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Notes of Stochastic Analysis



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1 Stochastic Analysis

1.1 Ito's Formula

To handle Ito's formula one only need to remember

$$dB_t^2 = dt, \quad dB_t dt = 0, \quad (dt)^2 = 0$$

To derive Ito's formula for an Ito process X_t satisfying $dX_t = b(t, X_t)dt + \sigma(t, X_t)dB_t$ and arbitrary function $f(t, x)$, remember to perform Taylor's expansion to 2 order:

$$df(X_t) = \nabla_t f(t, X_t)dt + \nabla_x f(t, X_t) \cdot dX_t + \frac{1}{2}(dX_t)^T \cdot \nabla_x^2 f(t, X_t) \cdot (dX_t) \quad (1.1)$$

$$= \nabla_t f dt + \nabla_x f \cdot (bdt + \sigma dB_t) + \frac{1}{2}(bdt + \sigma dB_t)^T \cdot \nabla_x^2 f \cdot (bdt + \sigma dB_t) \quad (1.2)$$

$$= \nabla_t f dt + \nabla_x f \cdot (bdt + \sigma dB_t) + \frac{1}{2}(\sigma dB_t)^T \cdot \nabla_x^2 f \cdot \sigma dB_t \quad (1.3)$$

Denote $A : B = \sum_{ij} a_{ij} b_{ji}$ we have

$$\begin{aligned} (dB_t)^T \cdot \nabla^2 f \cdot (dX_t) &= \sum_{l,k,i,j} dB_t^l \sigma_{il} \partial_{ij}^2 f \sigma_{jk} dB_t^k \\ &= \sum_{k,i,j} \sigma_{ik} \sigma_{jk} \partial_{ij}^2 f dt = \boldsymbol{\sigma} \boldsymbol{\sigma}^T : \nabla^2 f dt \end{aligned}$$

then we have Ito's formula

$$df(t, X_t) = (\nabla_t f + \nabla_x f \cdot \mathbf{b} + \frac{1}{2} \boldsymbol{\sigma} \boldsymbol{\sigma}^T : \nabla^2 f) dt + (\nabla_x f)^T \cdot \boldsymbol{\sigma} \cdot dB_t \quad (1.4)$$

For an SDE, sometimes we define an infinite small generator \mathcal{L} as

$$\mathcal{L}f = \nabla_x f \cdot \mathbf{b} + \frac{1}{2} \boldsymbol{\sigma} \boldsymbol{\sigma}^T : \nabla^2 f$$

1.2 Forward Equation

Here we wish to derive a PDE to describe $p(t, x)$, where for $s < t$

$$p(x, t | y, s) dx = \mathbb{P} \{X_t \in [x, x + dx) | X_s = y\}$$

For arbitrary $f(x)$, from Ito's formula 1.4 we have

$$\begin{aligned} f(\mathbf{X}_t) - f(\mathbf{X}_s) &= \int_s^t \nabla f(\mathbf{X}_\tau) \cdot \{\mathbf{b}(\mathbf{X}_\tau, \tau) d\tau + \boldsymbol{\sigma}(\mathbf{X}_\tau, \tau) d\mathbf{B}_\tau\} \\ &\quad + \frac{1}{2} \int_s^t \sum_{i,j} \partial_{ij}^2 f(\mathbf{X}_\tau) a_{ij}(\mathbf{X}_\tau, \tau) d\tau \end{aligned}$$

where the diffusion matrix $\mathbf{a}(\mathbf{x}, t) := \boldsymbol{\sigma}(\mathbf{x}, t) \boldsymbol{\sigma}^T(\mathbf{x}, t)$.

Because $\int [\cdot] d\mathbf{B}_t = 0$ and denote $X_s = y$, take expectation we get

$$\mathbb{E}f(\mathbf{X}_t) - f(y) = \mathbb{E} \int_s^t \mathcal{L}f(\mathbf{X}_\tau, \tau) d\tau$$

Take derivative of time on both side

$$\int_{\mathbb{R}^d} f(\mathbf{x}) \cdot \partial_t p(\mathbf{x}, t | \mathbf{y}, s) d\mathbf{x} = \int_{\mathbb{R}^d} \mathcal{L}f(\mathbf{x}, \tau) \cdot p(\mathbf{x}, \tau | \mathbf{y}, s) d\mathbf{x}$$

that is

$$(f, \partial_t p)_{L^2} = (\mathcal{L}f, p)_{L^2} = (f, \mathcal{L}^* p)_{L^2}$$

we get

$$\partial_t p = \mathcal{L}^* p$$

This is forward equation (or Fokker-Planck equation), where "forward" means taking derivative of future time t . We can calculate that the adjoint of \mathcal{L} is

$$\mathcal{L}^* f(\mathbf{x}, t) = -\nabla_{\mathbf{x}} \cdot (\mathbf{b}(\mathbf{x}, t) f(\mathbf{x})) + \frac{1}{2} \nabla_{\mathbf{x}}^2 : (\mathbf{a}(\mathbf{x}, t) f(\mathbf{x}))$$

where $\nabla_{\mathbf{x}}^2 : (\mathbf{a}f) = \sum_{ij} \partial_{ij} (a_{ij} f)$.

1.3 Backward Equation

For arbitrary $f(x)$ define

$$u(\mathbf{y}, s) = \mathbb{E}^{\mathbf{y}, s} f(\mathbf{X}_t) = \int_{\mathbb{R}^d} f(\mathbf{x}) p(\mathbf{x}, t | \mathbf{y}, s) d\mathbf{x}, \quad s \leq t$$

$$du(\mathbf{X}_\tau, \tau) = (\partial_\tau u + \mathcal{L}u)(\mathbf{X}_\tau, \tau) d\tau + \nabla u \cdot \boldsymbol{\sigma} \cdot d\mathbf{W}_\tau$$

Taking expectation

$$\begin{aligned} \lim_{t \rightarrow s} \frac{1}{t-s} (\mathbb{E}^{\mathbf{y}, s} u(\mathbf{X}_t, t) - u(\mathbf{y}, s)) &= \lim_{t \rightarrow s} \frac{1}{t-s} \int_s^t \mathbb{E}^{\mathbf{y}, s} (\partial_\tau u + \mathcal{L}u)(\mathbf{X}_\tau, \tau) d\tau \\ &= \partial_s u(\mathbf{y}, s) + \mathcal{L}u(\mathbf{y}, s) \end{aligned}$$

Based on

$$\mathbb{E}^{\mathbf{y},s} u(\mathbf{X}_t, t) = \mathbb{E}^{\mathbf{y},s} f(\mathbf{X}_t) = u(\mathbf{y}, s)$$

we get

$$\partial_s u(\mathbf{y}, s) + \mathcal{L}u(\mathbf{y}, s) = 0$$

and then

$$\partial_s p(x, t | \mathbf{y}, s) + \mathcal{L}_{\mathbf{y}} p(x, t | \mathbf{y}, s) = 0$$

This is backward equation. Backward means taking derivative of previous time s .

2 SDE & MCMC

2.1 SGLD

Let's say we want to sample from $p(\theta|X) = p(\theta)p(X|\theta)/Z$. We hope $p(\theta|X)$ is a stationary distribution of SDE $d\theta_t = b(\theta_t)dt + \sigma(\theta_t)dW_t$. The forward equation is

$$\frac{\partial \mu_t}{\partial t} = -\nabla_{\theta} \cdot (\mu_t b(\theta_t)) + \frac{1}{2} \nabla_{\theta}^2 : (\sigma \sigma^T \mu_t)$$

If $\mu_t = \mu_t(\theta_t)$ is the stationary distribution, then $\frac{\partial \mu_t}{\partial t} = 0$.

Now we set

$$U(\theta) = \log p(X|\theta) + \log p(\theta)$$

(which means $p(\theta|X) = \exp(U(\theta))/Z$),

$b(\theta) = \frac{1}{2} \nabla_{\theta} U(\theta)$ and $\sigma(\theta) = I$, then $\frac{\partial \mu_t}{\partial t} = -\nabla_{\theta} \cdot (\frac{1}{2} \mu_t \nabla U(\theta_t)) + \frac{1}{2} \nabla_{\theta} \cdot (\nabla \mu_t) = 0$:

$$\nabla_{\theta} \cdot (\mu_t \nabla_{\theta} U(\theta)) = \nabla_{\theta} \cdot (\nabla_{\theta} \mu_t) \quad (2.1)$$

$$\mu_t \nabla_{\theta} U(\theta) = \nabla_{\theta} \mu_t \quad (2.2)$$

$$\mu_t \propto \exp(U(\theta)) \propto p(\theta|X) \quad (2.3)$$

Now we can discrete the SDE ($d\theta_t = \frac{1}{2} \nabla_{\theta} U(\theta_t)dt + dW_t$) to simulate $p(\theta|X)$! (And we only need to use the score function $\nabla_{\theta} U(\theta) = \nabla_{\theta} \log p(\theta|X)$.)

2.2 Stochastic Gradient Hamiltonian MC

Still we define $U(\theta) = \log p(X|\theta) + \log p(\theta)$ and $H(\theta, r) = U(\theta) + \frac{1}{2} r^T M^{-1} r$. Introduce an augment variable r and, define a joint distribution $\pi(\theta, r) \propto \exp(-H(\theta, r))$.

Now let's dive into this 2-order SDE:

$$d \begin{bmatrix} \theta \\ r \end{bmatrix} = - \begin{bmatrix} 0 & -I \\ I & B \end{bmatrix} \begin{bmatrix} \nabla U(\theta) \\ M^{-1} r \end{bmatrix} dt + \begin{bmatrix} 0 & 0 \\ 0 & \sqrt{2B} \end{bmatrix} dW_t \quad (2.4)$$

$$= -[D + G] \nabla H(\theta, r) dt + \mathcal{N}(0, 2Ddt) \quad (2.5)$$

where $G = \begin{bmatrix} 0 & -I \\ I & 0 \end{bmatrix}$, $D = \begin{bmatrix} 0 & 0 \\ 0 & B \end{bmatrix}$.

Its Fokker-Planck equation is

$$\partial_t p_t(\theta, r) = \nabla^T \{ [D + G] [\nabla H(\theta, r) p_t(\theta, r)] \} + \nabla^T [D \nabla p_t(\theta, r)] \quad (2.6)$$

$$= \nabla^T \{ [D + G] [p_t(\theta, r) \nabla H(\theta, r) + \nabla p_t(\theta, r)] \} \quad (2.7)$$

Let $z = (\theta, r)$, here we use

$$\begin{aligned} \nabla^T [D \nabla p_t(\theta, r)] &= \sum_{ij} \partial_{z_i} [D_{ij}(z) \partial_{z_j} p_t(z)] \\ &= \sum_{ij} \partial_{z_i} [D_{ij}(z) \partial_{z_j} p_t(z)] + \sum_{ij} \partial_{z_i} \left[\left(\partial_{z_j} D_{ij}(z) \right) p_t(z) \right] \\ &= \sum_{ij} \partial_{z_i} \partial_{z_j} [D_{ij}(z) p_t(z)] \end{aligned} \quad (2.8)$$

because $\partial_{z_j} D_{ij}(z) = \partial_{r_j} B_{ij}(\theta) = 0$

and $\nabla^T [G \nabla p_t(\theta, r)] = -\partial_\theta \partial_r p_t(\theta, r) + \partial_r \partial_\theta p_t(\theta, r) = 0$.

Because

$$e^{-H(\theta, r)} \nabla H(\theta, r) + \nabla e^{-H(\theta, r)} = 0$$

so it's easy to see $\pi(\theta, r)$ is the stationary distribution of the 2-order SDE.

3 Gradient Flow

3.1 General Case

$$\partial_t \mu_t = -\nabla \cdot (\mathbf{v}_t \mu_t) = \nabla \cdot \left(\mu_t \nabla \left(\frac{\delta E}{\delta \mu_t}(\mu_t) \right) \right) \quad (3.1)$$

3.2 SGLD

Define energy function

$$E(\mu) \triangleq \underbrace{-\int U(\boldsymbol{\theta}) \mu(\boldsymbol{\theta}) d\boldsymbol{\theta}}_{E_1} + \underbrace{\int \mu(\boldsymbol{\theta}) \log \mu(\boldsymbol{\theta}) d\boldsymbol{\theta}}_{E_2}$$

If $U(\boldsymbol{\theta}) = \log p_\theta$, then $E(\mu) = KL(\mu || p_\theta)$.

we have

$$\frac{\delta E_1}{\delta \mu} = -U, \quad \frac{\delta E_2}{\delta \mu} = \log \mu + 1$$

substitute this in Eq 3.1 we get

$$\partial_t \mu_t = \nabla \cdot (\mu_t \nabla (-U + \log \mu_t)) = -\nabla_\theta \cdot \left(\frac{1}{2} \mu_t \nabla U(\theta_t) \right) + \frac{1}{2} \nabla_\theta \cdot (\nabla \mu_t)$$

This is same as the FPE in 2.1. So that FPE is also a gradient flow.

4 Generator of Stochastic Process

4.1 Definition

Let's say $\{x_t\}_t$ is a continuous time stochastic process, then its generator is

$$\mathcal{G}f := \frac{d}{dt} \mathbb{E}[f(x_t)|x_0]|_{t=0} = \lim_{t \rightarrow 0} \mathbb{E}\left[\frac{f(x_t) - f(x_0)}{t}\right]$$

The generator of SVGD has not been studied yet due to the interaction of particles, while that of SGLD is straight forward:

4.2 Generator of SGLD

SGLD is

$$x_\epsilon \leftarrow x_0 + \frac{\epsilon}{2} \nabla \log p(x_0) + \sqrt{\epsilon} \eta$$

where $\eta \sim N(0, 1)$. Then its generator is

$$\mathcal{G}f(x_0) = \lim_{t \rightarrow 0} \frac{\mathbb{E}[f(x_t) - f(x_0)]}{t} \tag{4.1}$$

$$= \lim_{t \rightarrow 0} \frac{\mathbb{E}[\nabla f(x_0)^T (x_t - x_0) + \frac{1}{2} (x_t - x_0)^T \nabla^2 f(x_0) (x_t - x_0)] + O(t^2)}{t} \tag{4.2}$$

$$= \frac{1}{2} \nabla f(x_0)^T \nabla \log p(x_0) + \frac{1}{2} \mathbb{E}[\eta^T \nabla^2 f \eta] \tag{4.3}$$

$$= \frac{1}{2} \nabla f^T \nabla \log p + \frac{1}{2} \text{Trace}(\nabla^2 f)|_{x=x_0} \tag{4.4}$$