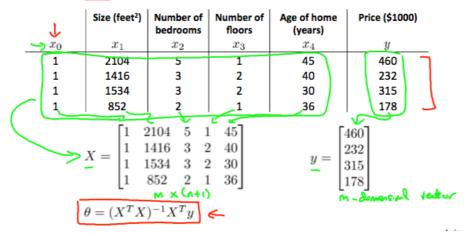
## **Computing Parameters Analytically**

## **Normal Equation**

Gradient descent gives one way of minimizing J. Let's discuss a second way of doing so, this time performing the minimization explicitly and without resorting to an iterative algorithm. In the "Normal Equation" method, we will minimize J by explicitly taking its derivatives with respect to the  $\theta$ j 's, and setting them to zero. This allows us to find the optimum theta without iteration. The normal equation formula is given below:

$$\theta = (X^T X)^{-1} X^T y$$

Examples: m=4.



There is no need to do feature scaling with the normal equation.

The following is a comparison of gradient descent and the normal equation:

Gradient Descent	Normal Equation
Need to choose alpha	No need to choose alpha
Needs many iterations	No need to iterate
$O(kn^2)$	O $(n^3)$ , need to calculate inverse of $\boldsymbol{X}^T\boldsymbol{X}$
Works well when n is large	Slow if n is very large

With the normal equation, computing the inversion has complexity  $\mathcal{O}(n^3)$ . So if we have a very large number of features, the normal equation will be slow. In practice, when n exceeds 10,000 it might be a good time to go from a normal solution to an iterative process.

## **Normal Equation Noninevitability**

When implementing the normal equation in octave we want to use the 'pinv' function rather than 'inv.' The 'pinv' function will give you a value of  $\theta$  even if  $X^TX$  is not invertible.

If  $X^TX$  is **noninvertible**, the common causes might be having :

- · Redundant features, where two features are very closely related (i.e. they are linearly dependent)
- Too many features (e.g. m ≤ n). In this case, delete some features or use "regularization" (to be explained in a later lesson).

Solutions to the above problems include deleting a feature that is linearly dependent with another or deleting one or more features when there are too many features.

inv - inverse/ pinv - pseudoinverse