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main.c
// filename ***** Main.C *****
// LCD Display (HD44780) on Port H for the 9S12DP512
// Jonathan W. Valvano 9/18/09
// TCNT runs at 667ns,

// This example accompanies the books
// "Embedded Microcomputer Systems: Real Time Interfacing",
// Thompson, copyright (c) 2006,
// "Introduction to Embedded Systems: Interfacing to the Freescale 9S12",
// Cengage Publishing 2009, ISBN-10: 049541137X | ISBN-13: 9780495411376

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// Purpose: test program for 4-bit LCD.C driver

/*
size is 1*16
if do not need to read busy, then you can tie R/W=ground
ground = pin 1 Vss
power = pin 2 Vdd +5V
ground = pin 3 Vlc grounded for highest contrast
PH4 = pin 4 RS (1 for data, 0 for control/status)
PH5 = pin 5 R/W (1 for read, 0 for write)
PH6 = pin 6 E (enable)
PH3 = pin 14 DB7 (4-bit data)
PH2 = pin 13 DB6
PH1 = pin 12 DB5
PH0 = pin 11 DB4
16 characters are configured as 2 rows of 8
addr 00 01 02 03 04 05 06 07 40 41 42 43 44 45 46 47
*/

#include <hidef.h> /* common defines and macros */
#include <mc9s12dp512.h> /* derivative information */
#pragma LINK_INFO DERIVATIVE "mc9s12dp512"

#include <stdio.h>
#include "LCD.H"
#include "PLL.H"
#include "fixed.h"

//-----TimerInit-----
// initialize timer module to 0.667us(Boot Mode) TCNT clock
// inputs: none
// outputs: none
void TimerInit(void){
    TSCR1 = 0x80; // Enable TCNT, 24MHz in both boot and run modes
    TSCR2 = 0x04; // divide by 16 TCNT prescale, TCNT at 667nsec
    PACTL = 0; // timer prescale used for TCNT
    /* Bottom three bits of TSCR2 (PR2,PR1,PR0) determine TCNT period
    divide FastMode(24MHz) Slow Mode (8MHz)
    000 1 42ns TOF 2.73ms 125ns TOF 8.192ms
    001 2 84ns TOF 5.46ms 250ns TOF 16.384ms
    010 4 167ns TOF 10.9ms 500ns TOF 32.768ms
    011 8 333ns TOF 21.8ms 1us TOF 65.536ms
    100 16 667ns TOF 43.7ms 2us TOF 131.072ms
    101 32 1.33us TOF 87.4ms 4us TOF 262.144ms
    110 64 2.67us TOF 174.8ms 8us TOF 524.288ms
    111 128 5.33us TOF 349.5ms 16us TOF 1.048576s */
    // Be careful, TSCR1 and TSCR2 maybe set in other rituals
}

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//-----mwait-----
// wait specified number of msec
// Input: number of msec to wait
// Output: none
// assumes TCNT timer is running at 667ns
void mwait(unsigned short msec){
    unsigned short startTime;
    for(; msec>0; msec--){
        startTime = TCNT;
        while((TCNT-startTime) <= 1500){}
    }
}

//-----check-----
// if LCD broken toggle LED1 at 2Hz
// Input: last LCD status, 0 means bad
// Output: none
// Error: if status is zero, this function will not return
void check(short status){ // 0 if LCD is broken
    if(status ==0){
        for(;;) {
            PTP ^= 0x80; // fast toggle LED
            mwait(250); // 0.25 sec wait
        }
    }
}

//-----swait-----
// wait specified 2 sec, then clear LCD
// Input: none
// Output: none
// uses mwait and TCNT timer
void swait(void){
    PTP ^= 0x80; // toggle LED0
    mwait(2000); // 2 sec wait
    check(LCD_Clear());
}

//-----blank-----
// move cursor to second half of LCD display
// 32 spaces from address 08 to 40
// Input: none
// Output: none
void blank(void){
    check(LCD_OutString("
"));
}

void main(void) {
    PLL_Init(); // set E clock to 24 MHz
    TimerInit(); // enable timer
    DDRP |= 0x80; // PortP bit 7 is output to LED, used for debugging
    check(LCD_Open());
    check(LCD_Clear());
    for(;;) { // Tests the three functions of Fixed.c
        LCD_OutString("Fixed_uD"); blank();
        LCD_OutString("ecOut2");
        swait();
        LCD_OutString("0 = "); blank();
        Fixed_uDecOut2(0);
        swait();
        LCD_OutString("1 = "); blank();
        Fixed_uDecOut2(1);
        swait();
        LCD_OutString("99 = "); blank();
    }
}

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Fixed_uDecOut2(99);
swait();
LCD_OutString("100  = "); blank();
Fixed_uDecOut2(100);
swait();
LCD_OutString("999  = "); blank();
Fixed_uDecOut2(999);
swait();
LCD_OutString("1000 = "); blank();
Fixed_uDecOut2(1000);
swait();
LCD_OutString("9999 = "); blank();
Fixed_uDecOut2(9999);
swait();
LCD_OutString("10000 = "); blank();
Fixed_uDecOut2(10000);
swait();
LCD_OutString("65534 = "); blank();
Fixed_uDecOut2(65534);
swait();
LCD_OutString("65535 = "); blank();
Fixed_uDecOut2(65535);
swait();

LCD_OutString("Fixed_sD"); blank();
LCD_OutString("ecOut3");
swait();
LCD_OutString("-32768 ="); blank();
Fixed_sDecOut3(-32768);
swait();
LCD_OutString("-10000 ="); blank();
Fixed_sDecOut3(-10000);
swait();
LCD_OutString("-9999  ="); blank();
Fixed_sDecOut3(-9999);
swait();
LCD_OutString("-999   ="); blank();
Fixed_sDecOut3(-999);
swait();
LCD_OutString("-1     ="); blank();
Fixed_sDecOut3(-1);
swait();
LCD_OutString("0       ="); blank();
Fixed_sDecOut3(0);
swait();
LCD_OutString("123     ="); blank();
Fixed_sDecOut3(123);
swait();
LCD_OutString("1234    ="); blank();
Fixed_sDecOut3(1234);
swait();
LCD_OutString("9999    ="); blank();
Fixed_sDecOut3(9999);
swait();
LCD_OutString("32767 = "); blank();
Fixed_sDecOut3(32767);
swait();

LCD_OutString("Fixed_uB"); blank();
LCD_OutString("inOut8");
swait();
LCD_OutString("0       = "); blank();
Fixed_uBinOut8(0);

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main.c

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swait();
LCD_OutString("2      = "); blank();
Fixed_uBinOut8(2);
swait();
LCD_OutString("64     = "); blank();
Fixed_uBinOut8(64);
swait();
LCD_OutString("100    = "); blank();
Fixed_uBinOut8(100);
swait();
LCD_OutString("500    = "); blank();
Fixed_uBinOut8(500);
swait();
LCD_OutString("512    = "); blank();
Fixed_uBinOut8(512);
swait();
LCD_OutString("5000   = "); blank();
Fixed_uBinOut8(5000);
swait();
LCD_OutString("30000  = "); blank();
Fixed_uBinOut8(30000);
swait();
LCD_OutString("65534  = "); blank();
Fixed_uBinOut8(65534);
swait();
LCD_OutString("65535  = "); blank();
Fixed_uBinOut8(65535);
swait();
}
}
```