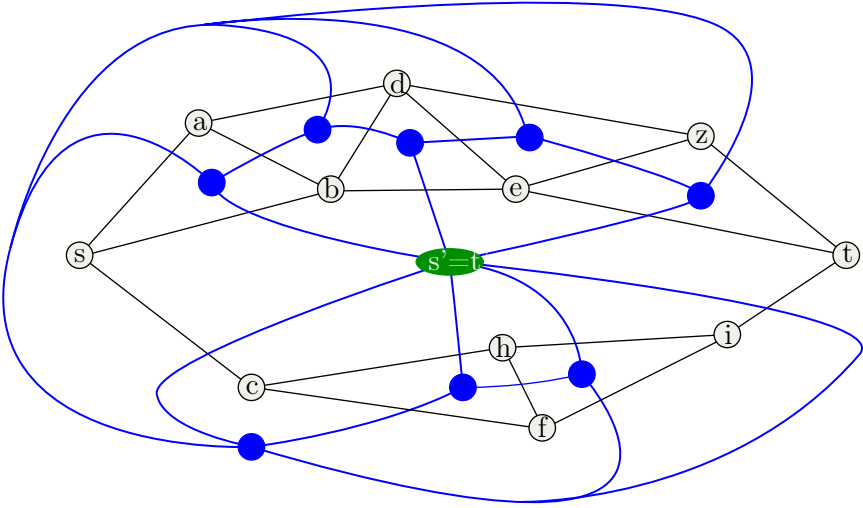
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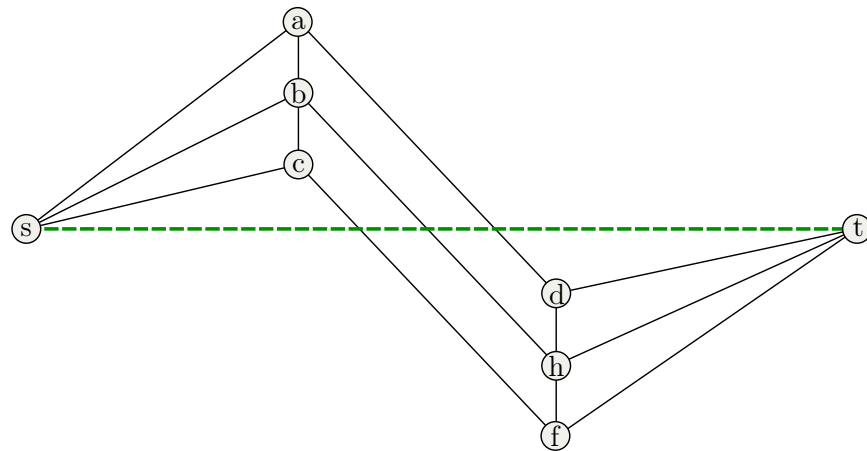
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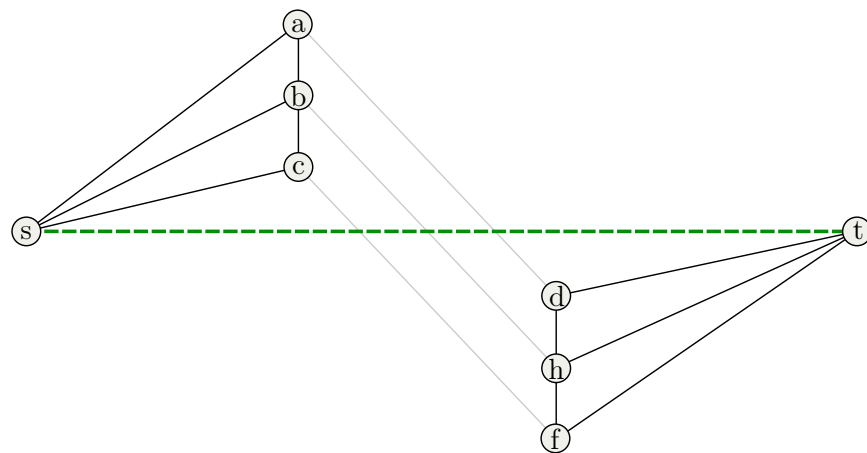
Proof



Counterexample



Counterexample



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Questions?

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