## 1 Mechanics

### 1.1 Formulae

• 
$$F\Delta t = m\Delta v$$

• 
$$W = \Delta K$$

• 
$$I = I_{\rm cm} + mD^2$$
  
•  $r_{\rm cm} = \frac{1}{mD} \int r dm$ 

• 
$$r_{\rm cm} = \frac{1}{m_{\rm total}} \int r \mathrm{d}m$$

• 
$$L = mvr$$
  
•  $\omega_f^2 = \omega_i^2 + 2\alpha\Delta\theta$ 

• 
$$\Delta\theta = \frac{1}{2}(\omega_f + \omega_i)\Delta t$$

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•  $F_{g\parallel} = mg \sin \theta$ ;  $F_{g\perp} = mg \cos \theta$  ( $\theta$ : angle of incline)

• 
$$F_x = -\frac{\mathrm{d}U}{\mathrm{d}x}$$

• 
$$v_{\text{ideal}} = \sqrt{rg \tan \theta}$$
 (banked curve)  
•  $v_{\text{escape}} = \sqrt{\frac{2GM}{r_e}}$ 

# EMag

• 
$$E_x = \int \frac{1}{4\pi\varepsilon_0} \frac{1}{r^2} dq = \int \frac{1}{4\pi\varepsilon_0} \frac{\lambda}{r^2} dr$$

$$E_x = \int \frac{1}{4\pi\varepsilon_0} \frac{1}{r^2} \mathrm{d}q = \int \frac{1}{r^2} \mathrm{d}q$$

• 
$$i_L(t) = I(1 - e^{-t/\tau})$$
  
•  $q_C(t) = Q(1 - e^{-t/\tau})$ 

$$i_L(t) = I(1 - e^{-t})$$

• 
$$\tau_{\text{RL}} = \frac{L}{R}$$
;  $\tau_{RC} = RC$   
•  $\varepsilon_{\text{induced}} = \vec{B}v\ell$ ;  $I_{\text{induced}} = \frac{\vec{B}v\ell}{R}$ 

•  $F_{\text{mag}} = ILB$ 

• 
$$\Phi_E = \frac{Q}{\varepsilon_0} = \oint E \cdot \mathrm{d}A$$

## 2.2 Notes

- Current/Charge is at max after 5  $\tau$ 's
- Terminal velocity occurs when  $F_{\text{mag}} = F_{\text{ext/grav}}$