# Zhicheng ZHANG — CV

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"There is nothing certain, but the uncertain." — Proverb

Z. Zhang is currently a Ph.D Candidate (Informatics) at Osaka University. His research interests include sparse modeling, robust optimization and networked control. He is a student member of SIAM, INFORMS and IEEE.

# **Education**

Osaka University Osaka, Japan 2020.10 - present

Ph.D Candidate, Informatics Fields: Probabilistic Control under Uncertainty

Advisor: Prof. Yasumasa Fujisaki

University of Kitakyushu Fukuoka, Japan 2019.09 - 2020.09 Visiting Master Student, EECS

Fields: Sparse Modeling and Optimal Control

Advisor: Prof. Masaaki Nagahara

Guilin University of Electronic and Technology Guilin, China

2017.09 - 2020.06M.S., Mathematics

Fields: ODEs and Dynamical Systems Theory

Advisor: Prof. Zhongjun Ma

Changzhou Institute of Technology Changzhou, China 2013.09 - 2017.06

B.A., Japanese (Major)

B.S., Applied Mathematics (Minor)

## **Research Interests**

- Decision Making under Uncertainty
  - Robust optimization
  - Stochastic Programming
- Sparse Modeling
  - Sparse Optimization
  - Sparse Optimal Control
- Networked Control
  - Consensus of Multi-Agent Systems
  - Synchronization of Complex Networks

## **Honors and Awards**

- o 2020 Guangxi Outstanding Graduates, China, 2020 (top 1%)
- Outstanding Master's Thesis of GUET, China, 2020 (top 3%)
- O Postgraduate Scholarship, First Prize, GUET, China, 2019, 2020 (top 3%)
- O Graduate Fellowship for Study Abroad, GUET, China, 2019
- O National Scholarship for Master's Student, China, 2019 (top 3%)

# **Research Projects and Academic Foundations**

#### Practical Stability of Nonlinear Dynamical Systems

Collaborator, School of Mathematics and Computing Science, GUET

2017.10 - 2018.06

o The Innovation Project of GUET Graduate Education, Grant No. 2017YJCX79 (CNY 10,000)

#### Stability of Impulsive Ordinary Differential Equations and its Applications

Co-Investigator (CI), School of Mathematics and Computing Science, GUET

2018.10 - 2019.06

o The Innovation Project of GUET Graduate Education, Grant No. 2018YJCX60 (CNY 10,000)

#### Intermittent Feedback Control of Nonlinear Multi-Agent Systems

Principal Investigator (PI), School of Mathematics and Computing Science, GUET

2018.12 - 2020.06

Cultivation of Excellent Thesis Project of GUET Graduate Education, Grant No. 2018YJSPY01 (CNY 10,000)

## Cooperative Control of Multi-Agent Networked Systems

**Principal Investigator** (PI), School of Mathematics and Computing Science, GUET

2019.09 - 2020.08

o The Study Abroad Program for Graduate Student of GUET, Grant No. GDYX2019015 (CNY 120,600)

### Partial Component Synchronization of Nonlinear Networks and its Control Applications

Collaborator, School of Mathematics and Computing Science, GUET

2019.01 - 2021.12

O Guangxi Natural Science Foundation, China, Grant No. 2018GXNSFAA281068 (CNY 50,000)

#### Partial Variable Stability of Neural Networks

Collaborator, School of Mathematics and Computing Science, GUET

2020.03 - 2021.06

The Innovation Project of GUET Graduate Education, Grant No. 2020YJSCX03 (CNY 5,000)

# **Positions of Responsibility**

- o **Teaching Assistant** for Undergraduate courses like *Mathematical Analysis*, *Advanced Algebra*, and *Calculus*.
- o **Teaching Assistant** for Graduate courses like *operations research*, and *research seminars*.

## **Professional Service**

### Reviewer (Journals)

- O International Journal of Robust and Nonlinear Control (IJRNC)
- o IEEE Transactions on Systems, Man and Cybernetics (IEEE TSMC)

# Reviewer (Conferences)

- O IFAC Symposium on Robust Control Design (ROCOND 2022)
- o IFAC World Congress (2023)

## **Publications**

## **Peer Review Journals**

- [J2] Z. Zhang, Z. Ma, Y. Wang and K. Li, Wait-and-track characteristics for a generic multiagent system under control input attacks, *IEEE Transactions on Network Science and Engineering*, 2023. (accepted)
- [J1] Z. Zhang, Z. Ma and Y. Wang, Partial component consensus of leader-following multi-agent systems via intermittent pinning control, *Physica A: Statistical Mechanics and its Applications*, 2019, 536: 122569. Doi: 10.1016/j.physa.2019.122569.

## **Proceeding Conferences**

- [C4] Z. Zhang and Y. Fujisaki, Risk-aware sparse predictive control, IFAC Word Congress, July 2023. (to be presented)
- [C3] Z. Zhang and Y. Fujisaki, Sparse feedback control realiztion using linear dynamic compensator, SICE ISCS, Mar. 2023.
- [C2] Z. Zhang and Y. Fujisaki, Sparse robust control design via scenario optimization, ISCIE SSS, Oct. 2021.
- [C1] Z. Zhang and M. Nagahara, Linear quadratic tracking control with sparsity-promoting regularization. *2021 American Control Conference (ACC)*, IEEE, May 2021. pp. 3812–3817.

#### **Preprints**

[P2] Z. Zhang and Y. Fujisaki, Sparse feedback controller: From open-loop solution to closed-loop realization. *SICE Journal of Control, Measurement, and System Integration*, arXiv.2303.15175. (under review)

[P1] Z. Zhang and Z. Ma, Lag synchronization for large-scale complex networks under stochastic input disturbances, *Chaos: An Interdisciplinary Journal of Nonlinear Science*. 2022, (under review)

# **Technical Strengths**

- $\,\circ\,$  Languages: Chinese (native), Japanese (N2), and English (fluent).
- **Skills:** L<sup>A</sup>T<sub>E</sub>X, Matlab, Python, Julia

# **Personal Information**

- O Born in Dec. 1994, in Jiangsu Province, China
- O Citizenship: Chinese