

Signals and Systems 3.3

--- Properties of Fourier Representation

*School of Information & Communication
Engineering, BUPT*

Reference:

1. Textbook: Chapter 3.8 - 3.18

Properties of Fourier Representation

- Periodicity Properties
- Linearity Properties
- Symmetry Properties
- Convolution Property
- Differentiation and Integration Properties
- Time-shift Properties
- Frequency-shift Properties
- Multiplication Properties
- Scaling Properties
- Duality Properties
- Inverse Fourier representation
- Parseval relationship
- Time bandwidth products

Periodicity properties

Table 3.2 The Four Fourier Representations

Time Domain	Periodic (t, n)	Non-periodic (t, n)	
Continuous (t)	Fourier Series $x(t) = \sum_{k=-\infty}^{\infty} X[k] e^{jk\omega_o t}$ $X[k] = \frac{1}{T} \int_0^T x(t) e^{-jk\omega_o t} dt$ $x(t) \text{ has period } T$ $\omega_o = \frac{2\pi}{T}$	Fourier Transform $x(t) = \frac{1}{2\pi} \int_{-\infty}^{\infty} X(j\omega) e^{j\omega t} d\omega$ $X(j\omega) = \int_{-\infty}^{\infty} x(t) e^{-j\omega t} dt$	Nonperiodic (k, ω)
Discrete [n]	Discrete-Time Fourier Series $x[n] = \sum_{k=0}^{N-1} X[k] e^{jk\Omega_o n}$ $X[k] = \frac{1}{N} \sum_{n=0}^{N-1} x[n] e^{-jk\Omega_o n}$ $x[n] \text{ and } X[k] \text{ have period } N$ $\Omega_o = \frac{2\pi}{N}$	Discrete-Time Fourier Transform $x[n] = \frac{1}{2\pi} \int_{-\pi}^{\pi} X(e^{j\Omega}) e^{j\Omega n} d\Omega$ $X(e^{j\Omega}) = \sum_{n=-\infty}^{\infty} x[n] e^{-j\Omega n}$ $X(e^{j\Omega}) \text{ has period } 2\pi$	Periodic (k, Ω)
	Discrete [k]	Continuous (ω, Ω)	Frequency Domain

1. Four Fourier representations:
Table 3.2.

Periodicity properties

2. Signals that are periodic in time have discrete frequency-domain representations, while nonperiodic time signals have continuous frequency- domain representations.

Table 3.3 Periodicity Properties of Fourier Representations

Time-Domain Property	Frequency-Domain Property
<i>Continuous</i>	<i>Nonperiodic</i>
<i>Discrete</i>	<i>Periodic</i>
<i>Periodic</i>	<i>Discrete</i>
<i>Nonperiodic</i>	<i>Continuous</i>

Linearity Properties

$$z(t) = ax(t) + by(t) \quad \xleftrightarrow{FT} \quad Z(j\omega) = aX(j\omega) + bY(j\omega)$$

$$z(t) = ax(t) + by(t) \quad \xleftrightarrow{FS; \omega_o} \quad Z[k] = aX[k] + bY[k]$$

$$z[n] = ax[n] + by[n] \quad \xleftrightarrow{DTFT} \quad Z(e^{j\Omega}) = aX(e^{j\Omega}) + bY(e^{j\Omega})$$

$$z[n] = ax[n] + by[n] \quad \xleftrightarrow{DTFS; \Omega_o} \quad Z[k] = aX[k] + bY[k]$$

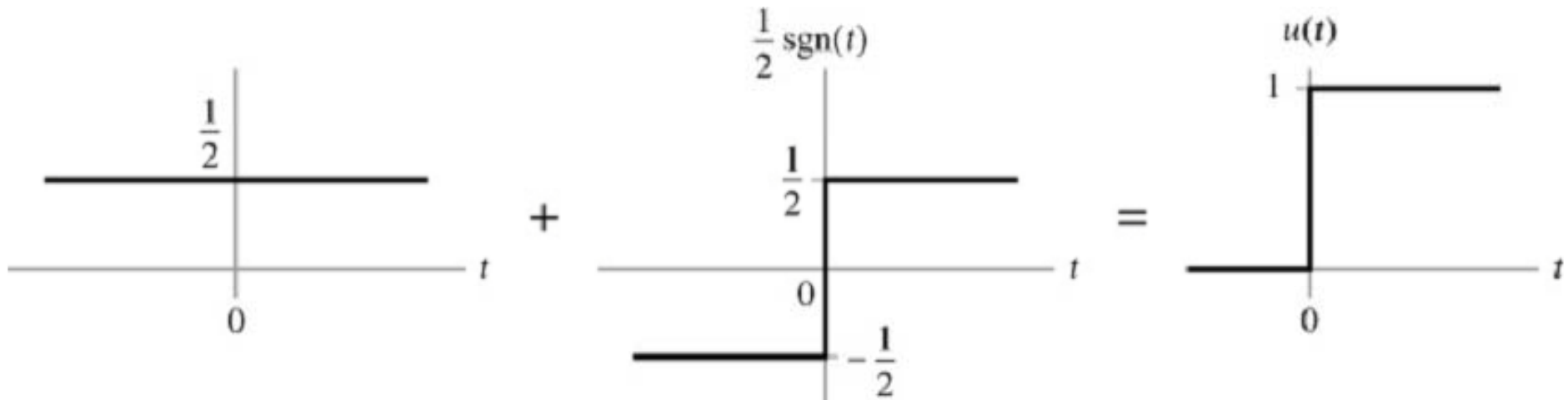
Both a and b are constant.

The linearity property is used to find Fourier representations of signals that are constructed as sums of signals whose representations are already known

Example 1 of Linearity in FT: : Representation of a Unit Step signal as a weighted sum of a constant and a signum signal

$$u(t) = \frac{1}{2} + \frac{1}{2} \operatorname{sgn}(t) \quad F[u(t)] = \pi \delta(\omega) + \frac{1}{j\omega}$$

$$F\left[\frac{1}{2}\right] = 2\pi \delta(\omega) \quad F[\operatorname{sgn}(t)] = \frac{2}{j\omega}$$



*Example 2 of Linearity in The FS: Representation of a periodic signal as a weighted **sum** of periodic square waves*

Example 3.30

$$z(t) = \frac{3}{2}x(t) + \frac{1}{2}y(t)$$

$$x(t) \xleftrightarrow{FS; \omega_0} X[k]$$

$$y(t) \xleftrightarrow{FS; \omega_0} Y[k]$$

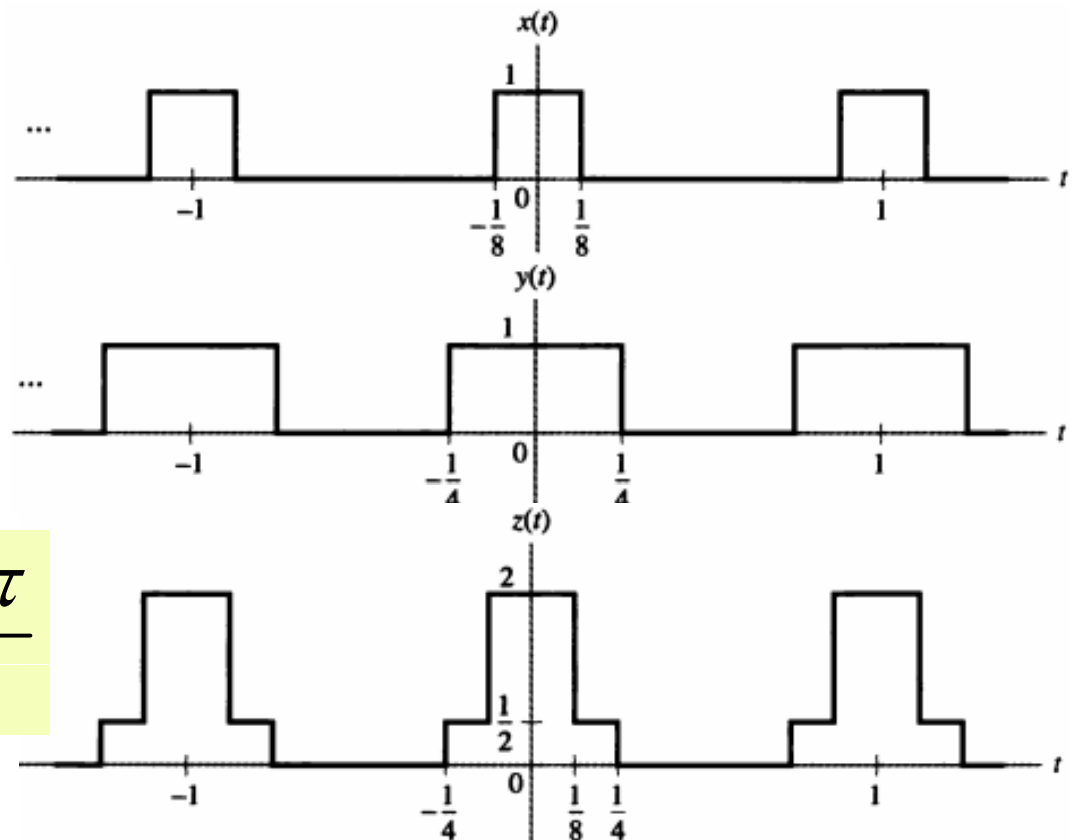
$$z(t) \xleftrightarrow{FS; \omega_0} Z[k]$$

$$X[k] = \frac{1}{k\pi} \sin \frac{k\pi}{4}$$

$$Y[k] = \frac{1}{k\pi} \sin \frac{k\pi}{2}$$

$$Z[k] = \frac{3}{2}X[k] + \frac{1}{2}Y[k]$$

$$= \frac{1}{2k\pi} \sin \frac{k\pi}{4} + \frac{3}{2k\pi} \sin \frac{k\pi}{2}$$



Symmetry Properties: Real and Imaginary Signals

$$x(t) \xleftrightarrow{FT} X(j\omega)$$

$$x^*(t) \xleftrightarrow{FT} X^*(-j\omega)$$

$$F[x^*(t)] = \int_{-\infty}^{\infty} x^*(t) e^{-j\omega t} dt = \left[\int_{-\infty}^{\infty} x(t) e^{-j(-\omega)t} dt \right]^* = X^*(-j\omega)$$

$$X(j\omega) = |X(j\omega)| e^{j\phi(j\omega)} = \text{Re}[X(j\omega)] + j \text{Im}[X(j\omega)]$$

For continuous real valued signal $x(t) = x^*(t)$

$$X(j\omega) = X^*(-j\omega)$$

$$X^*(j\omega) = X(-j\omega)$$

$$\text{Re}\{X(j\omega)\} = \text{Re}\{X(-j\omega)\}$$

Real of $X(j\omega)$ is even

$$\text{Im}\{X(j\omega)\} = -\text{Im}\{X(-j\omega)\}$$

Imagery of $X(j\omega)$ is odd

$$|X(j\omega)| = |X(-j\omega)|$$

Magnitude spectrum of $X(j\omega)$ is even

$$\phi(j\omega) \triangleq \arg\{X(j\omega)\} = -\phi(-j\omega)$$

Phase spectrum of $X(j\omega)$ is odd

Symmetry Properties: Real and Imaginary Signals

Table 3.4 *Symmetry Properties for Fourier Representation of Real- and Imaginary-Valued Signals*

Representation	Real-Valued Time Signals	Imaginary-Valued Time Signals
<i>FT</i>	$X^*(j\omega) = X(-j\omega)$	$X^*(j\omega) = -X(-j\omega)$
<i>FS</i>	$X^*[k] = X[-k]$	$X^*[k] = -X[-k]$
<i>DTFT</i>	$X^*(e^{j\Omega}) = X(e^{-j\Omega})$	$X^*(e^{j\Omega}) = -X(e^{-j\Omega})$
<i>DTFS</i>	$X^*[k] = X[-k]$	$X^*[k] = -X[-k]$

Example: Symmetry Properties

1. $x(t)$ is real valued and has even symmetry.

$$x^*(t) = x(t)$$

$$x(-t) = x(t)$$



$$x^*(t) = x(-t)$$

$$X^*(j\omega) = \int_{-\infty}^{\infty} x(-t) e^{-j\omega(-t)} dt$$

Change of variable $\tau = -t$



$$X^*(j\omega) = -\int_{-\infty}^{\infty} x(\tau) e^{-j\omega\tau} d\tau = X(j\omega)$$

$X^*(j\omega) = X(j\omega)$ 1) If $x(t)$ is real and even, then the imaginary part of $X(j\omega) = 0$, $X(j\omega)$ is real.

2) If $x(t)$ is real and odd, then $X^*(j\omega) = -X(j\omega)$ and $X(j\omega)$ is imaginary.

Convolution Properties: Nonperiodic CT Signals

■ Convolution of Nonperiodic Continuous-time Signals

$$x(t) \xleftrightarrow{FT} X(j\omega)$$

$$h(t) \xleftrightarrow{FT} H(j\omega)$$

$$y(t) = h(t) * x(t) = \int_{-\infty}^{\infty} h(\tau) x(t - \tau) d\tau$$

$$= \int_{-\infty}^{\infty} h(\tau) \left[\frac{1}{2\pi} \int_{-\infty}^{\infty} X(j\omega) e^{j\omega t} e^{-j\omega\tau} d\omega \right] d\tau$$

$$= \frac{1}{2\pi} \int_{-\infty}^{\infty} \left[\int_{-\infty}^{\infty} h(\tau) e^{-j\omega\tau} d\tau \right] X(j\omega) e^{j\omega t} d\omega$$

$$y(t) = \frac{1}{2\pi} \int_{-\infty}^{\infty} H(j\omega) X(j\omega) e^{j\omega t} d\omega$$

Convolution of $h(t)$ and $x(t)$ in the time domain corresponds to multiplication of their Fourier transforms, $H(j\omega)$ and $X(j\omega)$ in the frequency domain.

$$y(t) = h(t) * x(t) \xleftrightarrow{FT} Y(j\omega) = X(j\omega)H(j\omega)$$

Example1: Solving A Convolution Problem in The Frequency Domain

Example 3.31

$$x(t) = \frac{\sin(\pi t)}{\pi t} \longrightarrow h(t) = \frac{\sin(2\pi t)}{\pi t} \xrightarrow{\quad} y(t) = h(t) * x(t)$$

$$x(t) \xleftrightarrow{FT} X(j\omega) = \begin{cases} 1, & |\omega| < \pi \\ 0, & |\omega| > \pi \end{cases}$$

$$h(t) \xleftrightarrow{FT} H(j\omega) = \begin{cases} 1, & |\omega| < 2\pi \\ 0, & |\omega| > 2\pi \end{cases}$$

Time domain → Extremely Difficult
Frequency domain → Quite Simple

Convolution property

$$y(t) = h(t) * x(t) \xleftrightarrow{FT} Y(j\omega) = X(j\omega)H(j\omega)$$

$$Y(j\omega) = \begin{cases} 1, & |\omega| < \pi \\ 0, & |\omega| > \pi \end{cases} \longrightarrow y(t) = \frac{\sin(\pi t)}{\pi t}$$

Example2: Finding Inverse FT's by Means of The Convolution Property

Example 3.32 Use the convolution property to find $x(t)$

$$x(t) \xleftrightarrow{FT} X(j\omega) = \frac{4}{\omega^2} \sin^2(\omega)$$

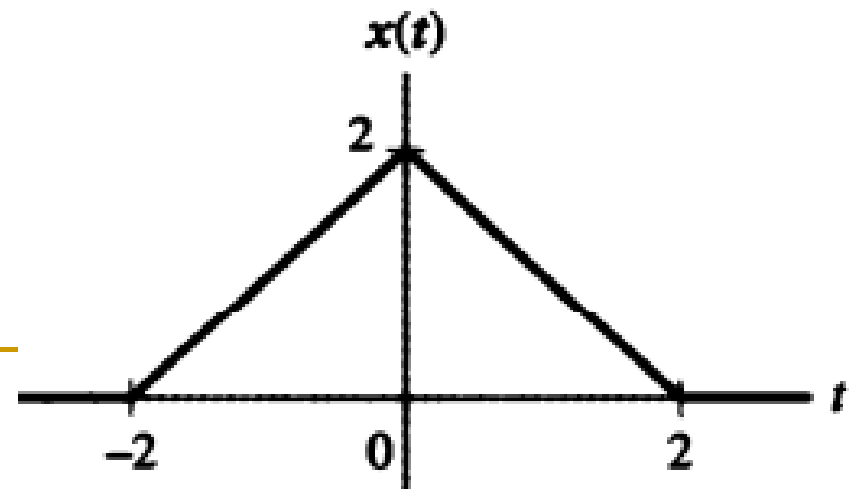
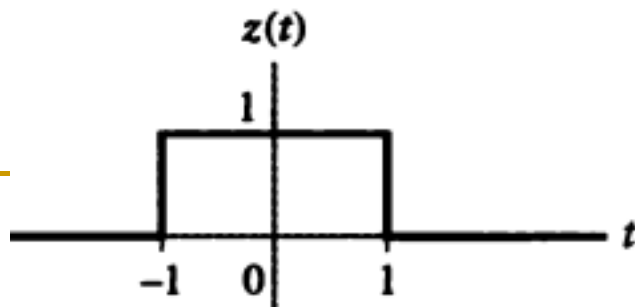
$$X(j\omega) = Z(j\omega) Z(j\omega)$$

$$z(t) = \begin{cases} 1, & |t| < 1 \\ 0, & |t| > 1 \end{cases} \xleftrightarrow{FT} Z(j\omega)$$

$$Z(j\omega) = \frac{2}{\omega} \sin(\omega)$$

$$z(t) * z(t) \xleftrightarrow{FT} Z(j\omega) Z(j\omega)$$

$$\Rightarrow x(t) = z(t) * z(t)$$



Convolution Properties: Nonperiodic DT Signals

♣ *Convolution of Nonperiodic Discrete-time Signals*

$$x[n] \xleftrightarrow{DTFT} X(e^{j\Omega})$$

$$h[n] \xleftrightarrow{DTFT} H(e^{j\Omega})$$

$$y[n] = x[n] * h[n] \xleftrightarrow{DTFT} Y(e^{j\Omega}) = X(e^{j\Omega})H(e^{j\Omega})$$

Convolution of $h[n]$ and $x[n]$ in the time domain corresponds to multiplication of their Fourier transforms, $H(e^{j\Omega})$ and $X(e^{j\Omega})$ in the frequency domain.

Frequency response of the LTI system

- The convolution property implies that the frequency response of a system may be expressed as the ratio of the FT or DTFT of the output to the input .

For CT system:

$$H(j\omega) = \frac{Y(j\omega)}{X(j\omega)}$$

For DT system:

$$H(e^{j\Omega}) = \frac{Y(e^{j\Omega})}{X(e^{j\Omega})}$$

Problem1: Find the system output (5~10min)

► **Problem 3.18** Use the convolution property to find the FT of the system output, either $Y(j\omega)$ or $Y(e^{j\Omega})$, for the following inputs and system impulse responses:

(a) $x(t) = 3e^{-t}u(t)$ and $h(t) = 2e^{-2t}u(t)$.

(b) $x[n] = \left(\frac{1}{3}\right)^{n+1} u[n]$ and $h[n] = \left(\frac{1}{6}\right)^n u[n]$

Sol (a):

$$x(t) = 3e^{-t}u(t) \Leftrightarrow X(j\omega) = \frac{3}{1+j\omega}$$

$$h(t) = 2e^{-2t}u(t) \Leftrightarrow H(j\omega) = \frac{2}{2+j\omega}$$

$$Y(j\omega) = X(j\omega)H(j\omega) = \frac{2}{(2+j\omega)} \frac{3}{(1+j\omega)}$$

Sol (b):

$$x[n] = \left(\frac{1}{3}\right)^{n+1} u[n] \Leftrightarrow X(e^{j\Omega}) = \frac{1}{3\left(1 - \frac{1}{3}e^{-j\Omega}\right)}$$

$$= \frac{1}{3} \left(\frac{1}{3}\right)^n u[n]$$

$$h[n] = \left(\frac{1}{6}\right)^n u[n] \Leftrightarrow H(e^{j\Omega}) = \frac{1}{1 - \frac{1}{6}e^{-j\Omega}}$$

$$Y(e^{j\Omega}) = X(e^{j\Omega})H(e^{j\Omega}) = \frac{1}{3\left(1 - \frac{1}{3}e^{-j\Omega}\right)} \frac{1}{\left(1 - \frac{1}{6}e^{-j\Omega}\right)}$$

Problem1: Find the system output (5~10min)

$$Y(j\omega) = \frac{2}{(2+j\omega)} \frac{3}{(1+j\omega)} = \frac{1}{6(1+j\omega)} - \frac{1}{6(2+j\omega)}$$

$$y(t) = \frac{1}{6} e^{-t} u(t) - \frac{1}{6} e^{-2t} u(t)$$

$$Y(e^{j\Omega}) = \frac{1}{3\left(1 - \frac{1}{3}e^{-j\Omega}\right)} \frac{1}{\left(1 - \frac{1}{6}e^{-j\Omega}\right)}$$

$$= \frac{2}{3\left(1 - \frac{1}{3}e^{-j\Omega}\right)} - \frac{1}{3\left(1 - \frac{1}{6}e^{-j\Omega}\right)}$$

$$e^{-\alpha t} u(t) \xleftrightarrow{FT} \frac{1}{\alpha + j\omega} \quad \alpha > 0$$

$$\alpha^n u[n] \xleftrightarrow{DTFT} \frac{1}{1 - \alpha e^{-j\Omega}} \quad |\alpha| < 1$$

$$y[n] = \frac{2}{3} \left(\frac{1}{3}\right)^n u[n] - \frac{1}{3} \left(\frac{1}{6}\right)^n u[n]$$

Problem2: Find the response of the system (5~10min)

The output of an LTI system in response to an input $x(t) = e^{-2t} u(t)$ is $y(t) = e^{-t} u(t)$. Find the frequency response and the impulse response of this system.

$$x(t) = e^{-2t} u(t) \Leftrightarrow X(j\omega) = \frac{1}{2 + j\omega}$$

$$y(t) = e^{-t} u(t) \Leftrightarrow Y(j\omega) = \frac{1}{1 + j\omega}$$

$$H(j\omega) = Y(j\omega) / X(j\omega)$$

$$= \frac{2 + j\omega}{1 + j\omega} = 1 + \frac{1}{1 + j\omega}$$

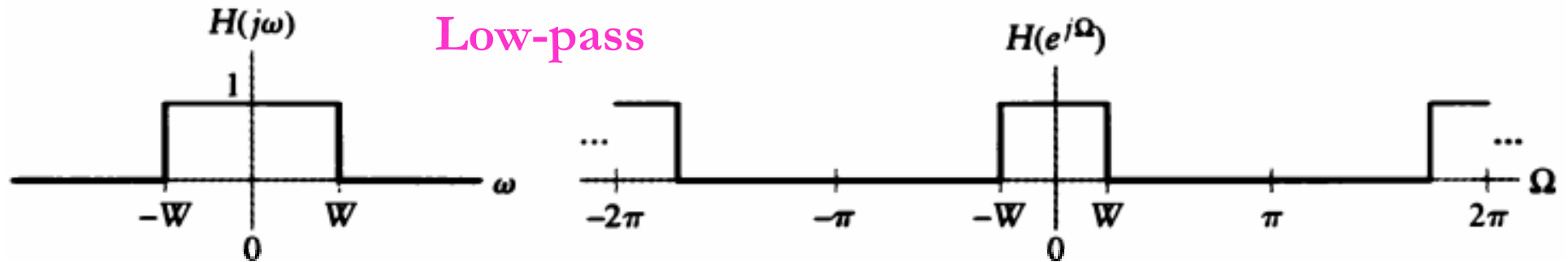
$$\Leftrightarrow h(t) = \delta(t) + e^{-t} u(t)$$

Filtering

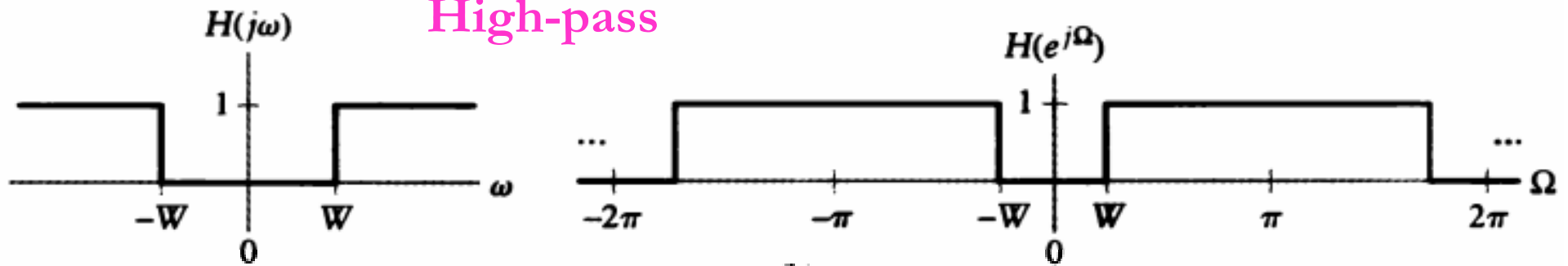
1. The terms “**filtering**” implies that some frequency components of the input are eliminated while others are passed by the system unchanged.
2. Multiplication in frequency domain \leftrightarrow **Filtering**.
3. System Types of filtering:
 - 1) Low-pass filter
 - 2) High-pass filter
 - 3) Band-pass filter
4. Realistic filter:
 - 1) Gradual transition band
 - 2) Nonzero gain of stop band

Filtering

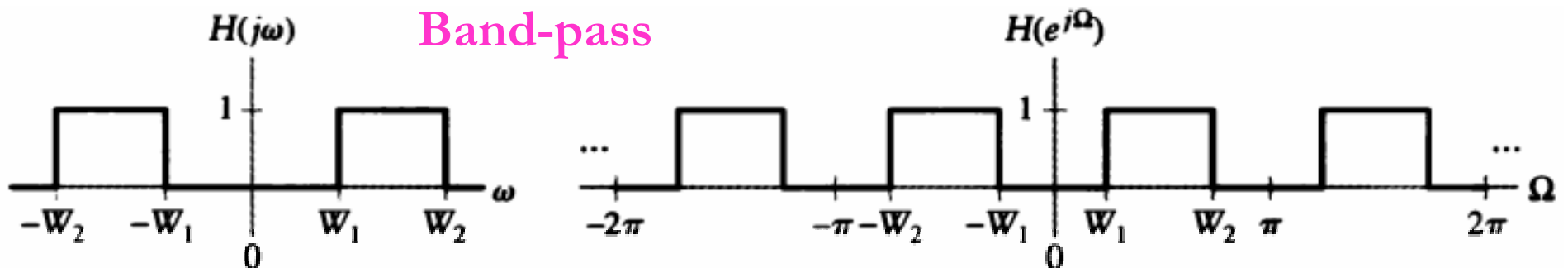
Low-pass



High-pass



Band-pass



Filtering

5. Magnitude response of filter:

$$20\log|H(j\omega)|$$

$$20\log|H(e^{j\Omega})| \quad [\text{dB}]$$

6. The edge of the passband is usually defined by the frequencies for which the response is – 3 dB, corresponding to a magnitude response of $(1/\sqrt{2})$.

♣ **Unity gain = 0 dB**

7. Energy spectrum of filter: $|Y(j\omega)|^2 = |H(j\omega)|^2 |X(j\omega)|^2$

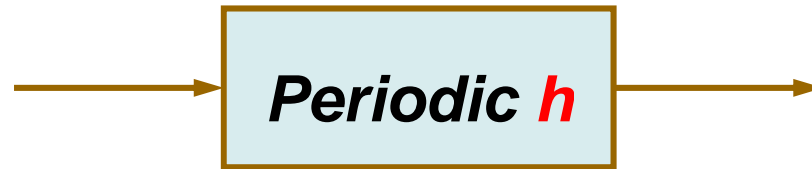


The – 3 dB point corresponds to frequencies at which the filter passes only half of the input power.

– 3 dB point  Cutoff frequency

Convolution of Periodic Signals

♣ Basic Concept:



1. Define the periodic convolution of two CT signals $x(t)$ and $z(t)$, each having period T , as

$$y(t) = x(t) \circledast z(t) = \int_0^T x(\tau) z(t - \tau) d\tau$$

where the symbol \circledast denotes that integration is performed over a single period of the signals involved.

$$y(t) = x(t) \circledast z(t) \quad \xleftrightarrow{FS; \frac{2\pi}{T}} \quad Y[k] = TX[k]Z[k]$$

◆ Convolution in Time-Domain

↔ Multiplication in Frequency-Domain

Convolution in Time-Domain \leftrightarrow Multiplication in Frequency-Domain

Table 3.5 Convolution Properties

$$x(t) * z(t) \xleftrightarrow{FT} X(j\omega)Z(j\omega)$$

$$x(t) \circledast z(t) \xleftrightarrow{FS; \omega_0} TX[k]Z[k]$$

$$x[n] * z[n] \xleftrightarrow{FT} X(e^{j\Omega})Z(e^{j\Omega})$$

$$x[n] \circledast z[n] \xleftrightarrow{DTFS; \Omega_0} NX[k]Z[k]$$

Differentiation Properties: Time Domain

Differentiation in Time Domain

$$x(t) \xleftrightarrow{FT} X(j\omega)$$

$$\frac{d}{dt} x(t) \xleftrightarrow{FT} j\omega X(j\omega)$$

$$x(t) = \frac{1}{2\pi} \int_{-\infty}^{\infty} X(j\omega) e^{j\omega t} d\omega$$

$$\frac{d}{dt} x(t) = \frac{1}{2\pi} \int_{-\infty}^{\infty} X(j\omega) j\omega e^{j\omega t} d\omega$$

$$\frac{d^n}{dt^n} x(t) = \frac{1}{2\pi} \int_{-\infty}^{\infty} X(j\omega) (j\omega)^n e^{j\omega t} d\omega$$

$$\frac{d^n}{dt^n} x(t) \xleftrightarrow{FT} (j\omega)^n X(j\omega)$$

Differentiation of $x(t)$ in Time-Domain $\leftrightarrow (j\omega) \times X(j\omega)$ in Frequency-Domain

$$e^{-\alpha t} u(t) \xleftrightarrow{FT} \frac{1}{\alpha + j\omega}$$

$$\frac{d}{dt} \{e^{-\alpha t} u(t)\} \xleftrightarrow{FT} \frac{j\omega}{\alpha + j\omega}$$

Differentiation Properties: Frequency Domain

Differentiation in Frequency Domain

$$x(t) \xleftrightarrow{FT} X(j\omega)$$

$$-jtx(t) \xleftrightarrow{FT} \frac{d}{d\omega} X(j\omega)$$

$$X(j\omega) = \int_{-\infty}^{\infty} x(t) e^{-j\omega t} dt$$

$$\frac{d}{d\omega} X(j\omega) = \int_{-\infty}^{\infty} -jtx(t) e^{-j\omega t} dt$$

Differentiation of $X(j\omega)$ in Frequency-Domain $\leftrightarrow (-jt) \times x(t)$ in Time-Domain

Example

$$\frac{d}{dt} x(t) \xleftrightarrow{FT} j\omega X(j\omega)$$

$$\frac{d}{dt} \{e^{-\alpha t} u(t)\} \xleftrightarrow{FT} \frac{j\omega}{\alpha + j\omega}$$

$$-jtx(t) \xleftrightarrow{FT} \frac{d}{d\omega} X(j\omega)$$

$$te^{-\alpha t} u(t) \xleftrightarrow{FT} j \frac{d}{d\omega} \left\{ \frac{1}{\alpha + j\omega} \right\} = \frac{1}{(\alpha + j\omega)^2}$$

$$e^{-\alpha t} u(t) \xleftrightarrow{FT} \frac{1}{\alpha + j\omega}$$

$$\begin{aligned} & \frac{d}{dt} \{e^{-\alpha t} u(t)\} \\ &= -\alpha e^{-\alpha t} u(t) + e^{-\alpha t} \delta(t) \\ &= -\alpha e^{-\alpha t} u(t) + \delta(t) \end{aligned}$$

Integration Properties

$$y(t) = \int_{-\infty}^t x(t) dt$$

$$\frac{d}{dt} y(t) = x(t)$$

$$x(t) \xleftrightarrow{FT} X(j\omega)$$

$$y(t) \xleftrightarrow{FT} Y(j\omega)$$

$$\Leftrightarrow j\omega Y(j\omega) = X(j\omega)$$

$$Y(j\omega) = \frac{X(j\omega)}{j\omega} \quad \omega \neq 0$$

c can be determined
by the average value
of $x(t)$

$$\int_{-\infty}^t x(t) dt \xleftrightarrow{FT} \frac{X(j\omega)}{j\omega} + \pi X(j0) \delta(\omega)$$

$$X(j0) = \int_{-\infty}^{\infty} x(t) e^{-j0t} dt = \int_{-\infty}^{\infty} x(t) dt = 0$$

$$u(t) = \int_{-\infty}^t \delta(t) dt \xleftrightarrow{FT} \frac{1}{j\omega} + \pi \delta(\omega)$$

Differentiation and Integration Properties

Table 3.6 summarizes the differentiation and integration properties of Fourier representations.

$$\begin{aligned}\frac{d}{dt}x(t) &\xleftrightarrow{FT} j\omega X(j\omega) & x(t) &\xleftrightarrow{FT} X(j\omega) \\ \frac{d}{dt}x(t) &\xleftrightarrow{FS; \omega_0} jk\omega_0 X[k] \\ -jtx(t) &\xleftrightarrow{FT} \frac{d}{d\omega} X(j\omega) \\ -jnx[n] &\xleftrightarrow{DTFT} \frac{d}{d\Omega} X(e^{j\Omega}) \\ \int_{-\infty}^t x(\tau)d\tau &\xleftrightarrow{FT} \frac{1}{j\omega} X(j\omega) + \pi X(j0)\delta(\omega)\end{aligned}$$

Time-Shift Properties

if $x(t) \xleftrightarrow{FT} X(j\omega)$

then $x(t - t_0) \xleftrightarrow{FT} X(j\omega) \cdot e^{-j\omega t_0}$

$$\begin{aligned} F[x(t - t_0)] &= \int_{-\infty}^{\infty} x(t - t_0) e^{-j\omega t} dt = e^{-j\omega t_0} \int_{-\infty}^{\infty} x(t - t_0) e^{-j\omega(t - t_0)} dt \\ &= X(j\omega) \cdot e^{-j\omega t_0} = |X(j\omega)| \cdot e^{j[\arg\{X(j\omega)\} - \omega t_0]} \end{aligned}$$

A shift in time leaves the magnitude spectrum unchanged and introduces a phase shift that is a linear function of frequency.

Time-Shift Properties

- ◆ The time-shifting properties of four Fourier representation are summarized in Table 3.7.

$$x(t - t_0) \xleftrightarrow{FT} e^{-j\omega t_0} X(j\omega)$$

$$x(t - t_0) \xleftrightarrow{FT; \omega_0} e^{-jk\omega_0 t_0} X(k)$$

$$x[n - n_0] \xleftrightarrow{DTFT} e^{-j\Omega n_0} X(e^{j\Omega})$$

$$x[n - n_0] \xleftrightarrow{DTFS; \Omega_0} e^{-jk\Omega_0 n_0} X[k]$$

Frequency-Shift Properties

$$z(t) = \frac{1}{2\pi} \int_{-\infty}^{\infty} Z(j\omega) e^{j\omega t} d\omega$$

$$= \frac{1}{2\pi} \int_{-\infty}^{\infty} X(j(\omega - \gamma)) e^{j\omega t} d\omega$$

$$z(t) = \frac{1}{2\pi} \int_{-\infty}^{\infty} X(j\eta) e^{j(\eta + \gamma)t} d\eta$$

$$= e^{j\gamma t} \frac{1}{2\pi} \int_{-\infty}^{\infty} X(j\eta) e^{j\eta t} d\eta = e^{j\gamma t} x(t)$$

$$x(t) \xleftrightarrow{FT} X(j\omega)$$

$$z(t) \xleftrightarrow{FT} Z(j\omega)$$

$$Z(j\omega) = X(j(\omega - \gamma))$$

$$\eta = \omega - \gamma$$

$$e^{j\gamma t} x(t) \xleftrightarrow{FT} X(j(\omega - \gamma))$$

◆ Frequency-shifting of $X(j\omega)$ by γ in Frequency-Domain [i.e. $X(j(\omega - \gamma))$] \leftrightarrow ($e^{-j\gamma t}$) \times $x(t)$ in Time-Domain

Frequency-Shift Properties

Table 3.8 Frequency-Shift Properties of Fourier Representations

$$e^{j\gamma t} x(t) \quad \xleftrightarrow{FT} \quad X(j(\omega - \gamma))$$

$$e^{jk_0\omega_0 t} x(t) \quad \xleftrightarrow{FS; \omega_0} \quad x[k - k_0]$$

$$e^{j\Gamma n} x[n] \quad \xleftrightarrow{DTFT} \quad X[e^{j(\Omega - \Gamma)}]$$

$$e^{jk_0\Omega_0 n} x[n] \quad \xleftrightarrow{FS; \Omega_0} \quad X[k - k_0]$$

Example

$$1 \xleftrightarrow{FT} 2\pi\delta(\omega)$$

$$e^{j\gamma t} x(t) \xleftrightarrow{FT} X(j(\omega - \gamma))$$

$$e^{j\omega_0 t} \xleftrightarrow{FT} 2\pi\delta(\omega - \omega_0)$$

$$\cos(\omega_0 t) = \frac{1}{2} (e^{j\omega_0 t} + e^{-j\omega_0 t}) \xleftrightarrow{FT} \pi [\delta(\omega + \omega_0) + \delta(\omega - \omega_0)]$$

$$\sin(\omega_0 t) = \frac{1}{2j} (e^{j\omega_0 t} - e^{-j\omega_0 t}) \xleftrightarrow{FT} -j\pi [\delta(\omega + \omega_0) - \delta(\omega - \omega_0)]$$

Finding Inverse Fourier Transforms by Using Partial-Fraction Expansions

Frequency response



A ratio of two
polynomials in $j\omega$ or $e^{j\Omega}$

$$X(j\omega) = \frac{b_M (j\omega)^M + \cdots + b_1 (j\omega) + b_0}{(j\omega)^N + a_{N-1} (j\omega)^{N-1} + \cdots + a_1 (j\omega) + a_0} = \frac{B(j\omega)}{A(j\omega)}$$

$$= \underbrace{c_0 + c_1 (j\omega) + c_2 (j\omega)^2 + \cdots + c_{M-N} (j\omega)^{M-N}}_{\text{Polynomial part}} + \frac{B(j\omega)}{A(j\omega)}$$

$$\delta(t) \xleftrightarrow{FT} 1$$

$$x(t) = c_0 \delta(t) + c_1 \delta'(t) + c_2 \delta''(t) + \cdots + c_{M-N} \delta^{(M-N)}(t) + F^{-1} \left[\frac{B(j\omega)}{A(j\omega)} \right]$$

$$v^N + a_{N-1} v^{N-1} + \cdots + a_1 v + a_0 = 0$$

Finding Inverse Fourier Transforms by Using Partial-Fraction Expansions

$$v^N + a_{N-1}v^{N-1} + \cdots + a_1v + a_0 = 0$$

$$d_k < 0$$

$$X(j\omega) = \frac{\sum_{k=0}^M b_k (j\omega)^k}{\prod_{k=1}^N (j\omega - d_k)}$$

$$= \sum_{k=1}^N \frac{C_k}{j\omega - d_k}$$

$$e^{d_k t} u(t) \xleftrightarrow{FT} \frac{1}{j\omega - d_k}$$

$$= \frac{C_1}{j\omega - d_1} + \frac{C_2}{j\omega - d_2} + \cdots + \frac{C_N}{j\omega - d_N}$$

$$x(t) = \sum_{k=1}^N C_k e^{d_k t} u(t) \xleftrightarrow{FT} X(j\omega) = \sum_{k=1}^N \frac{C_k}{j\omega - d_k}$$

Example

$$X(j\omega) = \frac{j\omega + 1}{(j\omega)^2 + 5j\omega + 6}$$

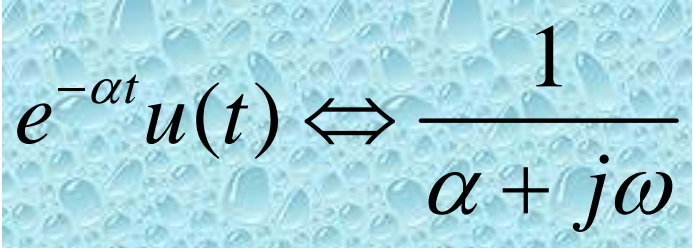
$$= \frac{A}{2 + j\omega} + \frac{B}{3 + j\omega}$$

$$= \frac{-1}{2 + j\omega} + \frac{2}{3 + j\omega}$$

$$= \frac{A(3 + j\omega) + B(2 + j\omega)}{(2 + j\omega)(3 + j\omega)}$$

$$= \frac{3A + 2B + j\omega(A + B)}{(2 + j\omega)(3 + j\omega)}$$

$$\begin{cases} 3A + 2B = 1 \\ A + B = 1 \end{cases} \Rightarrow \begin{cases} A = -1 \\ B = 2 \end{cases}$$


$$e^{-\alpha t} u(t) \Leftrightarrow \frac{1}{\alpha + j\omega}$$

$$x(t) = -e^{-2t} u(t) + 2e^{-3t} u(t) \Leftrightarrow X(j\omega)$$

Inverse Discrete-Time Fourier Transform

1. Suppose $X(e^{j\Omega})$ is given by a ratio of polynomial in $e^{j\Omega}$

$$X(e^{j\Omega}) = \frac{\beta_M e^{-j\Omega M} + \dots + \beta_1 e^{-j\Omega} + \beta_0}{\alpha_N e^{-j\Omega N} + \alpha_{N-1} e^{-j\Omega(N-1)} + \dots + \alpha_1 e^{-j\Omega} + 1}$$

Normalized to 1

2. Factor the denominator polynomial as

$$\alpha_N e^{-j\Omega N} + \alpha_{N-1} e^{-j\Omega(N-1)} + \dots + \alpha_1 e^{-j\Omega} + 1 = \prod_{k=1}^N (1 - d_k e^{-j\Omega})$$
$$v^N + \alpha_1 v^{N-1} + \alpha_2 v^{N-2} + \dots + \alpha_{N-1} v + \alpha_N = 0$$

3. Partial-fraction expansion: Assuming that $M < N$ and all the d_k are distinct, we may express $X(e^{j\Omega})$ as

$$(d_k)^n u[n] \xleftrightarrow{DTFT} \frac{1}{1 - d_k e^{-j\Omega}}, \quad |d_k| < 1$$

$$X(e^{j\Omega}) = \sum_{k=1}^N \frac{C_k}{1 - d_k e^{-j\Omega}}$$

$$x[n] = \sum_{k=1}^N C_k (d_k)^n u[n]$$

Example 3.45 *Inverse by Partial-Fraction Expansion*

Find the inverse DTFT of

1. Characteristic polynomial:

$$v^2 + \frac{1}{6}v - \frac{1}{6} = (v + \frac{1}{2})(v - \frac{1}{3}) = 0$$

2. The roots of above polynomial:

$$d_1 = -1/2 \text{ and } d_2 = 1/3.$$

3. Partial-Fraction Expansion

4. Coefficients C_1 and C_2



$$x[n] = 4(-1/2)^n u[n] + (1/3)^n u[n]$$

$$\begin{aligned} X(e^{j\Omega}) &= \frac{-\frac{5}{6}e^{-j\Omega} + 5}{1 + \frac{1}{6}e^{-j\Omega} - \frac{1}{6}e^{-j2\Omega}} \\ &= \frac{C_1}{1 + \frac{1}{2}e^{-j\Omega}} + \frac{C_2}{1 - \frac{1}{3}e^{-j\Omega}} \end{aligned}$$

$$C_1 = \left(1 + \frac{1}{2}e^{-j\Omega}\right) \frac{-\frac{5}{6}e^{-j\Omega} + 5}{1 + \frac{1}{6}e^{-j\Omega} - \frac{1}{6}e^{-j2\Omega}} \bigg|_{e^{-j\Omega}=-2} = \frac{-\frac{5}{6}e^{-j\Omega} + 5}{1 - \frac{1}{3}e^{-j\Omega}} \bigg|_{e^{-j\Omega}=-2} = 4$$

$$-C_2 = \left(1 - \frac{1}{3}e^{-j\Omega}\right) \frac{-\frac{5}{6}e^{-j\Omega} + 5}{1 + \frac{1}{6}e^{-j\Omega} - \frac{1}{6}e^{-j2\Omega}} \bigg|_{e^{-j\Omega}=3} = \frac{-\frac{5}{6}e^{-j\Omega} + 5}{1 + \frac{1}{2}e^{-j\Omega}} \bigg|_{e^{-j\Omega}=3} = 1$$

Multiplication Property: Non-periodic continuous-time signals

Non-periodic signals: $x(t)$, $z(t)$, and $y(t) = x(t)z(t)$.

$$x(t) = \frac{1}{2\pi} \int_{-\infty}^{\infty} X(j\nu) e^{j\nu t} d\nu \quad z(t) = \frac{1}{2\pi} \int_{-\infty}^{\infty} Z(j\eta) e^{j\eta t} d\eta$$

$$\Rightarrow y(t) = \frac{1}{(2\pi)^2} \int_{-\infty}^{\infty} \int_{-\infty}^{\infty} X(j\nu) Z(j\eta) e^{j(\eta+\nu)t} d\eta d\nu$$

Change variable: $\eta = \omega - \nu$

Inner Part: $Z(j\omega) * X(j\omega)$

$$y(t) = \frac{1}{2\pi} \int_{-\infty}^{\infty} \left[\frac{1}{2\pi} \int_{-\infty}^{\infty} X(j\nu) Z(j(\omega - \nu)) d\nu \right] e^{j\omega t} d\omega$$

Outer Part: FT of $y(t)$

$$y(t) = x(t)z(t) \xleftrightarrow{FT} Y(j\omega) = \frac{1}{2\pi} X(j\omega) * Z(j\omega)$$

◆ Multiplication of two signals in Time-Domain
 \leftrightarrow Convolution in Frequency-Domain $\times (1/2\pi)$

Multiplication Property : **Non-periodic discrete-time signals**

1. Non-periodic DT signals: $x[n]$, $z[n]$, and $y[n] = x[n]z[n]$.
2. DTFT of $y[n]$:

$$y[n] = x[n]z[n] \quad \xleftrightarrow{DTFT} \quad Y(e^{j\Omega}) = \frac{1}{2\pi} X(e^{j\Omega}) \circledast Z(e^{j\Omega})$$

where the symbol \circledast denotes periodic convolution.

Here, $X(e^{j\Omega})$ and $Z(e^{j\Omega})$ are 2π -periodic, so we evaluate the convolution over a 2π interval:

$$X(j\omega) \circledast Z(j\omega) = \int_{-\pi}^{\pi} X(e^{j\theta}) Z(e^{j(\Omega-\theta)}) d\theta$$

◆ **Multiplication of two signals in Time-Domain**
 \leftrightarrow Convolution in Frequency-Domain $\times (1/2\pi)$

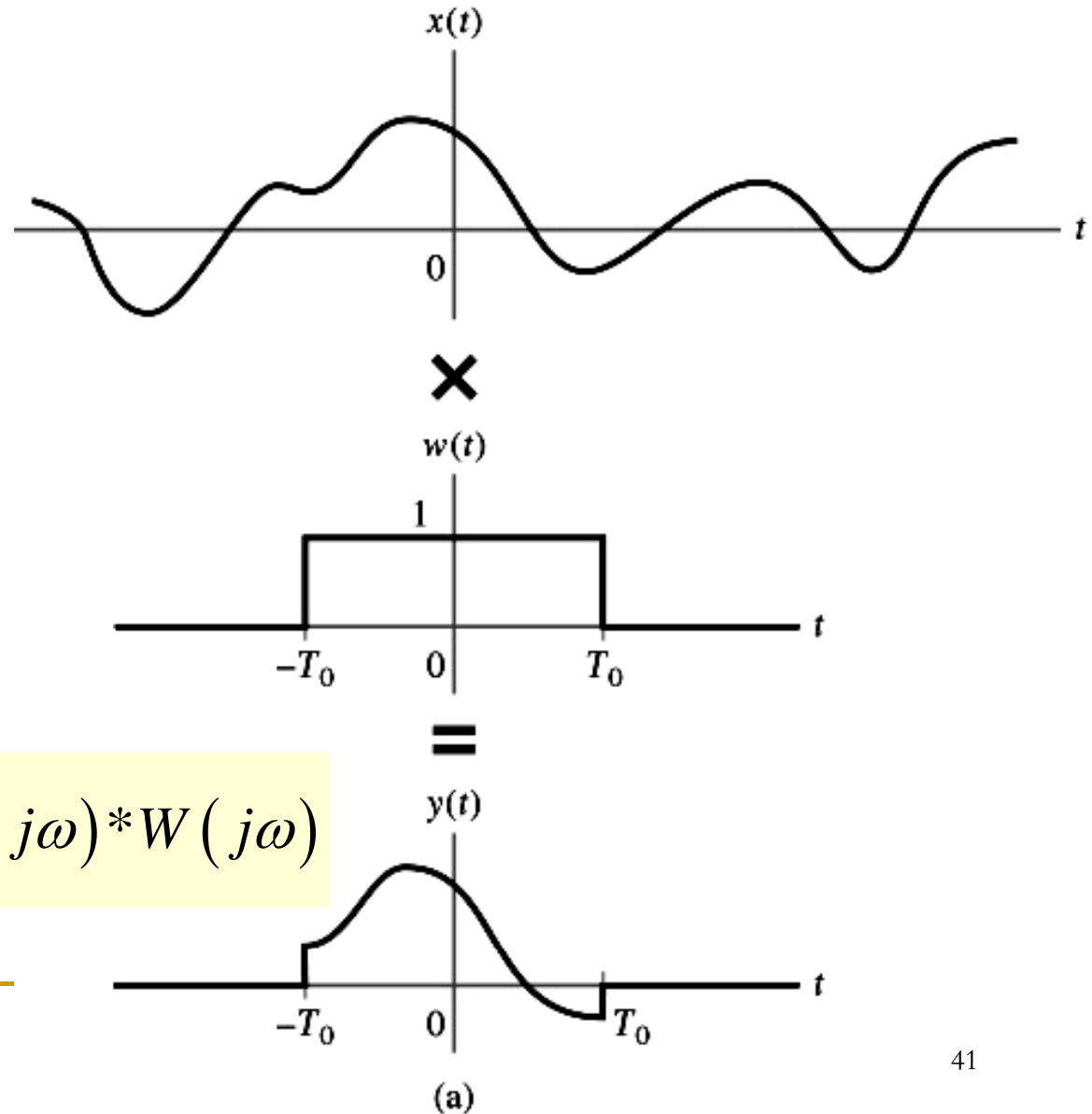
*Multiplication Property : **windowing***

Truncate signal
 $x(t)$ by a window
function $w(t)$ is
represented by

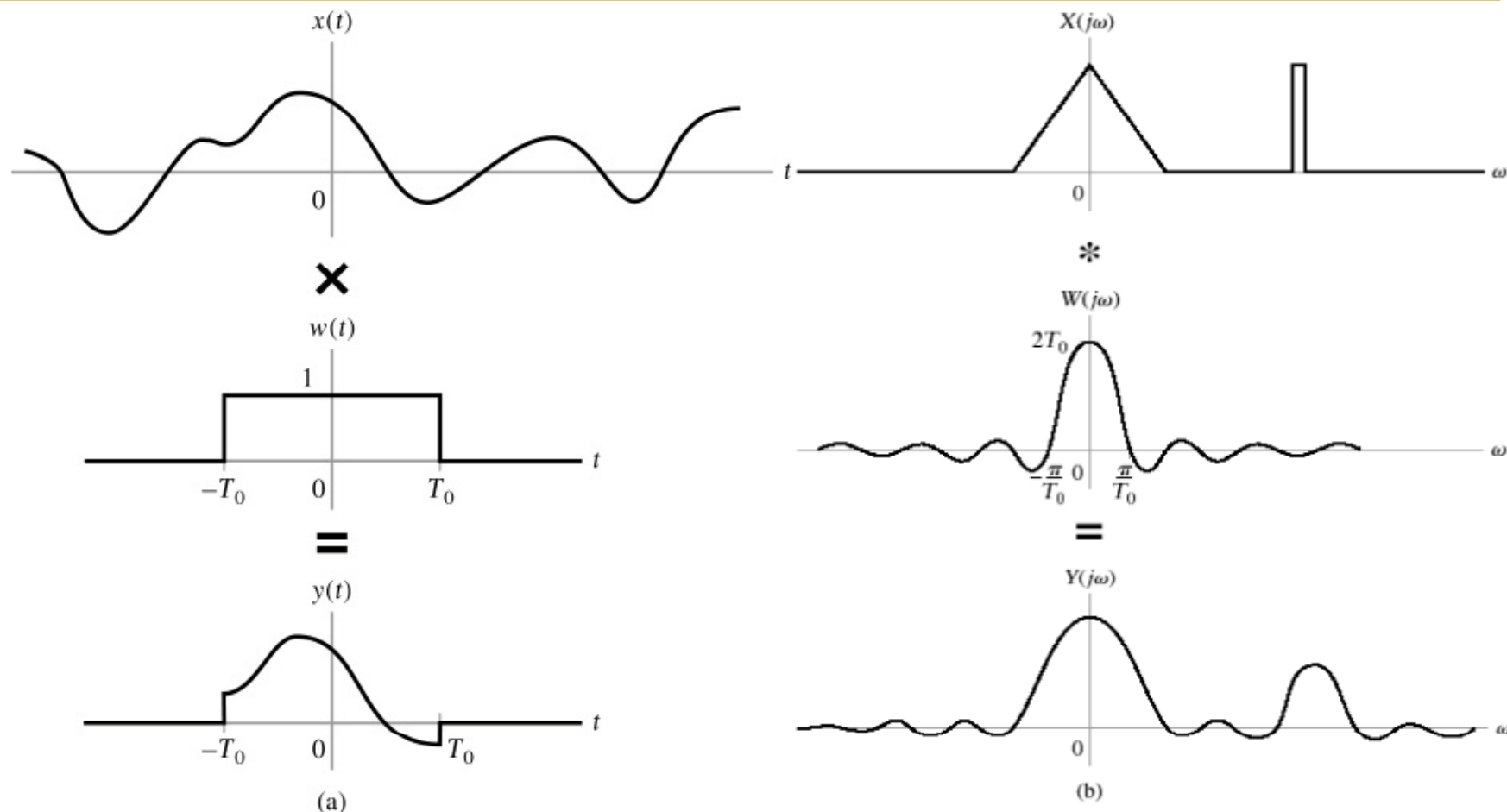
$$y(t) = x(t)w(t)$$

$$W(j\omega) = \frac{2}{\omega} \sin(\omega T_0)$$

$$y(t) \xleftrightarrow{FT} Y(j\omega) = \frac{1}{2\pi} X(j\omega) * W(j\omega)$$



Multiplication Property

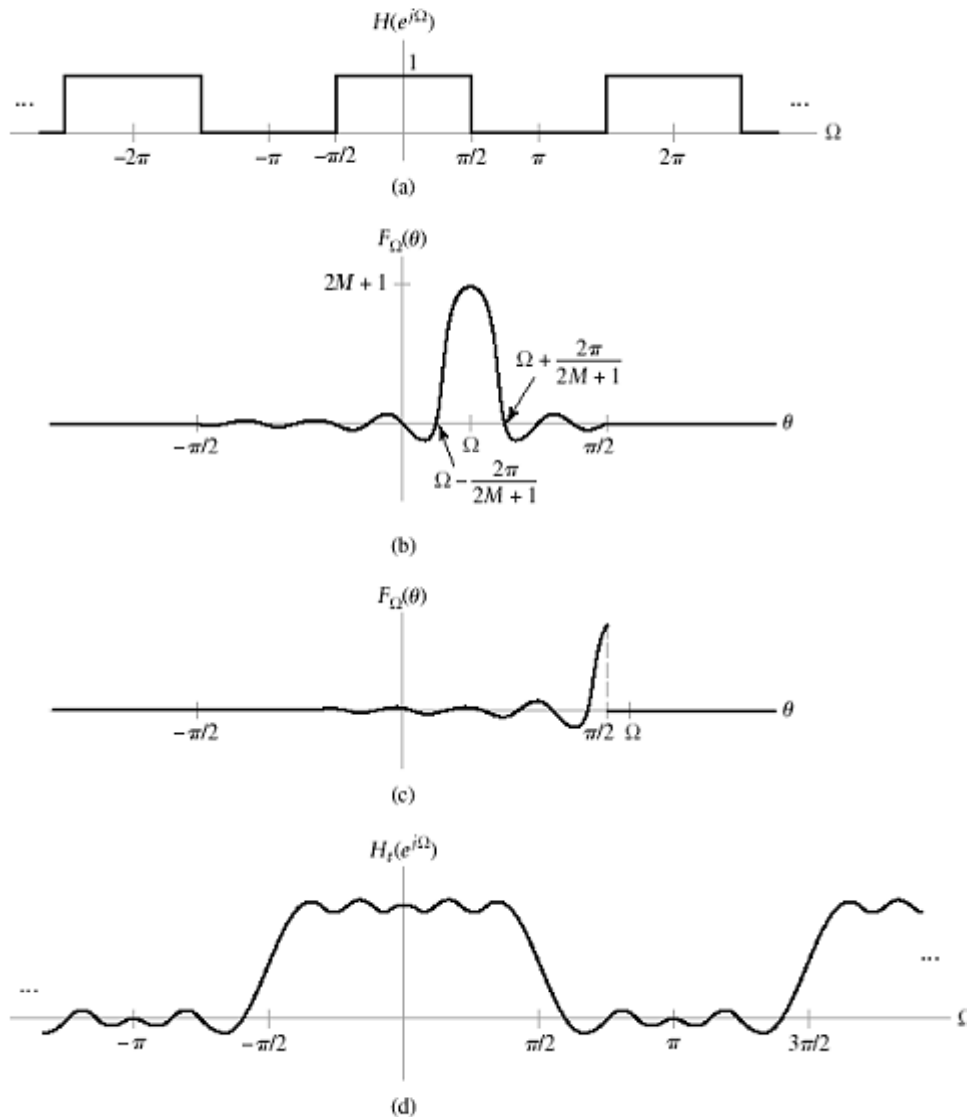


The effect of windowing.

(a) Truncating a signal in time by using a window function $w(t)$.

(b) Convolution of the signal and window FT's resulting from truncation in time.

$$x(n)z(n) \xleftrightarrow{DTFT} \frac{1}{2\pi} [X(e^{j\Omega}) \otimes Z(e^{j\Omega})] = \frac{1}{2\pi} \int_{-\pi}^{\pi} X(e^{j\theta}) Z(e^{j(\Omega-\theta)}) d\theta$$

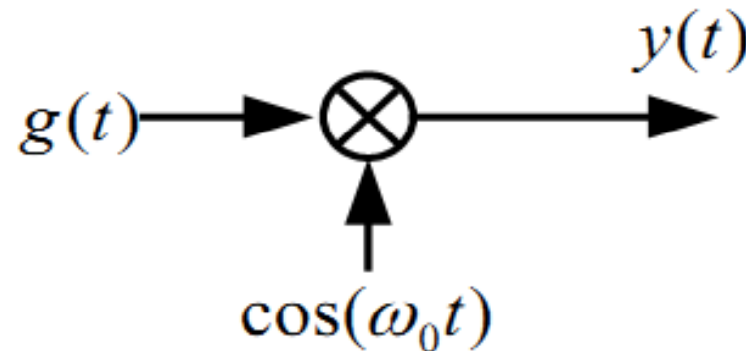


The effect of truncating the impulse response of a discrete-time system.

(a) Frequency response of ideal system. (b) $F_{\Omega}(\theta)$ for Ω near zero. (c) $F_{\Omega}(\theta)$ for Ω slightly greater than $\pi/2$.

(d) Frequency response of system with truncated impulse response.

Multiplication Property: Amplitude modulation

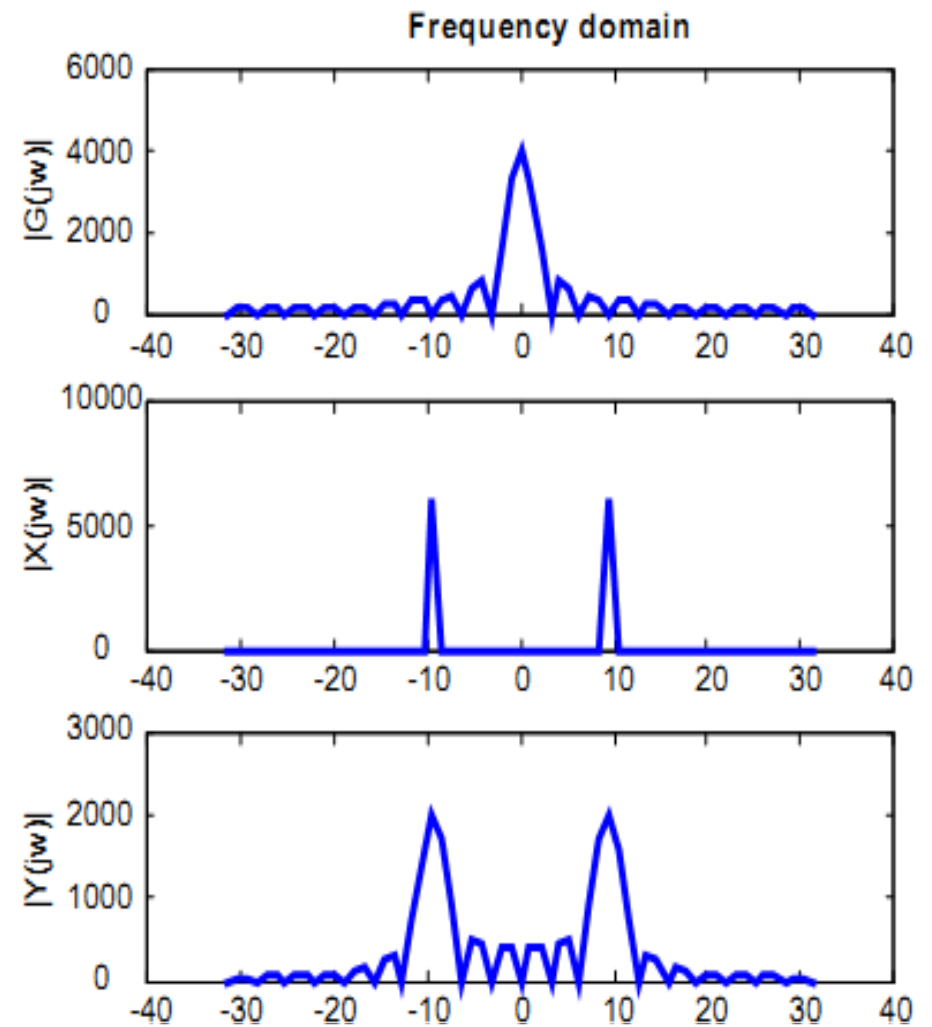
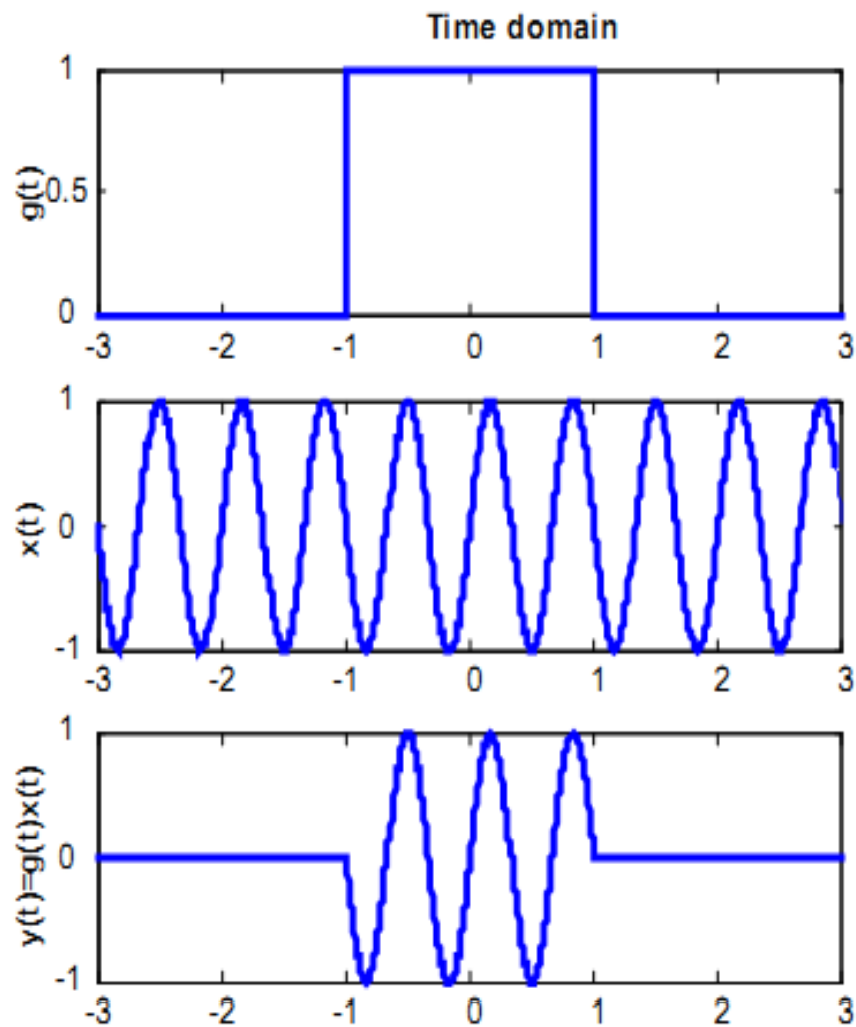


$$x(t) = \cos(\omega_0 t), \quad g(t) = \begin{cases} 1, & |t| \leq 1 \\ 0, & |t| > 1 \end{cases}, \quad \text{Find } Y(j\omega)$$

$$y(t) = g(t) \cos(\omega_0 t)$$

$$\begin{aligned} Y(j\omega) &= \frac{1}{2\pi} [G(j\omega) * \pi [\delta(\omega + \omega_0) + \delta(\omega - \omega_0)]] \\ &= \frac{1}{2} G[j(\omega + \omega_0)] + \frac{1}{2} G[j(\omega - \omega_0)] \end{aligned}$$

Multiplication Property: Amplitude modulation



Multiplication Properties of Fourier Representations

Table 3.9 Multiplication Properties of Fourier Representations

$$\begin{array}{lcl} x(t)z(t) & \xleftrightarrow{FT} & \frac{1}{2\pi} X(j\omega) * Z(j\omega) \\ x(t)z(t) & \xleftrightarrow{FS; \omega_o} & X[k] * Z[k] \\ x[n]z[n] & \xleftrightarrow{DTFT} & \frac{1}{2\pi} X(e^{j\Omega}) \circledast Z(e^{j\Omega}) \\ x[n]z[n] & \xleftrightarrow{DTFT; \omega_o} & X[k] \circledast Z[k] \end{array}$$

Scaling Property

$$z(t) = x(at)$$

$$Z(j\omega) = \int_{-\infty}^{\infty} z(t)e^{-j\omega t} dt = \int_{-\infty}^{\infty} x(at)e^{-j\omega t} dt$$

$$Z(j\omega) = \begin{cases} (1/a) \int_{-\infty}^{\infty} x(\tau)e^{-j(\omega/a)\tau} d\tau, & a > 0 \\ (1/a) \int_{\infty}^{-\infty} x(\tau)e^{-j(\omega/a)\tau} d\tau, & a < 0 \end{cases}$$

Changing
variable: $\tau = at$

$$Z(j\omega) = (1/|a|) \int_{-\infty}^{\infty} x(\tau)e^{-j(\omega/a)\tau} d\tau$$

$$z(t) = x(at) \xleftrightarrow{FT} (1/|a|)X(j\omega/a).$$

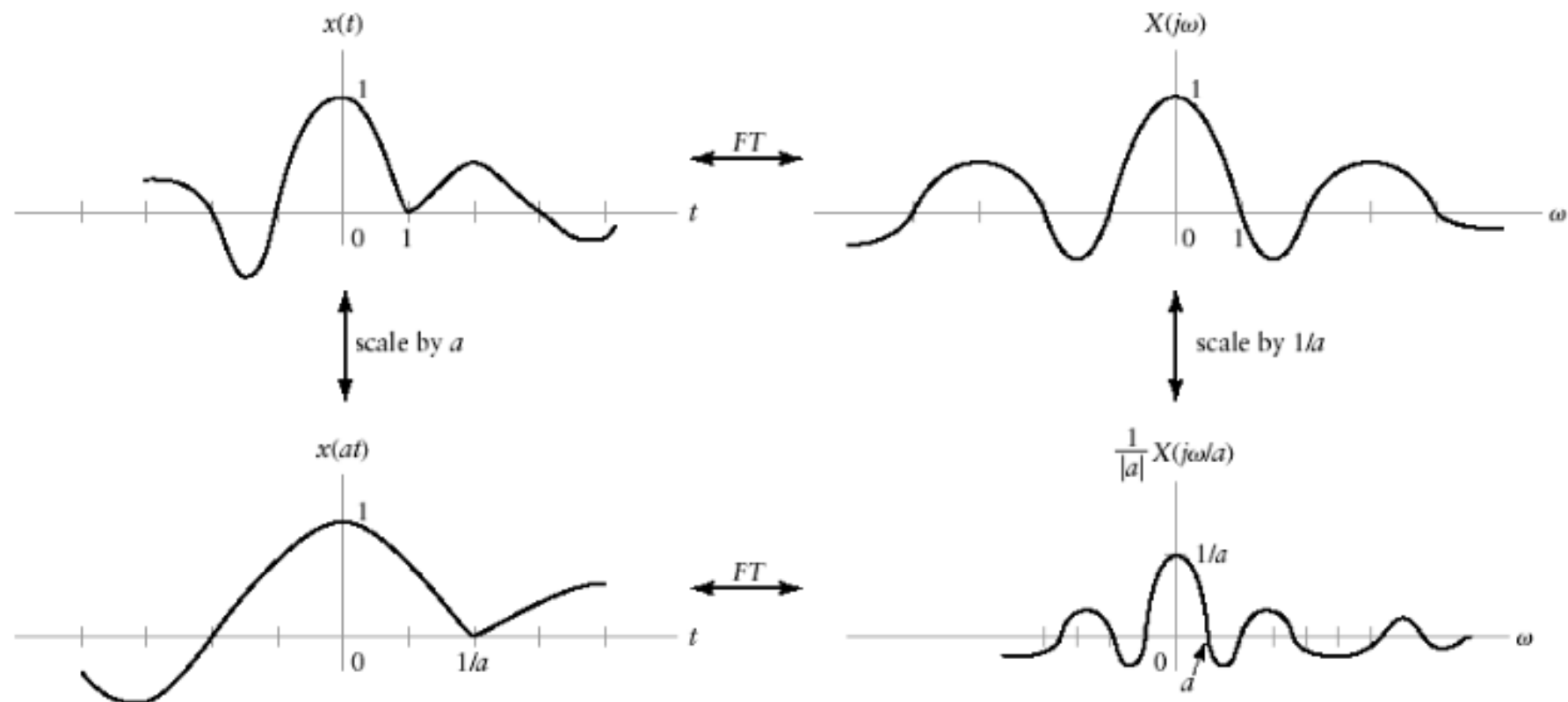
◆ **Scaling in Time-Domain \leftrightarrow Inverse Scaling in Frequency-Domain**

➡ **Signal expansion or compression!**

Scaling Property

$$x(t) \xleftrightarrow{FT} X(j\omega)$$

$$x(at) \xleftrightarrow{FT} \frac{1}{|a|} X(j\frac{\omega}{a})$$



The FT scaling property. The figure assumes that $0 < a < 1$.

Scaling Property: a Rectangular Pulse

$$z(t) = x(at) \xleftrightarrow{FT} \left(\frac{1}{|a|}\right) X\left(\frac{j\omega}{a}\right)$$

$$x(t) = \begin{cases} 1, & |t| < 1 \\ 0, & |t| > 1 \end{cases}$$

$$\Leftrightarrow X(j\omega) = \frac{2}{\omega} \sin(\omega)$$

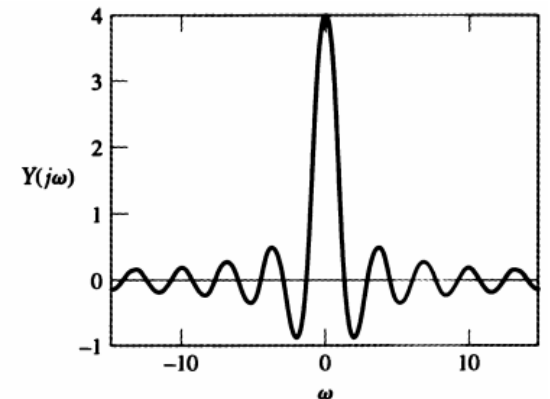
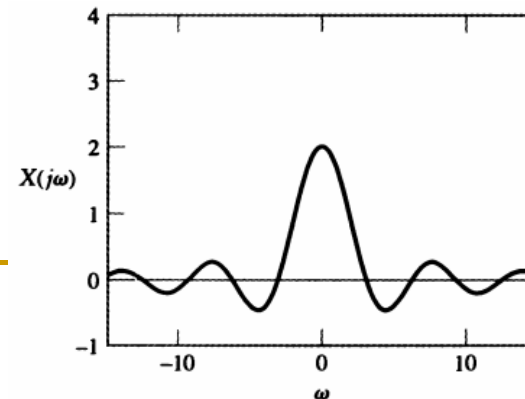
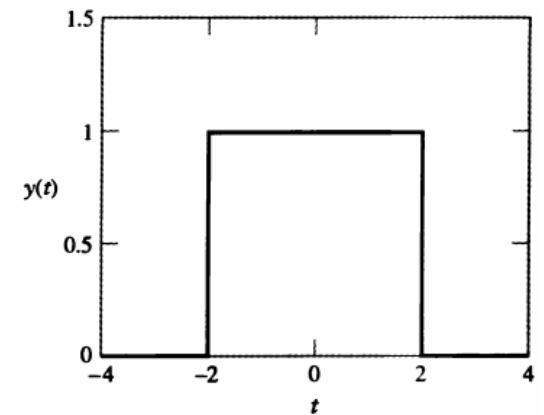
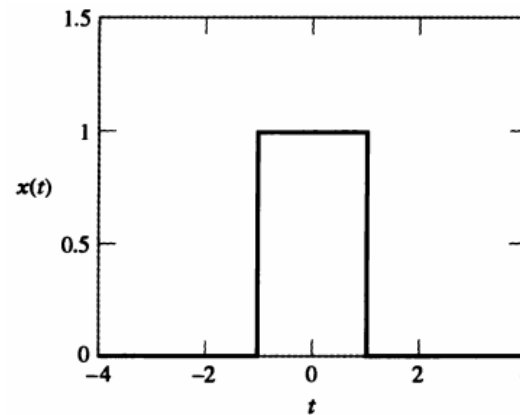
$$y(t) = \begin{cases} 1, & |t| < 2 \\ 0, & |t| > 2 \end{cases}$$

$$y(t) = x(t/2)$$

$$Y(j\omega) = 2X(j2\omega)$$

$$= 2 \left(\frac{2}{2\omega} \right) \sin(2\omega)$$

$$= \frac{2}{\omega} \sin(2\omega)$$



Parseval Relationships

♣ The energy or power in the time-domain representation of a signal is equal to the energy or power in the frequency-domain representation.

FT:

$$W_x = \int_{-\infty}^{\infty} |x(t)|^2 dt = \frac{1}{2\pi} \int_{-\infty}^{\infty} |X(j\omega)|^2 d\omega$$

DTFT:

$$W_x = \sum_{n=-\infty}^{\infty} |x(n)|^2 = \frac{1}{2\pi} \int_{\langle 2\pi \rangle} |X(e^{j\Omega})|^2 d\Omega$$

Parseval Relationships for CT nonperiodic signal

$$W_x = \int_{-\infty}^{\infty} |x(t)|^2 dt = \int_{-\infty}^{\infty} x(t)x^*(t)dt$$

$$W_x = \int_{-\infty}^{\infty} x(t) \left[\frac{1}{2\pi} \int_{-\infty}^{\infty} X^*(j\omega) e^{-j\omega t} d\omega \right] dt$$

$$W_x = \frac{1}{2\pi} \int_{-\infty}^{\infty} X^*(j\omega) \left\{ \int_{-\infty}^{\infty} x(t) e^{-j\omega t} dt \right\} d\omega$$

$$W_x = \frac{1}{2\pi} \int_{-\infty}^{\infty} X^*(j\omega) X(j\omega) d\omega$$

$$\int_{-\infty}^{\infty} |x(t)|^2 dt = \frac{1}{2\pi} \int_{-\infty}^{\infty} |X(j\omega)|^2 d\omega$$

Energy in $x(t)$

$$|x(t)|^2 = x(t)x^*(t)$$

$$x^*(t) = \frac{1}{2\pi} \int_{-\infty}^{\infty} X^*(j\omega) e^{-j\omega t} d\omega$$

◆ **Energy in Time-Domain Representation \leftrightarrow Energy in Frequency-Domain Representation $\times (1/2\pi)$**

Parseval Relationships

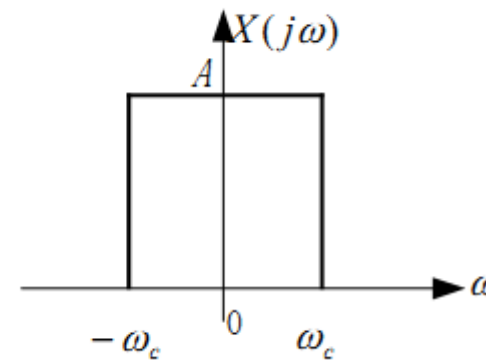
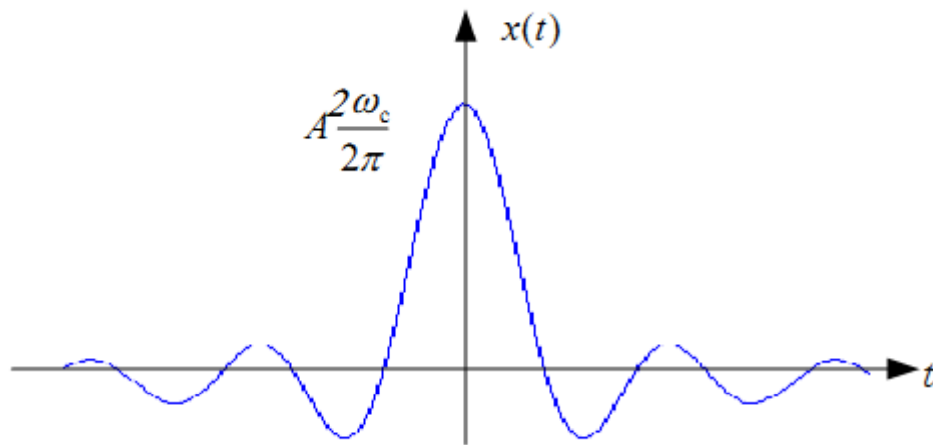
◆ The Parseval Relationships of all four Fourier representations are summarized in Table 3.10.

Representations	Parseval Relationships
FT	$\int_{-\infty}^{\infty} x(t) ^2 dt = \frac{1}{2\pi} \int_{-\infty}^{\infty} X(j\omega) ^2 d\omega$
FS	$\frac{1}{T} \int_0^T x(t) ^2 dt = \sum_{k=-\infty}^{\infty} X[k] ^2$
DTFT	$\sum_{n=-\infty}^{\infty} x[n] ^2 = \frac{1}{2\pi} \int_{-\pi}^{\pi} X(e^{j\Omega}) ^2 d\Omega$
DTFS	$\frac{1}{N} \sum_{n=0}^{N-1} x[n] ^2 = \sum_{k=0}^{N-1} X[k] ^2$

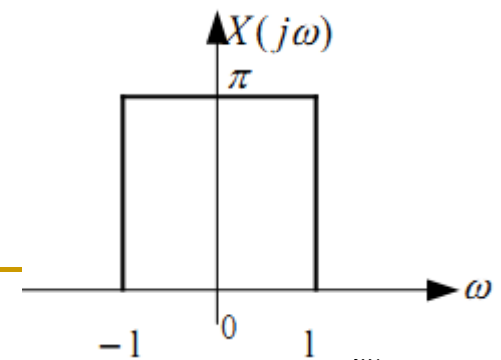
Example:

Evaluate $\int_{-\infty}^{\infty} \left(\frac{\sin t}{t}\right)^2 dt$

$$x(t) = \frac{\sin t}{t} = s_a(t) = \frac{A2\omega_c}{2\pi} s_a(\omega_c t) \quad \begin{cases} A = \pi \\ \omega_c = 1 \end{cases}$$



$$\int_{-\infty}^{\infty} \left(\frac{\sin t}{t}\right)^2 dt = \frac{1}{2\pi} \int_{-1}^1 \pi^2 d\omega = \pi$$

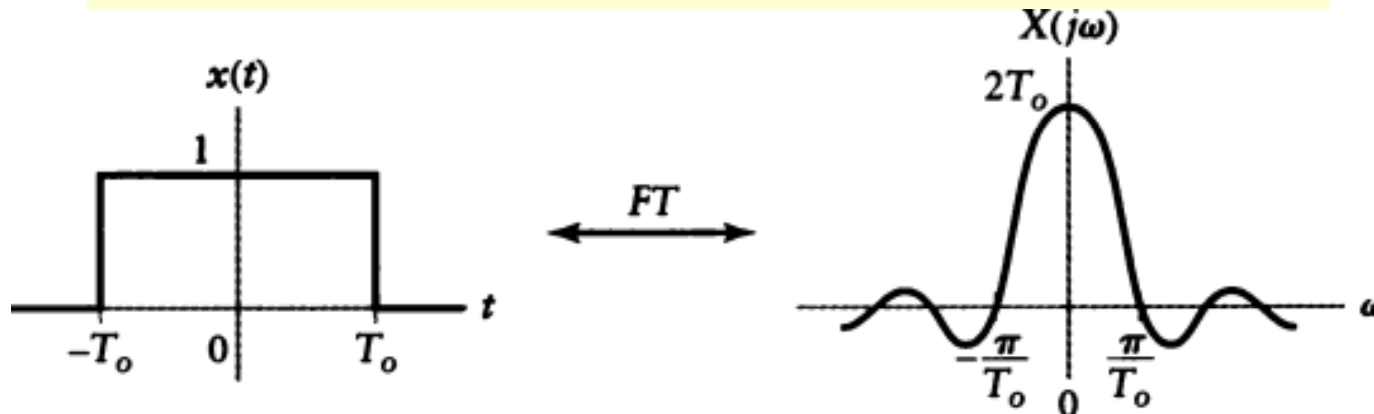


Time-Bandwidth Product

$$x(t) = \begin{cases} 1, & |t| \leq T_o \\ 0, & |t| > T_o \end{cases} \xleftrightarrow{FT} X(j\omega) = 2 \sin(\omega T_o) / \omega$$

$$2T_o \left(\pi / T_o \right) = 2\pi$$

Compressing a signal in time leads to expansion in frequency and vice versa.



1. Effective duration of a signal $x(t)$ 2. Effective bandwidth of a signal $x(t)$

$$T_d = \left[\frac{\int_{-\infty}^{\infty} t^2 |x(t)|^2 dt}{\int_{-\infty}^{\infty} |x(t)|^2 dt} \right]^{1/2}$$

$$B_w = \left[\frac{\int_{-\infty}^{\infty} \omega^2 |X(j\omega)|^2 d\omega}{\int_{-\infty}^{\infty} |X(j\omega)|^2 d\omega} \right]^{1/2}$$

The time-bandwidth product for any signal is lower bounded according to the relationship

$$T_d B_w \geq 1/2$$

Time-Bandwidth Product

Example 3.51 Bounding the Bandwidth of a Rectangular Pulse

$$x(t) = \begin{cases} 1, & |t| \leq T_o \\ 0, & |t| > T_o \end{cases}$$

- Use the **uncertainty principle** to
- place a lower bound on the effective
- bandwidth of $x(t)$.

<Sol.>

1. T_d of $x(t)$:

$$T_d = \left[\frac{\int_{-T_o}^{T_o} t^2 dt}{\int_{-T_o}^{T_o} dt} \right]^{1/2} \Rightarrow T_d = \left[\frac{\int_{-T_o}^{T_o} t^2 dt}{\int_{-T_o}^{T_o} dt} \right]^{1/2} = [(1/(2T_o))(1/3)t^3 \Big|_{-T_o}^{T_o}]^{1/2} = T_d / \sqrt{3}$$

2. According to the uncertainty principle

$$B_w \geq 1/(2T_d)$$



$$B_w \geq \sqrt{3}/(2T_o)$$

Duality Property of FT

Difference in the factor 2π and the sign change in the complex sinusoid.

1. FT pair:

$$x(t) = \frac{1}{2\pi} \int_{-\infty}^{\infty} X(j\omega) e^{j\omega t} d\omega$$

$$X(j\omega) = \int_{-\infty}^{\infty} x(t) e^{-j\omega t} dt$$

2. General equation:

Choose $\nu = t$ and $\eta = \omega$

$$y(\nu) = \frac{1}{2\pi} \int_{-\infty}^{\infty} z(\eta) e^{j\nu\eta} d\nu$$

$$y(t) = \frac{1}{2\pi} \int_{-\infty}^{\infty} z(\omega) e^{j\omega t} d\omega$$



$$y(t) \xleftrightarrow{FT} z(\omega)$$

Let $\nu = -\omega$ and $\eta = t$ Interchange the role of time and frequency

$$y(-\omega) = \frac{1}{2\pi} \int_{-\infty}^{\infty} z(t) e^{-j\omega t} dt$$



$$z(t) \xleftrightarrow{FT} 2\pi y(-\omega)$$

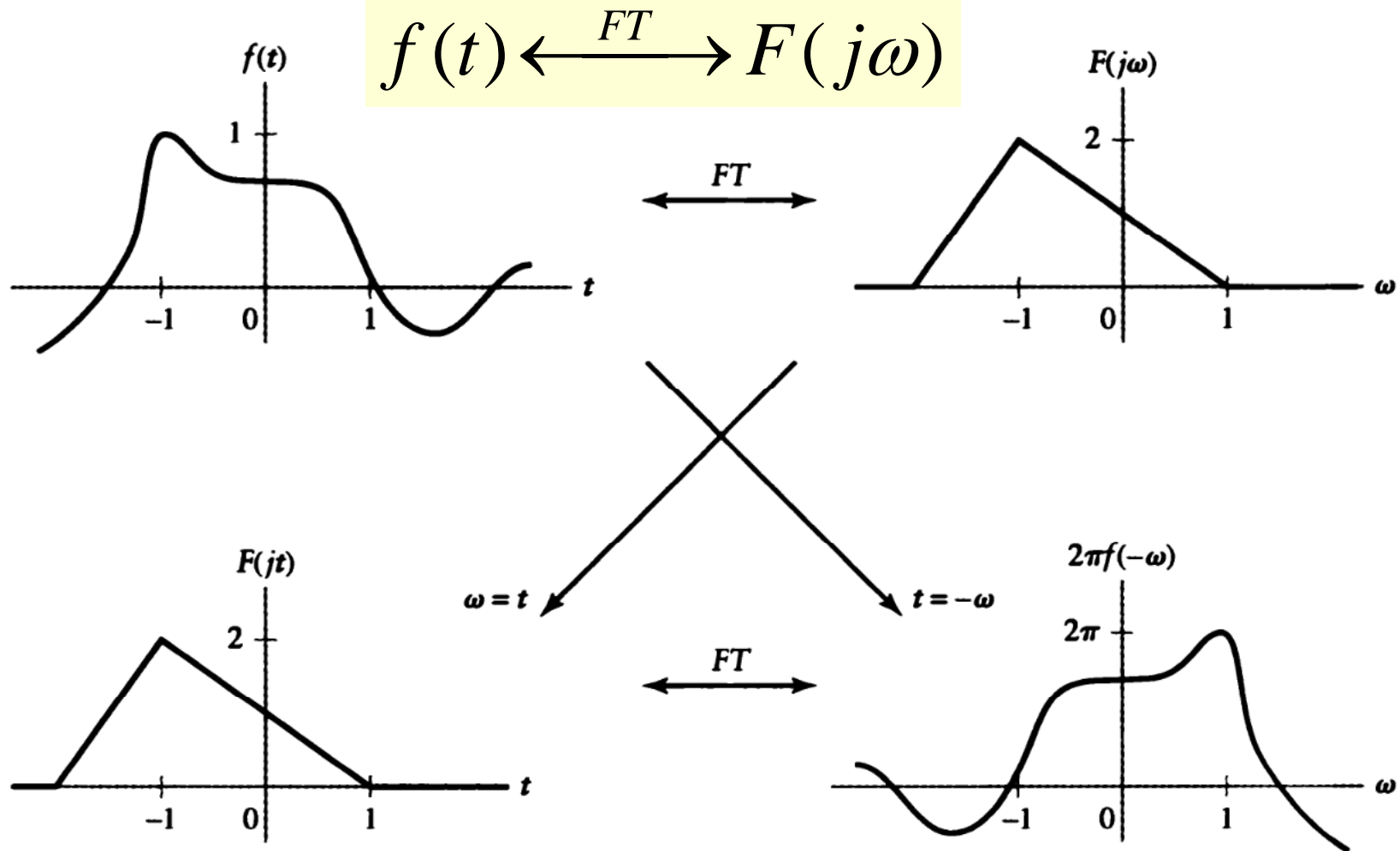
3. A new FT pair

$$y(t) \xleftrightarrow{FT} z(j\omega)$$



$$z(jt) \xleftrightarrow{FT} 2\pi y(-\omega)$$

Duality Property of FT

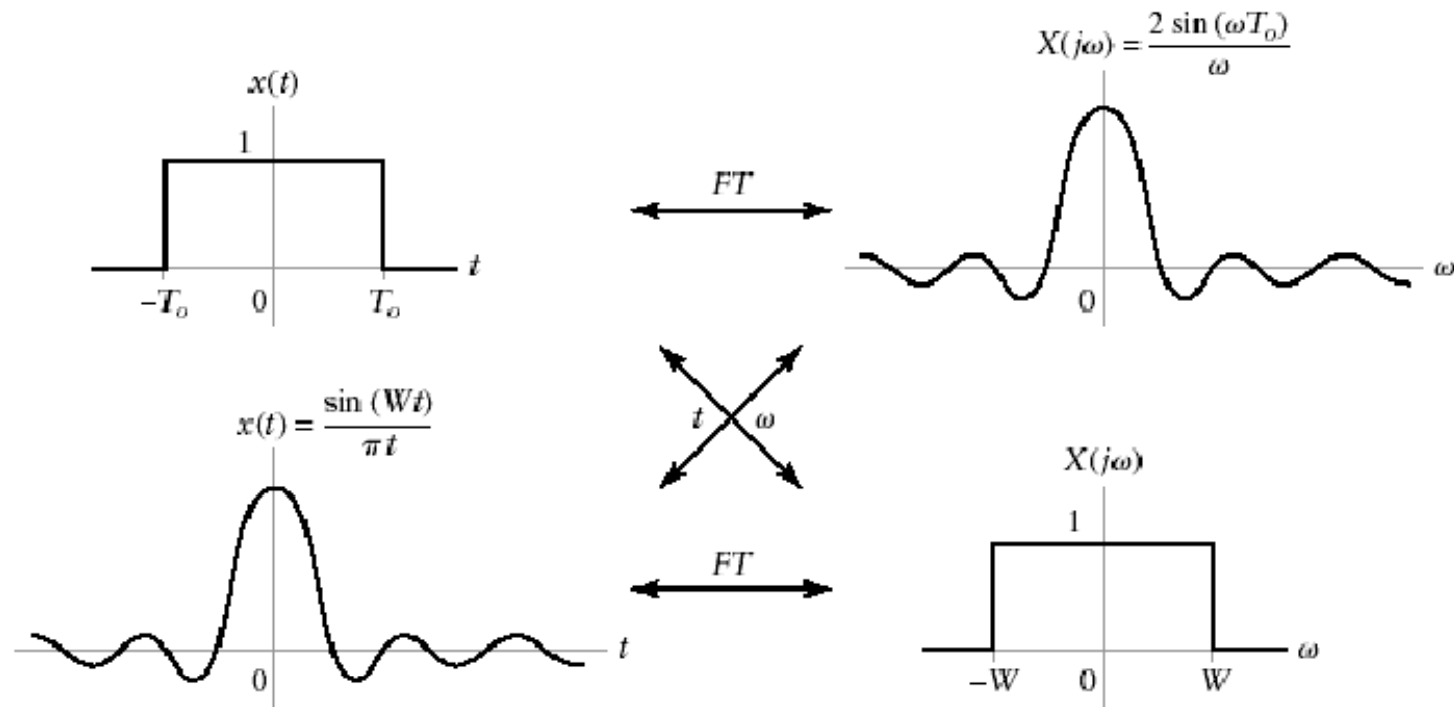


$$F(jt) \xleftrightarrow{FT} 2\pi f(-\omega)$$

Duality Property of Rectangular pulses and sinc functions

$$x(t) \xleftrightarrow{FT} X(j\omega)$$

$$X(jt) \xleftrightarrow{FT} 2\pi x(-\omega)$$



FT	$f(t) \xleftrightarrow{FT} F(j\omega)$	$F(jt) \xleftrightarrow{FT} 2\pi f(-\omega)$
DTFS	$x[n] \xleftrightarrow{DTFS; 2\pi/N} X[k]$	$X[n] \xleftrightarrow{DTFS; 2\pi/N} (1/N)x[-k]$
FS-DTFT	$x[n] \xleftrightarrow{DTFS} X(e^{j\Omega})$	$X(e^{jt}) \xleftrightarrow{FS; 1} x[-k]$

Summary and Exercises

- Summary and Exercises
 - Complex Sinusoids and Frequency Response of LTI Systems
 - Fourier Representations for Four classes of Signals
 - Properties of Fourier Representations
- Exercises (**P322-333**)
 - **3.66(a-d), 3.67(a-e), 3.68(a), 3.69(b), 3.73(a, c), 3.74(a, c), 3.76(a, b)**

FT pairs

$$\delta[n] \xleftrightarrow{DTFT} 1$$

$$\delta(t) \xleftrightarrow{FT} 1$$

$$\alpha^n u[n] \xleftrightarrow{DTFT} \frac{1}{1 - \alpha e^{-j\Omega}} \quad |\alpha| < 1$$

$$\alpha > 0$$

$$e^{-\alpha t} u(t) \xleftrightarrow{FT} \frac{1}{\alpha + j\omega}$$

$$te^{-\alpha t} u(t) \xleftrightarrow{FT} \frac{1}{(\alpha + j\omega)^2}$$

$$1 \xleftrightarrow{FT} 2\pi\delta(\omega)$$

$$1 \xleftrightarrow{DTFT} 2\pi\delta(\Omega) \quad -\pi < \Omega \leq \pi$$

$$e^{j\omega_0 t} \xleftrightarrow{FT} 2\pi\delta(\omega - \omega_0)$$

$$\cos(\omega_0 t) \xleftrightarrow{FT} \pi [\delta(\omega + \omega_0) + \delta(\omega - \omega_0)]$$

$$\sin(\omega_0 t) \xleftrightarrow{FT} -j\pi [\delta(\omega + \omega_0) - \delta(\omega - \omega_0)]$$

$$u(t) \xleftrightarrow{FT} \frac{1}{j\omega} + \pi\delta(\omega)$$

$$\text{sgn}(t) \xleftrightarrow{FT} \frac{2}{j\omega}$$

$$A \text{rect}\left(\frac{t}{\tau}\right) \xleftrightarrow{FT} A\tau \text{sinc}\left(\frac{\omega\tau}{2}\right)$$

幅度A，宽度τ，关于y轴对称的矩形脉冲

任意周期信号 $f_0 = 1/T$

$$\sum_{n=-\infty}^{\infty} F_n e^{j2\pi n f_0 t} \xleftrightarrow{FT} \sum_{n=-\infty}^{\infty} F_n \delta(f - n f_0)$$

$$\delta_T(t) = \sum_{n=-\infty}^{\infty} \delta(t - nT) \xleftrightarrow{FT} f_0 \sum_{n=-\infty}^{\infty} \delta(f - n f_0) = \sum_{m=-\infty}^{\infty} e^{-j2\pi f n T}$$