

doris::vectorized::
VSortedRunMerger::get_next

doris::vectorized::
VExchangeNode::get_next

doris::ExecNode::reached
_limit

set_num_rows

```
graph LR; A[doris::vectorized::VSortedRunMerger::get_next] --> D[set_num_rows]; B[doris::vectorized::VExchangeNode::get_next] --> D; C[doris::ExecNode::reached_limit] --> D;
```

The diagram illustrates a control flow where three different execution paths converge on a single target. The target node, 'set_num_rows', is a gray rectangle on the right. Three white rectangles on the left represent the source nodes. Blue arrows point from each source node to the target node. The top source node is 'doris::vectorized::VSortedRunMerger::get_next', the middle one is 'doris::vectorized::VExchangeNode::get_next', and the bottom one is 'doris::ExecNode::reached_limit'.