

1. Determine if the following signals are periodical, and determine the fundamental period.

(1)  $x(n) = \cos(0.125n\pi) + \sin(0.05n\pi)$

(2)  $x(n) = \cos(0.125n\pi) \cdot \sin(0.05n\pi)$

Remark:

For the discrete-time signal, its fundamental period is very different from the analog one. How to calculate the fundamental period? A simple equation is available with the relationship of phase between the discrete-time signal and the analog signal.

$N\omega = 2\pi k$  Where  $\omega$  is the digital angle frequency,  $N$  is the number of the sample in one period,  $r$  is the corresponding number of the period.

So, the above equation means that  $N$  digital periods has the same phase shift as  $r$  analog periods.

Solution:

(1) For  $\cos(0.125n\pi)$ , its  $\omega = 0.125\pi$ , then  $N / r = 16$

For  $\sin(0.05n\pi)$ , its  $\omega = 0.05\pi$ , then  $N / r = 40$

So the fundamental period is least common multiple  $[16, 40] = 80$ .

(2) With  $\cos A \sin B = 1/2[\sin(A+B) - \sin(A-B)]$

$x(n) = \cos(0.125n\pi) \cdot \sin(0.05n\pi) = 1/2[\sin(0.175n\pi) - \sin(0.075n\pi)]$

For  $\sin(0.175n\pi)$ , its  $\omega = 0.175\pi$ , then  $N / r = 80 / 7$

For  $\sin(0.075n\pi)$ , its  $\omega = 0.075\pi$ , then  $N / r = 80 / 3$

So the fundamental period is 80

Attention:

1,  $N / r$  的物理含义, 就是在数字域  $N$  个采样点对应着模拟域  $r$  个周期, 所以只需要取数字域采样点的最小公倍数即可, 无需一定具有相同的模拟周期的约束。

2 Determine the sequence  $x(n)$  from the following sampling process and calculate its fundamental period:

$$x_a(t) = 2\sin(20\pi t) - 4\cos(24\pi t) - 5\sin(120\pi t) - \cos(176\pi t), f_s = 50\text{Hz}$$

Solution:

$$\begin{aligned}\text{For } x_a(nT_s) &= x_a(t)|_{t=nT_s} \\ &= 2\sin(20\pi n/50) - 4\cos(24\pi n/50) - 5\sin(120\pi n/50) - \cos(176\pi n/50) \\ &= 2\sin(0.4\pi n) - 4\cos(0.48\pi n) - 5\sin(2.4\pi n) - \cos(3.52\pi n) \\ &= 2\sin(0.4\pi n) - 4\cos(0.48\pi n) - 5\sin(0.4\pi n) - \cos(0.48\pi n) \\ &= -3\sin(0.4\pi n) - 5\cos(0.48\pi n)\end{aligned}$$

For  $-3\sin(0.4\pi n)$ , its  $\omega = 0.4\pi$ , then  $N/k = 5$

For  $-5\cos(0.48\pi n)$ , its  $\omega = 0.48\pi$ , then  $N/k = 25/6$

So the fundamental period is least common multiple  $[5, 25] = 25$ .

Attention:

(1) Many students don't know  $\sin(0.4\pi n) = \sin(2.4\pi n)$ .

(2) Some students write the unit for the fundamental period, such as s (second).

3. Consider the discrete-time signal  $x(n) = \cos(n\pi/8)$ , and try to find two different continuous-time signals which generate  $x(n)$  when sampled at 10Hz rate.

Solution:

$$\text{For } \cos(nT_s) = \cos(2\pi f t)|_{t=nT_s}$$

$$\cos(n) = \cos(2\pi n f / f_s) = \cos(\pi n f / 5) \quad (2-1)$$

$$\text{And } \cos(n\pi/8) = \cos(n\pi/8 + 2\pi k n), k \text{ is any integer.} \quad (2-2)$$

Let (2-1) is equal to (2-2), we get

$$\pi n f / 5 = n\pi/8 + 2\pi k n$$

$$f = 5/8 + 10k, k \text{ is any integer}$$

So the analog signal is  $\cos[2\pi t(5/8 + 10k)]$ ,  $k$  is any integer

For  $k=0$ , it's the critical sample rate, the analog one is  $\cos(5\pi t/4)$

And we can get the others for the different  $k$ .

Attention:

Many students don't know the relationship between the analog signal and discrete signal, especially for the sin family functions.

4. Given discrete sequence  $x(n) = 2 \cos(2\pi n / 3)$ , its

period  $N = \underline{3}$ , assume the sample rate is 3000Hz, so the analogue signal is  $\underline{x_a(t) = 2 \cos(2000\pi t)}$ .

5. One analogue signal is  $x(t) = 5 \sin 400\pi t + 8 \cos 1000\pi t$ . Its Nyquist sampling rate is  $\underline{1000}$  Hz.

6. For each of the following discrete-time systems, where  $y(n)$  and  $x(n)$  are, respectively, the output and the input sequences, determine whether or not the system is (1) linear, (2) time shift-invariant, (3) causal and (4) stable.

a)  $y(n) = \sum_{m=-\infty}^n x(m)$ .

Solution:

$$\sum_{m=-\infty}^n [Ax_1(m) + Bx_2(m)] = A \sum_{m=-\infty}^n x_1(m) + B \sum_{m=-\infty}^n x_2(m)$$

So the system is **linear**.

If  $x(n) = x(n - n_0)$

$$\text{Then } y(n) = \sum_{m=-\infty}^n x(m) = \sum_{m=-\infty}^{n-n_0} x(m) = y(n - n_0)$$

So it is **time-invariant**.

$$\text{Since } h(n) = \sum_{m=-\infty}^n \delta(m) = \begin{cases} 1 & n \geq 0 \\ 0 & n < 0 \end{cases} = u(n)$$

Thus, if  $n < 0$ ,  $h(n) = 0$

So it is **causal**.

$$\text{Since } \sum_{m=-\infty}^{\infty} |h(n)| = \sum_{m=-\infty}^{\infty} u(n) = \sum_{n=0}^{\infty} 1 = \infty$$

So it is **not stable**.

b)  $y(n) = 2x^2(n) + 3$ .

Solution:

$$2[Ax_1(n) + Bx_2(n)]^2 + 3 \neq A[2x_1^2(n) + 3] + B[2x_2^2(n) + 3]$$

So it is **not linear**.

$$\text{If } x(n) = x(n - n_0)$$

$$\text{Then } y(n) = 2x^2(n) + 3 = 2x^2(n - n_0) + 3 = y(n - n_0)$$

So it is **time-invariant**.

Since there is no output before the input hence the system is **causal**.

If  $x(n)$  is a bounded input,  $y(n)$  is a bounded output.

So it is **stable**.

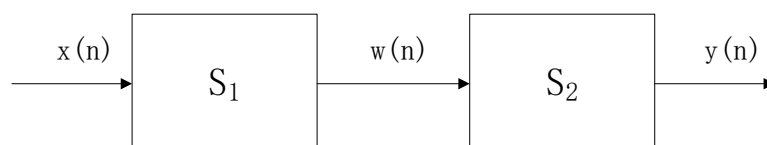
7. Determine if the system  $y(n) = Ax(n)$  is a linear system. Linear(OR Yes)

8. Let the Nyquist frequency of  $X_a(t)$  is  $\Omega_s$ . The Nyquist frequency of

$X_a(t)\cos(\Omega_0 t)$  is  $\Omega_N = \Omega_s + 2\Omega_0$ . The Nyquist frequency of  $X_a(2t)$  is

$\Omega_N = 2\Omega_s$ .

9. Consider the two systems are connected in cascade.



(a) If  $S_1$  and  $S_2$  are linear, time-invariant, stable and causal, then the system is linear, time-invariant or not?

(b) If  $S_1$  is linear and  $S_2$  is nonlinear, then the whole system is linear or nonlinear?

(a) For linear:

$$y_1(n) = T[x_1(n)] = S_2[S_1[x_1(n)]] = S_2[w_1(n)]$$

$$y_2(n) = T[x_2(n)] = S_2[S_1[x_2(n)]] = S_2[w_2(n)]$$

$$\begin{aligned} T[ax_1(n) + bx_2(n)] &= S_2[S_1[ax_1(n) + bx_2(n)]] \\ &= S_2[aS_1[x_1(n)] + bS_1[x_2(n)]] \\ &= S_2[aw_1(n) + bw_2(n)] \\ &= aS_2[w_1(n)] + bS_2[w_2(n)] \\ &= ay_1(n) + by_2(n) \end{aligned}$$

So linear

For time-invariant:

$$T[x(n-m)] = S_2[S_1[x(n-m)]] = S_2[w(n-m)] = y(n-m)$$

So time-invariant.

(b) for linear:

$$y_1(n) = T[x_1(n)] = S_2[S_1[x_1(n)]] = S_2[w_1(n)]$$

$$y_2(n) = T[x_2(n)] = S_2[S_1[x_2(n)]] = S_2[w_2(n)]$$

$$ay_1(n) + by_2(n) = aS_2[w_1(n)] + bS_2[w_2(n)]$$

$$\begin{aligned} T[ax_1(n) + bx_2(n)] &= S_2[S_1[ax_1(n) + bx_2(n)]] \\ &= S_2[aw_1(n) + bw_2(n)] \\ &\neq aS_2[w_1(n)] + bS_2[w_2(n)] \end{aligned}$$

So

non-linear

10. Assuming using the same sampling frequency for analogue signals:

$x_1(t) = 2\sin(200\pi t)$  and  $x_2(t) = \sin(400\pi t)$ . According to the Shannon Sampling

Theorem, the lowest sampling frequency is 400Hz. After the sampling process, the discrete-time signals  $x_1(n) = \underline{2\sin(0.5\pi n)}$ ,  $x_2(n) = \underline{\sin(\pi n)}$ .

The analogue angular frequencies for each signal are  $\Omega_1 = \underline{200\pi \text{ rad/s}}$ ,

$\Omega_2 = \underline{400\pi \text{ rad/s}}$ . And the digital angular frequencies for each signal are

$\omega_1 = \underline{0.5\pi}$ ,  $\omega_2 = \underline{\pi}$ .

11.If the impulse response of a LTI system is  $h(n)$ , then the casual condition of this

system is  $h[n] = 0, n < 0$  and the stable condition is  $\sum_{n=-\infty}^{\infty} |h[n]| < \infty$ .

12.One analogy signal  $x_a(t) = a \cdot \sin(100\pi t)$ ,  $a$  is nonzero constant, the sample frequency

is  $f_s = 200\text{Hz}$ , then the discrete sequence is  $x(n) = x_a(nT_s)$ , its

period  $N =$ 4 $$ .

13.For each of the following discrete-time systems, where  $y(n)$  and  $x(n)$  are, respectively, the output and the input sequences, determine whether or not the system is (1) linear, (2) time shift-invariant, (3) causal and (4) stable.

i)  $y(n) = nx(n)$

**Solution:**

**nonlinear[2 marks], not time shift-invariant[2 marks], causal[2 marks], not stable[2 marks].**

ii)  $y(n) = \sum_{k=-\infty}^{\infty} x(k)x(n+k)$

**Solution:**

**nonlinear[2 marks], not time shift-invariant[2 marks], not causal[2 marks], not stable[2 marks].**

14.One analogue signal is

$x(t) = 4\sin(20\pi t) - 5\cos(24\pi t) + 3\sin(120\pi t) + 2\cos(176\pi t)$ , If the sampling rate is 50Hz, then the digital signal could be expressed as:

$x[n] = 4\sin\left(\frac{2\pi n}{5}\right) - 5\cos\left(\frac{12\pi n}{25}\right) + 3\sin\left(\frac{2\pi n}{5}\right) + 2\cos\left(\frac{12\pi n}{25}\right)$ . [2 marks]

15.onsidering the continuous-time signal  $g_a(t) = \sin(\Omega_m t)$ , it must be sampled at a

rate  $\Omega_s \geq 2\Omega_m$  to recover it fully from its samples.. [2 marks]

16. one signal  $x(n) = \cos(0.125n\pi)$ , its fundamental period  $N = \underline{8}$ . One signal  $x(n) = \cos(0.125n\pi) + \sin(0.05n\pi)$ , its fundamental period  $N = \underline{80}$ . [4 marks]

17. For each of the following discrete-time systems, where  $y(n)$  and  $x(n)$  are, respectively, the output and the input sequences, determine whether or not the system is (1) linear, (2) time shift-invariant, (3) causal and (4) stable.

iii)  $y(n) = 2x(n) + 3$

**Solution:**

$$2(Ax_1[n] + Bx_2[n]) + 3 \neq A(2x_1(n) + 3) + B(2x_2(n) + 3)$$

so it is not linear.

$$\text{if } x[n] = x[n - n_0]$$

$$\text{then } y(n) = 2x(n) + 3 = 2x[n - n_0] + 3 = y[n - n_0]$$

so it is time-invariant.

Since there is no output before the input hence the system is **causal**.

if  $x[n]$  is a bounded input

$y[n]$  is a bounded output. So it is **stable**.

iv)  $y(n) = x^2(n)$

**Solution:**

$$(Ax_1[n] + Bx_2[n])^2 \neq A^2x_1^2(n) + B^2x_2^2(n)$$

So the system is **not linear**. [2 marks]

$$\text{If } x_1[n] = x[n - n_0] \text{ then } y[n] = x^4[n] = x^4[n - n_0] = y[n - n_0].$$

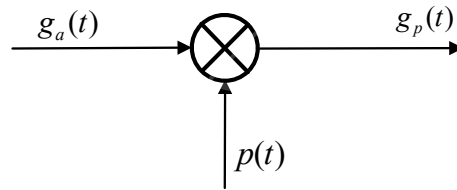
so it is time-invariant. [2 marks]

Since there is no output before the input hence the system is **causal**. [2 marks]

if  $x[n]$  is a bounded input

$y[n]$  is a bounded output. so it is **stable**. [2 marks]

18. Consider the sampling process:



Given:

$$p(t) = \sum_{n=-\infty}^{+\infty} \delta(t - nT)$$

$$g_p(t) = g_a(t) \cdot p(t) = \sum_{n=-\infty}^{+\infty} g_a(nT) \delta(t - nT)$$

Prove the sampling theorem:  $G_p(j\Omega) = \frac{1}{T} \sum_{n=-\infty}^{+\infty} G_a(j(\Omega - n\Omega_T))$

**Solution:**

$p(t)$  is a periodic signal with the period  $T$ , and satisfies the Dirichlet conditions, then it can be expanded as:

$$p(t) = \sum_{n=-\infty}^{+\infty} \delta(t - nT) = \sum_{n=-\infty}^{+\infty} a_n e^{jn\Omega_0 t}, \quad \Omega_0 = \frac{2\pi}{T}$$

$$\text{Here, } a_n = \frac{1}{T} \int_{-\frac{T}{2}}^{\frac{T}{2}} p(t) e^{-jn\Omega_0 t} dt = \frac{1}{T}$$

$$\text{Then } p(t) = \frac{1}{T} \sum_{n=-\infty}^{+\infty} e^{jn\Omega_0 t}$$

$$\text{By the Fourier transform, } F[p(t)] = \frac{2\pi}{T} \sum_{n=-\infty}^{+\infty} \delta(\Omega - n\Omega_0)$$

Then, the Fourier transform of  $g_p(t) = g_a(t) \cdot p(t)$  is:

$$G_p(j\Omega) = \frac{1}{2\pi} [G_a(j\Omega) * p(j\Omega)]$$

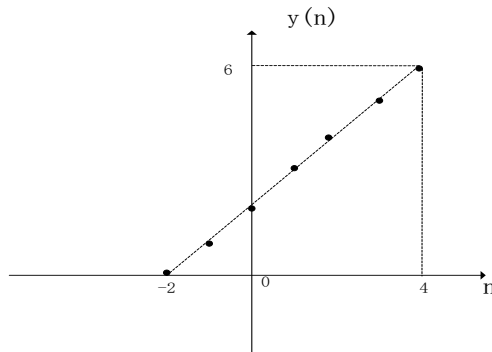
$$= \frac{1}{2\pi} \left[ G_a(j\Omega) * \frac{2\pi}{T} \sum_{n=-\infty}^{+\infty} \delta(\Omega - n\Omega_T) \right], \quad \Omega_T = \Omega_0 T$$

$$= \frac{1}{T} \sum_{n=-\infty}^{+\infty} G_a(j(\Omega - n\Omega_T))$$



Then  $G_p(j\Omega) = \frac{1}{T} \sum_{-\infty}^{+\infty} G_a(j(\Omega - n\Omega_T))$

19. Let the signal  $x(n] = (6 - n)[u(n) - u(n - 6)]$ . Sketch the signal  $y(n) = x(4 - n)$ .



20. Let the Nyquist frequency of  $X_a(t)$  is  $\Omega_s$ . The Nyquist frequency of  $X_a(t) \cos(\Omega_0 t)$  is  $\Omega_N = \Omega_s + 2\Omega_0$ . The Nyquist frequency of  $X_a(2t)$  is  $\Omega_N = 2\Omega_s$ .

21. Determine if the system  $y(n] = e^{x(n]}$  is (a) Linear, (b) Time-Invariant, (c) Stable, (d) Causal. (a) Nonlinear, (b) Time-Invariant, (c) Stable, (d) Causal.

22. Given signal  $x(n] = \cos(0.125n\pi) + \sin(0.05n\pi)$ , then its period  $N = \underline{80}$ .  
[2 marks]

23. Given signal  $y(n] = \cos(0.125n\pi) \cdot \sin(0.05n\pi)$ , then its period  $N = \underline{80}$ .  
[2 marks]

24. For each of the following discrete-time systems, where  $y(n]$  and  $x(n]$  are, respectively, the output and the input sequences, determine whether or not the system is (1) linear, (2) shift-invariant, (3) causal and (4) stable.

v)  $y(n] = ax(n] + b$ ,  $a$  and  $b$  are nonzero constants.

**Solution: nonlinear, shift-invariant, causal, stable**

vi)  $y(n) = a + \sum_{l=-3}^3 x(n-l)$ ,  $a$  is a nonzero constant.

**Solution: nonlinear, shift-invariant, noncausal, stable**

25. One analogue signal is  $x(t) = 3 \sin 200\pi t + 7 \sin 1200\pi t$ . Its Nyquist sampling rate is **1200** Hz.

**[2 marks]**

26. Given signal  $x_a(t) = 3 \sin(100\pi t)$ , assume the sample frequency

is  $f_s = 300 \text{ Samples/s}$ , so the discrete sequence is  $x(n) = x_a(nT_s)$ , its period

$N = \underline{\underline{6}}$

27. For each of the following discrete-time systems, where  $y(n)$  and  $x(n)$  are, respectively, the output and the input sequences, determine whether or not the system is (1) linear, (2) shift-invariant, (3) causal and (4) stable?

i)  $y(n) = x^2(n)$

Solution:

$$(Ax_1[n] + Bx_2[n])^2 \neq Ax_1^2(n) + Bx_2^2(n)$$

So the system is **not linear**.

If  $x_1[n] = x[n - n_0]$  then  $y[n] = x^2[n] = x[n - n_0]^2 = y[n - n_0]$ .

so it is **time-invariant**.

Since there is no output before the input hence the system is **causal**.

if  $x[n]$  is a bounded input

$y[n]$  is a bounded output. so it is **stable**.

ii)  $y(n) = 2x(n) + 3$

Solution:

$$2(Ax_1[n] + Bx_2[n]) + 3 \neq A(2x_1(n) + 3) + B(2x_2(n) + 3)$$

so it is **not linear**.

$$\text{if } x[n] = x[n - n_0]$$

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28. One analogue signal is

$$x(t) = 4\sin(20\pi t) - 5\cos(24\pi t) + 3\sin(120\pi t) + 2\cos(176\pi t), \text{ If the sampling rate is}$$

50Hz, then the digital signal could be expressed as:

$$\underline{x[n] = 4\sin\left(\frac{2\pi n}{5}\right) - 5\cos\left(\frac{12\pi n}{25}\right) + 3\sin\left(\frac{2\pi n}{5}\right) + 2\cos\left(\frac{12\pi n}{25}\right)}.$$

b) If the impulse response of a LTI system is  $h(n)$ , then the stable condition of this

system is  $\underline{\sum_{n=-\infty}^{\infty} |h[n]| < \infty}$  and the casual condition is  $\underline{h[n] = 0, n < 0}$ .

c) Consider the sequence defined by  $\{g[n]\} = e^{j\pi n}$ . Is it bounded or not? YES  
(‘Yes’ or ‘No’).

d) Considering the continuous-time signal  $g_a(t) = \sin(\Omega_m t)$ , it must be sampled at

least at a rate  $\underline{\Omega_s > 2\Omega_m}$  to recover it fully from its samples..

29. For each of the following discrete-time systems, where  $y(n)$  and  $x(n)$  are, respectively, the output and the input sequences, determine whether or not the system is (1) linear, (2) shift-invariant, (3) causal and (4) stable.

i)  $y(n) = x^3(n-1)$ .

**nonlinear, shift-invariant, causal, stable**

ii)  $y(n) = 2x(n+1) + 3$ .

**nonlinear, shift-invariant, noncausal, stable**