

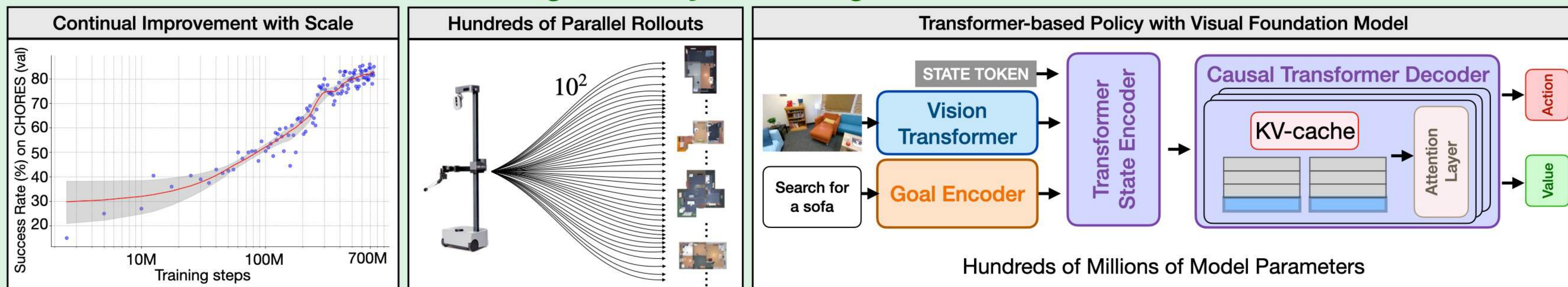
# PoliFormer: Scaling On-Policy RL with Transformers Results in Masterful Navigators

Kuo-Hao Zeng, Zichen "Charles" Zhang, Kiana Ehsani, Rose Hendrix, Jordi Salvador, Alvaro Herrasti, Ross Girshick, Aniruddha Kembhavi, Luca Weihs

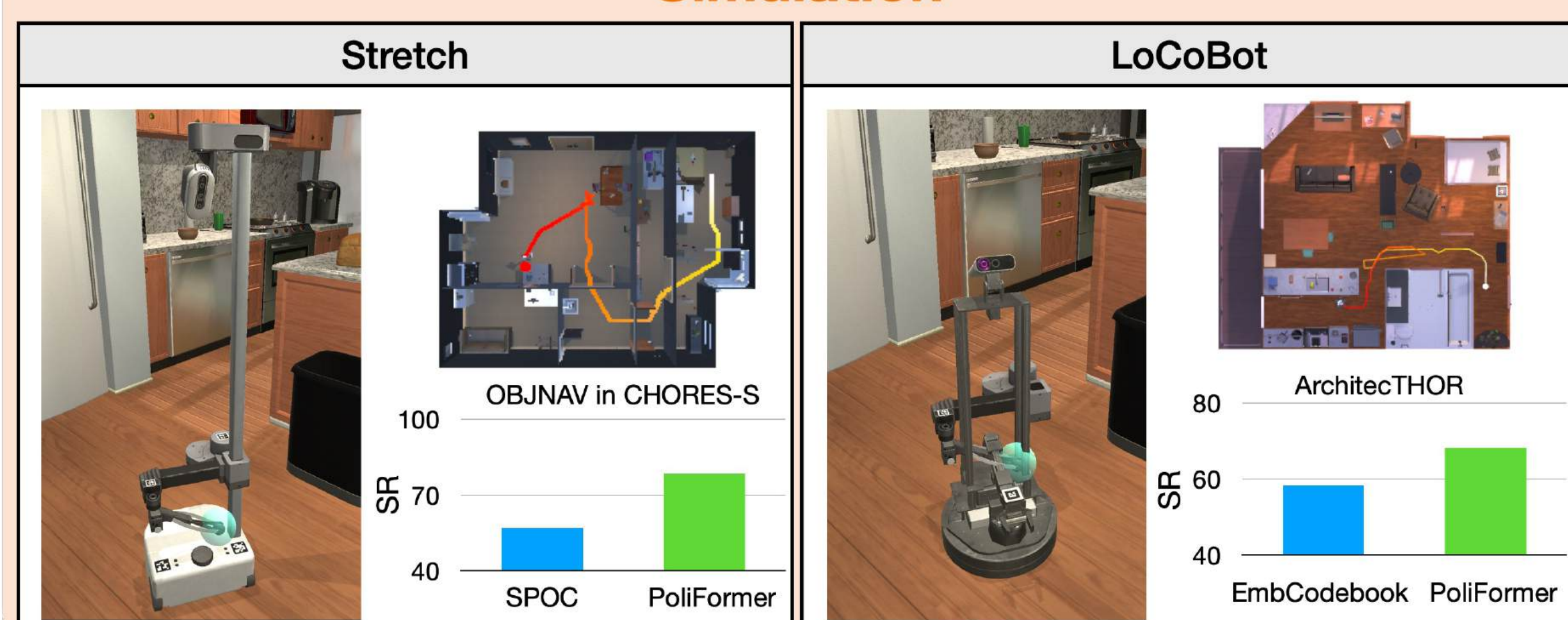


poliformer.allen.ai

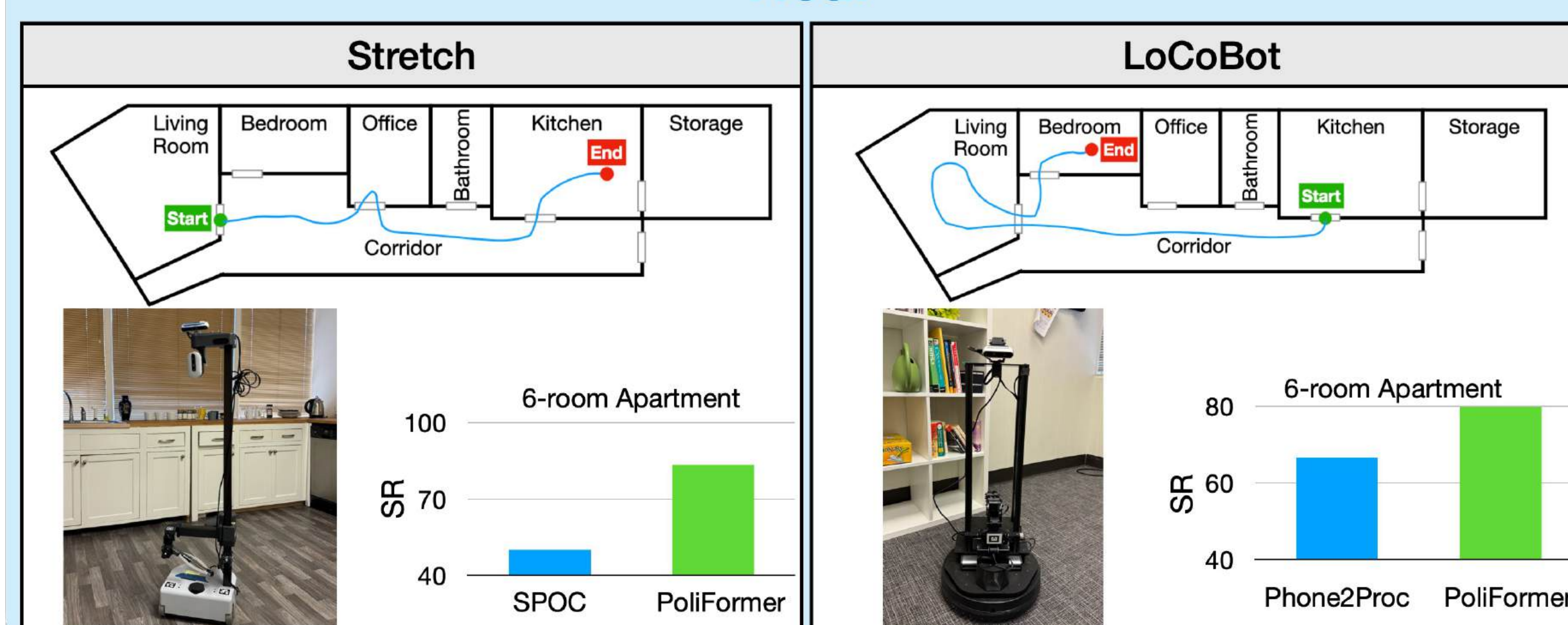
## Scaling On-Policy RL Training with Transformers



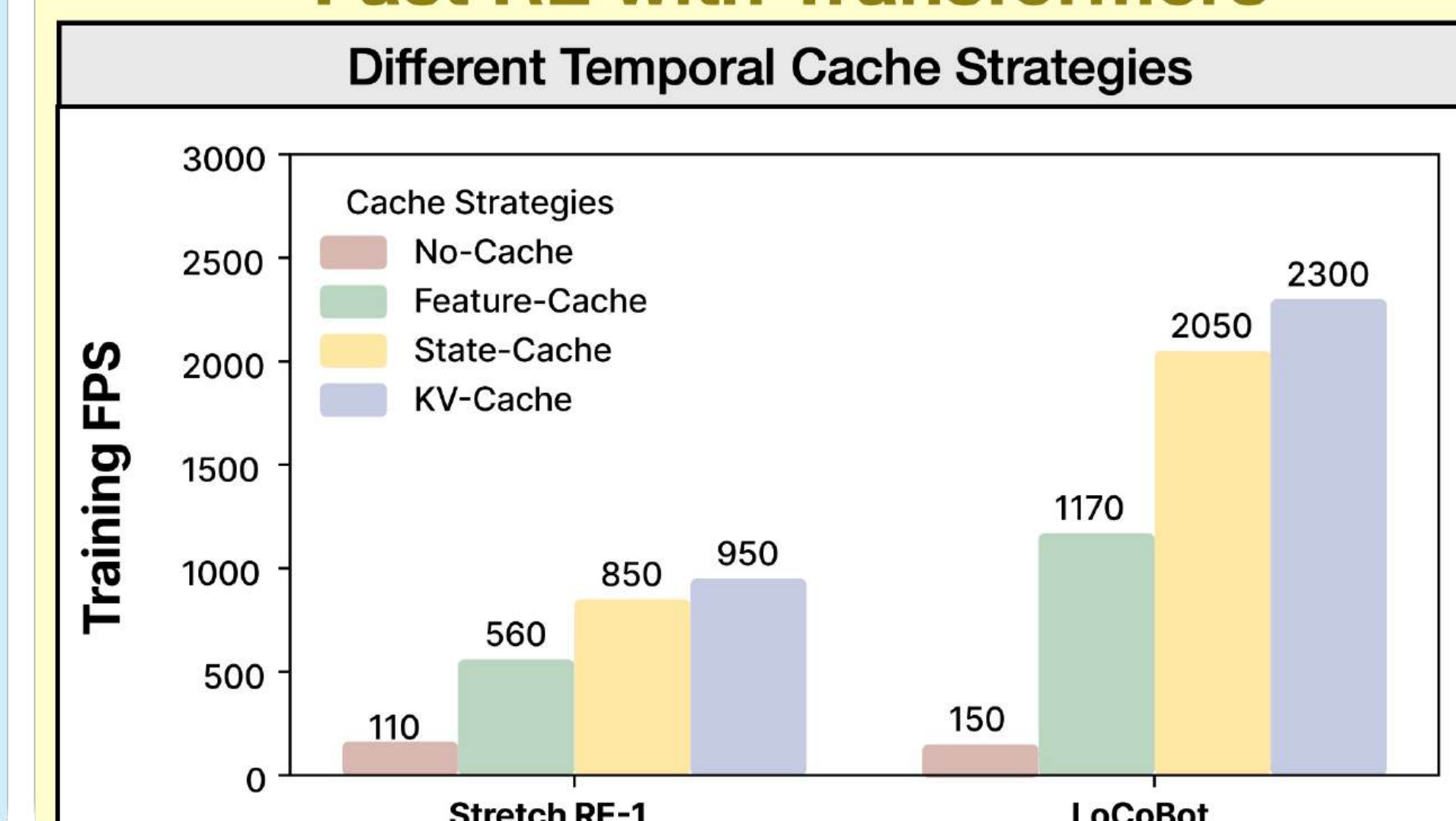
### Simulation



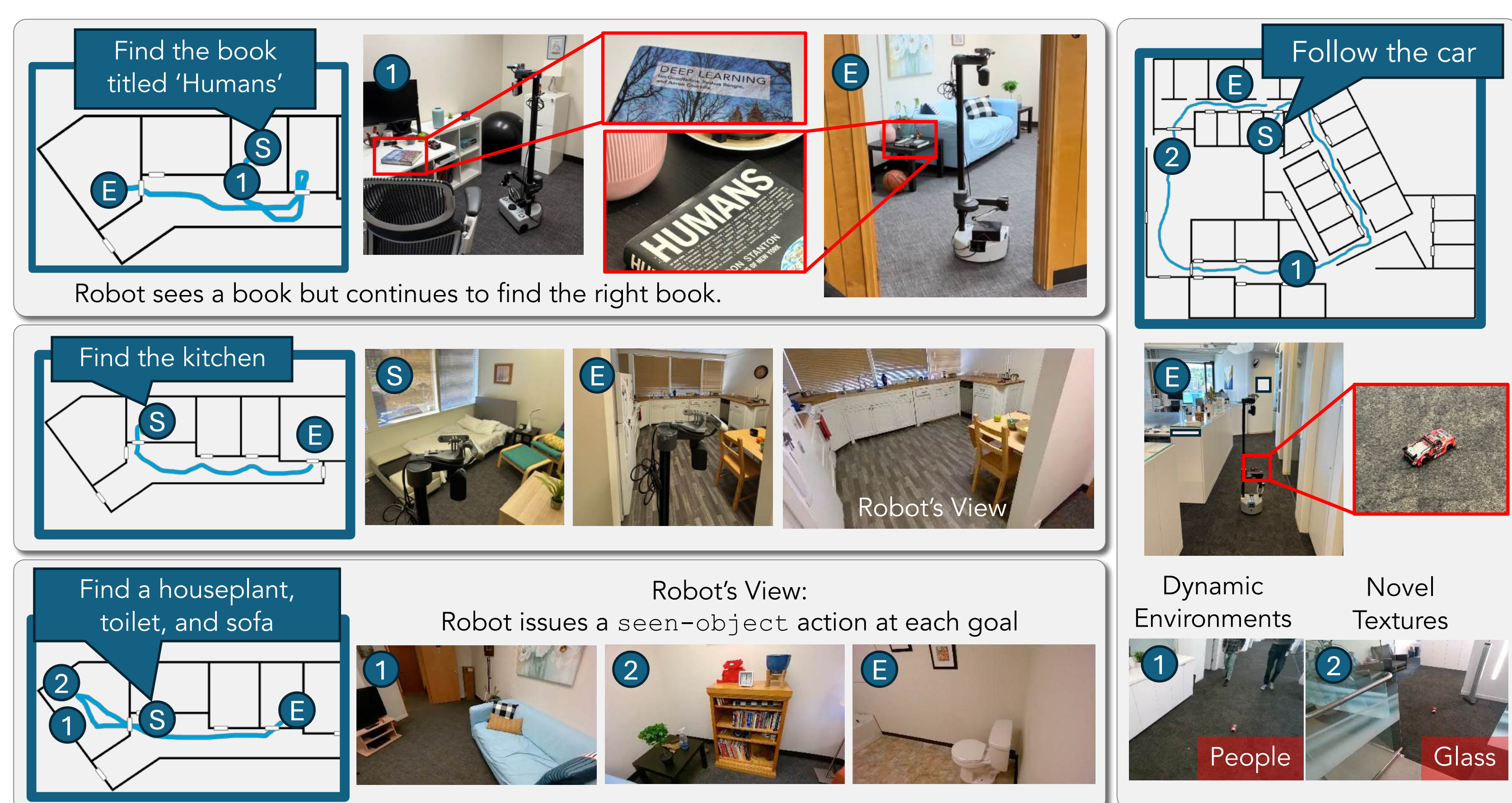
### Real



### Fast RL with Transformers

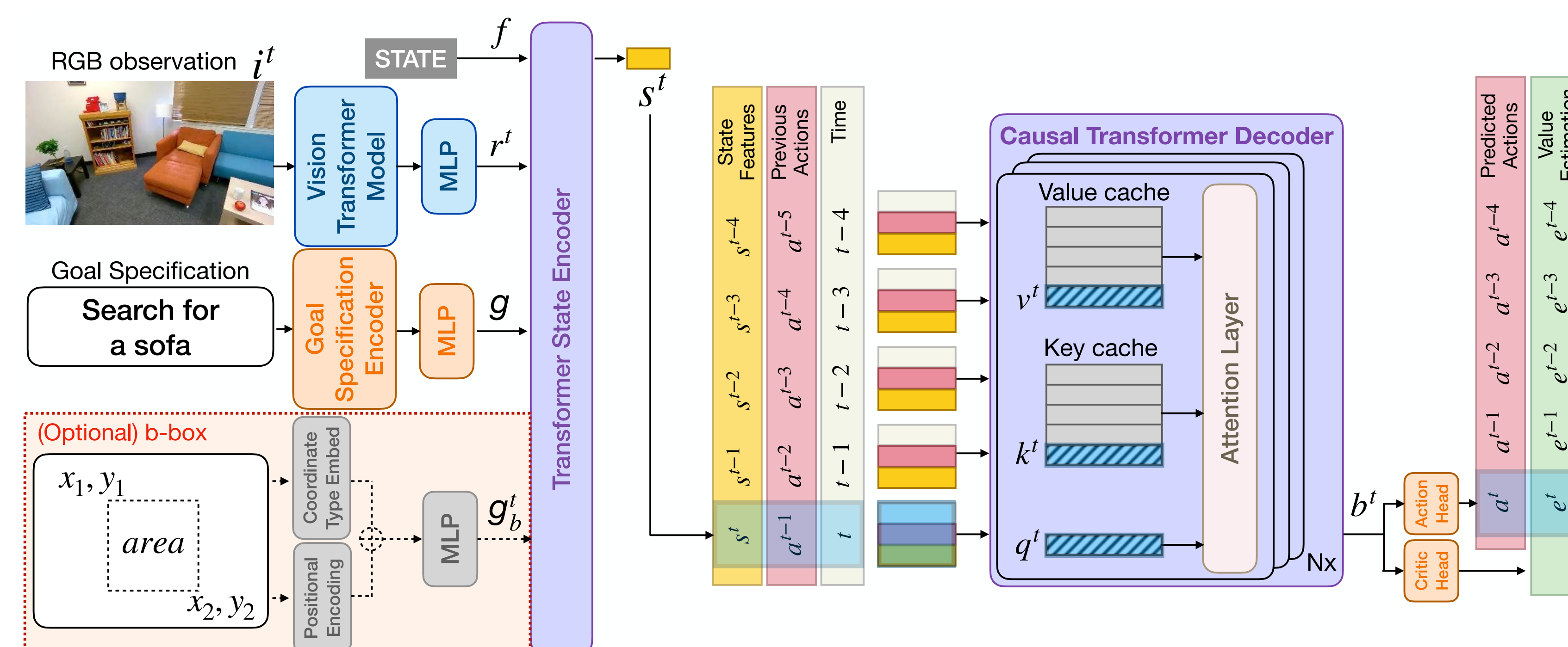


## Zero-Shot Downstream Tasks



## Scale Model and Data

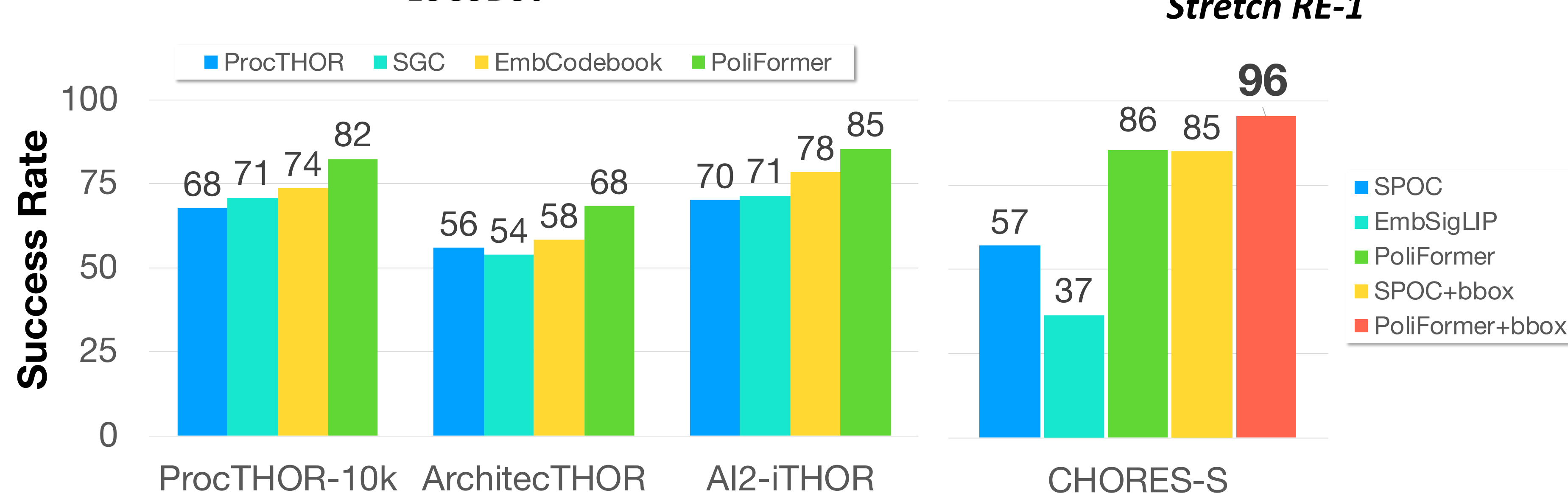
### Scale in Architecture



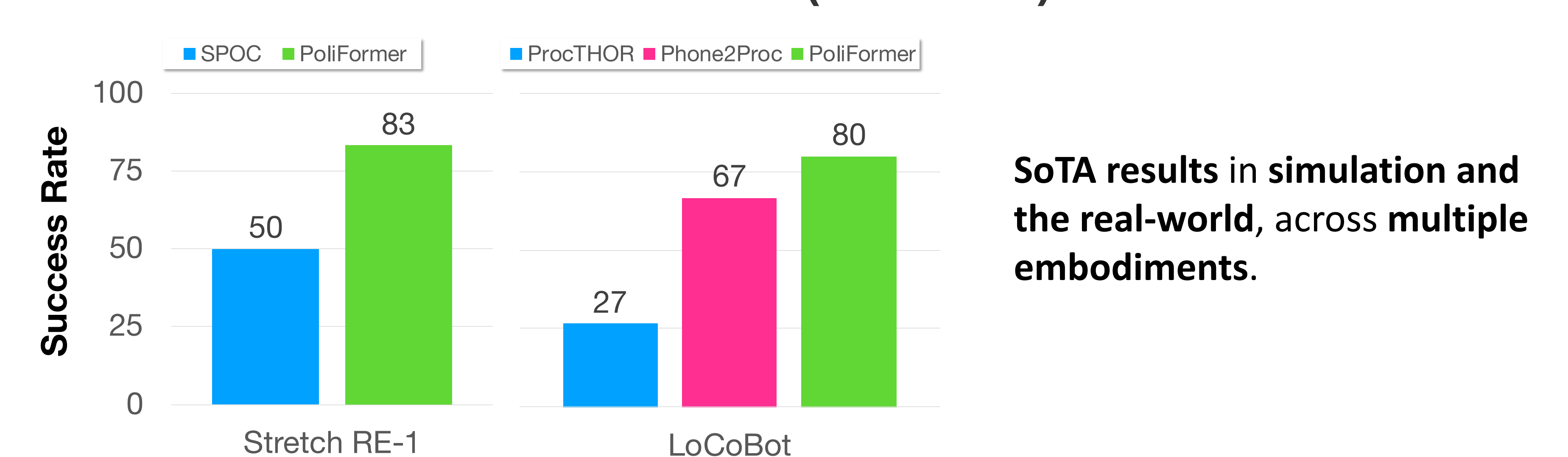
## Quantitative Results

### Simulation

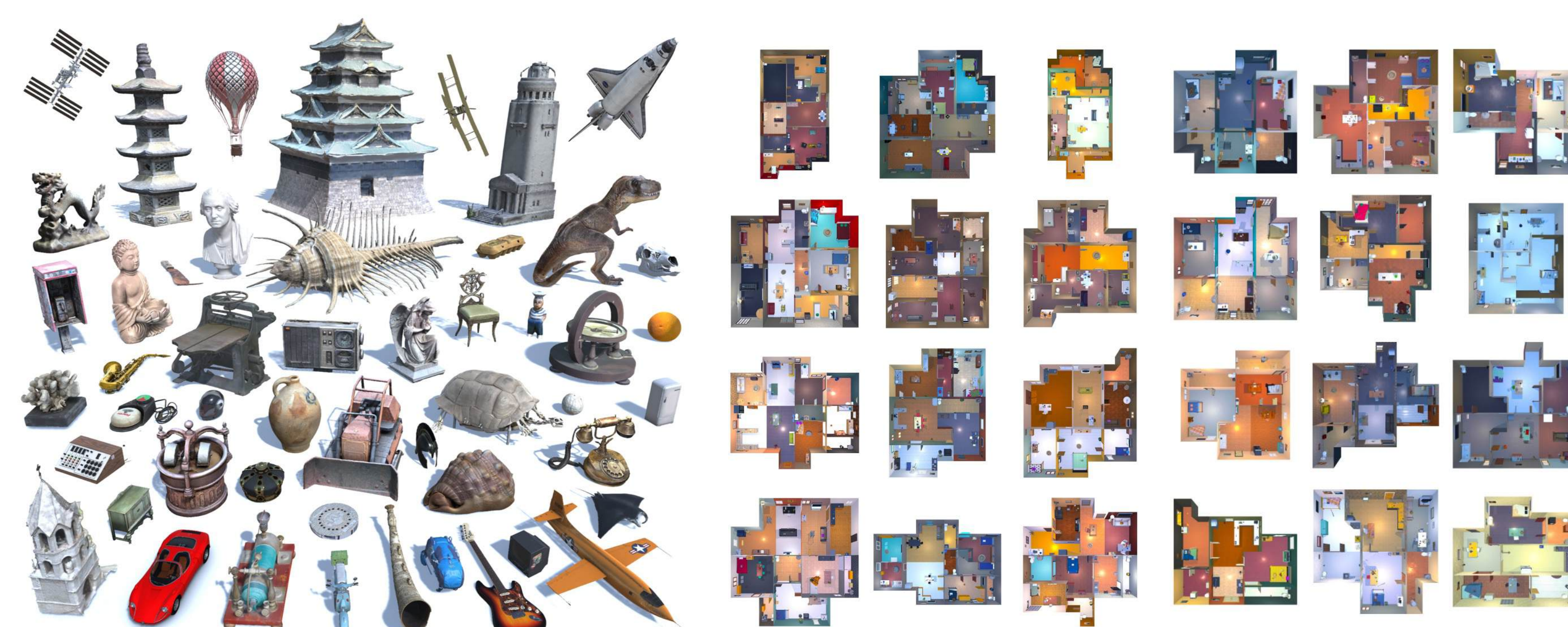
#### LoCoBot



### Real-World (zero-shot)



### Scale in Diverse Environment Interactions



Hundreds of parallel rollouts and large batch sizes lead to high training throughput and allow us to train for 700M training interactions.

150k ProcTHOR houses with ~40k Objaverse assets.