# Signals and Systems 3.2

### --- Fourier transform

School of Information & Communication Engineering, BUPT

Reference:
1. Textbook: Chapter 3

## Clue of this chapter

- In chapter 2, by representing signals as linear combinations of shifted impulses, we analyzed LTI systems through the convolution sum (integral).
- An alternative representation for signals and LTI systems: represent signals as linear combinations of a set of basic signals---complex exponentials. The resulting representations are known as the continuoustime and discrete-time Fourier series and transform.
  - which convert time-domain signals into frequencydomain (or *spectral*) representations

# Outline of Today's Lecture

### Fourier transform

- Complex Sinusoids and Frequency Response of LTI Systems
- Fourier Representations for Four classes of Signals
  - Discrete-time periodic signals DTFS
  - □ Discrete-time nonperiodic signals DTFT
  - Continuous-time periodic signals FS
  - □ Continuous-time nonperiodic signals FT
- Properties of Fourier Representations

### Summary of the Fourier series

- Three forms

$$x(t) = a_0 + \sum_{n=1}^{\infty} a_n \cos(n\omega t) + \sum_{n=1}^{\infty} b_n \sin(n\omega t)$$
- Cosine-with-phase form
$$x(t) = a_0 + \sum_{n=1}^{\infty} A_n \cos(n\omega t + \theta_k) \qquad -\infty < t < \infty$$
- Exponential form
$$x(t) = \sum_{n=-\infty}^{\infty} X_n. e^{jn\omega t}$$

$$x(t) = a_0 + \sum_{n=0}^{\infty} A_n \cos(n\omega t + \theta_k)$$
  $-\infty < t < \infty$ 

$$x(t) = \sum_{n=-\infty}^{\infty} X_n. e^{in\omega t}$$

- Dirichlet conditions
- Gibbs phenomenon

$$x(t) = \sum_{n=-\infty}^{\infty} X_n e^{jn\omega_1 t}$$

Complex Exponentials and Frequency Response of LTI Systems

The response of an LTI system to a complex exponentials input lead to a characterization of system behavior that is termed the frequency response of the

- ♣ Frequency response = The response of an LTI system to a complex exponentials input.
- Frequency response of a Discrete-time LTI system
- 1. Impulse response of discrete-time LTI system = h[n], input =  $x[n] = e^{j\Omega n}$

2. Output

$$y[n] = \sum_{k=-\infty}^{\infty} h[k]x[n-k] = \sum_{k=-\infty}^{\infty} h[k]e^{j\Omega(n-k)}$$

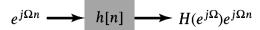
Complex Exponentials and Frequency Response of LTI Systems

### ■ Frequency response of Discrete-time LTI system

$$y[n] = e^{j\Omega n} \sum_{k=-\infty}^{\infty} h[k] e^{-j\Omega k} = H(e^{j\Omega}) e^{j\Omega n}$$

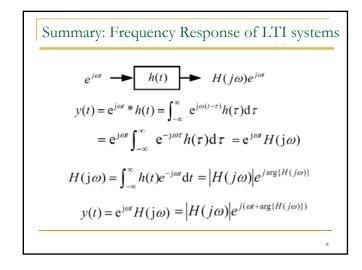
3. Frequency response:

A function of frequency Ω



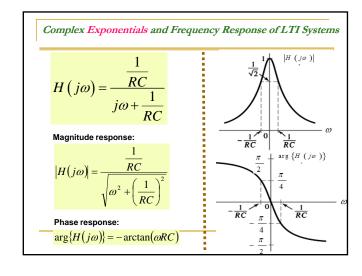
The output of a complex exponentials input to an LTI system is a complex exponentials of the same frequency as the input, multiplied by the frequency response of the system.

The systems modifies the amplitude of the input by  $|H(j\omega)| = |H(j\omega)| e^{j\omega t + arg\{H(j\omega)\}}$ To provide the first system and Frequency Response of LTI System and Frequency Response of LTI System and LTI system are L system and L system and L system are L system are L system and L system are L system are L system and L system are L system and L system are L system are L system are L system and L system are L system are L system and L system are L system are L system and L system are L system are L system are L system and L system are L system are



Complex Exponentials and Frequency Response of LTI Systems

Example 3.1 RC Circuit: Frequency response  $h(t) = \frac{1}{RC} e^{-t/RC} u(t)$  < Sol.> Frequency response:  $H(j\omega) = \frac{1}{RC} \int_{-\infty}^{\infty} e^{-\frac{\tau}{RC}} u(\tau) e^{-j\omega\tau} d\tau = \frac{1}{RC} \int_{0}^{\infty} e^{-\left(\frac{j\omega + \frac{1}{RC}}{RC}\right)\tau} d\tau$   $= \frac{1}{RC} \frac{-1}{\left(j\omega + \frac{1}{RC}\right)} e^{-\left(\frac{j\omega + \frac{1}{RC}}{RC}\right)\tau} \Big|_{0}^{\infty}$   $= \frac{1}{RC} \frac{-1}{\left(j\omega + \frac{1}{RC}\right)} (0-1) = \frac{\frac{1}{RC}}{j\omega + \frac{1}{RC}}$ 



Eigenvalue and eigenfunction of LTI system

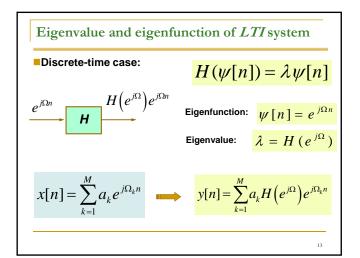
If  $\mathbf{e}_k$  is an eigenvector of a matrix  $\mathbf{A}$  with eigenvalue  $\lambda_k$ , then  $\mathbf{A}\mathbf{e}_k = \lambda_k \mathbf{e}_k$ Arbitrary input = weighted superpositions of eigenfunctions

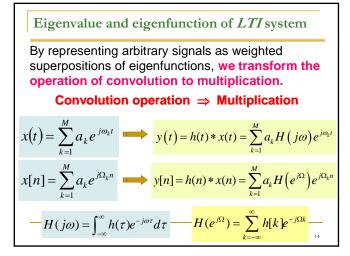
Eigenrepresentation  $\psi(t) \qquad \qquad \psi(t) \qquad \qquad \psi(t)$ 

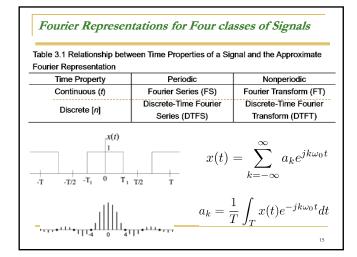
Eigenvalue and eigenfunction of LTI system

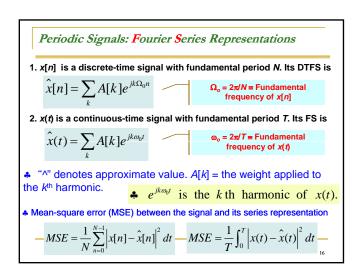
Continuous-time case:  $H\left\{\psi(t)\right\} = \lambda \psi(t)$   $e^{j\omega t} \qquad H$ Eigenfunction:  $\psi(t) = e^{j\omega t}$ Eigenvalue:  $\lambda = H(j\omega)$ Arbitrary input = weighted superpositions of eigenfunctions

Convolution operation  $\Rightarrow$  Multiplication  $x(t) = \sum_{k=1}^{M} a_k e^{j\omega_k t}$   $y(t) = \sum_{k=1}^{M} a_k H(j\omega) e^{j\omega_k t}$ 





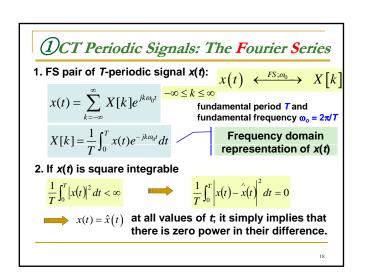




Nonperiodic Signals: Fourier-Transform Representations

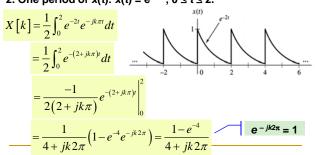
1. x(t) is a continuous-time signal. Its FT is  $\hat{x}(t) = \frac{1}{2\pi} \int_{-\infty}^{\infty} X\left(j\omega\right) e^{j\omega t} d\omega$   $X(j\omega)/(2\pi) = \text{the weight applied to a sinusoid of frequency } \omega \text{ in the FT representation.}$ 2. x[n] is a discrete-time signal. Its DTFT is  $\hat{x}[n] = \frac{1}{2\pi} \int_{-\infty}^{\infty} X\left(e^{j\Omega}\right) e^{j\Omega n} d\omega$   $X(e^{j\Omega})/(2\pi) = \text{the weight applied to the sinusoid } e^{j\Omega n} \text{ in the DTFT representation.}$ Problem 3.1 Identify the appropriate Fourier representation for each of the following signals:

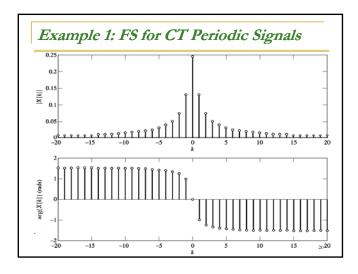
(a)  $x[n] = (1/2)^n u[n]$ (b)  $x(t) = 1 - \cos(2\pi t) + \sin(3\pi t)$ (c)  $x(t) = e^{-t} \cos(2\pi t) u(t)$ (d)  $x[n] = \sum_{m=-\infty}^{\infty} \delta[n-20m] - 2\delta[n-2-20m]$ (e)  $x[n] = \sum_{m=-\infty}^{\infty} \delta[n-20m] - 2\delta[n-2-20m]$ 



Example 1: Determine the FS coefficients for CT Periodic Signals Using Defination

- 1. The period of x(t) is T = 2, so  $\omega_0 = 2\pi/2 = \pi$ .
- 2. One period of x(t):  $x(t) = e^{-2t}$ ,  $0 \le t \le 2$ .





Example 2(3.10): FS Coefficients for An Impulse Train

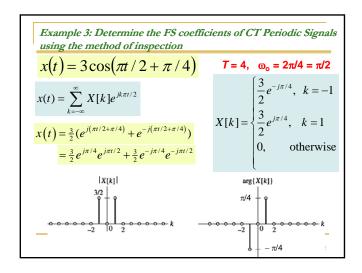
-Sol >

$$x(t) = \sum_{l=-\infty}^{\infty} \delta(t - 4l)$$

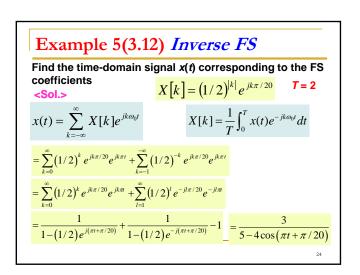
- 1. Fundamental period of x(t) is T = 4, each period contains an impulse, frequency  $\omega_0 = 2\pi/T$
- 2. By integrating over a period that is symmetric about the origin  $-2 < t \le 2$ , to obtain X[k]

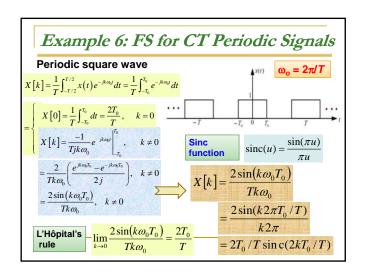
$$X[k] = \frac{1}{4} \int_{-2}^{2} \delta(t) e^{-jk(\pi/2)t} dt = \frac{1}{4}$$

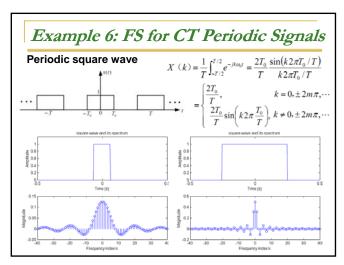
3. The magnitude spectrum is constant and the phase spectrum is zero.

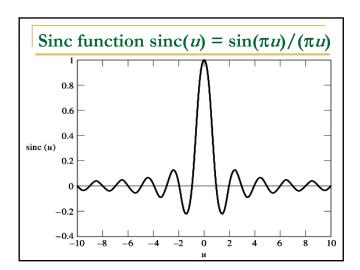


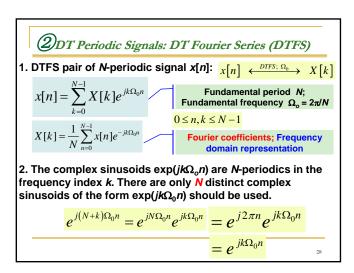
# Determine the DTFS coefficients of $x(t) = 1 - \cos(\pi t) + 2\sin(2\pi t) + \cos(3\pi t)$ using the method of inspection. $x(t) = 1 - \cos(\pi t) + 2\sin(2\pi t) + \cos(3\pi t)$ $= 1 - \frac{e^{j\omega_0 t} + e^{-j\omega_0 t}}{2} + 2\frac{e^{j2\omega_0 t} - e^{-j2\omega_0 t}}{2j} + \frac{e^{j3\omega_0 t} + e^{-j3\omega_0 t}}{2}$ $= \begin{cases} 1, & k = 0 \\ -\frac{1}{2}, & k = \pm 1 \\ \mp j, & k = \pm 2 \end{cases}$ $X(k\omega_0) = \begin{cases} 1, & k = \pm 1 \\ \pm j, & k = \pm 3 \\ 0, & others \end{cases}$

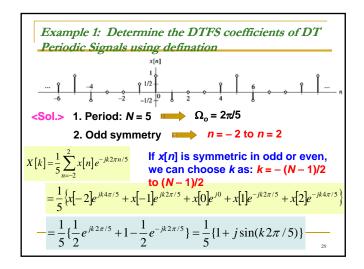


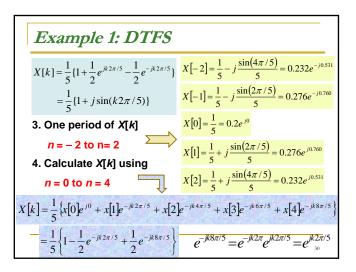


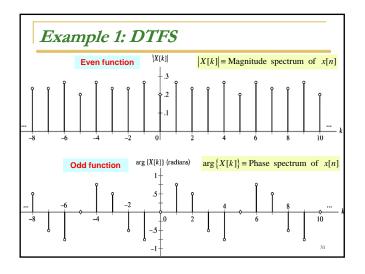


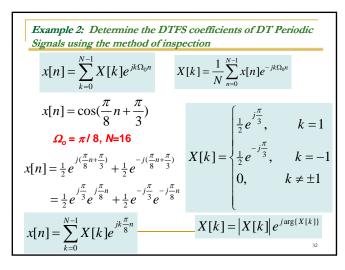


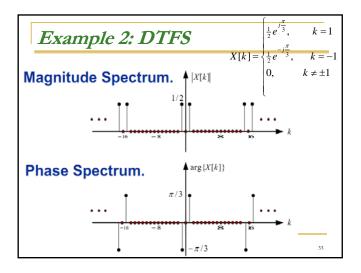


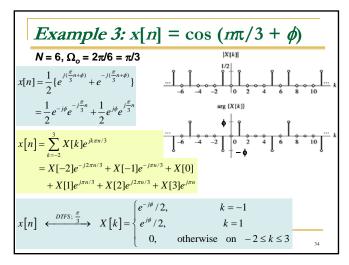


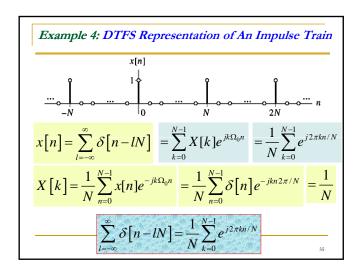


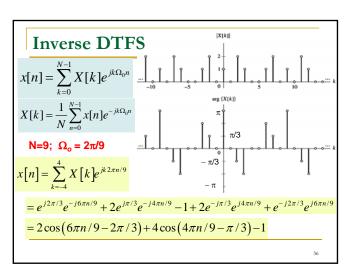


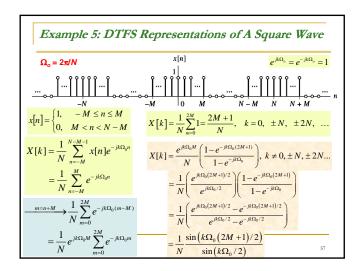


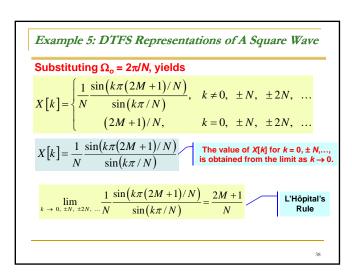


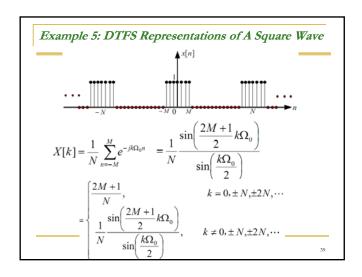


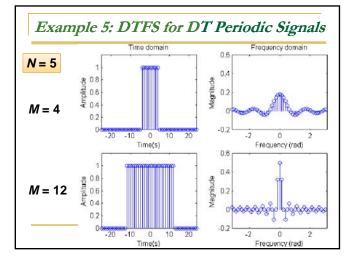


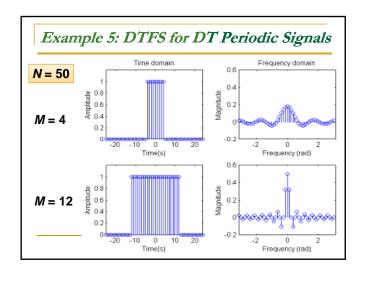


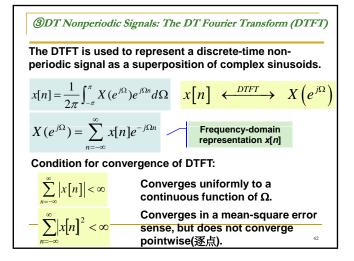


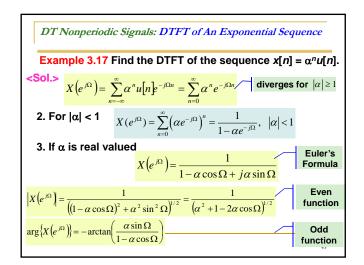


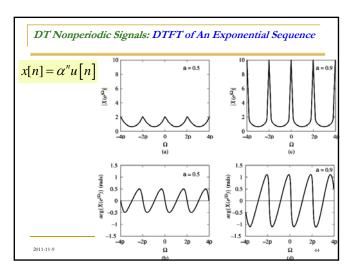


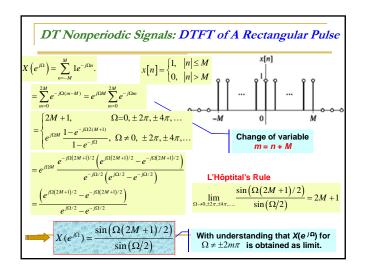


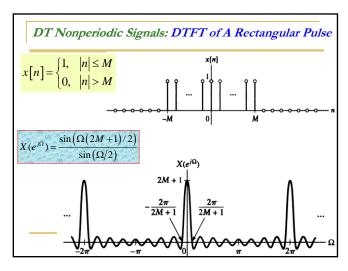


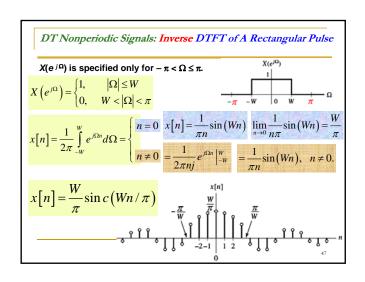


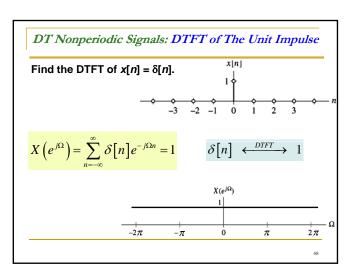




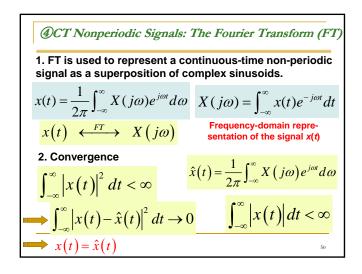




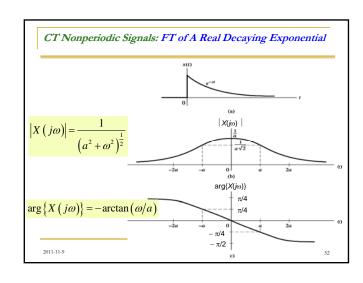


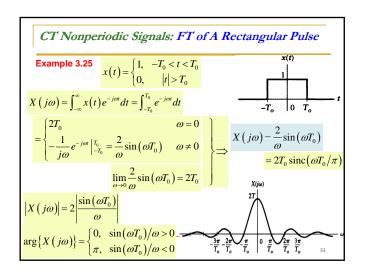


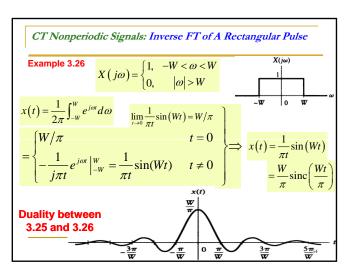
 $\begin{array}{c} \textit{DT Nonperiodic Signals: Inverse DTFT of A Unit Impulse} \\ \textit{Spectrum} \\ \hline \textbf{Find the inverse DTFT of } X(e^{j\Omega}) = \delta(\Omega), -\pi < \Omega \leq \pi. \\ x[n] = \frac{1}{2\pi} \int_{-\pi}^{\pi} \delta(\Omega) e^{j\Omega n} d\Omega. & = \frac{1}{2\pi} \int_{-\pi}^{\pi} \delta(\Omega) d\Omega = \frac{1}{2\pi} \\ \hline \frac{1}{2\pi} \longleftrightarrow \delta(\Omega) & \text{Sifting property of impulse function} \\ -\pi < \Omega \leq \pi. & x(e^{j\Omega}) & x(e^{j\Omega}$ 

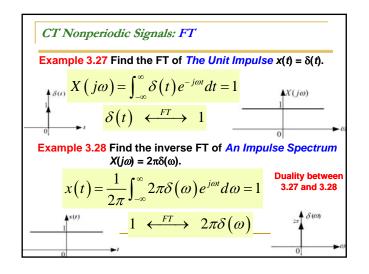


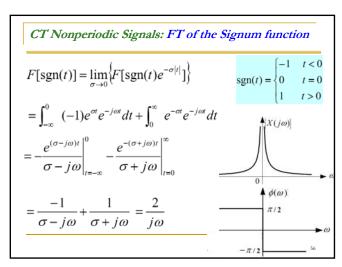
Find the FT of  $x(t) = e^{-at} u(t)$ 1. For  $a \le 0$ , since x(t) is not absolutely integrable,  $\int_0^\infty e^{-at} dt = \infty, \quad a \le 0 \quad \text{The FT of } x(t) \text{ does not converge}$ 2. For a > 0, the FT of x(t) is  $X(j\omega) = \int_{-\infty}^\infty e^{-at} u(t) e^{-j\omega t} dt = \int_0^\infty e^{-(a+j\omega)t} dt$   $= -\frac{1}{a+j\omega} e^{-(a+j\omega)t} \Big|_0^\infty = \frac{1}{a+j\omega}$   $|X(j\omega)| = \frac{1}{\left(a^2 + \omega^2\right)^{\frac{1}{2}}} \quad \arg\{X(j\omega)\} = -\arctan(\omega/a)$ 

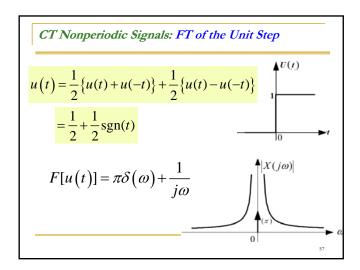


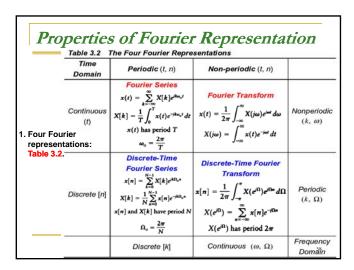












# Properties of Fourier Representation

2. Signals that are periodic in time have discrete frequency-domain representations, while nonperiodic time signals have continuous frequency- domain representations.

Table 3.3 Periodicity Properties of Fourier Representations

Time-Domain Property	Frequency-Domain Property
Continuous	Nonperiodic
Discrete	Periodic
Periodic	Discrete
Nonperiodic	Continuous

### Summary and Exercises

- Summary and Exercises
  - Complex Sinusoids and Frequency Response of LTI Systems
  - Fourier Representations for Four classes of Signals
  - Properties of Fourier Representations
- Exercises (P322-333)
  - 3.48(a, c), 3.49(a, c), 3.50(a, b), 3.51(a, b), 3.52(a, d), 3.53(a,c), 3.54(a, d), 3.55(a, b)

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