INVX4(data type: typ)

Function

Y=!A

Static Power:

When	Static Power [nW]	
-	0.0614	

Port:

Name	Direction
A	INPUT
Y	OUTPUT

Name	Pin Capacitance [pF]		
	Rise	Fall	
A	0.0663	0.0665	

Output Driving Strength

Name	me Rise Strength (sec/F) Limit (pF)		Fall	
Name			Strength (sec/F)	Limit (pF)
Y	431	1.86	491	1.86

Link To Path

PATH	WHEN
(01A=>10Y)	-
(10A=>01Y)	-

(01A=>10Y)

DELAY [ns]

cl[pF]	0.1	0.2	0.4	1.2	2.4
ts[ns]					
0.06	0.0832	0.133	0.232	0.625	1.21
0.18	0.103	0.157	0.253	0.645	1.23
0.42	0.125	0.195	0.307	0.691	1.28
0.6	0.136	0.215	0.338	0.73	1.31
1.2	0.155	0.255	0.411	0.868	1.44

POWER [pJ]

cl[pF]	0.1	0.2	0.4	1.2	2.4
ts[ns]	0.1	0.2	0.4	1.4	2.4
0.06	0.594	0.564	0.544	0.522	0.516
0.18	0.344	0.403	0.45	0.484	0.497
0.42	0.466	0.26	0.0438	0.235	0.351
0.6	1.17	0.878	0.546	0.0602	0.165
1.2	3.68	3.21	2.58	1.44	0.784

Back To Path Index

(10A = > 01Y)

DELAY [ns]

cl[pF]	0.1	0.2	0.4	1.2	2.4
ts[ns]	U.1	U. 2	0.4	1.4	2.4
0.06	0.0795	0.123	0.207	0.553	1.07
0.18	0.111	0.158	0.242	0.584	1.1
0.42	0.158	0.22	0.318	0.654	1.17
0.6	0.184	0.257	0.367	0.71	1.22
1.2	0.258	0.354	0.499	0.904	1.4

POWER [pJ]

cl[pF]	0.1	0.2	0.4	1.2	2.4
ts[ns]	U.1	U. 2	0.4	1.4	2.4
0.06	1.34	1.36	1.36	1.4	1.41
0.18	1.66	1.58	1.51	1.44	1.42
0.42	2.55	2.34	2.11	1.78	1.63
0.6	3.29	3.02	2.69	2.15	1.87
1.2	5.86	5.48	4.93	3.79	3.05