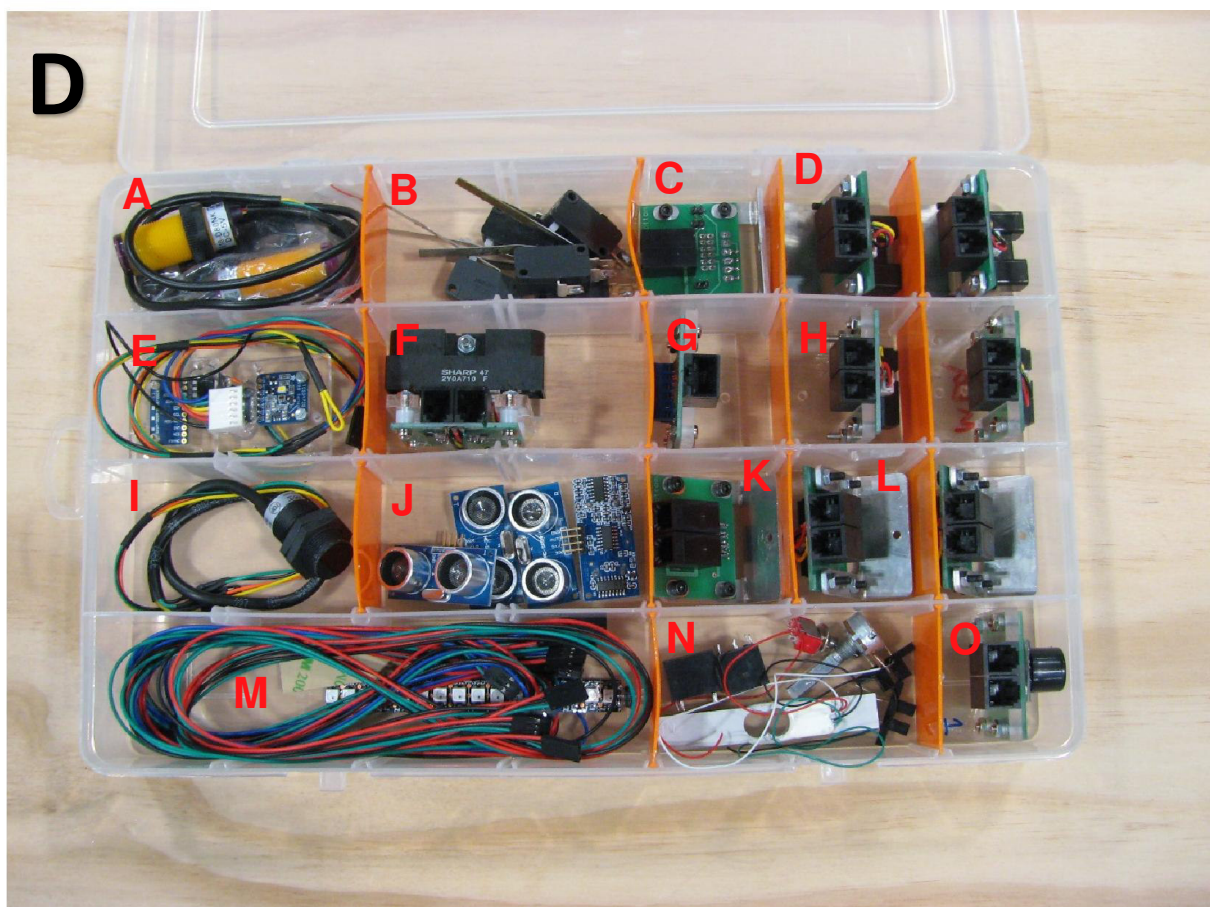
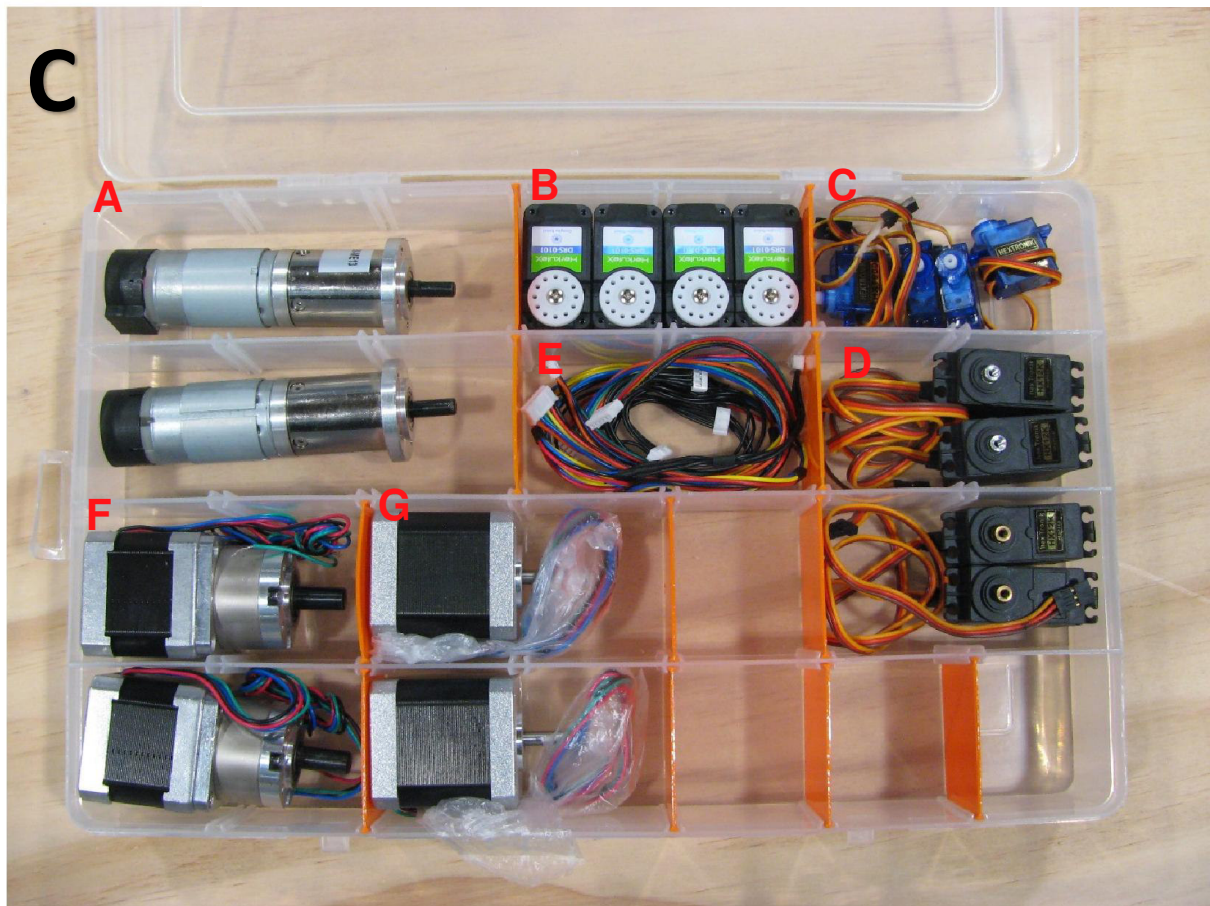


Box Parts

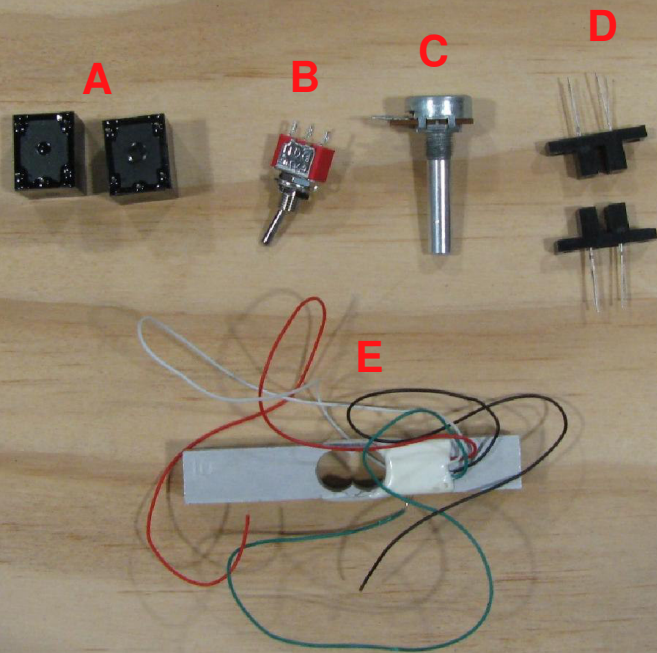
A	A	25mm right angle aluminium
	B	12mm right angle aluminium
	C	12mm box section aluminium
	D	12mm U shaped aluminium
	E	25mm flat bar aluminium
	F	12mm flat bar aluminium
	G	8mm round bar aluminium
	H	6.5mm round bar aluminium
B	A	Bearing assemble for track
	B	GT2 Timing Belt
	C	GT2 Timing Pulley 16 teeth
	D	Track
	E	Nuts and hex bolts
	F	Laser cut support structures
	G	Open beam main robot support structure
	H	Open beam main small
	I	Open beam main Longer
C	A	DC Motor, includes gear box and encoder
	B	Smart servo
	C	Small servo
	D	Standard servo
	E	DC Motor and smart servo connection cables
	F	Stepper motor with gear box
	G	Stepper motor
D	A	Digital Infrared distance sensor
	B	Micro switch
	C	Digital interface board for use with limit switches
	D	Infrared distance sensor
	E	Colour sensor and IMU
	F	Infrared distance sensor
	G	Digital interface board
	H	Infrared distance sensor
	I	Infrared camera
	J	Ultrasound sensor
	K	Analogue interface board
	L	Infrared distance sensor
	M	Cables and RGB smart LED's
	N	Relay, load cell, switch, variable resistor, IR interruption sensor
	O	Ultrasound sensor

E	A	Relay
	B	Switch
	C	Variable resistor
	D	IR interruption sensor
	E	Load Cell
F		RGB smart LED
G		IMU
H		Colour sensor
I	A	Main CPU board with IO Board
	B	Dual DC motor driver
	C	Servo IO Board
	D	Camera and wireless IO board
	E	Fan
	F	Signal test board
	G	Main power supply and battery protection board
	H	Speaker
	I	Large Servo
J		Ultrasound sensor
K		Infrared distance sensor
L		Digital interface board
M		Analogue interface board
N		Digital interface board for use with limit switches
O		Infrared distance sensor
P		Infrared distance sensor
Q		Infrared distance sensor
R		Infrared distance sensor
S		Ultrasound sensor

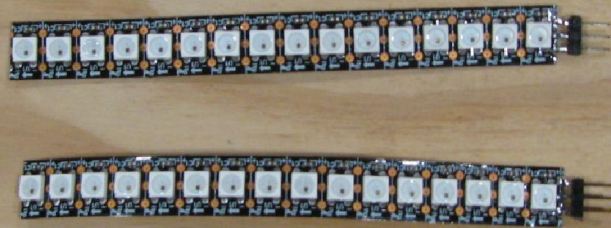




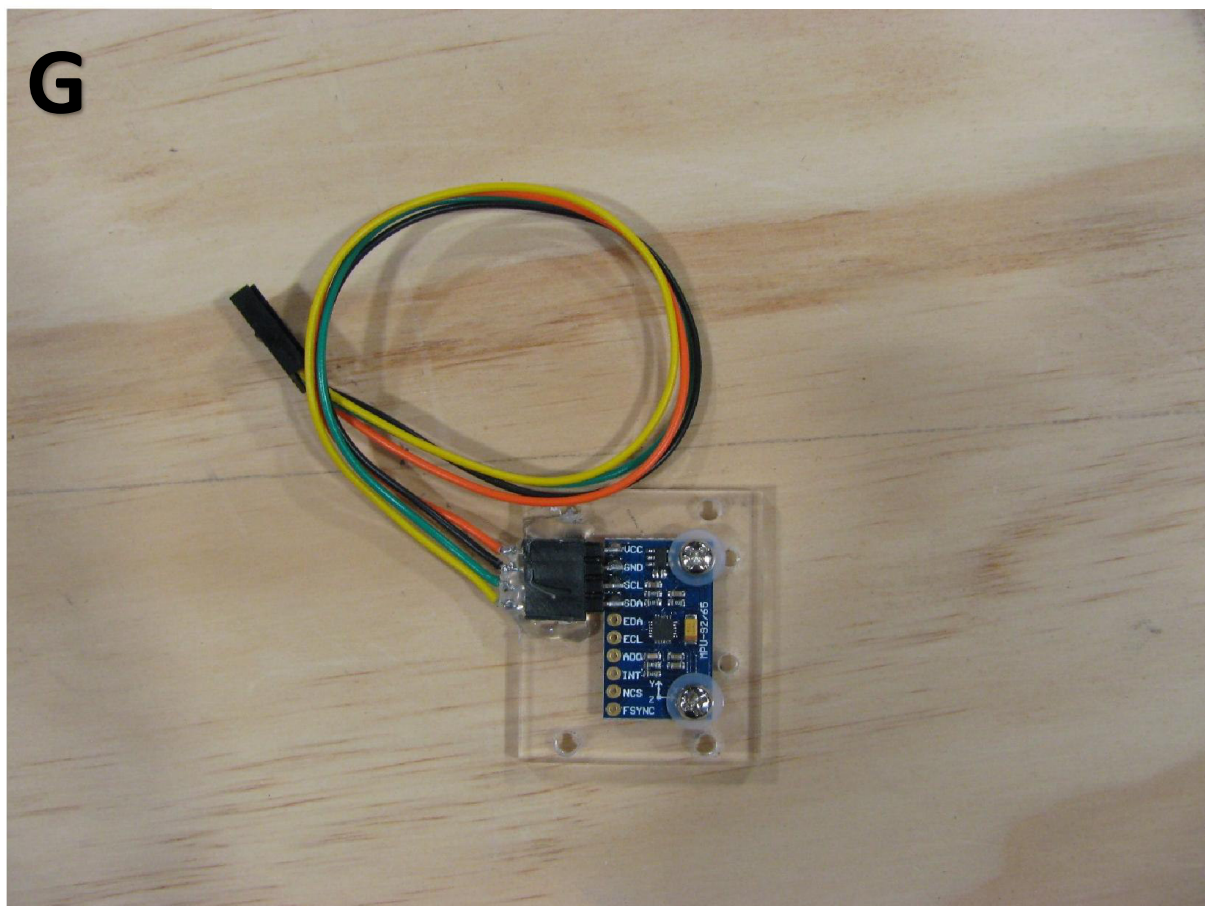
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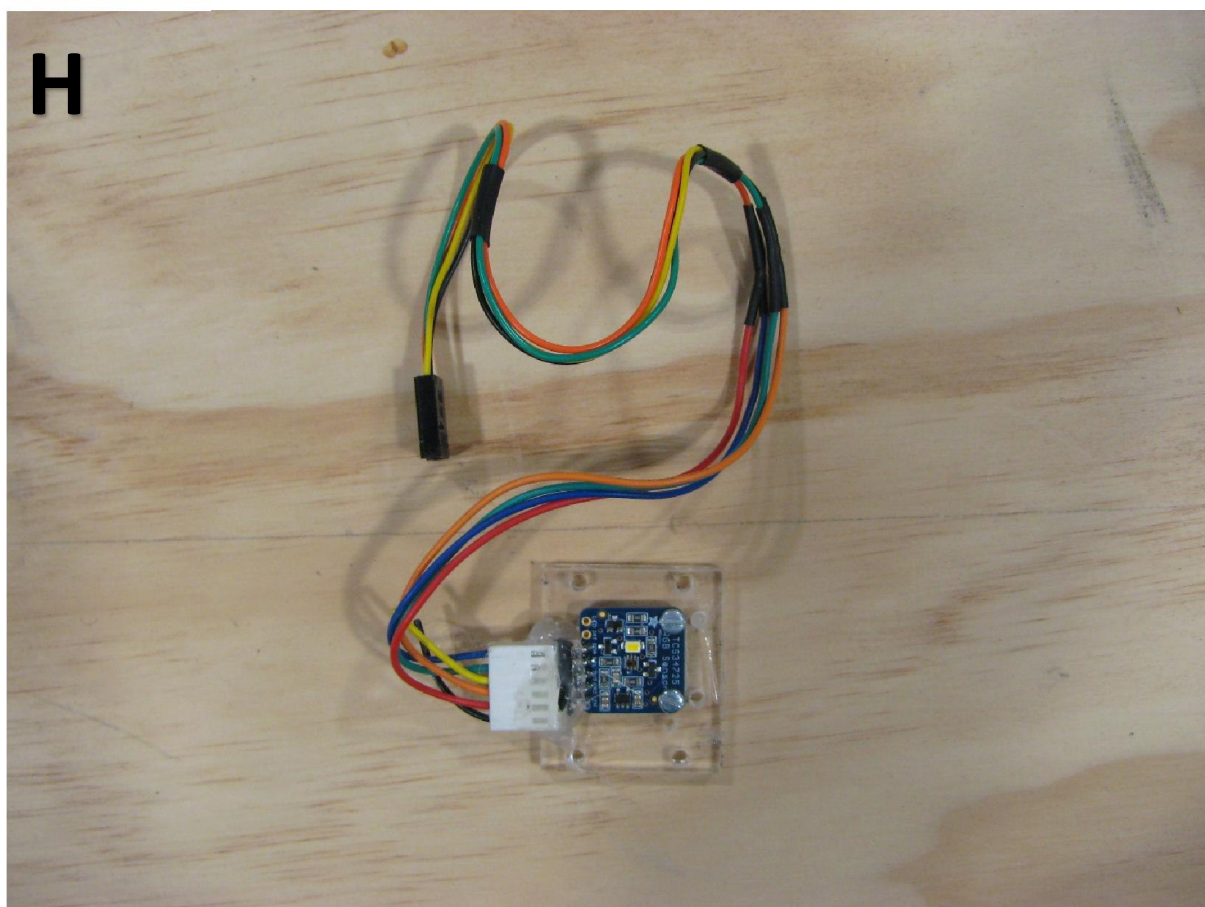
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G

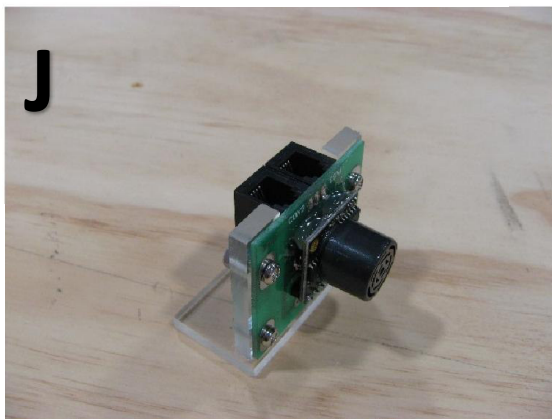


H

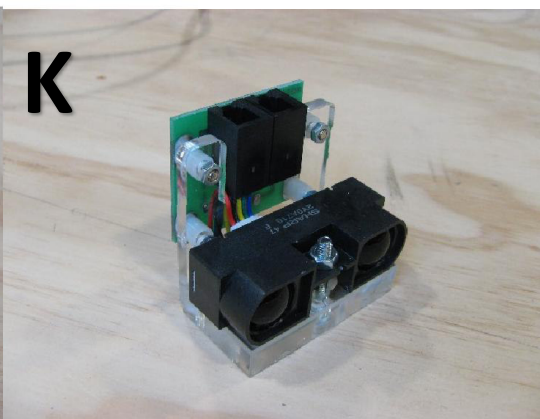




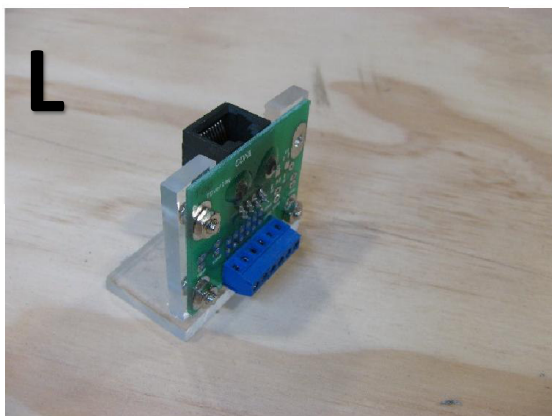
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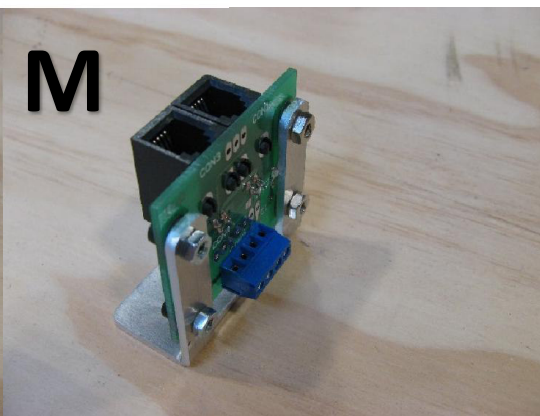
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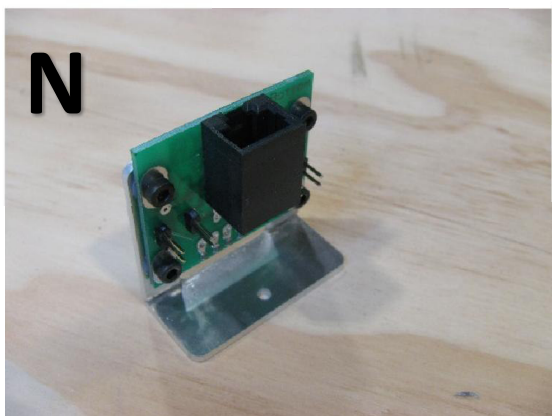
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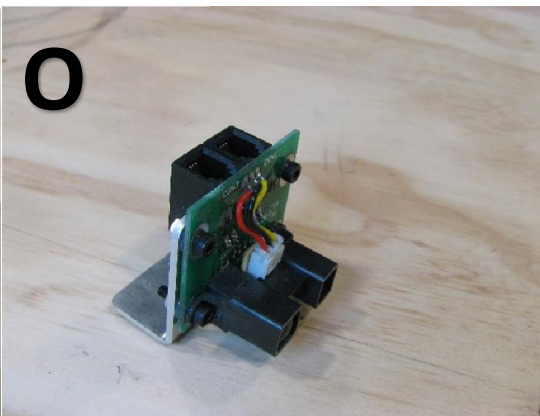
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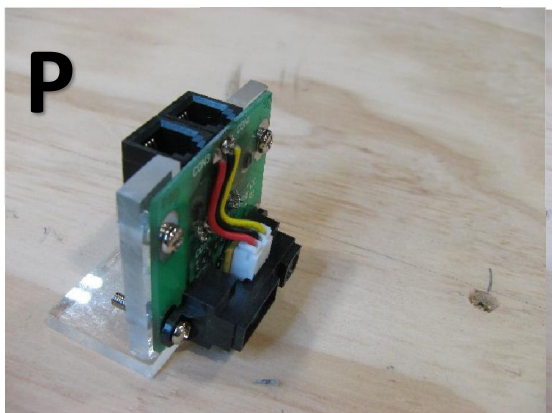
N



O



P



Q

