

CSC 580 Principles of Machine Learning

# 12 A closer look at PGMs; Hidden Markov Models

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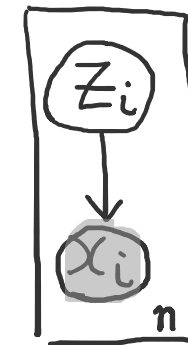
**Department of Computer Science**



\*slides credit: built upon CSC 580 Fall 2021 lecture slides by Kwang-Sung Jun

# Background: A deeper look at conditional independence

- Recall the graphical representation (plate notation) specifies the dependency
- More precisely, it specifies how a joint distribution can be factored in *a structured way*
- Remark: We focus on directed graphical models (Bayes nets)
  - another world: undirected models

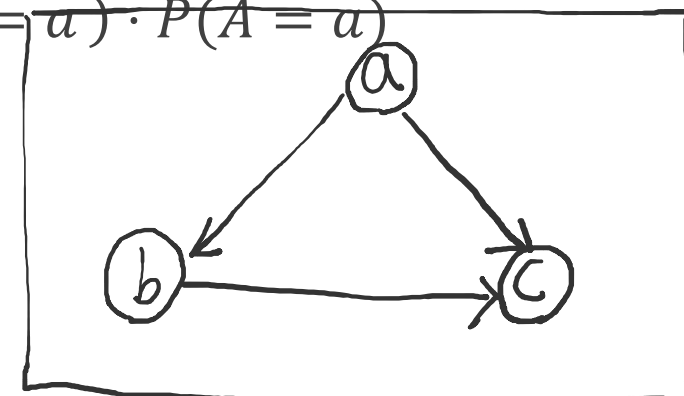


- Intro example:

$$\begin{aligned} P(A = a, B = b, C = c) &= P(C = c \mid A = a, B = b) \cdot P(A = a, B = b) \\ &= P(C = c \mid A = a, B = b) \cdot P(B = b \mid A = a) \cdot P(A = a) \end{aligned}$$

- Graphical representation:

For each conditional distribution, add direct links from *the nodes being conditioned to the node whose distribution is of interest*



# Warning: notation convention

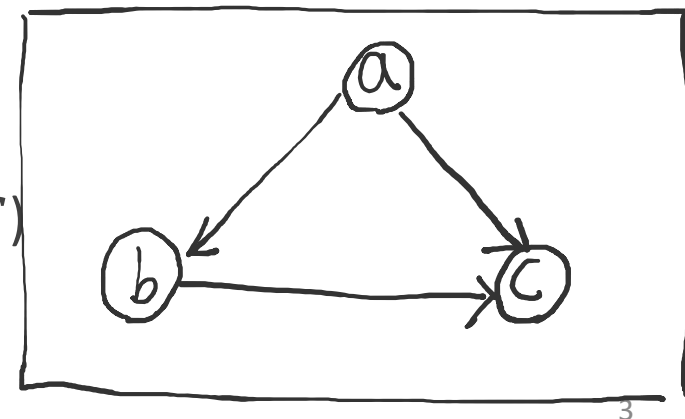
- Notation easily gets overwhelming, no easy way out.
  - Fully-specified notation: explicit, but takes too long to process
  - Simplified notation: concise, but takes time to train yourself to be familiar
- Probabilistic models: For fully-specified notation, we always need to specify the random variable and the value that it takes separately.

- E.g. 
$$P(A = a, B = b, C = c) = P(C = c \mid A = a, B = b) \cdot P(A = a, B = b)$$
$$= P(C = c \mid A = a, B = b) \cdot P(B = b \mid A = a) \cdot P(A = a)$$

- Simplified notation: 
$$P(a, b, c) = P(c \mid a, b) \cdot P(a, b)$$
$$= P(c \mid a, b) \cdot P(b \mid a) \cdot P(a)$$

- i.e. reserve symbol  $a$  for values taken by random variable  $A$  (same for  $B, C$ )

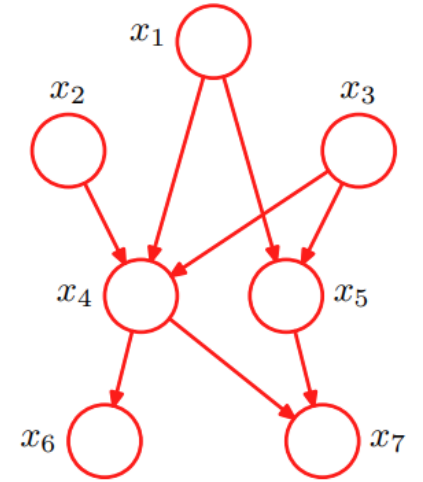
- We will use simplified notation throughout this lecture



# PGM: flexible modeling of data distributions

- Q: what kind of distribution does this graph represent?

- $$P(x_1, x_2, \dots, x_7) = P(x_1)P(x_2)P(x_3)P(x_4 \mid x_1, x_2, x_3) \cdot \\ P(x_5 \mid x_1, x_3)P(x_6 \mid x_4)P(x_7 \mid x_4, x_5)$$



- For a general directed acyclic graph (DAG)  $G$  with  $K$  nodes  $x_1, \dots, x_K$ ,

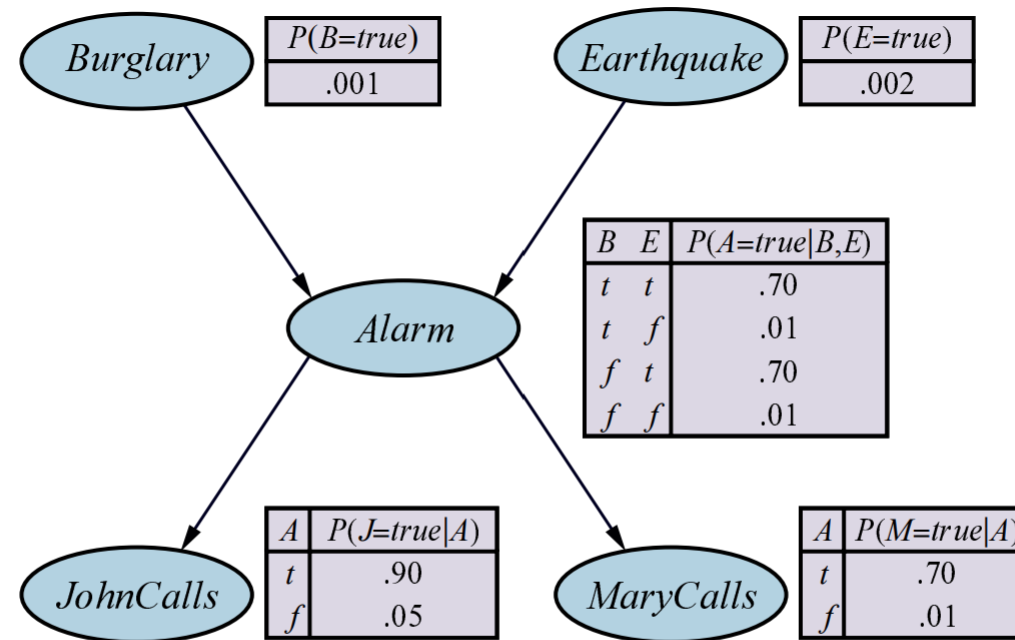
$$P(x_1, x_2, \dots, x_K) = \prod_{k=1}^K P(x_k \mid \text{pa}_k),$$

Parent nodes of  $x_k$  in  $G$

- Fact: this implicitly implies  $P(x_k \mid \text{pa}_k) = P(x_k \mid x_1, \dots, x_{k-1})$ , i.e.  $x_k \perp\!\!\!\perp \{x_1, \dots, x_{k-1}\} \setminus \text{pa}_k \mid \text{pa}_k$ 
  - E.g.  $x_6 \perp\!\!\!\perp \{x_1, x_2, x_3, x_5\} \mid x_4$
- Edges oftentimes encode *causal relationships* between the node variables

# Bayes net = DAG + Conditional probability table

- $P(x_1, x_2, \dots, x_K) = \prod_{k=1}^K P(x_k \mid \text{pa}_k)$  <- also need to specify each  $P(x_k \mid \text{pa}_k)$  respectively
- Aside:  $J \perp\!\!\!\perp B, E \mid A \Rightarrow$  the effect of B, E to John's calling is "completely captured" in Alarm status



**Figure 13.2** A typical Bayesian network, showing both the topology and the conditional probability tables (CPTs). In the CPTs, the letters *B*, *E*, *A*, *J*, and *M* stand for *Burglary*, *Earthquake*, *Alarm*, *JohnCalls*, and *MaryCalls*, respectively.

# PGM: parsimonious representation of distributions

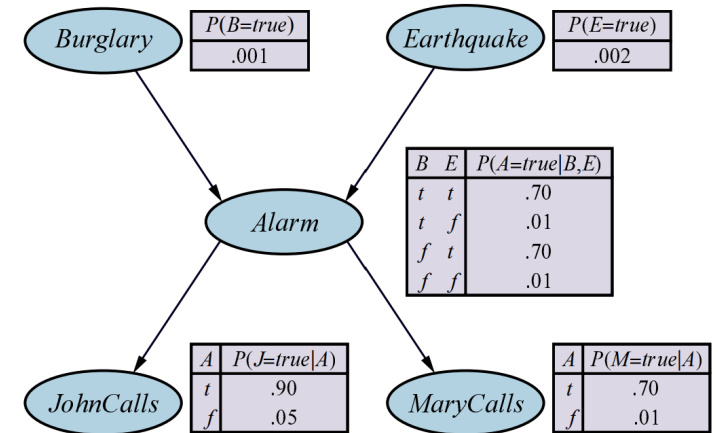
- Suppose each  $x_1, x_2, \dots, x_K$  take binary values
- Naively representing  $P(x_1, x_2, \dots, x_K)$  requires  $2^K$  entries
- With graphical model representation

$$P(x_1, x_2, \dots, x_K) = \prod_{k=1}^K P(x_k \mid \text{pa}_k)$$

Each  $P(x_k \mid \text{pa}_k)$  takes  $2^{|\text{pa}_k|+1}$  entries

so total representation complexity  $\leq \sum_k 2^{|\text{pa}_k|+1} \leq 2^{O(\max_k |\text{pa}_k|)}$

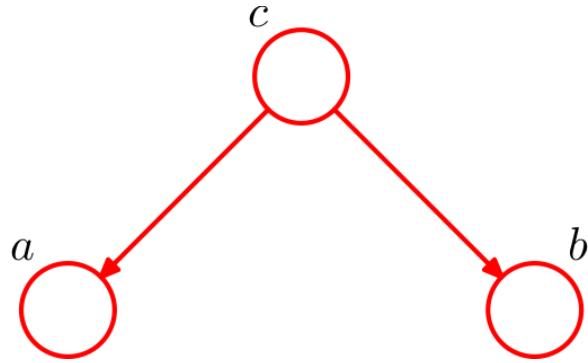
much smaller than  $2^K$  if  $\max_k |\text{pa}_k| \ll K$  (we will see that this happens in many natural PGMs)



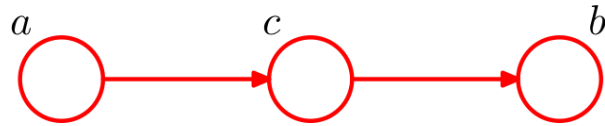
**Figure 13.2** A typical Bayesian network, showing both the topology and the conditional probability tables (CPTs). In the CPTs, the letters  $B$ ,  $E$ ,  $A$ ,  $J$ , and  $M$  stand for *Burglary*, *Earthquake*, *Alarm*, *JohnCalls*, and *MaryCalls*, respectively.

# Three landmark examples

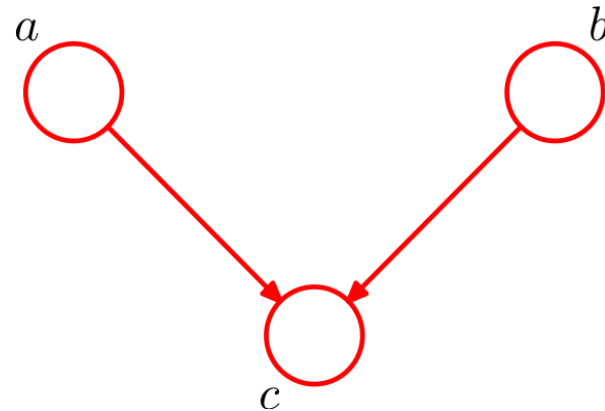
- tail-to-tail



- Head-to-tail



- head-to-head

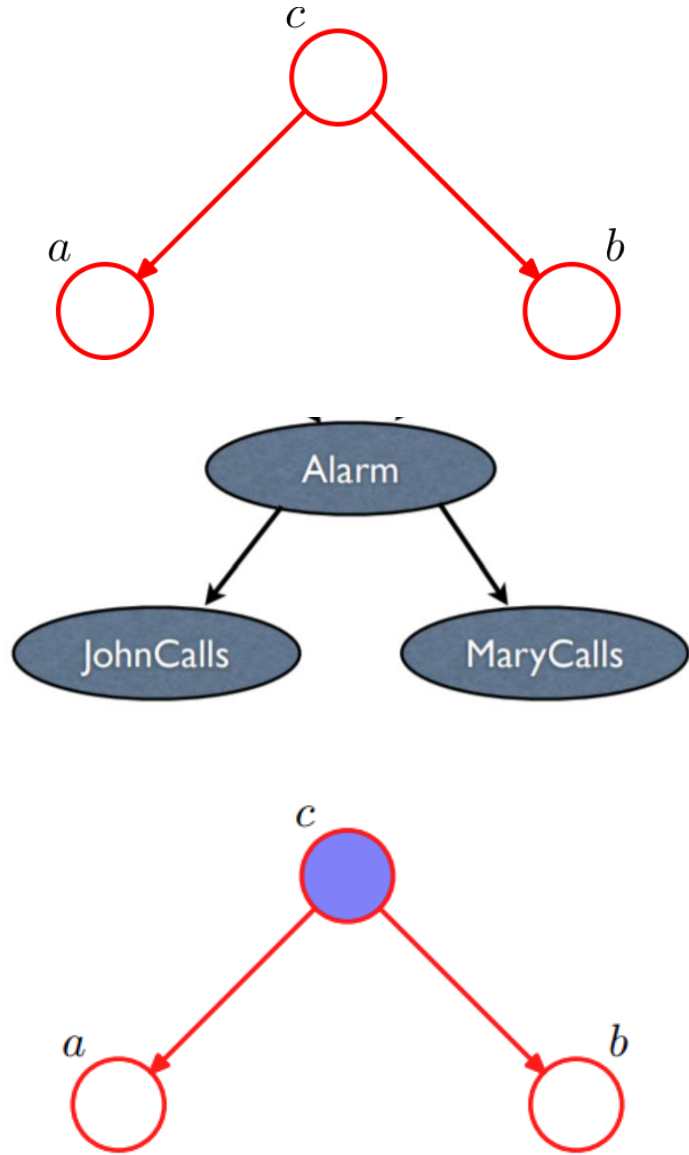


# Ex 1: Tail-to-tail (common cause)

- $P(a, b, c) = P(c)P(a | c)P(b | c)$
- $P(a, b) = \sum_c P(c)P(a | c)P(b | c)$  and in general it does not factorize  
=> It is generally not true that  $a \perp\!\!\!\perp b$   
(e.g. John's calling is correlated with Mary's calling)

- However,  $P(a, b | c) = \frac{P(a, b, c)}{P(c)} = P(a | c)P(b | c)$

=>  $a \perp\!\!\!\perp b | c$





# Ex 2: head-to-tail

- $P(a, b, c) = P(a)P(c | a)P(b | c)$

- $P(a, b) = P(a) \sum_c P(c | a)P(b | c) = P(a) \cdot P(b | a)$

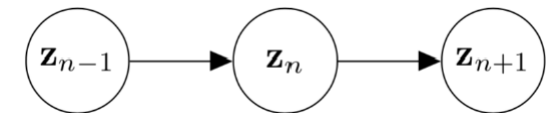
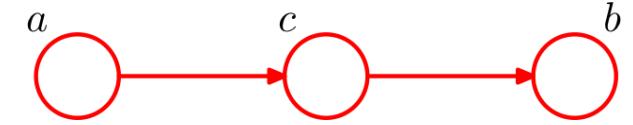
=> It is generally not true that  $a \perp\!\!\!\perp b$

(e.g. “Cloudy” is correlated with “Wet grass”)

- However,  $P(a, b | c) = \frac{P(a, b, c)}{P(c)} = \frac{P(a)P(c|a)P(b|c)}{P(c)} = P(a | c)P(b | c)$

=>  $a \perp\!\!\!\perp b | c$

- Another important example: Markov chain (for time series data)



# Ex 3: head-to-head (common effect)

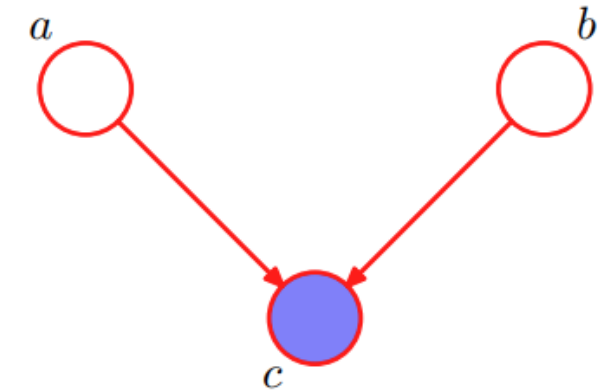
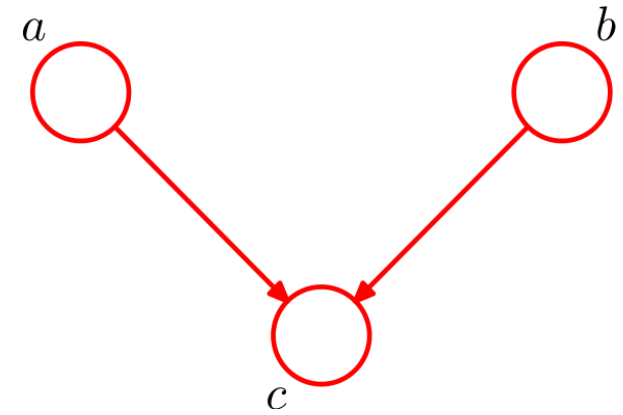
- $P(a, b, c) = P(a)P(b)P(c \mid a, b)$

- $P(a, b) = \sum_c P(a)P(b)P(c \mid a, b) = P(a)P(b)$

$\Rightarrow a \perp\!\!\!\perp b$

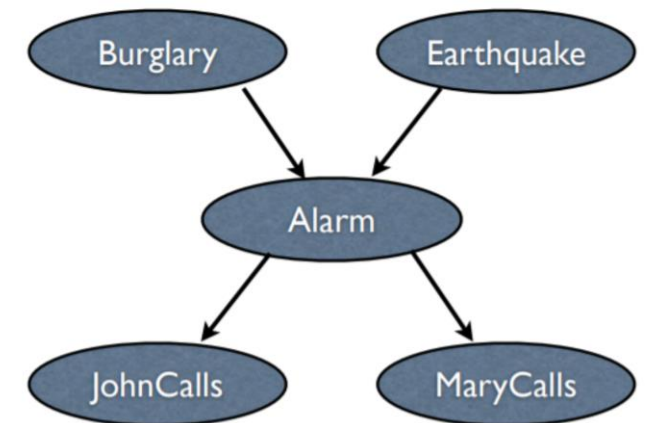
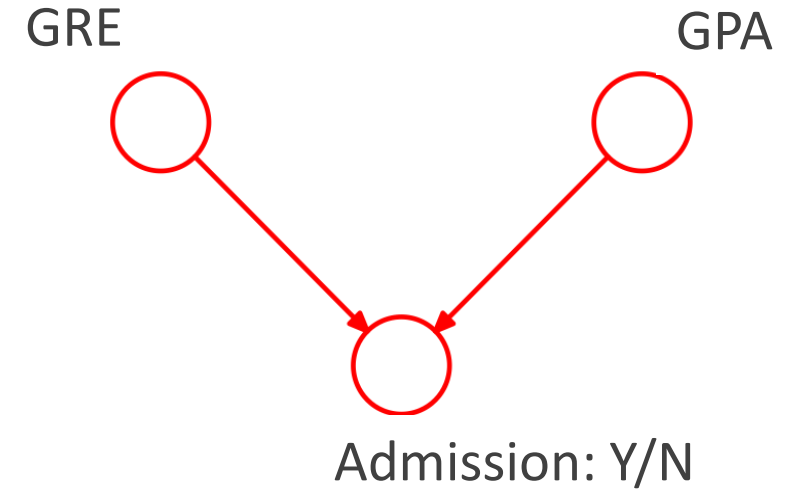
- However,  $P(a, b \mid c) = \frac{P(a, b, c)}{P(c)} = \frac{P(a)P(b)P(c \mid a, b)}{P(c)}$  does not necessarily factorize

$\Rightarrow$  It is generally not true that  $a \perp\!\!\!\perp b \mid c$



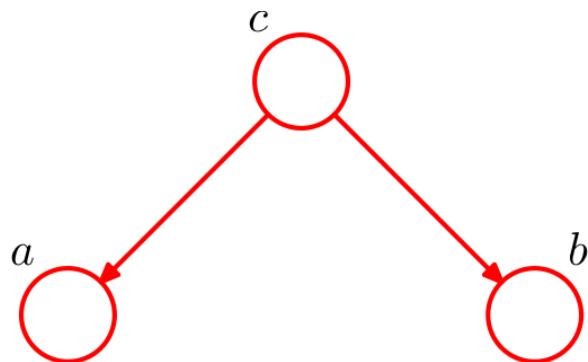
# Ex 3: head-to-head (cont'd)

- If you pick an applicant randomly, the GRE and GPA is independent (according to our model)
- However, if you randomly pick an applicant who was accepted, then the low GRE may indicate that she had a high GPA.
  - Otherwise the student would have been rejected.
- This is called the **explain-away** phenomenon.
- Another example:
  - $B$  and  $E$  are dependent, conditioned on  $A$
  - It is also true that  $B$  and  $E$  are dependent, conditioned on *descendants of  $A$*  (e.g.  $J$ )

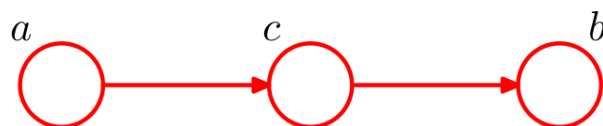


# Summary

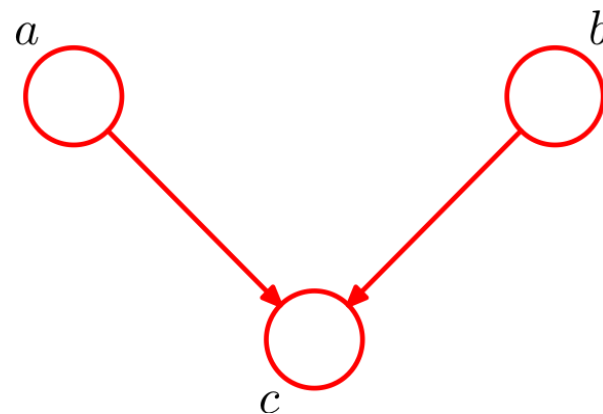
- tail-to-tail



- Head-to-tail



- head-to-head



$a \perp\!\!\!\perp b ?$

No

No

Yes

$a \perp\!\!\!\perp b | c ?$

Yes

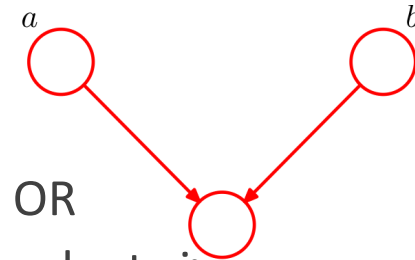
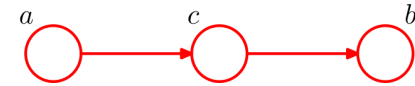
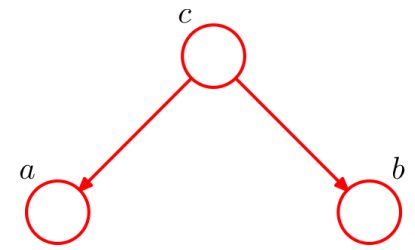
Yes

No

# D-separation

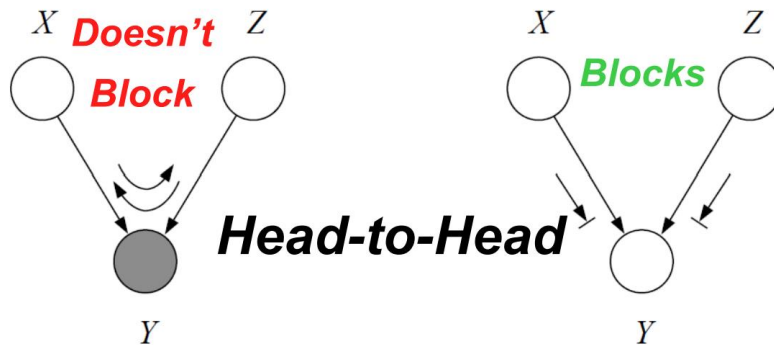
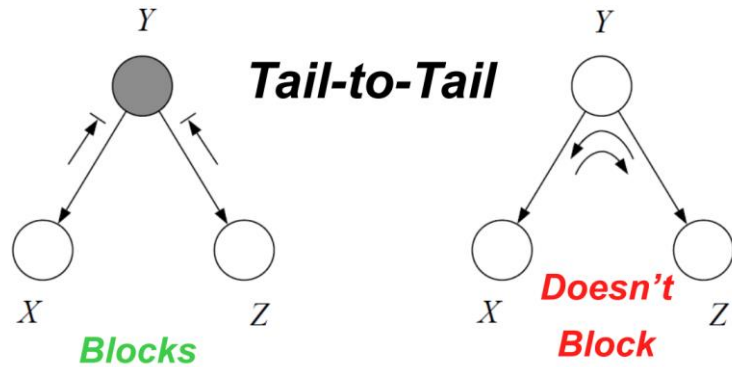
- Systematic Rules for determining conditional independence given a **directed acyclic** graph.
- Answer questions of the form: Is  $a \perp\!\!\!\perp b \mid c$  true or false ?
- [Def]  $b$  is a **descendent** of  $a$  if there exists a directed path from  $a$  to  $b$ .
  - $\Rightarrow a$  is a descendent of  $a$  by definition.
- [Def] An undirected path  $p$  from  $a$  to  $b$  is **blocked given**  $c$  if it includes a node:
  - (a) the arrows on  $p$  meet either head-to-tail or tail-to-tail at the node, and the node is  $c$ , OR
  - (b) the arrows meet head-to-head at the node, and neither the node nor any of its descendants is  $c$

“Conditioned on  $c$  being observed, information can flow from  $a$  to  $b$  through  $p$ ”
- [Def] (D-separation)  
 $a$  is **d-separated from**  $b$  **given**  $c$  if every undirected path between  $a$  and  $b$  is blocked given  $c$ .
- [Thm] If  $a$  is **d-separated from**  $b$  **given**  $c$ , then  $a \perp\!\!\!\perp b \mid c$ .



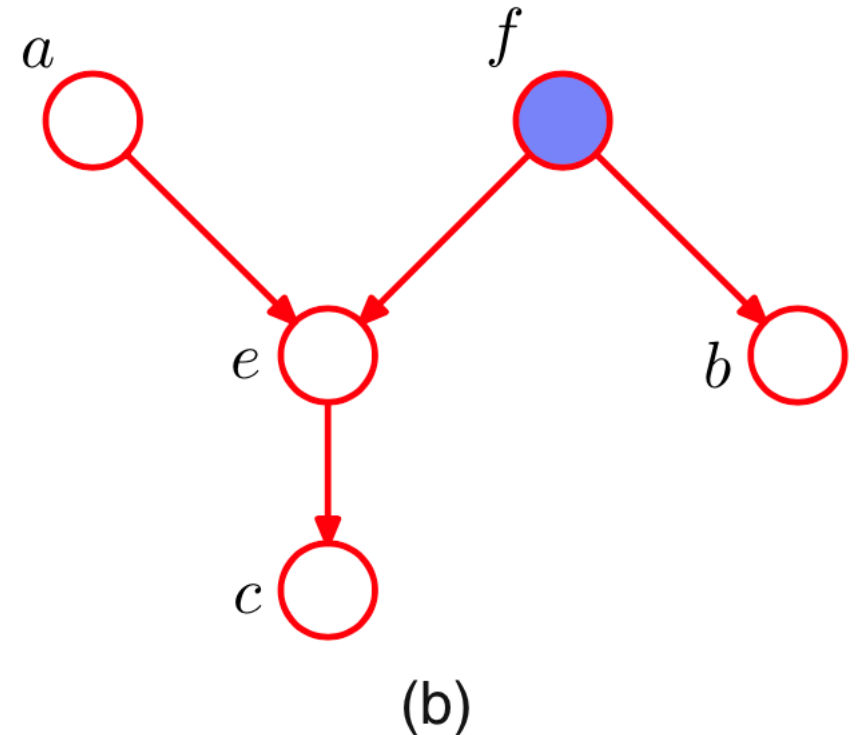
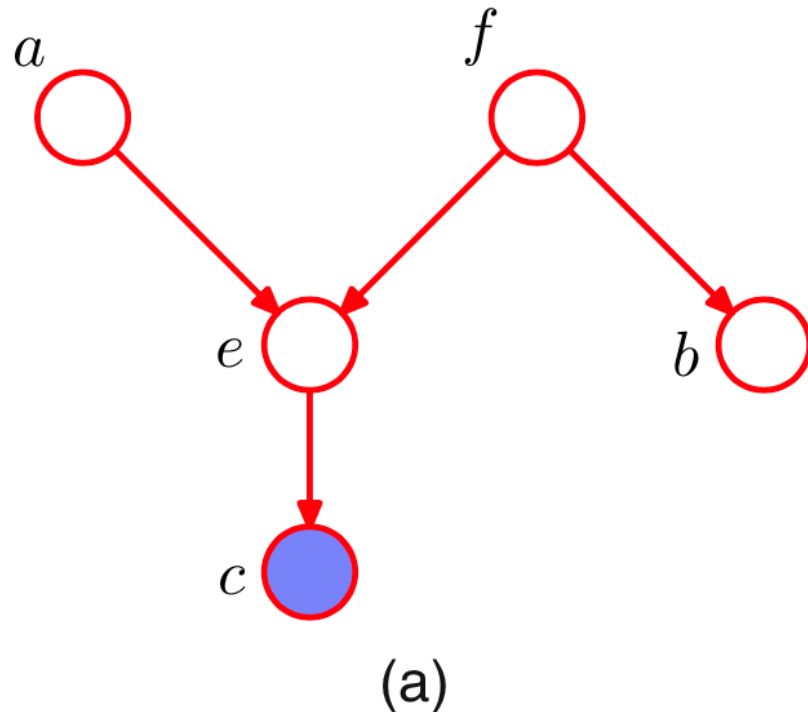
# Blockage: pictorial illustration

An undirected path  $p$  is *blocked* given  $c$  if it includes a node:  
(1) the arrows on  $p$  meet either head-to-tail or tail-to-tail at the node, and the node is  $c$ , or  
(2) the arrows meet head-to-head at the node, and neither the node nor any of its descendant is  $c$



# D-separation examples

- Let path  $p = a - e - f - b$
- In (a):  $p$  is not blocked given  $c \Rightarrow$  Not necessarily true that  $a \perp\!\!\!\perp b \mid c$
- In (b):  $p$  is blocked given  $f \Rightarrow a \perp\!\!\!\perp b \mid f$
- Is  $p$  blocked given  $\emptyset$ ?



An undirected path  $p$  is *blocked* given  $c$  if it includes a node:  
(1) the arrows on  $p$  meet either head-to-tail or tail-to-tail at the node, and the node is  $c$ , or  
(2) the arrows meet head-to-head at the node, and neither the node nor any of its descendant is  $c$

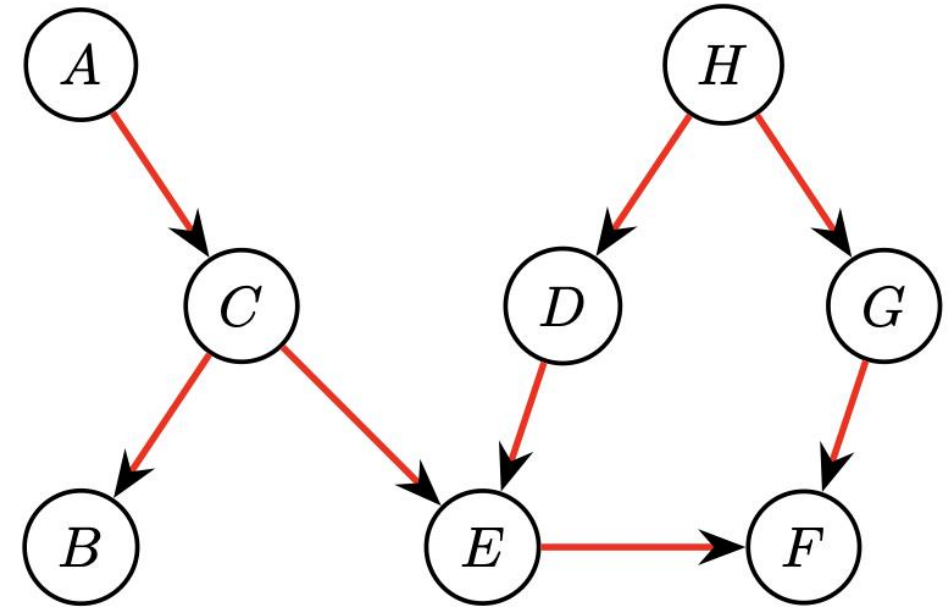
# D-separation: general definition for node sets

- Q: Is  $A \perp\!\!\!\perp B \mid C$  true or false ?
  - Each of  $A, B, C$  is a **set** of random variables
- [Def] An undirected path  $p$  from  $a$  to  $b$  is **blocked given**  $C$  if it includes a node:
  - (a) the arrows on  $p$  meet either head-to-tail or tail-to-tail at the node, and the node is in  $C$
  - (b) the arrows meet head-to-head at the node, and neither the node nor any of its descendants is in  $C$
- [Def] (D-separation)  
 $A$  is **d-separated from**  $B$  **given**  $C$  if every undirected path between  $a \in A$  and  $b \in B$  is blocked given  $C$ .
- [Thm] If  $A$  is **d-separated from**  $B$  **given**  $C$ , then  $A \perp\!\!\!\perp B \mid C$ .



# D-separation: an exercise

- Is  $G \perp\!\!\!\perp A$  - equivalently,  $G \perp\!\!\!\perp A \mid \emptyset$ ?
- Yes, all paths from  $A$  to  $G$  are blocked by  $E$
- Is  $E \perp\!\!\!\perp H \mid \{D, G\}$ ?
- Yes,  $E-D-H$  is blocked by  $D$ ;  $E-F-G-H$  blocked by  $F$  (or  $G$ )
- Is  $E \perp\!\!\!\perp H \mid \{C, D, F\}$ ?
- No, although  $E-D-H$  is blocked by  $D$ ,  $E-F-G-H$  is not blocked



# Next lecture (10/31)

- Markov models; Hidden Markov models (HMMs)
- Assigned reading: Prof. Jason Pacheco's PGM slides:  
[https://www2.cs.arizona.edu/~pacheco/courses/csc535\\_fall20/lectures/pgms.pdf](https://www2.cs.arizona.edu/~pacheco/courses/csc535_fall20/lectures/pgms.pdf)
- Additional reading: Bishop, "Pattern Recognition and Machine Learning", Section 8.1-8.2