# **Real Variables**

Textbook: Real Analysis, Modern Techniques

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Introduction to Measure Theory

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#### **Definition 1.1**

Limsup  $E_n = \bigcap_{k=1}^{\infty} \bigcup_{n=k}^{\infty} E_n$  And

 $Liminf E_n = \bigcup_{k=1}^{\infty} \cap_{n=k}^{\infty} E_n$ 

*Proof.* For Limsup  $E_n = \{x : x \in E_n \text{ For infinitely many } n\}$ 

It is the intersection of all sets formed from n onward. And it there must be infinitely many n's.

Liminf  $E_n = \{x : x \in E_n \text{ For all but finitely many n} \}$ 

There's a sequecne  $E_1, E_2, ... E_n$  where you are not in  $E_n$  and then from n onwards you are in.

## **Definition 1.2**

Symmetric difference:  $E \triangle F = (E \backslash F) \cup (F \backslash E)$ 

Equivalence relations: (From Analysis)

~ is an equivalence relation if

- 1.  $x \sim x$  for all  $\Omega$
- 2.  $x \sim y$  if and only if  $y \sim x$
- 3.  $x \sim y$  and  $y \sim z \implies x \sim z$

### **Definition 1.3**

A mapping  $f: X \to Y$  is a relation from X to Y with the property that for every  $x \in X$  there is a unique  $y \in Y$  such that  $x \sim y$ . In this case, we can write y = f(x)

# Example 1.4

If  $f: X \to Y$  and  $g: Y \to Z$  are mappings, we denote  $f \circ g$  their **Composition**  $g \circ f: X \to Z$   $g \circ f(x) = g(f(x))$ 

If  $D \subset X$  and  $E \subset Y$ , we define the image of D and reverse image of E under a mapping  $f: X \to Y$  by

$$f(D) = \{f(x) : x \in D\}, f^{-1}(E) = \{x : f(x) \in E\}$$

Here, we define f(D) as the mapping of the image  $x \in D$  over f onto f(x) If  $A \subset X$ , we denote f|A the restriction of f to A:

$$(f|A): A \to Y$$
,  $(f|A)(x)$  for  $x \in A$ 

We define a finite sequence to be a map from  $\{1, 2, ... n\}$  into X where  $n \in \mathbb{N}$ .

A subsequence is when g(n) < g(m) whenever n < m, then this is called a subsequence.

#### **Definition 1.5**

Cartesian Product:  $\prod_{\alpha \subset A} X_{\alpha}$  is the set of maps  $f: A \to \bigcup_{\alpha \in A} X_{\alpha}$  such that  $f(\alpha) \in X_{\alpha}$  for every  $\alpha \in A$ 

# 1.1 Orderings

#### **Definition 1.6**

A partial ordering on a non-empty set X is a relation R on X with the properties (same as equivalence). However, not every partial ordering needs to be comparable.

## Example 1.7

Lets say we have  $\{0, 1, 2, 3\}$ . We can have  $\{0\} \le \{0, 1\}$ , but  $\{1, 3\}$  and  $\{2, 3\}$  can't be compared.

#### **Definition 1.8**

Well-Ordering.

This is similar to partial ordering, except every element is comparable. Formally, this is known as **Totality**.

For every  $a, b \in S$ , either  $a \le b$  or  $a \ge b$ .

Because every set is comparable, we also have the well-foundedness principle where every non-empty subset of S has a least element.

#### Example 1.9

The set (0,1) is not well ordered because 0 is not in S and from analysis we can show there is no  $n = \inf(S) \in S$ 

Linear (total) orderings have one more requirement: Everything can be compared.

E.g.: Fractions, Modulus,  $\{nxn\}$  matrixes that can be row-reduced.

If R also satisfies  $x, y \in X$ , then either xRy or yRx

Two partially ordered sets X and Y are said to be **Order Isomorphic** if there is a bijection  $f: X \to Y$  such that  $x_1 \le x_2$  iff  $f(x_1) \le f(x_2)$ 

Fundamental Principle of set theory and some consequences:

#### Definition 1.10

### Hausdorff Maximal Principle

Every partially ordered set has a maximal linearly ordered subset.

#### Example 1.11

A chain is contained in the maximal chain (because it contains all of the chains)

**Zorn's Lemma** If X is a partially ordered set and every linearly ordered subset of X has an upper bound, then X has a maximal element

**The Well Ordering Principle**: Every nonempty set X can be well ordered.

Using Zorn's Lemma, we can say that there is a maximal element in W. And this maximal ordering must exist on the whole set X because otherwise there would be a larger chain.

## The Axiom of Choice:

If 
$$\{X_{\alpha}\}_{\alpha\in A}$$
 is a nonempty collection of nonempty sets, then  $\prod_{\alpha\in A}X_{\alpha}$  is non-empty (1)

*Proof.* To prove H to Z: We can note that the maximal element in a maximal chain is still the maximal element of its subsets. Therefore, this maximal element is the maximal element we need from Zorn.

To prove Z to H: We need to look at the powerset of X, P(X).

We choose  $E \subset P(X)$  Such that  $c \in E$  is in Linear Order

With P(X), this contains every linearly ordered subset and has a maximal element. Therefore, we have partially ordered sets that are bounded by the maximal element X from P(X).

# 1.2 Cardinality

#### **Definition 1.12**

Injective (one to one): If different elements in the domain A map to different elements in the codomain B.

If 
$$f(a_1) = f(a_2)$$
 then  $a_1 = a_2$ 

#### **Definition 1.13**

Surjective (onto): If every element in the codomain B is the image of at least one element of the domain A.

For every  $b \in B$ , there exists  $a \in A$  such that f(a) = b. From this, lets get the simple laws.

 $card(X) \le card(Y)$  iff  $card(Y) \ge card(X)$ 

#### **Definition 1.14**

**Schroder-Bernstein Theorem**: For sets X, Y, either  $Card(X) \le Card(Y)$  or  $Card(Y) \le Card(X)$ . This implies Card(X) = Card(Y)

*Proof.* Our gameplan is to bounce back and forth between smaller subsets of A and B. Let  $f: X \to Y$  and  $g: Y \to X$ .

$$Let A_0 = A, B_0 = B$$
  
 $A_1 = g(B_0), B_1 = f(A_0)$ 

•••

We note that

$$A_0 \supseteq A_1 \supseteq A_2...$$

$$B_0 \supseteq B_1 \supseteq B_2...$$

$$A = A_0 \sim B_1 \sim A_2...$$

$$B = B_0 \sim A_1 \sim B_2...$$

We now need analogues that are pairwise disjoint. Define  $A_n^* := A_n - A_{n+1}$ 

Now we can rewrite

$$A^* = A_0^* \sim B_1^* \dots B^* = B_0^* \sim A_1^* \dots$$
 (2)

Now we get

$$A_0^* \cup A_1^* \sim B_0^* \cup B_1^*$$

Taking the Union over all N gives us

$$\bigcup_{n\geq 0} A_n^* \sim \bigcup_{n\geq 0} B_n^*$$

Rewrite the lefthand side as  $\tilde{A}$  and the righthand side as  $\tilde{B}$ . Note that  $A \neq \tilde{A}$ 

So finally we let  $A = \Box$ 

Wow! We're finally done with that.

Here's an easier proposition: card(X) < card(P(X)). I think it's trivial.

#### **Definition 1.15**

A set X is countable (denumerable) if  $card(X) \le card(N)$ . In particular, all finite sets are countable, and for these it is convenient to interpret "card(X)" as the number of elements in X.

If X is countable but infintie, card(X) is countably-infinite.

### Propositions with countability

- (a) If X and Y are countable, so is X x Y
- (b) If A is countable and  $X_a$  is countable for every  $a \in A$ , then  $\bigcup_{a \in A} X_a$  is countable.
- (c) If X is countable infinite, then  $card(X) = card(\mathbb{N})$

Z and Q are countable.

*Proof.* Z is the union of sets  $\{-n : n \in \mathbb{N}\} \cup 0$ . We can make the surjection  $f: Z^2 \to \mathbb{Q}$  by  $f(m, n) = \frac{m}{n}$ 

A set has the **cardinality of the continuum** if card(X) = card(R)

**Definition 1.16** 

 $card(P(\mathbb{N})) = \varsigma$ 

*Proof.* If  $A \in \mathbb{N}$ , define  $f(A) \in \mathbb{R}$ 

If  $card(X) > \varsigma$ , then X is uncountable.

## 1.3 Well Ordered Sets

Let X be a well ordered set. This set has an infinum and sup.

If  $x \in X$ , Define an initial segment to be:

$$I_x = \{ y \in X : y < x \} \tag{3}$$

The elements of  $I_x$  are called predecessors of x.

## **Principle of Transfinite Induction**

Let X be well ordered. If A is a subset of X such that  $x \in A$  whenever  $I_x \subset A$  then A = X

*Proof.* If 
$$X \neq A$$
, let  $x = \inf(X \setminus A)$ . Then  $I_x \subset A$  but  $x \notin A$ 

There are elements in X that are not in A.  $I_x$  is the set of all elements X that are strictly less than x. If  $I_x \subset A$  then x must be in a. We have a contradiction.

**Misconception** The interval [0,10] is not a well-ordered set. It is a partially-ordered set. A subset of [0,10] is (0,10] which does not have a least element in the subset.

#### **Definition 1.17**

If X is well ordered and  $A \subset X$ , then  $\bigcup_{x \in A} I_x$  is either an initial segment or X itself.

I think this is intuitively easy to understand, and the proof is that let  $b = \inf(X \setminus J)$ . We note that J = b.

### **Definition 1.18**

Order Isomorphic means that there is a bijecetive mapping between them that preserves their order.

Formally, Let  $(A, \leq_A)$  and  $(B, \leq_B)$  be two ordered sets.

Every countable subset has an upper bound.

# 1.4 real numbers

$$\bar{R} = \mathbb{R} \cup \{-\infty, \infty\}$$

Define sup, inf, limsup, liminf to be what you expect:

$$\limsup_{n} := \inf_{k>1} (\sup_{n>k} x_n) \liminf_{n} x_n := \sup(\inf_{n} x_n)$$

A sequence  $x_n$  converges if its limsup = liminf + it is finite. (not infinity)

Right-continuous  $f(a^+) := \lim_{x \downarrow a} f(x) = f(a)$  Left-continuous  $f(a^-) := \lim_{x \uparrow a} f(x) = f(a)$ 

Open sets: (a, b) Not open set: [a, b]

Every open set in  $\mathbb{R}$  is a countable disjoint union of open intervals.

*Proof.* 
$$x \in U$$
,  $I_x := \bigcup \{openintervalscontaining x, contained in U\}$ 

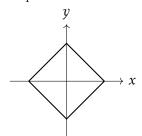
Some notes on the Euclidian norm for n dimensions:

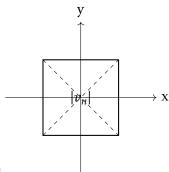
#### **Definition 1.19**

For a vector  $\mathbf{v}=(v_1,v_2,v_3,...v_n)\in\mathbb{R}^n$  we define the Euclidian norm, $\|\mathbf{v}\|_3=\left(\sum_{i=1}^n|v_i|^n\right)^{1/n}$ 

Some examples: The  $V_2$  euclidian norm looks like a circle:  $\circ$ 

The  $V_1$  euclidian norm is |x| + |y| = 1





The  $|V_n|$  euclidian norm is  $\max(|\mathbf{x}|, |\mathbf{y}|)$ 

# 1.5 Metric Spaces

A metric on a set X is a function  $\rho: X \to X \to [0, \infty)$  such that

1. 
$$\rho(x,y) = 0$$
 iff  $x = y$ 

- 2.  $\rho(x,y) = \rho(y,x)$  for all  $x, y \in X$ .
- 3. The distance thing

We can think of  $\rho$  as d(x,y)

A set equipped with a metric ( $\rho$ ) is known as a metric space.

- 1. Euclidian Distance |x y|
- 2.  $\rho_1(f,g) = \int_0^1 |f(x) g(x)| dx$  are metrics on the space of continuous functions [0,1].

Density (I am dense)

E(circle) is the largest open set contained in E  $\bar{E}$  is the smallest closed set containing E.

E is dense if  $\bar{E} = X$  and is nowhere dnese if  $\bar{E}$  has empty interior

X is **Seperable** if it has a countable dense subset. Eg:  $\{a+bi\}_{a,b\in\mathbb{Q}}$ 

Proposition: f:  $X_1 \to X_2$  is continuous iff  $f^{-1}(U)$  is open in  $X_1$  for every open U  $\subset X_2$  (preimage of any open set is open)

*Proof.* We have  $x \in X_1$  and  $\epsilon > 0$ . The set  $f^{-1}(B(\epsilon, f(x)))$  maps us back to x except now we have an open ball around x. Assume we are continuous. Then for  $y \in U$  we can make  $B(\epsilon_y, y) \in U$  since U is open. And since f is continuous, we let  $x \in f^{-1}(\{y\})$  and define  $\delta_x > 0$  s.t. $B(\delta_x, x) \subset f^{-1}(B(\epsilon_y, y)) \subset f^{-1}(u)$ 

Thus 
$$f^{-1}(u) = \bigcup_{x \in f^{-1}(u)} B(\delta_x, x)$$
 is open.

For a counterexample, if f is not continuous, then we are unsure how f could map us.

#### **Definition 1.20**

A sequence  $\{X_n\}$  in a metric space (X, p) is Cauchy if  $p(X_n, X_m) \to 0$  as n, m  $\to \infty$ . A subset is called complete if every Cauhcy sequence in E converges and its limit is in E.

 $\mathbb{R}$  is complete, and  $\mathbb{Q}$  is not.

A closed subsetof a complete metric space is complete, and a complete subset of an arbitrary metric space is closed.

*Proof.* If X is complete,  $E \subset X$  is closed.

 $x \in \overline{E}$  HEY WHERES THE PROOF

True: intersection of finite open sets is open

False: intersection of all open sets is open. B/c  $\{0, 1/n\} \rightarrow 0$ 

We can define distances from a point to a set and distances between two sets. Let's say we have E,  $F \subset X$ . Then we take the distance between the sets as  $\inf(e \in E, f \in F)$ .

The following are equivalent

- 1. E is complete and totally bounded
- 2. Every sequence in E has a subsequence that converges to a point of E.
- 3. Heine-Borel: If  $\{V_a\}_{a\in A}$  is a cover of E by open sets, there is a finite set  $F\subset A$  such that  $V_a$  covers E.

From (a) to (b): Suppose E can be covered by finitely many balls of radius  $2^{-1}$ . At least one of them must contain X. We can keep making the balls smaller and we can become smaller than any  $\epsilon > 0$ .

From (b) to (a): If either condition in A fails, then (b) fails. If E is not complete, then there is some subsequence that won't converge in E. No subsequence can converge in E otherwise the whole sequence would converge.

Lets assume E can't be totally bounded: Let  $\epsilon > 0$  such that E can't be covered by finitely many balls of radius  $\epsilon$ . Assume  $x_n \in E$  but then  $x_{n+1} \notin$  the covered section of E. Then  $p(x_n, x_m) > \epsilon$ .

From (a, b) to (c): If (b) holds and  $\{V_a\}_{a\in A}$  is a cover of E by open sets, **idk write** the rest of the proof later

From (c) to (b): If  $X_n$  is a sequence in E with no converging subsequence, then there are finitely many Balls such that  $x_n \in B(B_{\epsilon}, x)$ . Then  $\{B_x\}_{x \in E}$  is a cover of E by open sets.

### **Definition 1.21**

A set that is coverable is compact

If you look very closely then you will see this is true.

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Motivation: For a function to be riemann integrable, it is almost everywhere continuous.

Reminder: Riemann sums are defined as:  $\sum_{n=1}^{n=\infty} \left( G_j(x_{n+1} - x_n) \right) = \sum_{n=1}^{n=\infty} \left( g_j(x_{n+1} - x_n) \right)$  where  $g_n$  = is the lower end of a function and  $G_n$  is the upper end.

A function is defined to be riemann integratable if this lower and upper bound both converge to the same value.

We want to define a Lebesgue integral such that we don't run into these issues.

1. If  $E_1, E_2, ...$  is a finite or infinite sequence of disjoint sets, then

$$\mu(E_1 \cup E_2 \cup ...) = \mu(E_1) + \mu(E_2) + ..., \tag{4}$$

- 2. If E is congruent to F (that is, if E can be transformed info F by translations, rotations, and reflections), then  $\mu(E) = \mu(F)$ .
- 3.  $\mu(Q) = 1$ , where Q is the unit cube

$$Q = \{x \in \mathbb{R}^n : 0 \le x_j < 1 \text{ for } j = 1,...n\}$$

TLDR: Sadly, we can't really define a measure like this.

Counterexample: consider a circular set on [0, 1) with equivalence relations being that  $x \sim y$  if  $x - y \in \mathbb{Q}$ . This means x and y must be  $\pi$  away. Construct  $N_r$  to be this set transformed to the right by  $r \in \mathbb{Q}$ . We can construct all numbers in [0, 1) through the union of all  $N_r$ 's. Then we have  $\mu([0, 1)) = \sum_{r \in R} \mu(N_r)$ . But since  $\mu(N) = \mu(N_r)$  by (ii) since translations shouldn't add or subtract measure from a set, we get  $\mu([0, 1)) = \sum_{r \in R} \mu(N)$ .

We have a contradiction since  $\mu([0,1)) = 1$  by definition of a measure, and if  $\mu(N) > 0$ , then the sum goes to infinity, but if it equals 0, then the measure is 0.

Another comment: in higher dimensions with a weaker (i), Banach and Tarski proved that you can multiply a pea until infinite peas.

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# 2.1 $\sigma$ -algebras

Let's start by defining a  $\sigma$ -algebra.

#### **Definition 2.1**

To be a  $\sigma$ -algebra on X means

- 1. (Closure under complements) If  $A \in X$ , then  $A^c \in X$
- 2. (Closure under countable unions) If  $A_1, A_2, ... A_n \in X$ , then  $\bigcup_{n=1}^{\infty} A_n \in X$
- 3. A is in X.

The intersection of any family of  $\sigma$ -algebras is another  $\sigma$ -algebra. (The textbook said this is Trivial, I do not think so)

*Proof.* A  $\sigma$ -algebra can't be empty. It must contain  $\{\Omega,\emptyset\}$ . If A is included in this  $\sigma$ -algebra, then A must have been included and also  $A^c$ . Then,  $A^c$  is in our new algebra and also the old ones, and our set now contains A alongside  $A^c$  to form another functional algebra.

Now, using this we have that if  $\epsilon$  is in any subset of P(X) there must be a unique smallest  $\sigma$ -algebra M( $\epsilon$ ) containing  $\epsilon$ . Specifically, the intersection of all  $\sigma$ -algebras containing  $\epsilon$ . M( $\epsilon$ ) is called the  $\sigma$ -algebra generated by  $\epsilon$ .

# **Proposition 2.1**

If  $\epsilon \subset M(\mathcal{F})$ , then  $M(\epsilon) \subset M(\mathcal{F})$ 

Bring up next class: Should it be  $\subseteq$ . Example:  $M(F) = \{\emptyset, F, F^c, \Omega\} \in \{\emptyset, F\}$ Then  $M(\epsilon) = M(F)$ .