

Learning Objectives

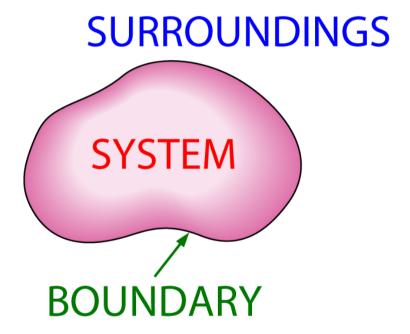
To understand

- System, control volume, boundary
- Eulerian and Lagragian descriptions of fluid flow
- Classification of fluid flows: viscous and inviscid flows; laminar and turbulent flows; compressible and incompressible flows; steady and unsteady flows; internal and external flows; one-, two- and threedimensional flows
- Material derivative, acceleration of fluid particle
- Flow visualization: streamline, pathline, streakline, timeline
- Mass conservation: mass flow rate, continuity equation (integral and differential forms)

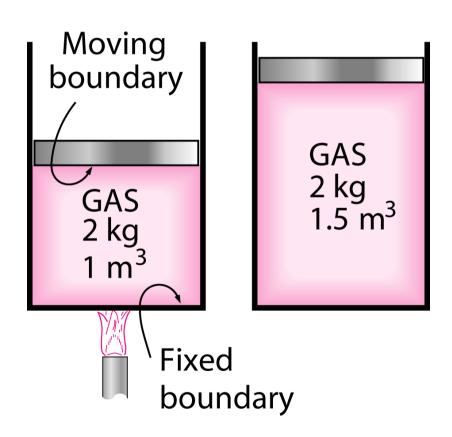
Momentum conservation: Navier-Stokes equations, Euler equations



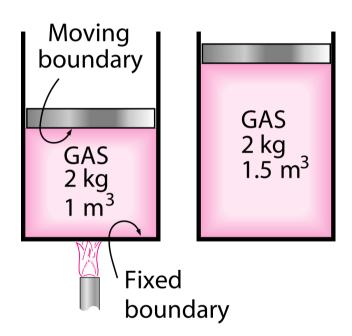
- System
 - Quantity of matter of a region in space chosen for study
- Surroundings
 - Mass or region outside the system
- Boundary
 - Real or imaginary surface that separates system from its surroundings
 - Can be either movable or fixed



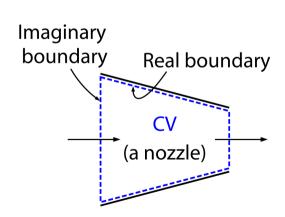
- Closed System
 - Consists of fixed amount of mass
 - No mass can cross its boundary
 - Energy, in the form of heat or work, can cross boundary
 - Volume does not have to be fixed



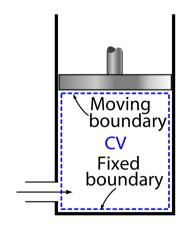
- Closed System
 - Example: Piston-cylinder device
 - ✓ System: gas trapped in cylinder by piston
 - ✓ Energy: inner surfaces of piston and cylinder
 - ✓ Surroundings: everything outside the gas, including piston and cylinder
 - ✓ closed system: No mass crossing boundary. Energy may cross boundary
 - ✓ Part of boundary (inner surface of the piston) may move



- Control volume/Open system
 - Both mass and energy can cross boundary
 - Usually encloses a device that involves mass flow such as a compressor, turbine, or nozzle
 - Any arbitrary region in space can be selected as a control volume, but proper and good choice often makes analysis much easier
 - Can be fixed in size and shape or involve a moving boundary

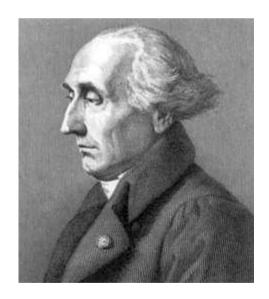


(a) A control volume (CV) with real and imaginary boundaries



(b) A control volume (CV) with fixed and moving boundaries

- Two Methods to Describe Fluid Flows
 - Lagrangian description
 - Eulerian description

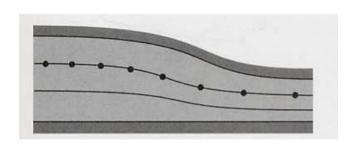


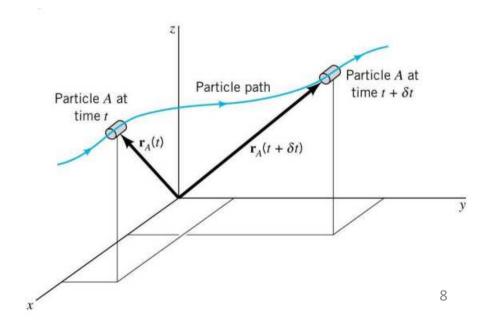
Lagrange 1736-1813



Euler 1707-1783

- Lagrangian Description
 - Tracks the motion (position and velocity vectors) of a generic individual fluid particle
 - Observer moves with the fluid
 - The main difficulty is that the observer moves with the fluid





- Lagrangian Description
 - The initial position of fluid particles is $r_A(t_0)$
 - The variation of position of fluid particles with time is described by $r_A(t)$
 - The velocity *u* and acceleration *a* of each fluid particle are obtained from the first and second temporal derivatives of particle position

Particle A at

Particle A at

time $t + \delta t$

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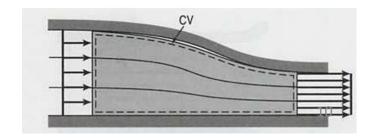
Particle path

 $\mathbf{r}_{A}(t+\delta t)$

$$\mathbf{u} = dr_A(t)/dt$$
$$\mathbf{a} = d^2r_A(t)/dt^2$$

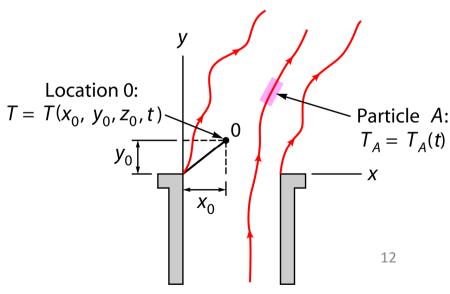
 All the variables are valid for the fluid particle when it moves along its trajectory through flow field

- Eulerian Description
 - A finite control volume (CV) is defined, through which particles flow in and out
 - Individual fluid particles are not identified and tracked
 - Define field variables (functions of space and time) within CV: pressure field P(x, y, z, t), velocity field V(x, y, z, t), temperature field T(x, y, z, t), etc.
 - Field variables define the flow field
 - All field variables are defined at any location (x, y, z) within CV and at any instant of time t

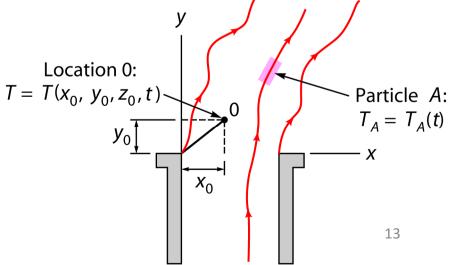


- Eulerian V.S. Lagragian Description
 - It is generally more common to use Eulerian approach to fluid flows. Measuring water temperature, or pressure at a point in a pipe.
 - Lagrangian methods sometimes used in experiments.
 Throwing tracers into moving water bodies to determine currents.
 - Eulerian description can be converted to Lagrangian description and vice versa

- Example: Smoke Discharging From a Chimney
 - Eulerian description:
 - ✓ Attach a temperature-measuring device to top of chimney (point 0)
 - ✓ Record temperature at point 0 as a function of time
 - ✓ At different times, different fluid particles pass by stationary device
 - ✓ Obtain temperature, T, for point 0 as a function of time, $T(x_0, y_0, z_0, t)$
 - ✓ Use of numerous temperaturemeasuring devices fixed at various locations yields the temperature field, T(x, y, z, t)



- Example: Smoke Discharging From a Chimney
 - Lagrangian description:
 - ✓ Attach temperature-measuring device to a particular fluid particle (particle A)
 - ✓ Record particle A's temperature as it moves about
 - ✓ Obtain particle A's temperature as a function of time, $T_A = T_A(t)$
 - ✓ Use of many such measuring devices moving with various fluid particles yields the temperature of these fluid particles as a function of time



• Example 1

- Question
 - ✓ Assume that the fluid motion is described by Eulerian method.

$$u = ax + t^{2}$$

$$v = by - t^{2}$$

$$(a + b = 0)$$

$$w = 0$$

- \checkmark The initial condition is $x_0 = \alpha$, $y_0 = \beta$, and $z_0 = \gamma$
- ✓ Obtain the fluid motion in Lagrangian description and find the acceleration

- Example 1
 - Solution:

$$u = \frac{dx}{dt} = ax + t^2$$

$$v = \frac{dy}{dt} = by - t^2$$

$$w = \frac{dz}{dt} = 0$$

$$x = c_1 e^{at} - \frac{1}{a} t^2 - \frac{2}{a^2} t - \frac{2}{a^3}$$

$$y = c_2 e^{bt} + \frac{1}{b} t^2 + \frac{2}{b^2} t + \frac{2}{b^3}$$

$$z = c_3$$

$$\begin{vmatrix} x_0 = \alpha \\ y_0 = \beta \end{vmatrix}$$

$$x = \left(\alpha + \frac{1}{a^{3}}\right)e^{at} - \frac{1}{a}t^{2} - \frac{2}{a^{2}}t - \frac{2}{a^{3}}$$

$$y = \left(\beta - \frac{1}{b^{3}}\right)e^{bt} + \frac{1}{b}t^{2} + \frac{2}{b^{2}}t + \frac{2}{b^{3}}$$

$$z = \gamma$$
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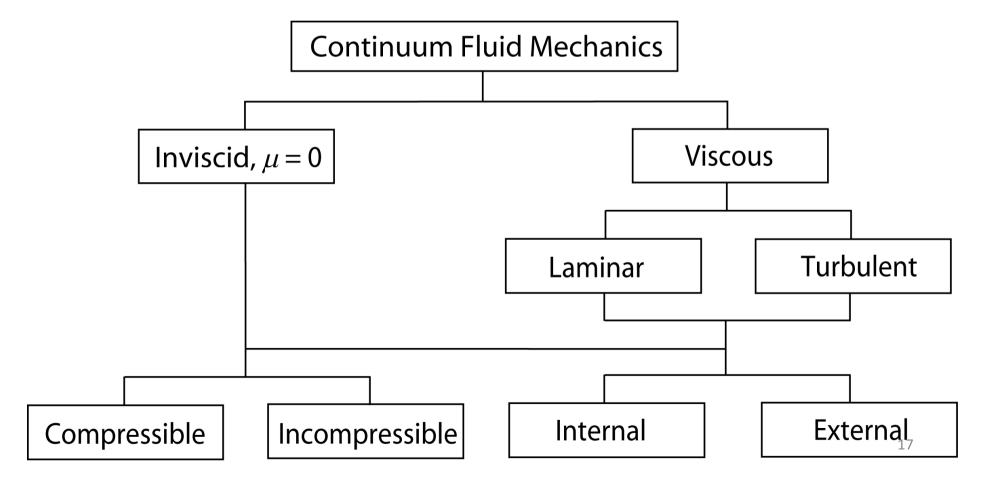
- Example 1
 - Solution:

$$u_{L} = a\left(\alpha + \frac{1}{a^{3}}\right)e^{at} - \frac{2}{a}t - \frac{2}{a^{2}} \qquad a_{xL} = a^{2}\left(\alpha + \frac{1}{a^{3}}\right)e^{at} - \frac{2}{a}$$

$$v_{L} = b\left(\beta - \frac{1}{b^{3}}\right)e^{bt} + \frac{2}{b}t + \frac{2}{b^{2}} \qquad b_{yL} = b^{2}\left(\beta - \frac{1}{b^{3}}\right)e^{bt} + \frac{2}{b}$$

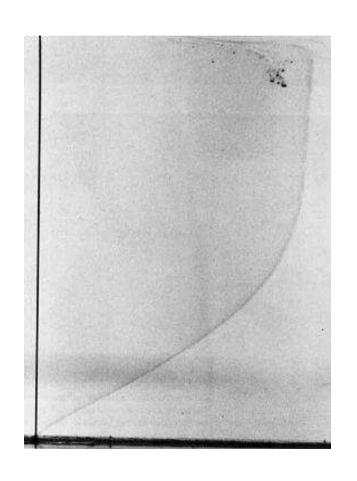
$$w_{L} = 0 \qquad a_{zL} = 0$$

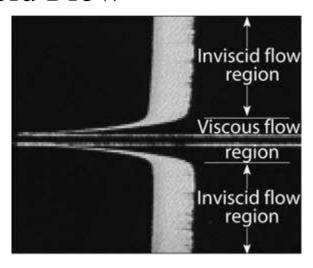
- There are many ways to classify fluid flows
 - One possible classification:

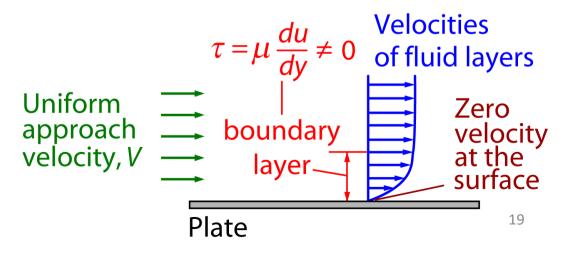


- Viscous Flow versus Inviscid Flow
 - Viscous flows: flows in which frictional or viscous effects are significant
 - There is no fluid with zero viscosity ⇒ all fluid flows involve viscous effects to some degree
 - In many practical flows, there are regions (typically away from solid surfaces) where viscous forces are negligible compared to other forces (inertia, pressure, gravity) ⇒ neglect viscous effects in these regions ⇒ inviscid (ideal) flow
 - Inviscid flow \Rightarrow assume $\mu = 0$
 - Generally easier to analyze an inviscid flow than a viscous flow

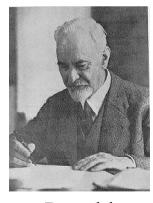
Viscous Flow versus Inviscid Flow



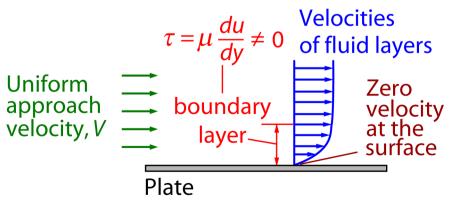




- Viscous Flow versus Inviscid Flow
 - No-slip condition ⇒ fluid has zero velocity at wall
 - Fluid velocity approaches V far away from wall
 - Fluid velocity increases from zero at wall to V far away from wall \Rightarrow non-zero velocity gradient in a thin layer adjacent to wall \Rightarrow boundary layer



Prandtl (1875-1953)



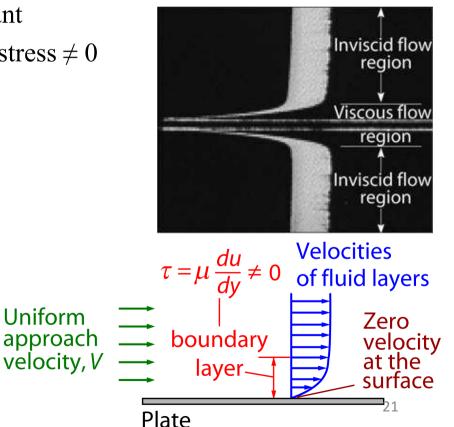
- Viscous Flow versus Inviscid Flow
 - Boundary layer
 - ✓ flow region adjacent to solid surface in which viscous effects and

velocity gradients are significant

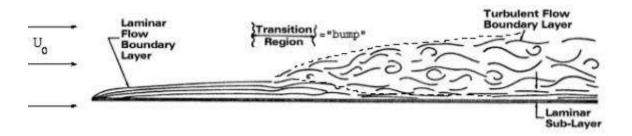
✓ velocity gradient $\neq 0 \Rightarrow$ shear stress $\neq 0$

$$\tau = \mu \frac{du}{dy} \neq 0$$

Outside boundary layer ⇒
 flow unaffected by presence
 of plate ⇒ viscous effects
 unimportant ⇒ assume flow
 to be inviscid



- Laminar Flow versus Turbulent Flow
 - Laminar flow: highly ordered fluid motion characterized by smoothly flowing layers of fluid
 - Turbulent flow: highly disordered fluid motion typically occurring at high velocities and is characterized by random three-dimensional velocity fluctuations
 - Transitional flow: flow that alternates between being laminar and turbulent



- Laminar Flow versus Turbulent Flow
 - Reynolds number
 - ✓ Defined as the ratio of inertial forces to viscous forces

$$\mathrm{Re} = \frac{\mathrm{inertial\ forces}}{\mathrm{viscous\ forces}} = \frac{(\mathrm{mass})(\mathrm{acceleration})}{(\mathrm{dynamic\ viscosity})(\mathrm{velocity/distance})(\mathrm{area})} = \frac{(\rho L^3)(v^2/L)}{\mu(v/L)L^2} = \frac{\rho v L}{\mu}$$

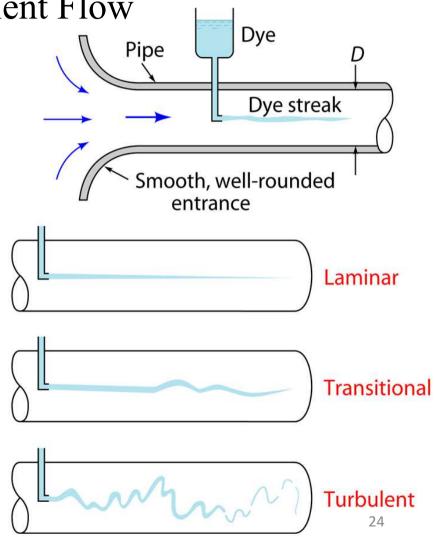
 μ and ρ are fluid viscosity and density respectively; v is the reference velocity (the velocity of the object or free stream velocity of fluid); L is the reference length.

- ✓ Nature of flow can be characterized by Reynolds number
- ✓ Laminar flow occurs at low Reynolds numbers, where viscous forces are dominant
- ✓ Turbulent flow occurs at high Reynolds numbers and is dominated by inertial force

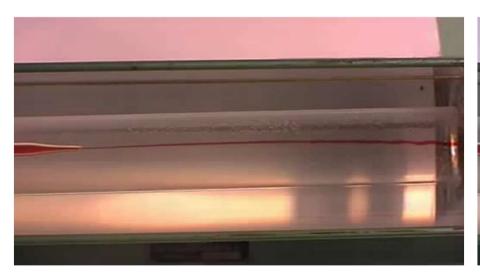
- Laminar Flow versus Turbulent Flow
 - Flow in the circular pipe
 - ✓ Reynolds number is defined as

$$Re = \frac{\rho VD}{\mu}$$

- $\checkmark Re < 2300$: Laminar flow
- ✓ 2300 < Re < 10⁵: Transitional flow
- $\checkmark Re > 10^5$: Turbulent flow



- Laminar Flow versus Turbulent Flow
 - Flow in the circular pipe





Laminar Turbulent

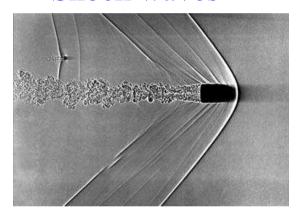
- Compressible Flow versus Incompressible Flow
 - Incompressible flow
 - flows in which variations in density are negligible
 - Liquids ⇒ incompressible
 - Gases \Rightarrow need to consider Mach number, Ma
 - Mach number

$$Ma = \frac{V}{c} = \frac{\text{Speed of flow}}{\text{Speed of sound}}$$

- Speed of sound c = 346 m/s in air at room temperature at sea level
- Gases \Rightarrow incompressible if $Ma < 0.3 \Rightarrow$ changes in density less than 5%
- Compressibility effects of air can be neglected at speeds < 100 m/s

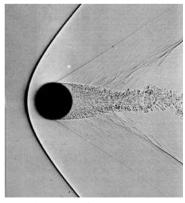
- Compressible Flow versus Incompressible Flow
 - Compressible flow
 - Density variations within flow are not negligible $\Rightarrow Ma > 0.3$
 - $Ma < 1 \Rightarrow$ subsonic flow
 - $Ma = 1 \Rightarrow$ sonic flow
 - $Ma > 1 \Rightarrow$ supersonic flow \Rightarrow shock waves can form \Rightarrow abrupt change in fluid properties across a shock wave

- Compressible Flow versus Incompressible Flow
 - Shock waves

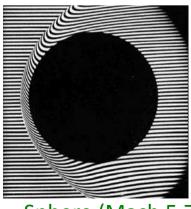


Bullet at Mach 1.5





Sphere (Mach 1.53)



Sphere (Mach 5.7)



F/A-18 Hornet

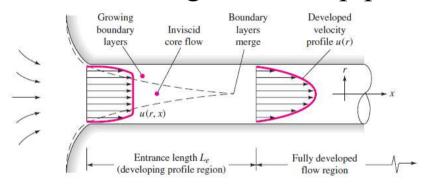
- Compressible Flow versus Incompressible Flow
 - Shock waves





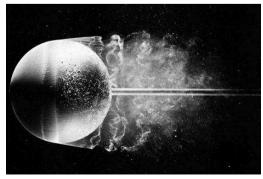
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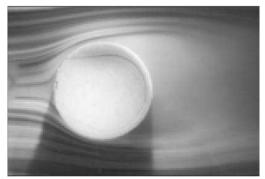
- Internal versus External Flow
 - Internal flow: fluid flow is completely bounded by solid surfaces; e.g. flow in a pipe or duct



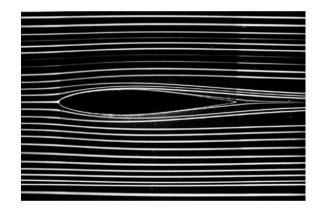


External flow: flow of an unbounded fluid over a surface;
 e.g. flow past sphere





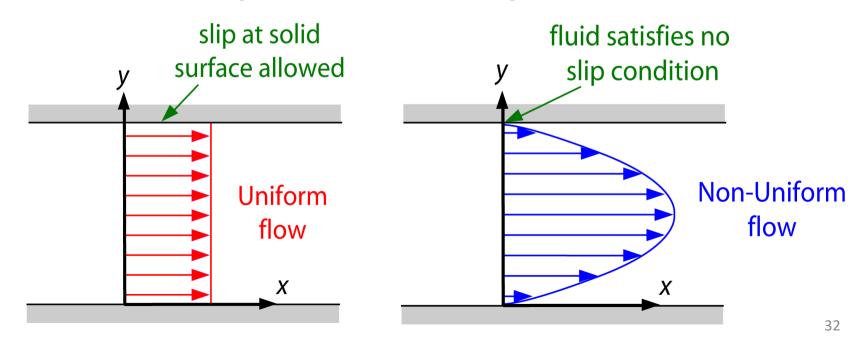
- Steady Flow versus Unsteady Flow
 - Steady flow: flow at any point does not change with time



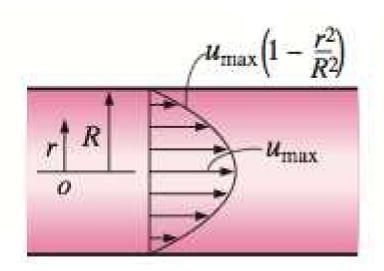
- Unsteady flow: flow pattern varies with time



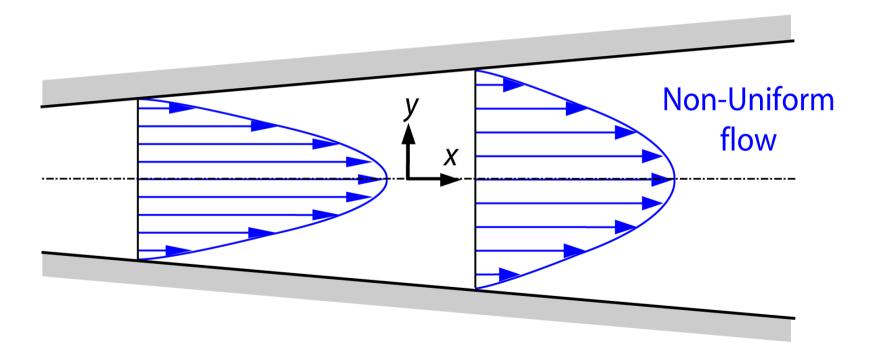
- Uniform versus Non-uniform Flow
 - Uniform flow ⇒ flow in which velocity does not vary with location ⇒ eg. inviscid flow through a channel:
 - Non-uniform flow ⇒ flow in which velocity varies with location ⇒ eg. viscous flow through a channel:



- One-, Two- and Three-Dimensional Flow
 - A flow is said to be one-, two- or three dimensional if flow velocity varies in one, two or three primary dimensions, respectively
 - One-dimensional flow: Fully developed flow in a circular pipe \Rightarrow flow velocity only varies in the r direction



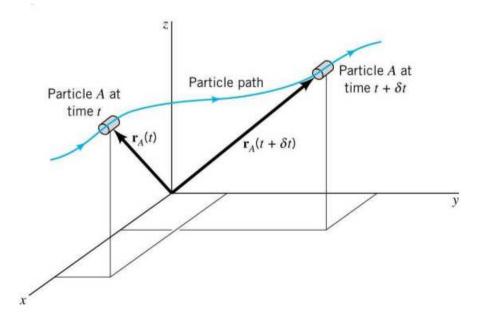
- One-, Two- and Three-Dimensional Flow
 - Two-dimensional \Rightarrow flow Velocity varies in both x- and y-directions



Basic Concept for Fluid Motion

Material Derivative

– In the Eulerian method, the fundamental property is the velocity field. The velocity field does not track the behaviour of individual particle, it describes the velocity of whatever happens to be at a given location. To do dynamics, need to apply F = ma. Getting the acceleration is not trivial



Basic Concept for Fluid Motion

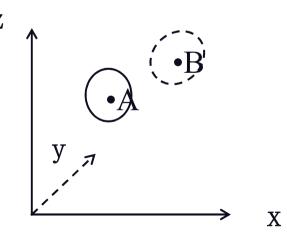
Material Derivative

- Also called substantial derivative
- Assume a fluid particle in a system with physical property N(x,y,z,t) moves from position A to position B after a time interval Δt
- The material derivative can be calculated as,

$$\frac{DN}{Dt} = \lim_{\Delta t \to 0} \frac{N(B, t + \Delta t) - N(A, t)}{\Delta t}$$

 $\frac{DN}{Dt} = \lim_{\Delta t \to 0} \frac{N(B, t + \Delta t) - N(A, t)}{\Delta t}$ $\frac{D()}{Dt} \text{ is used here because it is different}$

from the simple derivative $\frac{d(\)}{dt}$



- Material Derivative
 - Two types of contributions for the variation in N:
 - ✓ Unsteady effect: Variation in N due to the time rate-of-change during the time interval Δt
 - ✓ Spatial effect: Variation in N due to the non-uniform feature of the field when the fluid particle moves from positions A to B

$$\frac{DN}{Dt} = \lim_{\Delta t \to 0} \frac{N(B, t + \Delta t) - N(A, t)}{\Delta t}$$

$$= \lim_{\Delta t \to 0} \frac{N(B, t + \Delta t) - N(B, t)}{\Delta t} + \lim_{\Delta t \to 0} \frac{N(B, t) - N(A, t)}{\Delta t}$$

$$= \lim_{\Delta t \to 0} \frac{N(B, t + \Delta t) - N(B, t)}{\Delta t} + \lim_{\Delta t \to 0} \frac{N(B, t) - N(A, t)}{\Delta t}$$

$$= \lim_{\Delta t \to 0} \frac{N(B, t + \Delta t) - N(B, t)}{\Delta t} + \lim_{\Delta t \to 0} \frac{AB}{\Delta t} \bullet \lim_{AB \to 0} \frac{N(B, t) - N(A, t)}{AB}$$
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- Material Derivative
 - Two types of contributions for the variation in N:

$$\frac{DN}{Dt} = \lim_{\Delta t \to 0} \frac{N(B, t + \Delta t) - N(B, t)}{\Delta t} + \lim_{\Delta t \to 0} \frac{AB}{\Delta t} \bullet \lim_{AB \to 0} \frac{N(B, t) - N(A, t)}{AB}$$

$$\Delta t \to 0 \quad A \to B \quad velocity \quad A \to B$$

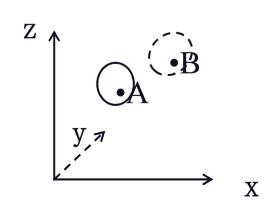
$$\frac{\partial N(B, t)}{\partial t} \quad \vec{V} \quad \bullet \quad \frac{\partial N(B, t)}{\partial s}$$

Z A B

local derivative convective derivative

- Material Derivative
 - Mathematical deduction by using the chain rule:

$$\frac{DN}{Dt} = \frac{\partial N}{\partial t} + \frac{\partial N}{\partial x} \frac{dx}{dt} + \frac{\partial N}{\partial y} \frac{dy}{dt} + \frac{\partial N}{\partial z} \frac{dz}{dt}
= \frac{\partial N}{\partial t} + u \frac{\partial N}{\partial x} + v \frac{\partial N}{\partial y} + w \frac{\partial N}{\partial z} = \frac{\partial N}{\partial t} + (\vec{V} \cdot \nabla) N$$



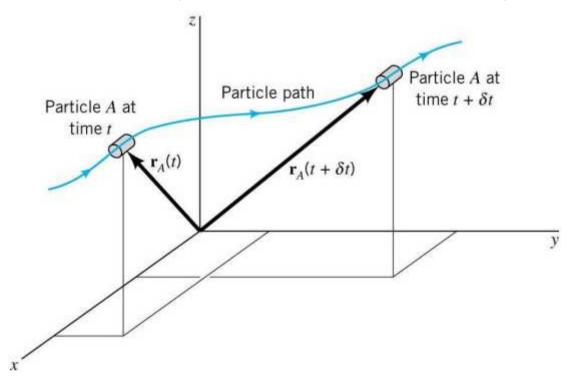
$$\nabla = \vec{i} \frac{\partial}{\partial x} + \vec{j} \frac{\partial}{\partial y} + \vec{k} \frac{\partial}{\partial z}$$

为哈密顿算子符 (Hamiltonian)

- Material Derivative
 - Acceleration of Fluid Particle:

✓ For particle A, $x_A(t)$, $y_A(t)$, $z_A(t)$ describe the motion of the particle.

$$\vec{V}_A = \vec{V}_A \left(X_A \left(t \right), y_A \left(t \right), z_A \left(t \right), t \right)$$



- Material Derivative
 - Acceleration of Fluid Particle:

$$a_{A} = \frac{D\vec{V_{A}}\left(x_{A}(t), y_{A}(t), z_{A}(t), t\right)}{Dt}$$

$$= \frac{\partial \vec{V_{A}}}{\partial t} + \frac{\partial \vec{V_{A}}}{\partial x} \frac{dx_{A}(t)}{dt} + \frac{\partial \vec{V_{A}}}{\partial y} \frac{dy_{A}(t)}{dt} + \frac{\partial \vec{V_{A}}}{\partial z} \frac{dz_{A}(t)}{dt}$$

$$= \frac{\partial \vec{V_{A}}}{\partial t} + u_{A}(t) \frac{\partial \vec{V_{A}}}{\partial x} + v_{A}(t) \frac{\partial \vec{V_{A}}}{\partial y} + w_{A}(t) \frac{\partial \vec{V_{A}}}{\partial z}$$

- Since A is any particle, the acceleration field is

$$\vec{a} = \frac{\partial \vec{V}}{\partial t} + u \frac{\partial \vec{V}}{\partial x} + v \frac{\partial \vec{V}}{\partial y} + w \frac{\partial \vec{V}}{\partial z}$$
local convective
acceleration acceleration

- Material Derivative
 - Acceleration of Fluid Particle:
 - \checkmark The component of the vector a:

$$a_{x} = \frac{\partial u}{\partial t} + u \frac{\partial u}{\partial x} + v \frac{\partial u}{\partial y} + w \frac{\partial u}{\partial z}$$

$$a_{y} = \frac{\partial v}{\partial t} + u \frac{\partial v}{\partial x} + v \frac{\partial v}{\partial y} + w \frac{\partial v}{\partial z}$$

$$a_{z} = \frac{\partial w}{\partial t} + u \frac{\partial w}{\partial x} + v \frac{\partial w}{\partial y} + w \frac{\partial w}{\partial z}$$

- ➤ Unsteady effect: the time rate-of-change of the velocity component at any specified spatial location
- Spatial effect: spatial changes in velocity (or any other fluid property) due to motion of a fluid parcel being carried (convected) by the flow field $(u, v, w) \Rightarrow$ fluid parcels may be accelerating even in a steady (time-independent) flow field

- Material Derivative
 - General Form:

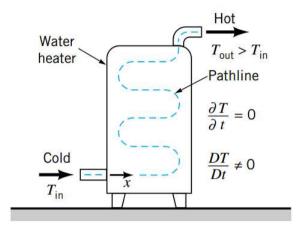
$$\frac{D(\)}{Dt} = \frac{\partial(\)}{\partial t} + u \frac{\partial(\)}{\partial x} + v \frac{\partial(\)}{\partial y} + w \frac{\partial(\)}{\partial z} = \frac{\partial(\)}{\partial t} + (\vec{V} \bullet \nabla)(\)$$

 One can define the material derivative for other properties for a fluid, e.g. temperature or pressure

$$\frac{DT}{Dt} = \frac{\partial T}{\partial t} + u \frac{\partial T}{\partial x} + v \frac{\partial T}{\partial v} + w \frac{\partial T}{\partial z} = \frac{\partial T}{\partial t} + (\vec{V} \bullet \nabla) (T)$$

Material Derivative

- Example for convective derivative
 - ✓ Consider water going through a water heater under steady state flow conditions
 - ✓ The water temperature at any fixed location is fixed



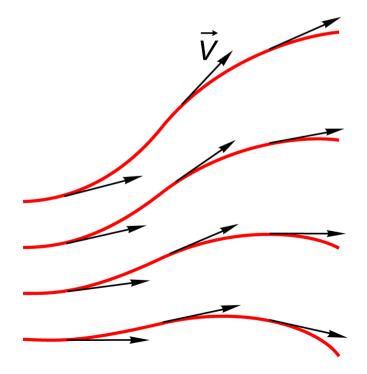
$$\frac{\partial T}{\partial t} = 0$$

✓ However, the water temperature for a given piece of water will increase as it progresses through the heater. The rate of change is

$$\frac{dT}{dt} = \begin{pmatrix} \text{Rate at which} \\ T \text{ changes} \\ \text{with postion} \end{pmatrix} \times \begin{pmatrix} \text{How quickly} \\ \text{water changes} \\ \text{postion} \end{pmatrix}$$
$$= \frac{\partial T}{\partial s} u_{s}$$

• Streamlines

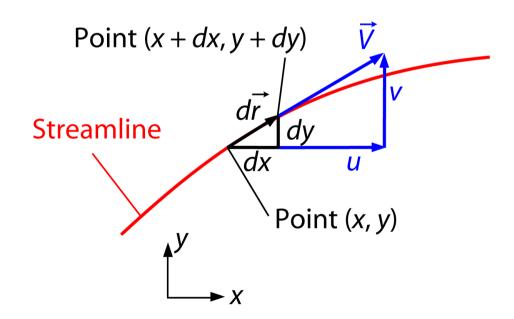
- A streamline is a curve that is everywhere tangent to the instantaneous local velocity vector – a mathematical concept
- Typical set of streamlines



Streamlines

- Streamlines are everywhere parallel to the local velocity
- Fluid cannot cross a streamline by definition
- Any particle starting on one streamline will stay on that same streamline
- Streamlines cannot cross each other
- Fluid flowing past a solid boundary does not flow into or out of the solid surface
- Close to a solid boundary, streamlines are parallel to that boundary
- Streamlines are difficult to generate experimentally

- Streamlines
 - Calculation of streamlines
 - ✓ Consider an infinitesimal arc length $d\vec{r} = dx\hat{i} + dy\hat{j} + dz\hat{k}$ along a streamline



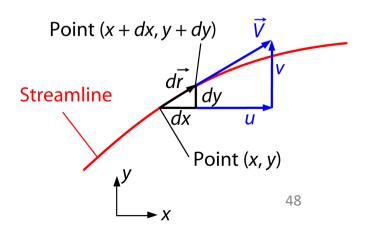
Streamlines

- Calculation of streamlines
 - ✓ According to definition of a streamline, $d\vec{r}$ is parallel to local velocity vector $\vec{V} = u\hat{i} + v\hat{j} + w\hat{k}$
 - ✓ Similar triangles ⇒ components of $d\vec{r}$ proportional to components of \vec{V}

$$\frac{dr}{V} = \frac{dx}{u} = \frac{dy}{v} = \frac{dz}{w}$$

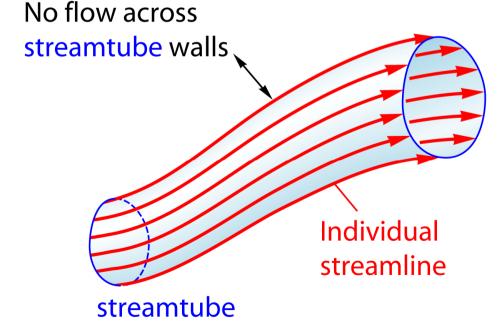
where dr and V are magnitudes of $d\vec{r}$ and \vec{V} , respectively

✓ If the velocities (u, v, w) are known functions of position and time, the above equation can be integrated to find the streamline passing through the initial point (x_0, y_0, z_0, t_0)



Streamtube

- Streamtube consists of a bundle of streamlines
 - ✓ The walls of a streamtube are streamlines
 - ✓ Fluid cannot flow across a streamline, so fluid cannot cross a streamtube wall
 - ✓ Streamtube walls need not be solid but may be fluid surfaces



Streamline and Streamtube

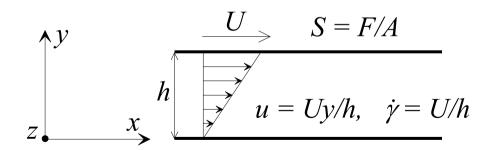
- Both streamlines and streamtubes are instantaneous quantities, defined at a particular instant in time according to the velocity field at that instant
- In an unsteady flow, streamline and streamtube pattern may change significantly with time
- In a steady flow, the positions of streamlines and streamtubes do not change
- Streamlines are visualized by taking a short-time exposure of fluid particles – each will trace out a velocity vector

- Example 2
 - Question

✓ Consider the 1-dimensional steady shear flow

$$u = U \frac{y}{h}, \quad v = w = 0$$

✓ To find the streamlines



• Example 2

- Solution
 - ✓ The streamlines are found by solving

$$\frac{dx}{u} = \frac{dy}{v}$$
 or $\frac{dy}{dx} = 0$

$$u = U \frac{y}{h}, \quad v = w = 0$$

✓ This yields y = constant for the streamlines (straight lines parallel to the flow direction)

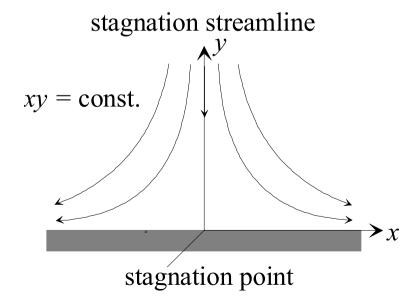


- Example 3
 - Question

✓ Consider the following steady 2-dimensional flow (bi-axial flow)

$$\mathbf{v} = \{u, v, w\}, \quad u = \dot{\gamma}x, \quad v = -\dot{\gamma}y, \quad w = 0$$

✓ To find the streamlines



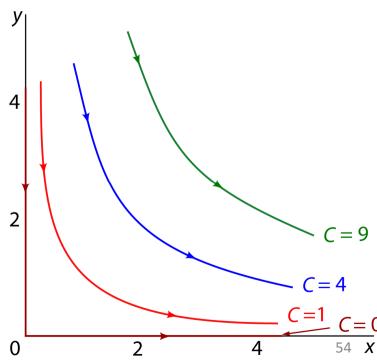
• Example 3

- Solution
 - ✓ The streamlines are found by solving

$$\frac{dx}{u} = \frac{dy}{v}$$
 or $\frac{dx}{\dot{y}x} = -\frac{dy}{\dot{y}y}$ or $\ln y = -\ln x + \text{constant}$

$$\therefore xy = C$$

- ✓ These streamlines are hypebolas
- ✓ Use different values of $C \Rightarrow plot$ various lines in x-y plane \Rightarrow streamlines
- ✓ Arrows indicate flow direction



• Example 4

- Question
 - ✓ Consider the 2-dimensional unsteady flow

$$\mathbf{v} = \{u, v, w\}, \quad u = x, \quad v = yt, \quad w = 0$$

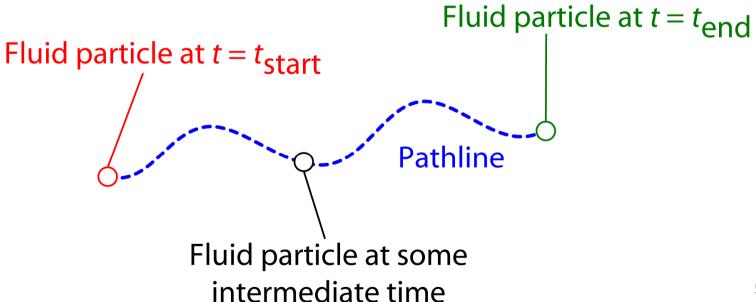
- \checkmark To find the streamlines (assume streamline pass (1,1))
- Solution
 - ✓ The streamlines are found by solving

$$\frac{dx}{u} = \frac{dy}{v}$$
 or $\frac{dx}{x} = \frac{dy}{ty}$: $\ln y = t \ln x + \text{constant}$: $y = Cx^t$

✓ The streamline passing through (1,1) has C = 1

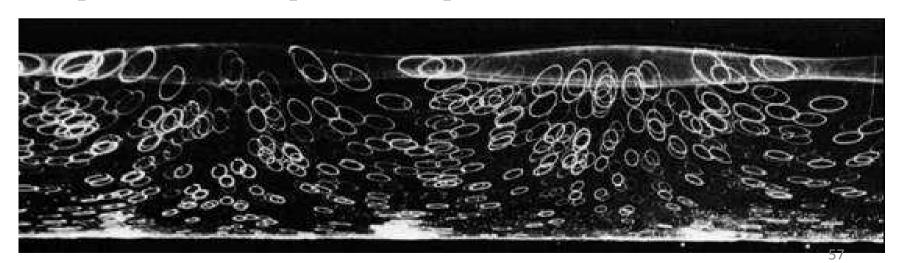
Pathline

- A pathline is the actual path travelled by an individual fluid over some time interval
- Pathline is a Lagrangian concept ⇒ the path of an individual fluid particle is tracked as it moves around in the flow field



Pathline

- Pathlines can be generated experimentally by marking a fluid particle (dying a small fluid element) and taking a long-time time exposure photograph of its motion through the flow
- Example: waves moving along surface of water in a tank ⇒ pathlines are elliptical in shape



Pathline

- Calculation of pathlines
 - ✓ Pathline is defined by integration of the velocity components:

$$\frac{d}{dt}\vec{x} = \vec{V}, \quad \vec{x}(t_0) = \vec{x}_0 + \int_{t_0}^t u dt$$

$$y(t) = y_0 + \int_{t_0}^t v dt$$

$$z(t) = z_0 + \int_{t_0}^t w dt$$

or in vector notation:

$$\vec{x}\left(t\right) = \vec{x}_0 + \int_{t_0}^t \vec{V}dt$$

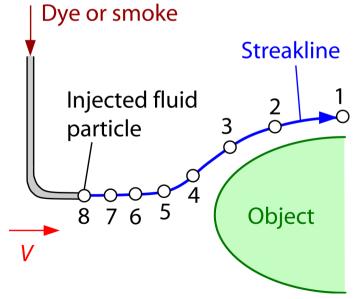
✓ Given velocity field (u, v, w, t), the integration is started at a specified initial position and time (x_0, y_0, z_0, t_0)

Streaklines

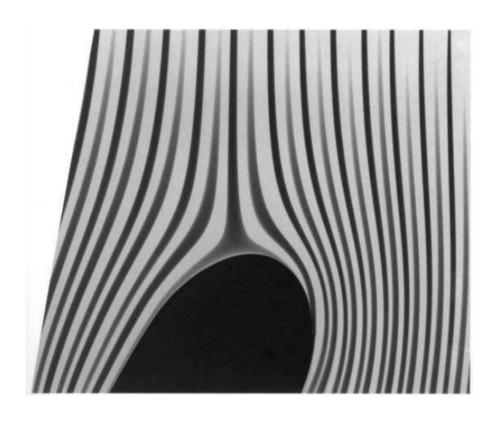
- A streakline is the locus of fluid particles that have passed sequentially through a prescribed point in the flow
- Main point: locus of particles passing through one common point in space

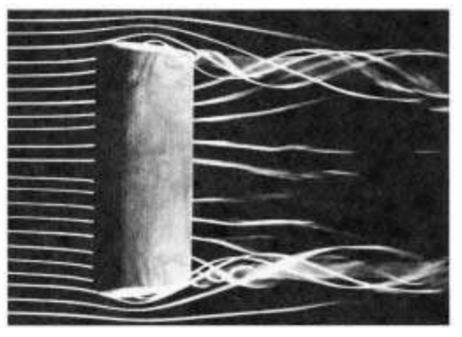
- Streaklines are the most flow pattern generated in physical

experiments



Streaklines

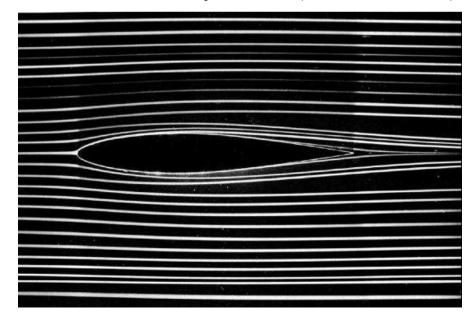




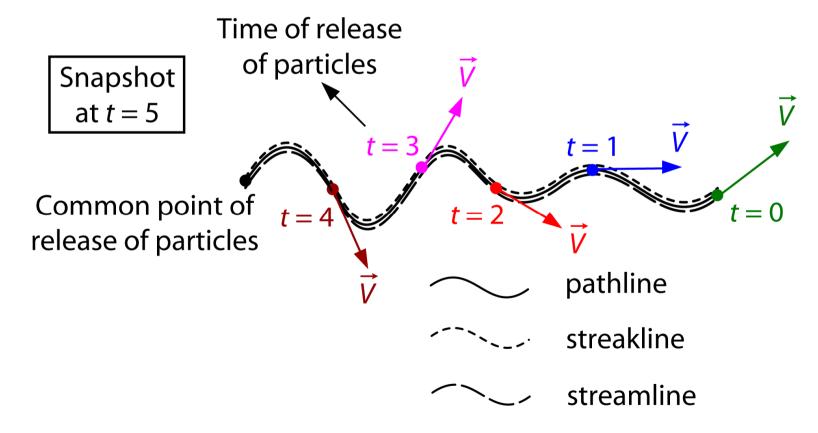
Streaklines of dye moving past obstruction. They are also the streamlines for the flow.

Streaklines of smoke moving past obstruction

- Steady Flow
 - Streamlines, pathlines and streaklines are identical
 - Path taken by a marked particle (pathline) is the same as line formed by all other particles that previously passed through point of injection (streakline) ⇒ these lines are in turn tangent to the velocity field (streamlines)

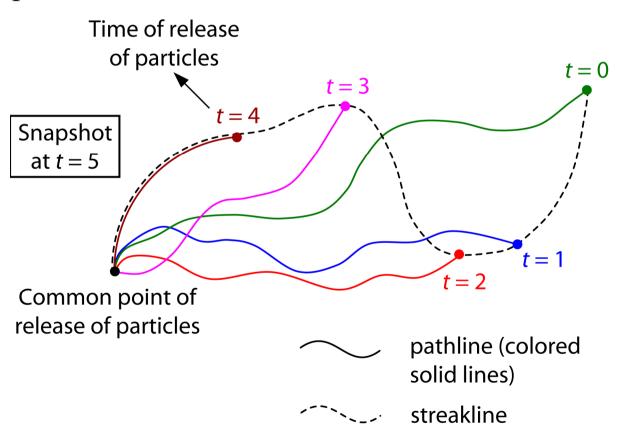


- Steady Flow
 - Example



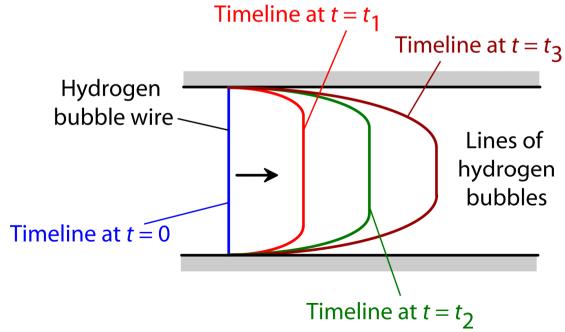
- Unsteady Steady Flow
 - Streamline represents instantaneous flow pattern at given instant of time
 - Streakline and pathline are flow patterns generated by passage of time, which means age and time history associated with flow pattern
 - Streakline is instantaneous snapshot of time-integrated flow pattern
 - Pathline is time-exposed flow path of individual particle over some time interval

- Unsteady Steady Flow
 - Example



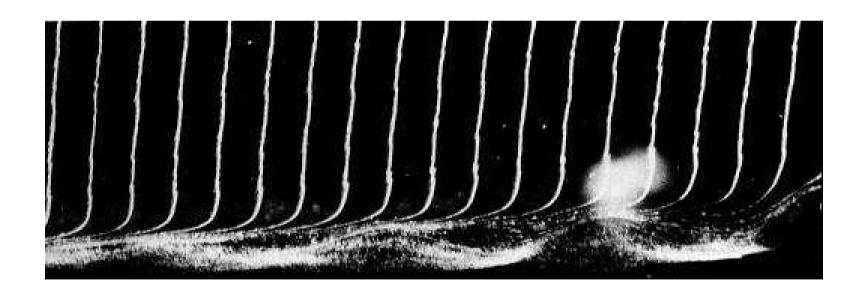
Timelines

- A timeline is a set of adjacent fluid particles that were marked at the same (earlier) instant in time
 - ✓ Timeline is useful for investigating uniformity of flow
 - ✓ Can be generated experimentally in water using hydrogen bubble wire

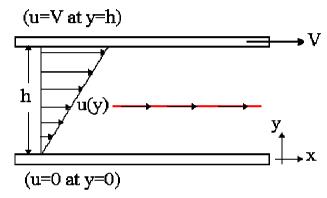


• Timelines

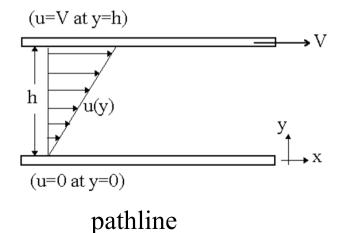
 Example: Timelines produced by a hydrogen bubble wire in a boundary layer

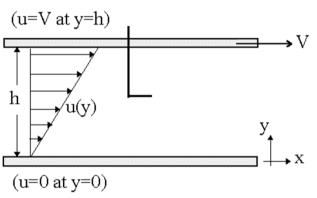


• Simple Shear Flow between Parallel Plates $u = V \frac{y}{h}$

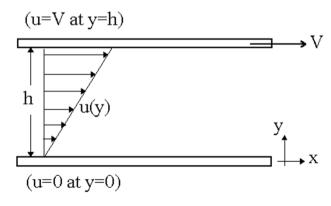


streamline





streakline



timeline

• Example 5

- Question
 - ✓ Consider the two-dimensional velocity field

$$\mathbf{v} = \{u, v, w\}, \quad u = x, \quad v = yt, \quad w = 0$$

- \checkmark Find out the pathline passing through point (1,1)
- Solution
 - ✓ The equation for pathlines

$$\frac{dx}{dt} = u = x : \frac{dx}{x} = dt, \quad \frac{dy}{dt} = v = ty : \frac{dy}{y} = tdt$$
$$x(0) = X, \quad y(0) = Y$$

✓ Solving these

$$\ln x = t + C_1, \quad \ln y = \frac{1}{2}t^2 + C_2$$
$$x = e^{t + C_1} = Xe^t, \quad y = e^{t^2/2 + C_2} = Ye^{t^2/2}$$

• Example 5

- Solution
 - ✓ The pathline passing through point (1,1) at time t = 0 is

$$1 = Xe^0 = X$$
, $1 = Ye^0 = Y$: $x = e^t$, $y = e^{t^2/2}$

✓ To find the streakline passing through (1,1) we note that any pathline passing through (1,1) at some point in time t_0 satisfies

$$1 = Xe^{t_0}, \ 1 = Ye^{t_0^2/2} \quad \therefore \quad X = e^{-t_0}, \ Y = e^{-t_0^2/2}$$

✓ This yields

$$x = e^{t-t_0}, \ \ y = e^{\left(t^2 - t_0^2\right)/2}$$

✓ A plot of this for different t_0 will yield a family of streaklines, all pass through (1,1) at some point in time

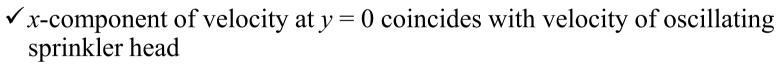
• Example 6

- Question
 - ✓ Water flows from oscillating slit produces velocity field

$$\vec{V} = u_0 \sin\left[\omega(t - y/v_0)\right]\hat{i} + v_0\hat{j}$$

where u_0 , v_0 , and ω are positive constants

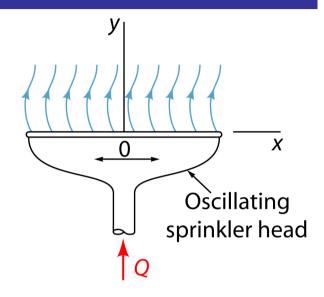




$$u = u_0 \sin(\omega t)$$
 @ $y = 0$

Determine

- a) streamline passing through origin at t = 0 and $t = \pi/2\omega$
- b) pathline of particle at origin at t = 0 and $t = \pi/2\omega$
- c) discuss shape of streakline passing through origin



- Example 6
 - Solution: Part (a)
 - ✓ Streamlines:

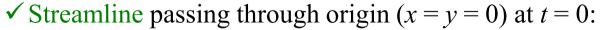
$$\frac{dy}{dx} = \frac{v}{u} = \frac{v_0}{u_0 \sin\left[\omega(t - y/v_0)\right]}$$

✓ Separating variables and integrating:

$$u_0 \int \sin \left[\omega (t - y/v_0)\right] dy = v_0 \int dx$$

$$u_0 (v_0/\omega) \cos \left[\omega (t - y/v_0)\right] = v_0 x + C$$

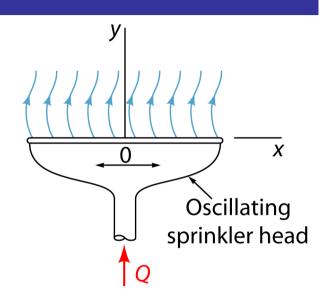
where C is a constant



$$C = u_0 v_0 / \omega$$

 \checkmark Equation of streamline passing through x = y = 0, at t = 0

$$x = \frac{u_0}{\omega} \left[\cos \left(\frac{\omega y}{v_0} \right) - 1 \right]$$



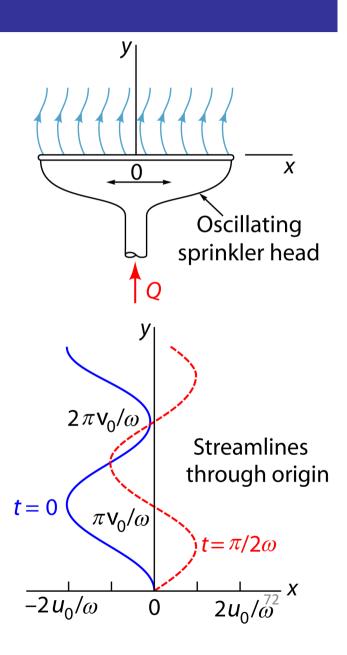
- Example 6
 - Solution: Part (a)
 - ✓ Streamline passing through origin (x = y = 0) at $t = \pi/2\omega$:

$$C = 0$$

✓ Equation of streamline:

$$x = \frac{u_0}{\omega} \sin\left(\frac{\omega y}{v_0}\right)$$

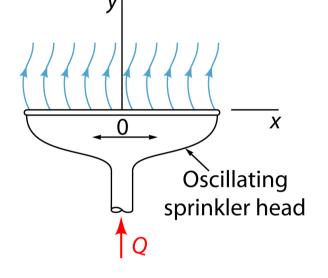
✓ Flow is unsteady: streamlines vary with time



- Example 6
 - Solution: Part (b)
 - ✓ Pathlines:

$$u = \frac{dx}{dt} = u_0 \sin \left[\omega \left(t - \frac{y}{v_0} \right) \right]$$

$$v = \frac{dy}{dt} = v_0 \implies y = v_0 t + C_1$$



where C_I is a constant

$$\frac{dx}{dt} = u_0 \sin \left[\omega \left(t - \frac{v_0 t + C_1}{v_0}\right)\right] = -u_0 \sin \left(\frac{C_1 \omega}{v_0}\right)$$

$$\Rightarrow x = -\left[u_0 \sin \left(\frac{C_1 \omega}{v_0}\right)\right] t + C_2$$

where C_2 is a constant

• Example 6

- Solution: Part (b)
 - ✓ Particle at origin (x = y = 0) at t = 0:

$$C_1 = C_2 = 0$$

✓ Pathline:

$$x = 0$$
 $y = v_0 t$

✓ Particle at origin (x = y = 0) at $t = \pi/2\omega$:

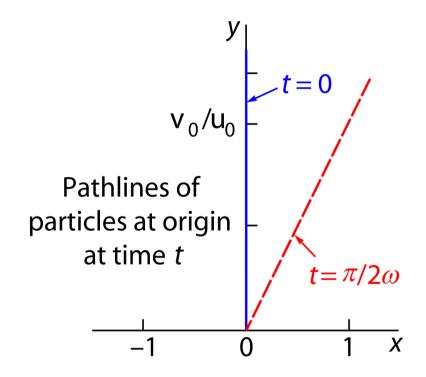
$$C_1 = -\frac{\pi v_0}{2\omega} \qquad C_2 = -\frac{\pi u_0}{2\omega}$$

✓ Pathline:

$$x = u_0 \left(t - \frac{\pi}{2\omega} \right) \qquad y = v_0 \left(t - \frac{\pi}{2\omega} \right)$$

$$\Rightarrow y = \frac{v_0}{u_0} x$$

- Example 6
 - Solution: Part (b)

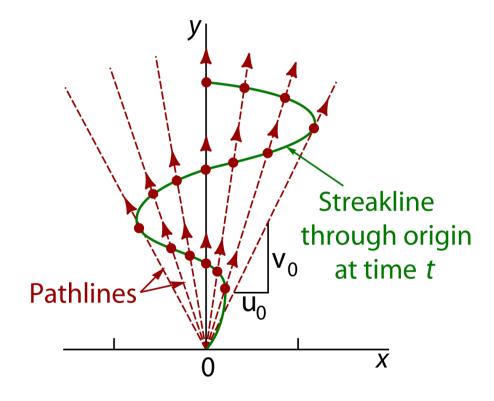


✓ Flow is unsteady: pathlines do not coincide

• Example 6

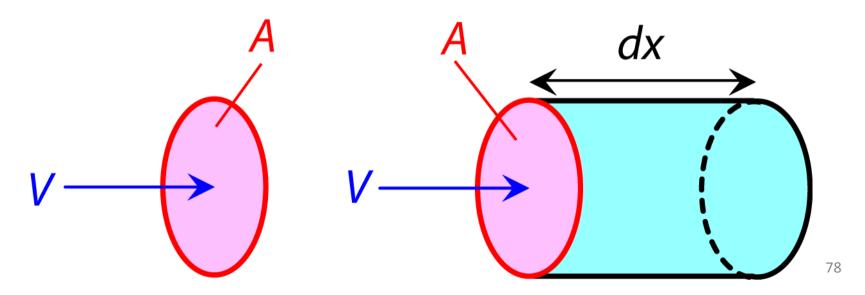
- Solution: Part (c)
 - ✓ Streakline through origin at time t = 0 is locus of particles at t = 0 that previously (t < 0) passed through origin
 - ✓ Each particle flowing through origin travels in a straight line (pathlines are rays from the origin), the slope of which lies between $\pm v_0/u_0$
 - ✓ Particles passing through origin at different times located on different rays from origin and at different distances from origin
 - ✓ Flow is unsteady: streakline varies with time, although it always has the oscillating, sinuous character

- Example 6
 - Solution: Part (c)



✓ Unsteady flow: streamlines, pathlines, and streaklines do not coincide

- Mass and Volume Flow Rates
 - Mass flow rate
 - ✓ Amount of mass flowing through a cross section per unit time
 - ✓ Usually denoted by \dot{m}
 - \checkmark Consider a plane surface of arbitrary shape with area A
 - $\checkmark \rho$ is fluid density, V is uniform velocity normal to A.

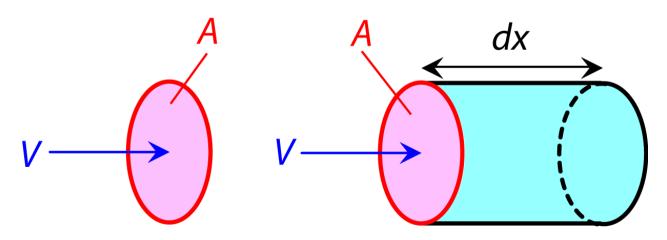


- Mass and Volume Flow Rates
 - Mass flow rate
 - ✓ In time dt, fluid passing through A sweeps through distance dx
 - ✓ Mass of fluid contained in fluid column of length dx:

$$dm = \rho A dx$$

✓ and

$$dx = Vdt$$



- Mass and Volume Flow Rates
 - Mass flow rate
 - ✓ Hence:

$$dm = \rho AVdt$$

- $\checkmark dm$ is the mass of fluid which has passed through area A in time dt
- ✓ Mass flow rate (\dot{m}) = mass of fluid passing through area A per unit time

$$\dot{m} = \frac{dm}{dt} = \rho AV$$

- Volume flow rate
 - ✓ Volume flow rate (Q) = volume of fluid passing through area A per unit time

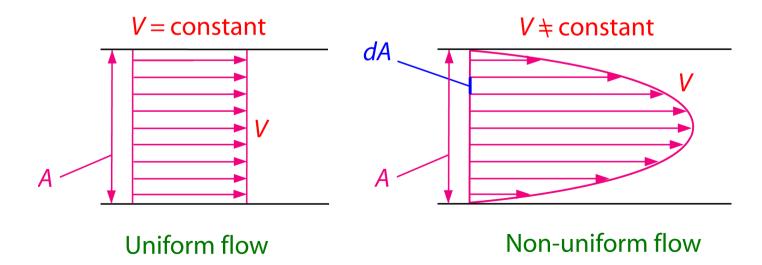
$$Q = \frac{\dot{m}}{\rho} = AV$$

- Mass and Volume Flow Rates
 - Mass flow rate

$$d\dot{m} = \rho V dA \implies \dot{m} = \int_{A} d\dot{m} = \int_{A} \rho V dA$$

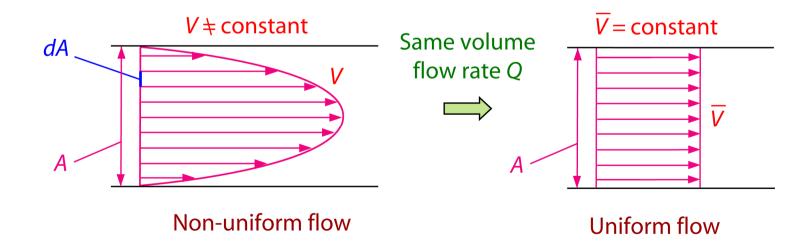
Volume flow rate

$$dQ = VdA \implies Q = \int_A dQ = \int_A VdA$$

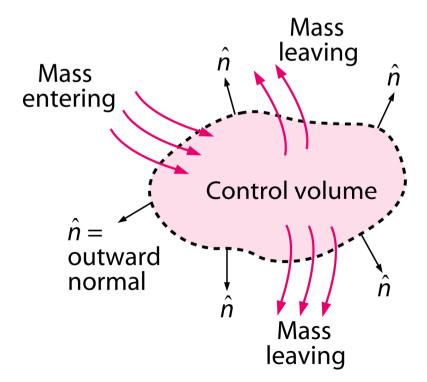


- Mass and Volume Flow Rates
 - Average velocity

$$\overline{V} = \frac{Q}{A} = \frac{\int_{A} V dA}{A}$$



- Integral Form of Continuity Equation
 - Consider a general control volume (CV):
 - ✓ There are several inlet and outlet ports or streams
 - ✓ Velocities may not be normal to surfaces



- Integral Form of Continuity Equation
 - Conservation of mass:
 - ✓ The net mass transfer to or from a CV during a time interval Δt is equal to the net change (increase or decrease) in the total mass within the CV during Δt

or

$$m_{in} - m_{out} = \Delta m_{CV}$$

where

$$\Delta m_{CV} = m_{final} - m_{initial}$$

is the change in mass of CV

• Integral Form of Continuity Equation

(4.5.1)

- Conservation of mass:
 - ✓ In rate form

$$\dot{m}_{in} - \dot{m}_{out} = \frac{dm_{CV}}{dt}$$
(A) (B)

where $\dot{m}_{\rm in}$ and $\dot{m}_{\rm out}$ are the total mass flow rates into and out of the CV, respectively, and dm_{CV}/dt is the rate of change of mass within the CV

✓ Note: $\dot{m}_{\rm in}$ and $\dot{m}_{\rm out}$ are positive

- Integral Form of Continuity Equation
 - Evaluation of (B):
 - ✓ Consider CV of arbitrary shape
 - ✓ Mass of differential volume $d\Omega$ within CV:

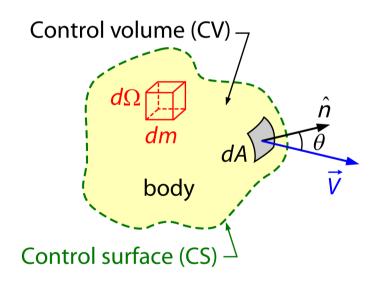
$$dm = \rho d\Omega$$

✓ Total mass within CV at time t:

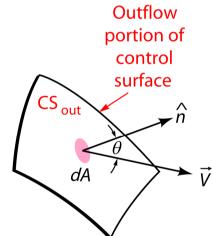
$$m_{CV} = \int_{CV} \rho d\Omega$$

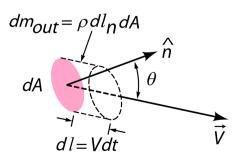
✓ Rate of change of mass within CV:

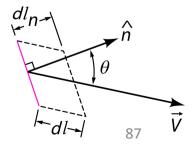
$$\frac{dm_{CV}}{dt} = \frac{d}{dt} \int_{CV} \rho d\Omega$$



- Integral Form of Continuity Equation
 - Evaluation of (A):
 - ✓ Consider mass flow out of CV through differential area *dA* on control surface of CV
 - ✓ Let \hat{n} be outward unit vector of dA normal to dA:
 - ✓ Let \vec{V} be the flow velocity at dA:
 - ✓ In general, velocity may cross at angle θ off normal:







- Integral Form of Continuity Equation
 - Evaluation of (A):
 - ✓ In time *dt* mass of fluid coming out of CV and passing across each area element

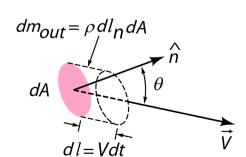
 Outflow

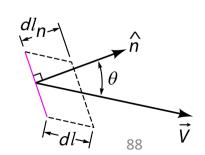
$$dm_{out} = \rho dl_n dA$$

where $dl_n = dl \cos \theta$ is height (normal to the base) of small volume element

- ✓ However, dl = Vdt
- ✓ Hence:

$$dm_{out} = \rho (dl \cos \theta) dA$$
$$= \rho (V \cos \theta dt) dA$$





portion of control

surface

CS _{out}

- Integral Form of Continuity Equation
 - Evaluation of (A):
 - ✓ Outflow mass flow rate across small area element

$$d\dot{m}_{out} = \frac{dm_{out}}{dt} = \rho V \cos\theta dA$$

✓ Integrating over entire outflow portion of control surface CS_{out} :

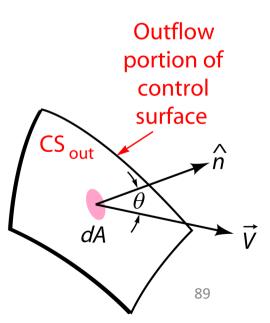
$$\dot{m}_{out} = \int_{CS_{out}} d\dot{m}_{out} = \int_{CS_{out}} \rho V \cos\theta dA$$

✓ Definition of dot product

$$V\cos\theta = \vec{V}\cdot\hat{n}$$

✓ Hence

$$\dot{m}_{out} = \int_{CS_{out}} \rho(\vec{V} \cdot \hat{n}) dA$$

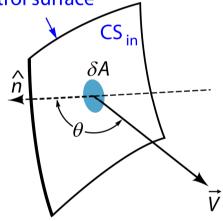


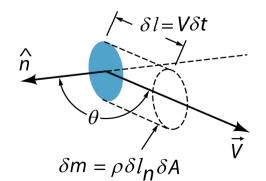
- Integral Form of Continuity Equation
 - Evaluation of (A):
 - ✓ Similarly, consider the inflow portion of the control surface CS_{in}
 - ✓ Inflow mass flow rate into CV

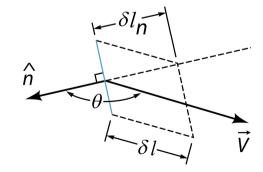
$$\dot{m}_{in} = -\int_{CS_{in}} \rho V \cos\theta dA$$

$$\dot{m}_{in} = -\int_{CS_{in}} \rho \left(\vec{V} \cdot \hat{n} \right) dA$$

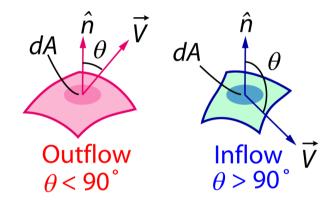
Inflow portion of control surface







- Integral Form of Continuity Equation
 - Evaluation of (A):



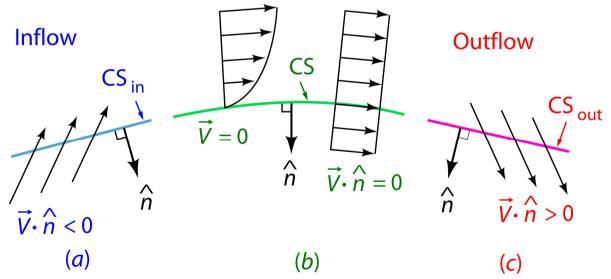
 \vec{V} : Velocity vector

 \hat{n} : Outer normal vector

$$\vec{V} \cdot \hat{n} = |\vec{V}||\hat{n}|\cos\theta = V\cos\theta$$

If $\theta < 90^\circ$, then $\cos\theta > 0$ (outflow).
If $\theta > 90^\circ$, then $\cos\theta < 0$ (inflow).
If $\theta = 90^\circ$, then $\cos\theta = 0$ (no flow).

- Integral Form of Continuity Equation
 - Evaluation of (A):
 - $\checkmark \theta > 90^{\circ} \Rightarrow \cos \theta < 0 \Rightarrow \vec{V} \cdot \hat{n} = V \cos \theta < 0 \Rightarrow \text{ inflow of mass into CV}$
 - $\checkmark \vec{V} \cdot \hat{n} = V \cos \theta = 0$ ⇒ no inflow or outflow ⇒ either V = 0 (fluid "sticks" to surface) or $\cos \theta = 0$ (fluid "slides" along surface without crossing it)
 - $\checkmark \theta < 90^{\circ} \Rightarrow \cos \theta > 0 \Rightarrow \vec{V} \cdot \hat{n} = V \cos \theta > 0 \Rightarrow \text{outflow of mass from CV}$



- Integral Form of Continuity Equation
 - Evaluation of (A):
 - ✓ Net mass flow rate across entire control surface

$$\dot{m}_{net} = \dot{m}_{out} - \dot{m}_{in}$$

$$\dot{m}_{net} = \int_{CS_{out}} \rho (\vec{V} \cdot \hat{n}) dA - \left(-\int_{CS_{in}} \rho (\vec{V} \cdot \hat{n}) dA \right)$$

$$\dot{m}_{net} = \int_{CS} \rho (\vec{V} \cdot \hat{n}) dA$$

- $\checkmark \dot{m}_{\rm net} > 0 \Longrightarrow$ net outflow of mass from CV
- $\checkmark \dot{m}_{\rm net} < 0 \Longrightarrow$ net inflow of mass from CV

$$\underbrace{\dot{m}_{in} - \dot{m}_{out}}_{A} = -\dot{m}_{net} = -\int_{CS} \rho \left(\vec{V} \cdot \hat{n}\right) dA$$

• Integral Form of Continuity Equation

– Put everything together:

$$\dot{m}_{in} - \dot{m}_{out} = \frac{dm_{CV}}{dt}$$

$$-\int_{CS} \rho (\vec{V} \cdot \hat{n}) dA = \frac{d}{dt} \int_{CV} \rho d\Omega$$
A

$$\frac{d}{dt} \int_{CV} \rho d\Omega + \int_{CS} \rho \left(\vec{V} \cdot \hat{n} \right) dA = 0$$

 The above equation is known as the integral form of the mass conservation equation or integral form of continuity equation

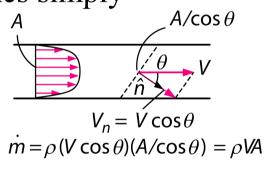
- Integral Form of Continuity Equation
 - Time rate of change of mass within CV plus net mass flow rate through control surface is equal to zero
 - Integral form of continuity equation can be also written as

$$\frac{d}{dt} \int_{CV} \rho d\Omega + \sum_{out} \int_{A} \rho |V_n| dA - \sum_{in} \int_{A} \rho |V_n| dA = 0$$
Outflow streams
Inflow streams

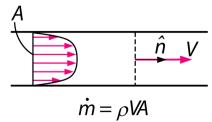
Or

$$\frac{d}{dt} \int_{CV} \rho d\Omega = \sum_{out} \dot{m} - \sum_{in} \dot{m}$$

- Integral Form of Continuity Equation
 - Proper choice of CV helps to simplify analysis
 - Choose control surface normal to flow \Rightarrow dot product $\vec{V} \cdot \hat{n}$ becomes magnitude of the velocity \Rightarrow integral $\int_{-L} \rho(\vec{V} \cdot \hat{n}) dA$ becomes simply



(a) Control surface at an angle to the flow



- Integral Form of Continuity Equation
 - Conservation of mass for steady flow processes

✓ Steady flow: "(.)" means "anything"

$$\frac{d}{dt}(.) = 0 \longrightarrow \frac{dm_{CV}}{dt} = 0$$

$$\frac{d}{dt} \int_{CV} \rho d\Omega = 0$$

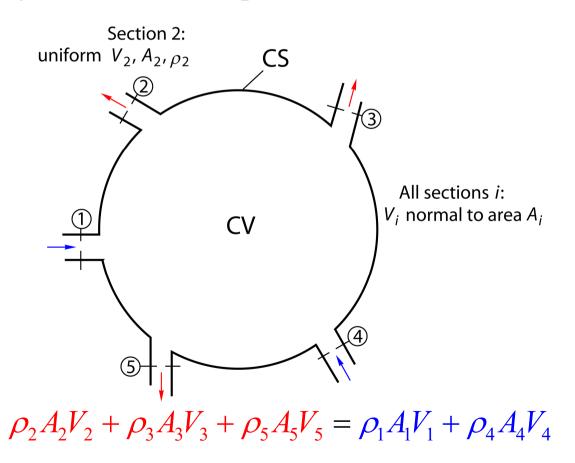
$$\int_{CS} \rho (\vec{V} \cdot \hat{n}) dA = 0$$

$$\sum_{in} \dot{m} - \sum_{out} \dot{m} = 0 \Longrightarrow \sum_{in} \dot{m} = \sum_{out} \dot{m}$$

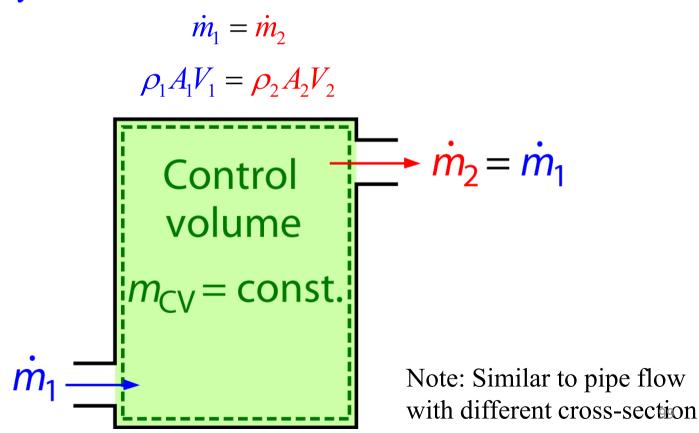
$$\sum_{in} \rho AV = \sum_{in} \rho AV$$

✓ Total mass flow rate entering CV = Total mass flow rate leaving CV

- Integral Form of Continuity Equation
 - Steady flow with multiple inlets and outlets



- Integral Form of Continuity Equation
 - Single stream ⇒ one inlet (station 1) and one outlet (station 2), steady flow



- Integral Form of Continuity Equation
 - Steady flow, incompressible flow

$$\frac{d}{dt}(.) = 0$$
 and $\rho = \text{constant}$
$$\sum_{in} \dot{m} = \sum_{out} \dot{m}$$

– Mass flow rate \dot{m} and volume flow rate Q are related via

$$\dot{m} = \rho Q$$

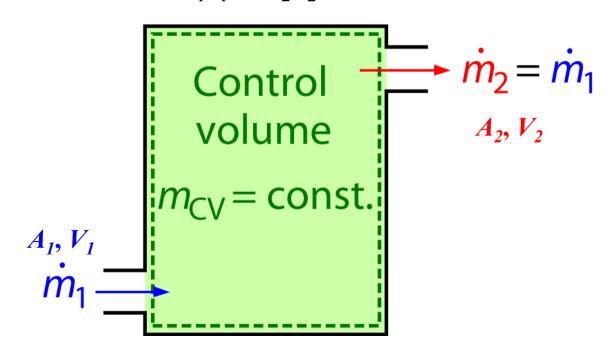
$$\sum_{in} \rho Q = \sum_{out} \rho Q$$

$$\sum_{in} Q = \sum_{out} Q$$

$$\sum_{in} AV = \sum_{out} AV$$

- Integral Form of Continuity Equation
 - Single stream \Rightarrow one inlet (station 1) and one outlet (station 2), steady, ρ = constant

$$Q_1 = Q_2$$
$$A_1 V_1 = A_2 V_2$$



- Integral Form of Continuity Equation
 - "Conservation of volume" is meaningless
 - Example: flow through air compressor
 - Mass flow rate of air through compressor is constant:

$$\dot{m}_1 = \dot{m}_2$$

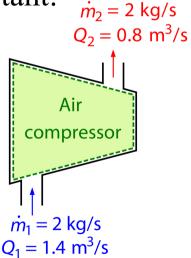
$$\rho_1 A_1 V_1 = \rho_2 A_2 V_2$$

- Since $\rho_2 > \rho_1$,

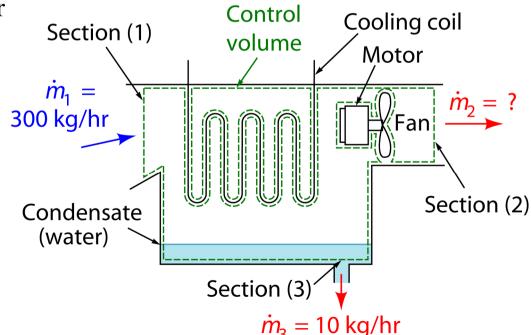
$$A_1V_1 > A_2V_2$$

$$Q_1 > Q_2$$

 $Q_1 > Q_2$ - Volume flow rate at outlet much less than that at inlet (volume flow rate is not conserved)



- Example 7
 - Question
 - ✓ Moist air enters dehumidifier at rate of 300 kg/hr
 - ✓ Liquid water drains out of dehumidifier at rate of 10 kg/hr
 - ✓ Determine mass flow rate of dry air and water vapor leaving dehumidifier

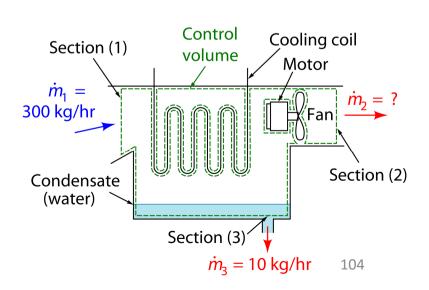


- Example 7
 - Solution
 - ✓ CV includes air and water vapor mixture and condensate in dehumidifier
 - ✓ CV does not include fan, motor, condenser coils and refrigerant

$$-\dot{m}_1 + \dot{m}_2 + \dot{m}_3 = 0$$

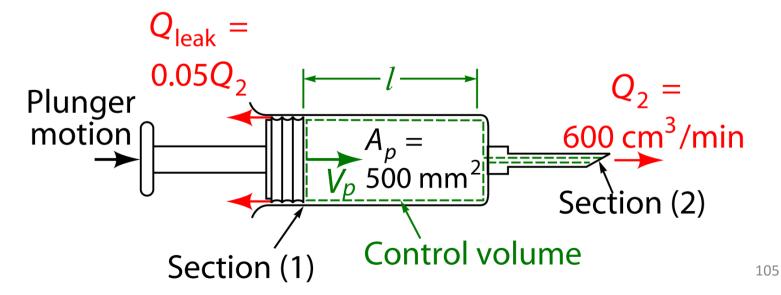
$$\dot{m}_2 = \dot{m}_1 - \dot{m}_3 = 300 - 10$$

$$\dot{m}_2 = 290 \text{ kg/hr}$$



• Example 8

- Question
 - ✓ Liquid in syringe to be injected steadily at rate of 600 cm³/min
 - ✓ Face area of plunger = 500 mm^2
 - ✓ Leakage rate past plunger is 0.05 times volume flow rate out of needle
 - ✓ Determine plunger speed V_p



• Example 8

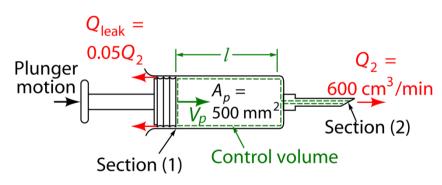
- Solution
 - ✓ Deformation CV: Section (1) of control surface moves with plunger
 - ✓ Apply the continuity equation with constant density ρ :

$$\frac{d}{dt} \int_{CV} \rho d\Omega + \int_{CS} \rho \left(\vec{V} \cdot \hat{n} \right) dA = 0$$

$$\frac{d}{dt} \int_{CV} d\Omega + Q_2 + Q_{leak} = 0$$

✓ Volume of CV

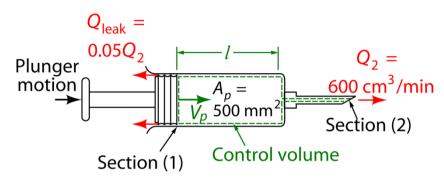
$$\int_{CV} d\Omega = lA_p + \Omega_{needle}$$



where *l* is the length of CV, which is varying with time.

- Example 8
 - Solution

$$\frac{d}{dt} \int_{CV} d\Omega = A_p \frac{dl}{dt} = -V_p A_p$$
$$-V_p A_p + Q_2 + Q_{leak} = 0$$



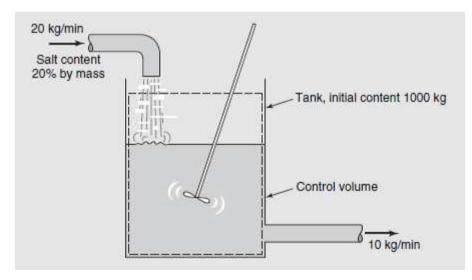
$$\frac{d}{dt} \int_{CV} d\Omega + Q_2 + Q_{leak} = 0$$

$$V_p = \frac{Q_2 + Q_{leak}}{A_p} = \frac{Q_2 + 0.05Q_2}{A_p} = \frac{1.05Q_2}{A_p}$$
$$V_p = \frac{(1.05)(600 \times 10^{-4}/60)}{500 \times 10^{-4}}$$

$$V_p = 0.021 \text{ m/s} = 2.1 \text{ cm/s}$$

• Example 9

- Question
 - ✓ A tank initially contains 1000 kg of brine containing 10% salt by mass. An inlet stream of brine containing 20% salt by mass flows into the tank at a rate of 20 kg/min. The mixture in the tank is kept uniform by stirring. Brine is removed from the tank via an outlet pipe at a rate of 10 kg/min. Find the amount of salt in the tank at any time t, and the elapsed time when the amount of salt in the tank is 200 kg.



• Example 9

- Solution
 - ✓ Assume the amounts of the brine and the salt at any time t are M_b and M_s , respectively. Initially, $M_{b0} = 1000 \text{kg}$ and $M_{s0} = 1000 \times 0.1 = 100 \text{kg}$
 - ✓ The mass balance of brine M_h :

$$\frac{d}{dt} \int_{CV} \rho d\Omega + \int_{CS} \rho (\vec{V} \cdot \hat{n}) dA = 0$$

$$\frac{d}{dt} \int_{M_{b0}}^{M_b} dM_b + \dot{m}_{b_out} - \dot{m}_{b_in} = 0$$

$$\frac{d}{dt} (M_b - 1000) - 10 = 0$$

$$M_b = 1000 + 10t$$

- Example 9
 - Solution
 - \checkmark Salt concentration at any time t

$$\frac{M_s}{M_b} = \frac{M_s}{1000 + 10t}$$

✓ The mass balance of salt M_s :

$$\frac{d}{dt} \int_{CV} \rho d\Omega + \int_{CS} \rho \left(\vec{V} \cdot \hat{n} \right) dA = 0$$

$$\frac{d}{dt} \int_{M_{s0}}^{M_s} dM_s + \dot{m}_{s_out} - \dot{m}_{s_in} = 0$$

$$\frac{d}{dt}(M_s - 100) + \frac{10M_s}{1000 + 10t} - 20 \times 0.2 = 0$$

- Example 9
 - Solution
 - ✓ The mass balance of salt M_s :

$$\frac{dM_s}{dt} + \frac{M_s}{100 + t} = 4$$

$$M_s = \frac{2t(200+t)}{100+t} + \frac{C}{100+t}$$

$$\checkmark M_{s0} = 100 \text{kg at } t = 0 \implies C = 10,000$$

$$M_s = \frac{2t^2 + 400t + 10000}{100 + t}$$

✓ t = 36.6min for $M_s = 200$ kg

• Differential Form of Continuity Equation

$$\frac{d}{dt} \int_{CV} \rho d\Omega + \int_{CS} \rho (\vec{V} \cdot \hat{n}) dA = 0$$
Gauss Theory: the outward flux of a vector field through a closed surface is equal to the volume integral of the divergence over the region inside the surface
$$\frac{d}{dt} \int_{CV} \rho d\Omega + \int_{CV} div (\rho \vec{V}) d\Omega = 0$$

$$\int_{CV} \frac{\partial \rho}{\partial t} d\Omega + \int_{CV} div (\rho \vec{V}) d\Omega = 0$$

$$\int_{CV} \left[\frac{\partial \rho}{\partial t} + div \left(\rho \vec{V} \right) \right] d\Omega = 0$$

$$\frac{\partial \rho}{\partial t} + div(\rho \vec{V}) = 0 \qquad \frac{D\rho}{Dt} + \rho div(\vec{V}) = 0$$

Differential Form of Continuity Equation

$$\frac{\partial \rho}{\partial t} + \frac{\partial}{\partial x} (\rho u) + \frac{\partial}{\partial y} (\rho v) + \frac{\partial}{\partial z} (\rho w) = 0$$

- Steady Flow: $\partial \rho / \partial t = 0$

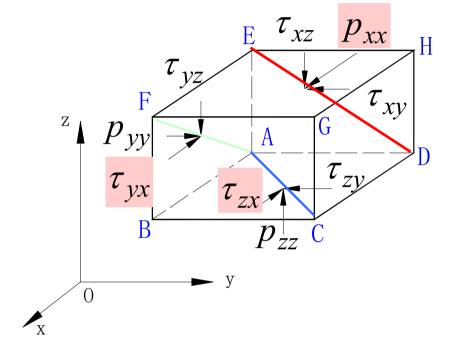
$$\frac{\partial}{\partial x}(\rho u) + \frac{\partial}{\partial y}(\rho v) + \frac{\partial}{\partial z}(\rho w) = 0$$

- Incompressible flow: ρ = constant

$$\frac{\partial u}{\partial x} + \frac{\partial v}{\partial y} + \frac{\partial w}{\partial z} = 0$$

• Stress on a fluid particle

$$\begin{bmatrix} p_{xx} & \tau_{xy} & \tau_{xz} \\ \tau_{yx} & p_{yy} & \tau_{yz} \\ \tau_{zx} & \tau_{zy} & p_{zz} \end{bmatrix}$$



Subscript: 1 surface normal 2 direction of stress

Assumption: Normal stress along positive direction Shear stress along negative direction

- Force Balance
 - Newton's Second Law F = ma
 - \checkmark In the x direction

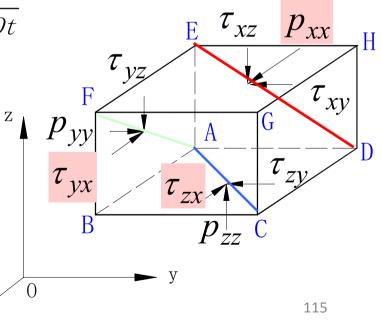
$$\rho dx dy dz X + p_{xx} dy dz - (p_{xx} + \frac{\partial p_{xx}}{\partial x} dx) dy dz - \tau_{zx} dx dy + (\tau_{zx} + \frac{\partial \tau_{zx}}{\partial z} dz) dx dy$$

$$-\tau_{yx}dxdz + (\tau_{yx} + \frac{\partial \tau_{yx}}{\partial y} dy)dxdz = \rho dxdydz \frac{Du}{Dt}$$

X denotes external body force such as gravity

✓ Rearrange the above equation

$$X - \frac{1}{\rho} \left(\frac{\partial p_{_{XX}}}{\partial X} - \frac{\partial \tau_{_{YX}}}{\partial Y} - \frac{\partial \tau_{_{ZX}}}{\partial Z} \right) = \frac{Du}{Dt}$$



Force Balance

- Newton's Second Law F = ma
 - ✓ Summary in the all directions

$$a_{x} = \frac{\partial u}{\partial t} + u \frac{\partial u}{\partial x} + v \frac{\partial u}{\partial y} + w \frac{\partial u}{\partial z}$$

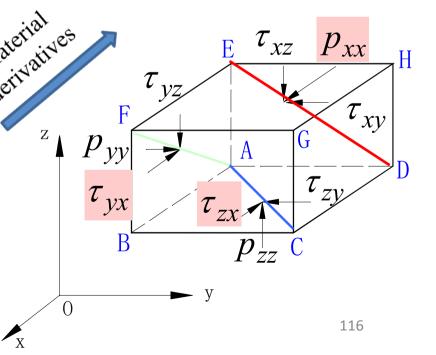
$$a_{y} = \frac{\partial v}{\partial t} + u \frac{\partial v}{\partial x} + v \frac{\partial v}{\partial y} + w \frac{\partial v}{\partial z}$$

$$a_{z} = \frac{\partial w}{\partial t} + u \frac{\partial w}{\partial x} + v \frac{\partial w}{\partial y} + w \frac{\partial w}{\partial z}$$

$$X - \frac{1}{\rho} \left(\frac{\partial p_{xx}}{\partial x} - \frac{\partial \tau_{yx}}{\partial y} - \frac{\partial \tau_{zx}}{\partial z} \right) = \frac{Du}{Dt} \text{Material}$$

$$Y - \frac{1}{\rho} \left(\frac{\partial p_{yy}}{\partial y} - \frac{\partial \tau_{zy}}{\partial z} - \frac{\partial \tau_{xy}}{\partial x} \right) = \frac{Dv}{Dt} \text{Material}$$

$$Z - \frac{1}{\rho} \left(\frac{\partial p_{zz}}{\partial z} - \frac{\partial \tau_{xz}}{\partial x} - \frac{\partial \tau_{yz}}{\partial y} \right) = \frac{Dw}{Dt}$$



Force Balance

Constitutive equations for stress

$$\tau_{xy} = \tau_{yx} = \mu(\frac{\partial v}{\partial x} + \frac{\partial u}{\partial y})$$

$$\tau_{yz} = \tau_{zy} = \mu(\frac{\partial w}{\partial y} + \frac{\partial v}{\partial z})$$

$$\tau_{zx} = \tau_{xz} = \mu(\frac{\partial u}{\partial z} + \frac{\partial w}{\partial x})$$

$$p_{xx} = -p + p'_{xx} = -p - \frac{2}{3} \mu divV + 2\mu \frac{\partial u}{\partial x}$$

$$p_{yy} = -p + p'_{yy} = -p - \frac{2}{3} \mu divV + 2\mu \frac{\partial v}{\partial y}$$

$$p_{zz} = -p + p'_{xx} = -p - \frac{2}{3} \mu divV + 2\mu \frac{\partial w}{\partial z}$$

$$(2)$$

Navier-Stokes Equations

$$X - \frac{1}{\rho} \frac{\partial p}{\partial x} + \nu \left(\frac{\partial^{2} u}{\partial x^{2}} + \frac{\partial^{2} v}{\partial y^{2}} + \frac{\partial^{2} w}{\partial z^{2}} \right) + \nu \frac{\partial}{\partial x} \left(\frac{\partial u}{\partial x} + \frac{\partial v}{\partial y} + \frac{\partial w}{\partial z} \right) = \frac{Du}{Dt}$$
Hamiltonian
$$\nabla = \vec{i} \frac{\partial}{\partial x} + \vec{j} \frac{\partial}{\partial y} + \vec{k} \frac{\partial}{\partial z}$$
Laplacian
$$\nabla^{2} = \nabla \cdot \nabla = \frac{\partial^{2}}{\partial x^{2}} + \frac{\partial^{2}}{\partial y^{2}} + \frac{\partial^{2}}{\partial z^{2}}$$

$$\frac{\partial u}{\partial t} + (\vec{V} \cdot \nabla) u = X - \frac{1}{\rho} \frac{\partial p}{\partial x} + \nu \nabla^{2} u + \nu \frac{\partial}{\partial x} (\nabla \cdot \vec{V})$$

$$\frac{\partial v}{\partial t} + (\vec{V} \cdot \nabla) v = Y - \frac{1}{\rho} \frac{\partial p}{\partial y} + \nu \nabla^{2} v + \nu \frac{\partial}{\partial y} (\nabla \cdot \vec{V})$$

$$\frac{\partial w}{\partial t} + (\vec{V} \cdot \nabla) w = Z - \frac{1}{\rho} \frac{\partial p}{\partial z} + \nu \nabla^{2} w + \nu \frac{\partial}{\partial z} (\nabla \cdot \vec{V})$$

- Navier-Stokes Equations
 - Incompressible flow

Continuity
$$\frac{\partial u}{\partial x} + \frac{\partial v}{\partial y} + \frac{\partial w}{\partial z} = 0 \quad \text{or} \quad \nabla \cdot \vec{V} = 0$$
Equation

$$\frac{\partial u}{\partial t} + (\vec{V} \cdot \nabla) u = X - \frac{1}{\rho} \frac{\partial p}{\partial X} + \nu \nabla^2 u$$

$$\frac{\partial v}{\partial t} + (\vec{V} \cdot \nabla) v = Y - \frac{1}{\rho} \frac{\partial p}{\partial Y} + \nu \nabla^2 v$$

$$\frac{\partial w}{\partial t} + (\vec{V} \cdot \nabla) w = Z - \frac{1}{\rho} \frac{\partial p}{\partial Z} + \nu \nabla^2 w$$

• Euler Equations (Inviscid flow v=0)

$$\frac{\partial u}{\partial t} + (\vec{V} \cdot \nabla) u = X - \frac{1}{\rho} \frac{\partial p}{\partial X}$$

$$\frac{\partial v}{\partial t} + (\vec{V} \cdot \nabla) v = Y - \frac{1}{\rho} \frac{\partial p}{\partial Y}$$

$$\frac{\partial w}{\partial t} + (\vec{V} \cdot \nabla) w = Z - \frac{1}{\rho} \frac{\partial p}{\partial Z}$$

• Fluid at Rest u = v = w = 0

$$X - \frac{1}{\rho} \frac{\partial p}{\partial X} = 0$$

$$Y - \frac{1}{\rho} \frac{\partial p}{\partial Y} = 0$$

$$Z - \frac{1}{\rho} \frac{\partial p}{\partial Z} = 0$$

Incompressible Flow in Cylindrical Coordinates

Continuity Equations

$$\frac{1}{r}\frac{\partial(ru_r)}{\partial r} + \frac{1}{r}\frac{\partial u_\theta}{\partial \theta} + \frac{\partial u_z}{\partial z} = 0$$

Navier-Stokes Equations

- Navier-Stokes Equations
$$\frac{\partial u_r}{\partial t} + u_r \frac{\partial u_r}{\partial r} + \frac{u_\theta}{r} \frac{\partial u_r}{\partial \theta} - \frac{u_\theta^2}{r} + u_z \frac{\partial u_r}{\partial z} = X_r - \frac{1}{\rho} \frac{\partial p}{\partial r}$$

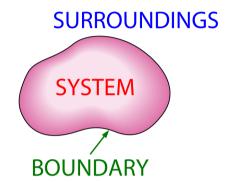
$$+ v \left[\frac{1}{r} \frac{\partial}{\partial r} \left(r \frac{\partial u_r}{\partial r} \right) - \frac{u_r}{r^2} + \frac{1}{r^2} \frac{\partial^2 u_r}{\partial \theta^2} - \frac{2}{r^2} \frac{\partial u_\theta}{\partial \theta} + \frac{\partial^2 u_r}{\partial z^2} \right]$$

$$\frac{\partial u_\theta}{\partial t} + u_r \frac{\partial u_\theta}{\partial r} + \frac{u_\theta}{r} \frac{\partial u_\theta}{\partial \theta} + \frac{u_r u_\theta}{r} + u_z \frac{\partial u_\theta}{\partial z} = X_\theta - \frac{1}{\rho r} \frac{\partial p}{\partial \theta}$$

$$+ v \left[\frac{1}{r} \frac{\partial}{\partial r} \left(r \frac{\partial u_\theta}{\partial r} \right) - \frac{u_\theta}{r^2} + \frac{1}{r^2} \frac{\partial^2 u_\theta}{\partial \theta^2} + \frac{2}{r^2} \frac{\partial u_r}{\partial \theta} + \frac{\partial^2 u_\theta}{\partial z^2} \right]$$

$$\frac{\partial u_z}{\partial t} + u_r \frac{\partial u_z}{\partial r} + \frac{u_\theta}{r} \frac{\partial u_z}{\partial \theta} + u_z \frac{\partial u_z}{\partial z} = X_z - \frac{1}{\rho} \frac{\partial p}{\partial z} + v \left[\frac{1}{r} \frac{\partial}{\partial r} \left(r \frac{\partial u_z}{\partial r} \right) + \frac{1}{r^2} \frac{\partial^2 u_z}{\partial \theta^2} + \frac{\partial^2 u_z}{\partial z^2} \right]$$

- System, surrounding, boundary;
- Closed system: mass cannot cross boundary,
 energy can cross boundary
- Open system/control volume: both mass and



energy can cross boundary

- Lagrangian description: tracks the motion of a generic individual fluid particle; observer moves with the fluid
- Eulerian description: individual fluid particles are not identified and tracked; field variables are defined
- Classification of fluid flows: viscous and inviscid flows; laminar and turbulent flows; compressible and incompressible flows; steady and unsteady flows; internal and external flows; one-, two- and three-dimensional flows

- Material (substantial) derivative

$$\frac{D(\)}{Dt} = \frac{\partial(\)}{\partial t} + u \frac{\partial(\)}{\partial x} + v \frac{\partial(\)}{\partial y} + w \frac{\partial(\)}{\partial z} = \frac{\partial(\)}{\partial t} + (\vec{V} \bullet \nabla)(\)$$

Acceleration of fluid particle

$$a_{x} = \frac{\partial u}{\partial t} + u \frac{\partial u}{\partial x} + v \frac{\partial u}{\partial y} + w \frac{\partial u}{\partial z}$$

$$a_{y} = \frac{\partial v}{\partial t} + u \frac{\partial v}{\partial x} + v \frac{\partial v}{\partial y} + w \frac{\partial v}{\partial z}$$

$$a_{z} = \frac{\partial w}{\partial t} + u \frac{\partial w}{\partial x} + v \frac{\partial w}{\partial y} + w \frac{\partial w}{\partial z}$$

$$local convective$$

$$acceleration acceleration$$

 Streamlines are everywhere parallel to the local velocity: instantaneous flow pattern

$$\frac{dr}{V} = \frac{dx}{u} = \frac{dy}{v} = \frac{dz}{w}$$

A pathline is the actual path traced out by a fluid particle:
 flow over a period of time by a single particle

$$\vec{x}(t) = \vec{x}_0 + \int_{t_0}^t \vec{V} dt$$

- A streakline is the locus of all fluid particles that have passed through a point in the flow: flow pattern over a period of time by many particles
- Steady flow: streamlines = pathlines = streaklines

Mass and volume flow rates

$$\rho$$
 = constant

$$\dot{m} = \int_{A} \rho V dA$$
 $\dot{m} = \rho AV$ $Q = \int_{A} V dA$ $Q = AV$

- Average flow velocity
$$\overline{V} = \frac{Q}{A} = \frac{\int_{A} V dA}{A} \frac{\int_{A} V dA}{\int_{A} dA}$$

Continuity equation

$$\frac{d}{dt} \int_{CV} \rho d\Omega + \int_{CS} \rho \left(\vec{V} \cdot \hat{n} \right) dA = 0$$

$$\frac{D\rho}{Dt} + \rho div(\vec{V}) = 0$$

$$\frac{\partial\rho}{\partial t} + div(\rho\vec{V}) = 0$$

$$\frac{\partial\rho}{\partial t} + div(\rho\vec{V}) = 0$$

$$\frac{\partial\rho}{\partial t} + div(\rho\vec{V}) = 0$$

Continuity equation for steady flow

$$\frac{d}{dt}\int_{CV}\rho d\Omega = 0$$

$$\sum_{in} \rho AV = \sum_{out} \rho AV$$

$$\sum_{in} \dot{m} = \sum_{out} \dot{m}$$

$$\frac{\partial}{\partial x}(\rho u) + \frac{\partial}{\partial y}(\rho v) + \frac{\partial}{\partial z}(\rho w) = 0$$

Continuity equation for incompressible steady flow

$$A_1V_1 = A_2V_2$$

$$Q_1 = Q_2$$

$$\frac{\partial u}{\partial x} + \frac{\partial v}{\partial y} + \frac{\partial w}{\partial z} = 0$$

Navier Stokes equations

$$\frac{\partial u}{\partial t} + (\vec{V} \cdot \nabla) u = X - \frac{1}{\rho} \frac{\partial p}{\partial X} + \nu \nabla^2 u + \nu \frac{\partial}{\partial X} (\nabla \cdot \vec{V})$$

$$\frac{\partial v}{\partial t} + (\vec{V} \cdot \nabla) v = Y - \frac{1}{\rho} \frac{\partial p}{\partial Y} + \nu \nabla^2 v + \nu \frac{\partial}{\partial Y} (\nabla \cdot \vec{V})$$

$$\frac{\partial w}{\partial t} + (\vec{V} \cdot \nabla) w = Z - \frac{1}{\rho} \frac{\partial p}{\partial Z} + \nu \nabla^2 w + \nu \frac{\partial}{\partial Z} (\nabla \cdot \vec{V})$$

Navier Stokes equation for incompressible flow

$$\frac{\partial u}{\partial t} + (\vec{V} \cdot \nabla) u = X - \frac{1}{\rho} \frac{\partial p}{\partial X} + \nu \nabla^2 u$$

$$\frac{\partial v}{\partial t} + (\vec{V} \cdot \nabla) v = Y - \frac{1}{\rho} \frac{\partial p}{\partial Y} + \nu \nabla^2 v$$

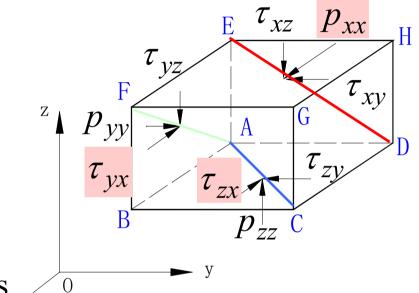
$$\frac{\partial w}{\partial t} + (\vec{V} \cdot \nabla) w = Z - \frac{1}{\rho} \frac{\partial p}{\partial Z} + \nu \nabla^2 w$$

Euler equations

$$\frac{\partial u}{\partial t} + (\vec{V} \cdot \nabla) u = X - \frac{1}{\rho} \frac{\partial p}{\partial X}$$

$$\frac{\partial v}{\partial t} + (\vec{V} \cdot \nabla) v = Y - \frac{1}{\rho} \frac{\partial p}{\partial Y}$$

$$\frac{\partial w}{\partial t} + (\vec{V} \cdot \nabla) w = Z - \frac{1}{\rho} \frac{\partial p}{\partial Z}$$



Constitutive equations for stress

$$\begin{bmatrix} p_{xx} & \tau_{xy} & \tau_{zz} \\ \tau_{yx} & p_{yy} & \tau_{yz} \end{bmatrix} \qquad \tau_{xy} = \tau_{yx} = \mu \left(\frac{\partial v}{\partial x} + \frac{\partial u}{\partial y}\right) \qquad p_{xx} = -p - \frac{2}{3} \mu divV + 2\mu \frac{\partial u}{\partial x}$$

$$\begin{bmatrix} \tau_{yx} & p_{yy} & \tau_{yz} \\ \tau_{zx} & \tau_{zy} & p_{zz} \end{bmatrix} \qquad \tau_{yz} = \tau_{zy} = \mu \left(\frac{\partial w}{\partial y} + \frac{\partial v}{\partial z}\right) \qquad p_{yy} = -p - \frac{2}{3} \mu divV + 2\mu \frac{\partial v}{\partial y}$$

$$\begin{bmatrix} \tau_{zx} & \tau_{zy} & p_{zz} \end{bmatrix} \qquad \tau_{zx} = \tau_{xz} = \mu \left(\frac{\partial u}{\partial z} + \frac{\partial w}{\partial x}\right) \qquad p_{zz} = -p - \frac{2}{3} \mu divV + 2\mu \frac{\partial w}{\partial z}$$

$$p_{xx} = -p - \frac{2}{3} \mu divV + 2\mu \frac{\partial u}{\partial x}$$

$$p_{yy} = -p - \frac{2}{3} \mu divV + 2\mu \frac{\partial v}{\partial y}$$

$$p_{zz} = -p - \frac{2}{3} \mu divV + 2\mu \frac{\partial w}{\partial z}$$

Conservation Law

• Example 10

Question: Does the following incompressible flow exist:

$$u = x, v = y, w = z$$

- Solution:
 - ✓ For incompressible flow, the continuity equation is

$$\frac{\partial u}{\partial x} + \frac{\partial v}{\partial y} + \frac{\partial w}{\partial z} = 0$$

✓ For the above mentioned flow:

$$\frac{\partial u}{\partial x} + \frac{\partial v}{\partial y} + \frac{\partial w}{\partial z} = \frac{\partial x}{\partial x} + \frac{\partial y}{\partial y} + \frac{\partial z}{\partial z} = 3 \neq 0$$

✓ The flow does not exist because it does not satisfy continuity equation

Conservation Law

• Example 11

 Question: Two dimensional steady incompressible flow; the velocity component in the x direction is given as

$$u = e^{-x} \cos y + 1$$

Determine the y-velocity component. (assume v = 0 at y = 0)

- Solution:

✓ For 2D incompressible flow, the continuity equation is

$$\frac{\partial u}{\partial x} + \frac{\partial v}{\partial y} = 0$$

$$u = e^{-x} \cos y + 1$$

$$\frac{\partial \left(e^{-x} \cos y + 1\right)}{\partial x} + \frac{\partial v}{\partial y} = 0$$

Conservation Law

- Example 11
 - Solution:

$$\frac{\partial v}{\partial y} = e^{-x} \cos y$$
$$v = e^{-x} \sin y + C$$

$$\checkmark v = 0 \text{ at } y = 0$$

$$C = 0$$

$$v = e^{-x} \sin y$$

