Random Forests – A Long-Short Strategy for Japanese Stocks

Wu Zhuoyuan, Wu Tingan, Qiu Zixin

WHU Fintech Stu

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Decision trees – learning rules from data

How trees learn and apply decision rules Decision trees in practice Overfitting and regularization Hyperparameter tuning

Random forests – making trees more reliable

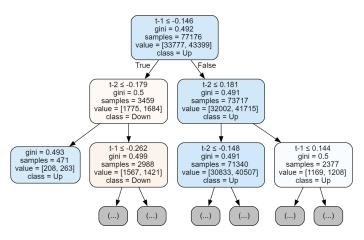
Why ensemble models perform better Bootstrap aggregation Random forests

What is a decision tree

- Decision trees learn and sequentially apply a set of rules that split data points into subsets and then make one prediction for each subset. The predictions are based on the outcome values for the subset of training samples that result from the application of a given sequence of rules.
- Classification trees predict a probability estimated from the relative class frequencies or the value of the majority class directly.
- Regression trees compute prediction from the mean of the outcome values for the available data points.

How trees learn and apply decision rules

What is a decision tree

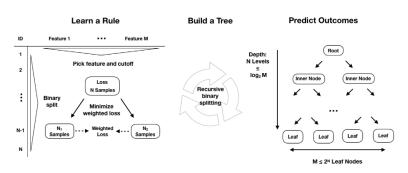


How decision trees grow?

- ▶ To build an entire tree during training, the learning algorithm repeats this process of dividing the feature space, that is, the set of possible values for the p input variables, X1, X2, ..., Xp, into mutually-exclusive and collectively exhaustive regions, each represented by a leaf node.
- Tree-based learning takes a top-down, greedy approach, known as recursive binary splitting, to overcome this computational limitation.
- The splitting logic of regression and classification trees are different.

How decision trees grow?

The following diagram highlights how the model learns a rule:



Differences between Linear Models and Decision Trees

- For a linear model, the parameter values allow an interpretation of the impact of the input variables on the output and the model's prediction.
- For a decision tree, the various possible paths from the root to the leaves determine how the features and their values lead to specific decisions by the model.
- As a consequence, decision trees are capable of capturing interdependence among features that linear models cannot capture.

The data – monthly stock returns and features

- We will select a subset of the Quandl US equity dataset covering the period 2006-2017. And we will compute monthly returns and 25 (hopefully) predictive features for the 500 most-traded stocks based on the 5-year moving average of their dollar volume, yielding 56756 observations. The features include:
 - ▶ **Historical returns** for the past 1, 3, 6, and 12 months.
 - Momentum indicators that relate the most recent 1- or 3-month returns to those for longer horizons.
 - ▶ **Technical indicators** designed to capture volatility like the (normalized) average true range (NATR and ATR) and momentum like the **relative strength index** (RSI).
 - Factor loadings for the five Fama-French factors based on rolling OLS regressions.
 - Categorical variables for year and month, as well as sector.

Building a regression tree with time-series data

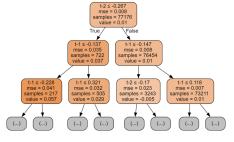
Regression trees make predictions based on the mean outcome value for the training samples assigned to a given node, and typically rely on the mean-squared error to select optimal rules during recursive binary splitting.

$$egin{aligned} D &= \{\mathbf{x}_i, y_i\}_{i=1}^n & \mathbf{x}_i &= \{x_i^1, x_i^2, \cdots, x_i^d\} \ R_1(j,s) &= \{\mathbf{x}_i | x_i^j \leq s\} & R_2(j,s) &= \{\mathbf{x}_i | x_i^j > s\} \ \hat{c}_1 &= rac{1}{|R_1(j,s)|} \sum_{\mathbf{x}_i \in R_1(j,s)} y_i & \hat{c}_2 &= rac{1}{|R_2(j,s)|} \sum_{\mathbf{x}_i \in R_2(j,s)} y_i \ &\min_{j,s} \left[\sum_{\mathbf{x}_i \in R_1(j,s)} (y_i - \hat{c}_1)^2 + \sum_{\mathbf{x}_i \in R_2(j,s)} (y_i - \hat{c}_2)^2
ight] \end{aligned}$$

Building a regression tree with time-series data

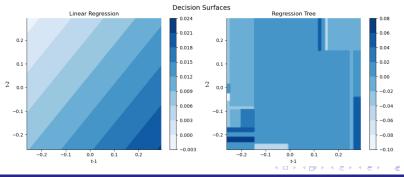
We will only use 2 months of lagged returns to predict the following month, in the vein of an AR(2) model from the previous chapter.

OLS Regression Results								
Dep. Variable Model: Method: Date: Time: No. Observati Df Residuals: Df Model: Covariance Ty	ons:	Sun, 04	Squar	50 76 73 2	Adj. F-st Prob	uared: R-squared: atistic: (F-statistic): Likelihood:		0.001 0.001 31.83 1.53e-14 75823. -1.516e+05 -1.516e+05
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Building a regression tree with time-series data

▶ To further illustrate the difference, we can visualize the current return predictions as a function of the feature space, that is, as a function of the range of values for the lagged returns.



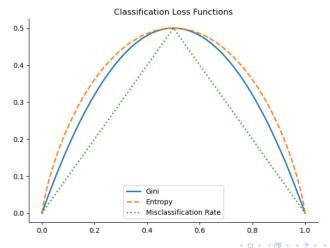
Building a classification tree

When growing a classification tree, we also use recursive binary splitting, but instead of evaluating the quality of a decision rule using the reduction of the mean-squared error, we can use Gini impurity or cross-entropy, which are more sensitive to node purity that refers to the extent of the preponderance of a single class in a node.

$$\begin{aligned} & \text{Gini impurity} = \sum_{k} p_{mk} (1 - p_{mk}) \\ & \text{cross entropy} = - \sum_{k} p_{mk} \log(p_{mk}) \end{aligned}$$

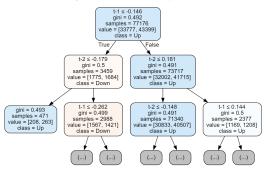
Decision trees in practice

Building a classification tree



Building a classification tree

The following diagram shows how the model uses different features and indicates the split rules for both continuous and categorical (dummy) variables:



Overfitting and regularization

Overfitting

- Decision trees have a strong tendency to overfit, especially when a dataset has a large number of features relative to the number of samples.
- There are multiple ways to address the risk of overfitting, including:
 - Dimensionality reduction improves the feature-to-sample ratio by representing the existing features with fewer, more informative, and less noisy features.
 - Ensemble models, such as random forests, combine multiple trees while randomizing the tree construction
- Decision trees provide several regularization hyperparameters to limit the growth of a tree and the associated complexity. And tree pruning is an more powerful tool to reduce the complexity of a tree.

Overfitting and regularization

How to regularize a decision tree

Parameter	Description	Default	Options	
max_depth	The maximum number of levels: split the nodes until max_depth has been reached. All leaves are pure or contain fewer samples than min_samples_split.	None	int	
max_features	Number of features to consider for a split.	None	None: all features int: # features float: fraction auto, sqrt: sqrt(n_ features) log2: log2(n_ features)	
max_leaf_nodes	Split nodes until creating this many leaves.	None	None: unlimited int	
min_impurity_decrease	Split node if impurity decreases by at least this value.	0	float	
min_samples_leaf	A split will only be considered if there are at least min_samples_ leaf training samples in each of the left and right branches.	1	int; float (as a percent of N)	



Decision tree pruning

- One approach to limit the number of leaf nodes is to avoid further splits unless they yield significant improvements in the objective metric. The downside of this strategy, however, is that sometimes, splits that result in small improvements enable more valuable splits later as the composition of the samples keeps changing.
- by adding a penalty for adding leaf nodes to the tree model and a regularization parameter. Applied to the large tree, an increasing penalty will automatically produce a sequence of subtrees. Cross-validation of the regularization parameter can be used to identify the optimal, pruned subtree.

Using GridsearchCV with a custom metric

As highlighted in Chapter 6, scikit-learn provides a method to define ranges of values for multiple hyperparameters. It automates the process of cross-validating the various combinations of these parameter values to identify the optimal configuration.

Ensemble model

- An ensemble integrates the predictions of several base estimators, trained using one or more learning algorithms, to reduce the generalization error that these models produce on their own.
- For ensemble learning to achieve this goal, the individual models must be:
 - Accurate
 - Independent



Why ensemble models perform better

Two groups of ensemble methods

- Averaging methods train several base estimators independently and then average their predictions.
 - Bagging
 - Random forest
- Boosting methods train base estimators sequentially with the specific goal of reducing the bias of the combined estimator. (Chapter 12, Boosting Your Trading Strategy)

Why we use bagging

- How to reduce the variance.
 - ► For a given a set of **independent** observations, each with a variance of σ^2 , the standard error of the sample mean is given by σ/\sqrt{n} .
- Bagging refers to the aggregation of bootstrap samples.
 - randomly sample with replacement.
 - has the same number of observations as the original dataset
 - may contain duplicates due to replacement.



How to apply bagging to decision trees

- **create bootstrap samples** from our training data by repeatedly sampling with replacement.
- train one decision tree on each of these samples.
- create an ensemble prediction by averaging over the predictions of the different trees.

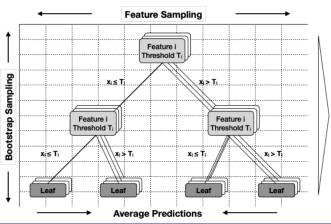
How to build a random forest

- Random forests would be:
 - To train each ensemble member on bootstrapped training data.
 - To randomly sample from the features used in the model without replacement.
- ▶ The **sample size** for the features differs:
 - For classification, the sample size is typically the square root of the number of features.
 - For regression, it can be anywhere from one-third to all features and should be selected based on cross-validation.



Random forests

How to build a random forest



Randomize tree growth to de-correlate the prediction errors and reduce the model variance



Feature importance for random forests

- For a given feature, the importance score is the total reduction in the objective function's value due to splits on this feature and is averaged over all trees.
- The score is measured in terms of the mean-squared error for regression trees and the Gini impurity or entropy for classification trees.

Random forests

Out-of-bag testing

Out-of-bag (OOB) observation

- Consider that a bootstrap sample has the same size, n, as the original sample.
- ▶ Hence, the probability of not entering a bootstrap sample at all is $(1 1/n)^n$, which converges (quickly) to 1/e, or roughly **one third**.

Random forests

Out-of-bag testing

- Predict the response for an OOB sample for each tree built without this observation.
- Average the predicted responses (if regression is the goal) or take a majority vote for a single ensemble prediction for each OOB sample.
- Average the errors of all OOB samples to produce an unbiased generalization error.

Out-of-bag testing

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(\mathbf{x}_1, y_1)	$\tilde{\mathcal{D}}_1$	*	$ ilde{\mathcal{D}}_3$		$\mathcal{ ilde{D}}_{ extcolored}$
$(\mathbf{x}_2, \mathbf{y}_2)$	*	*	$ ilde{\mathcal{D}}_3$		$\mathcal{ ilde{D}}_{ extcolored}$
$(\mathbf{x}_3, \mathbf{y}_3)$	*	$ ilde{\mathcal{D}}_{2}$	*		$\mathcal{ ilde{D}}_{ extcolored}$
• • •					
(\mathbf{x}_N, y_N)	$\mathcal{ ilde{D}}_{1}$	$ ilde{\mathcal{D}}_{2}$	*		*

Take care to avoid a lookahead bias that would ensue if OOB observations could be selected out-of-order.



Pros and cons of random forests

- Advantages
 - Perform on par with the best supervised learning algorithms.
 - ▶ Provide a **reliable feature importance** estimate.
 - Offer efficient estimates of the test error without incurring the cost of repeated model training associated with cross-validation.
- Disadvantages
 - Less interpretable
 - High computational costs
 - Slower

