

# NAND3X1(data type: typ)

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## Function

$Y = \neg(A \& B \& C)$

## Static Power:

When	Static Power [nW]
-	0.0798

## Port:

Name	Direction
A	INPUT
B	INPUT
C	INPUT
Y	OUTPUT

Name	Pin Capacitance [pF]	
	Rise	Fall
A	0.0269	0.0268
B	0.0269	0.0268
C	0.0271	0.0272

## Output Driving Strength

Name	Rise		Fall	
	Strength (sec/F)	Limit (pF)	Strength (sec/F)	Limit (pF)
Y	1.8e+03	0.416	1.26e+03	0.416

## Link To Path

PATH	WHEN
<a href="#">(01B=&gt;10Y)</a>	-
<a href="#">(10B=&gt;01Y)</a>	-
<a href="#">(01A=&gt;10Y)</a>	-
<a href="#">(10A=&gt;01Y)</a>	-

<a href="#">(01C=&gt;10Y)</a>	-
<a href="#">(10C=&gt;01Y)</a>	-

(01B=>10Y)

DELAY [ns]

cl[pF]	0.025	0.05	0.1	0.3	0.6
ts[ns]					
0.06	0.0764	0.107	0.172	0.426	0.804
0.18	0.0726	0.109	0.175	0.426	0.804
0.42	0.0506	0.0994	0.179	0.437	0.811
0.6	0.029	0.0835	0.173	0.446	0.819
1.2	-0.061	0.00887	0.124	0.458	0.851

POWER [pJ]

cl[pF]	0.025	0.05	0.1	0.3	0.6
ts[ns]					
0.06	0.149	0.143	0.136	0.131	0.129
0.18	0.0768	0.0891	0.0993	0.115	0.12
0.42	0.202	0.145	0.0806	0.0112	0.0553
0.6	0.446	0.365	0.265	0.106	0.0236
1.2	1.32	1.19	1	0.633	0.407

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(10B=>01Y)

DELAY [ns]

cl[pF]	0.025	0.05	0.1	0.3	0.6
ts[ns]					
0.06	0.127	0.174	0.264	0.627	1.17
0.18	0.167	0.212	0.3	0.658	1.2
0.42	0.253	0.301	0.387	0.733	1.27
0.6	0.313	0.365	0.456	0.796	1.32
1.2	0.494	0.561	0.671	1.03	1.53

POWER [pJ]

cl[pF]	0.025	0.05	0.1	0.3	0.6
ts[ns]					
0.06	0.823	0.838	0.852	0.873	0.878
0.18	0.9	0.902	0.888	0.882	0.883
0.42	1.19	1.15	1.09	0.992	0.947
0.6	1.45	1.38	1.29	1.12	1.03

<b>1.2</b>	2.33	2.24	2.09	1.73	1.47
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(01A=>10Y)

DELAY [ns]

<b>cl[pF]</b>	<b>0.025</b>	<b>0.05</b>	<b>0.1</b>	<b>0.3</b>	<b>0.6</b>
<b>ts[ns]</b>					
<b>0.06</b>	0.0781	0.113	0.176	0.43	0.808
<b>0.18</b>	0.0681	0.102	0.166	0.417	0.796
<b>0.42</b>	0.0286	0.0717	0.144	0.397	0.771
<b>0.6</b>	-0.00533	0.0426	0.122	0.385	0.757
<b>1.2</b>	-0.133	-0.0738	0.0271	0.334	0.718

POWER [pJ]

<b>cl[pF]</b>	<b>0.025</b>	<b>0.05</b>	<b>0.1</b>	<b>0.3</b>	<b>0.6</b>
<b>ts[ns]</b>					
<b>0.06</b>	0.155	0.146	0.139	0.131	0.128
<b>0.18</b>	0.0975	0.104	0.106	0.117	0.124
<b>0.42</b>	0.198	0.147	0.0884	0.00214	0.0475
<b>0.6</b>	0.462	0.385	0.29	0.131	0.0444
<b>1.2</b>	1.42	1.29	1.11	0.732	0.492

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(10A=>01Y)

DELAY [ns]

<b>cl[pF]</b>	<b>0.025</b>	<b>0.05</b>	<b>0.1</b>	<b>0.3</b>	<b>0.6</b>
<b>ts[ns]</b>					
<b>0.06</b>	0.146	0.192	0.284	0.646	1.19
<b>0.18</b>	0.188	0.232	0.319	0.678	1.22
<b>0.42</b>	0.283	0.328	0.41	0.754	1.29
<b>0.6</b>	0.352	0.398	0.484	0.819	1.34
<b>1.2</b>	0.568	0.624	0.72	1.06	1.56

POWER [pJ]

<b>cl[pF]</b>	<b>0.025</b>	<b>0.05</b>	<b>0.1</b>	<b>0.3</b>	<b>0.6</b>
<b>ts[ns]</b>					
<b>0.06</b>	1.09	1.09	1.1	1.12	1.12
<b>0.18</b>	1.18	1.17	1.14	1.13	1.12
<b>0.42</b>	1.48	1.43	1.37	1.25	1.2
<b>0.6</b>	1.76	1.69	1.59	1.4	1.29

<b>1.2</b>	2.73	2.63	2.46	2.06	1.77
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(01C=>10Y)

DELAY [ns]

<b>cl[pF]</b>	<b>0.025</b>	<b>0.05</b>	<b>0.1</b>	<b>0.3</b>	<b>0.6</b>
<b>ts[ns]</b>					
<b>0.06</b>	0.065	0.0989	0.162	0.414	0.793
<b>0.18</b>	0.07	0.114	0.181	0.431	0.808
<b>0.42</b>	0.0614	0.117	0.204	0.47	0.844
<b>0.6</b>	0.046	0.11	0.21	0.501	0.873
<b>1.2</b>	-0.0191	0.0637	0.194	0.562	0.977

POWER [pJ]

<b>cl[pF]</b>	<b>0.025</b>	<b>0.05</b>	<b>0.1</b>	<b>0.3</b>	<b>0.6</b>
<b>ts[ns]</b>					
<b>0.06</b>	0.139	0.138	0.133	0.129	0.128
<b>0.18</b>	0.0589	0.0733	0.091	0.11	0.118
<b>0.42</b>	0.212	0.151	0.0821	0.0132	0.0577
<b>0.6</b>	0.442	0.357	0.254	0.0943	0.0137
<b>1.2</b>	1.26	1.13	0.938	0.576	0.359

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(10C=>01Y)

DELAY [ns]

<b>cl[pF]</b>	<b>0.025</b>	<b>0.05</b>	<b>0.1</b>	<b>0.3</b>	<b>0.6</b>
<b>ts[ns]</b>					
<b>0.06</b>	0.101	0.15	0.243	0.608	1.15
<b>0.18</b>	0.143	0.188	0.277	0.638	1.18
<b>0.42</b>	0.214	0.269	0.361	0.711	1.25
<b>0.6</b>	0.263	0.325	0.426	0.772	1.3
<b>1.2</b>	0.41	0.491	0.618	0.994	1.5

POWER [pJ]

<b>cl[pF]</b>	<b>0.025</b>	<b>0.05</b>	<b>0.1</b>	<b>0.3</b>	<b>0.6</b>
<b>ts[ns]</b>					
<b>0.06</b>	0.537	0.565	0.588	0.625	0.636
<b>0.18</b>	0.62	0.62	0.609	0.626	0.636
<b>0.42</b>	0.895	0.849	0.796	0.722	0.692
<b>0.6</b>	1.13	1.07	0.985	0.842	0.77

<b>1.2</b>	1.96	1.87	1.72	1.4	1.17
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